



Asynchronous geared motors



STÖBER

Asynchronous geared motors

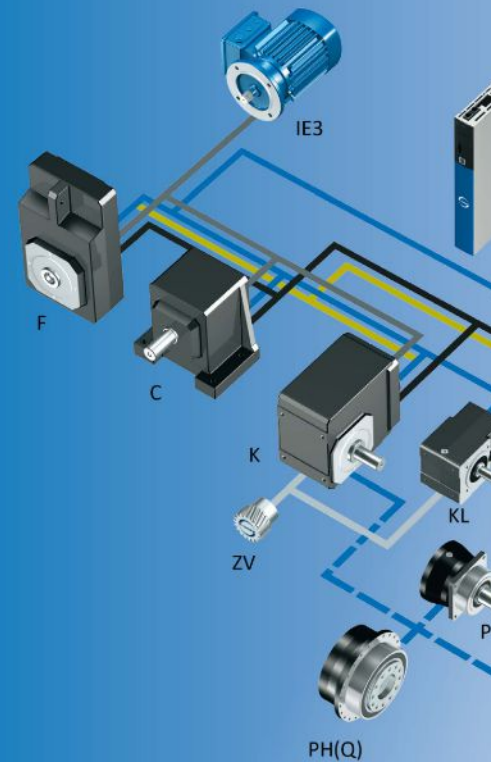
One partner. All the possibilities.

STOBER has developed and produced excellent drive technology since 1934 and is active internationally with around 1000 employees at 10 locations. STOBER impresses machine manufacturers in wide-ranging industries and markets around the world with tailor-made, highly efficient drive systems for demanding movements.



"Our vision is to be the preferred partner for perfect movement."

- Andreas Thiel, CEO of STÖBER Antriebstechnik.



Asynchronous geared motors – what you can expect!

Are you looking for a compact, economically attractive geared motor for harsh industrial environments? With high efficiency? Helical gearing? And an asynchronous motor with the IE3 energy efficiency class? Whether with helical, helical bevel or offset helical gear units, you can rely on classic, proven mechanics combined with a robust IE3D motor – a plus in terms of reliability and efficiency. Everything from a single source? Of course, we also have the appropriate electronics and connection technology. You can't get more reliable than that.

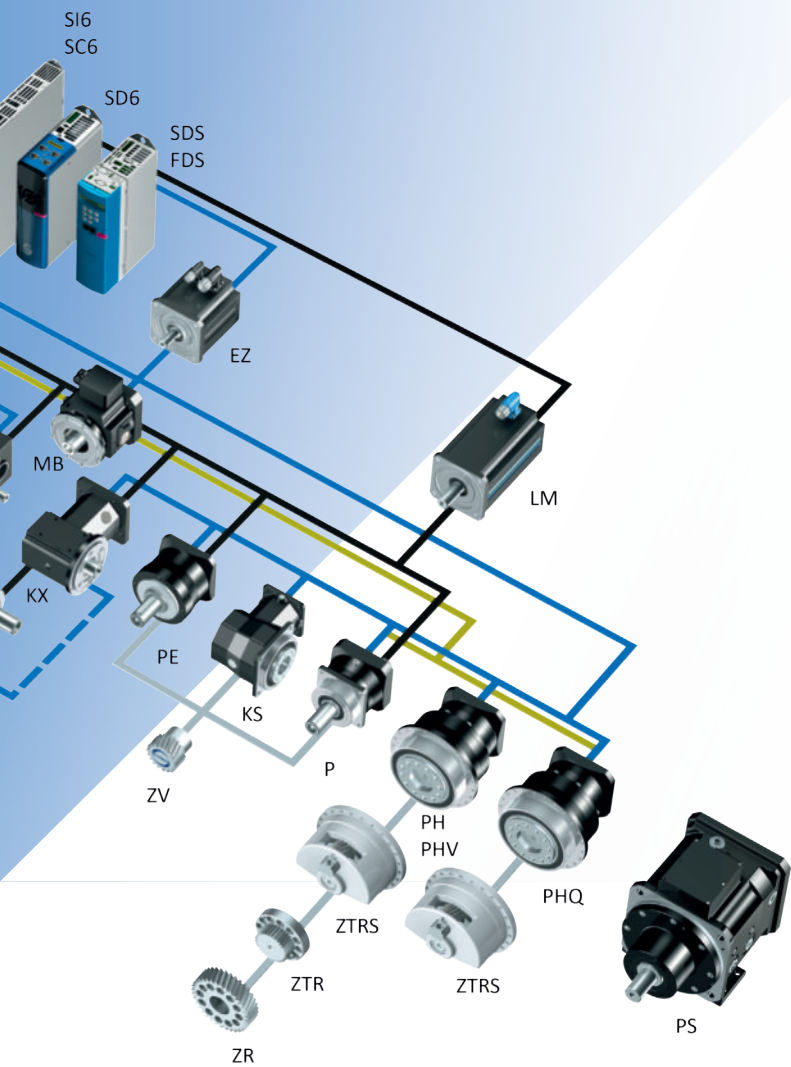
At home in the world of demanding motion

Gear units

Geared motors

Motors

Cables and drive controllers



Everything from a single source.

The STOBER drive system consisting of gear units, motors, cables and drive controllers has a modular design and is freely scalable—for tailor-made, compact and powerful machine concepts. It can be adapted to your individual requirements and combined as needed in nearly all industries and applications areas.

We check every single component and how it works together with others, taking on the responsibility for the complete drive train. For you, this means that one contact partner, certified operating safety and maximum availability are guaranteed.

Need special solutions?

Numerous one-of-a-kind product highlights and project-related adjustments make it possible. With a holistic approach to your specific task, we work together on individualized solutions that are optimally coordinated to your requirements. Dedicated and solution-oriented in the support of your visions and projects.

STOBER moves integrally and precisely.



"We put ideas in motion with passion and a great deal of dedication. In the process, we rely on our decades of experience and an exceptionally broad range of products. Our customers benefit from precise, practical system solutions with uncompromising quality and expert individual consultation."

- Patrick Stöber, CEO of STÖBER Antriebstechnik.



STOBER moves as a team and with personality.

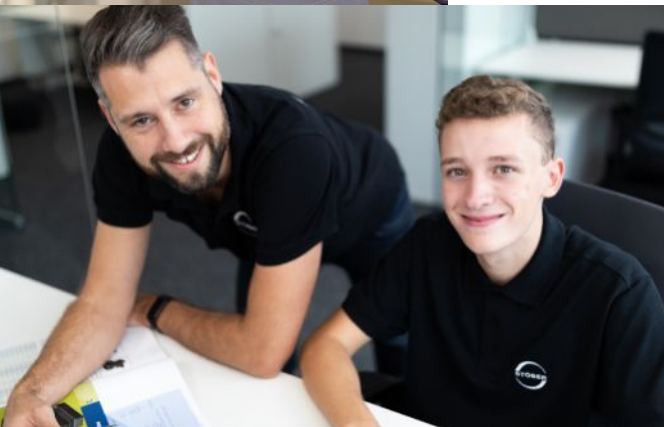
As a family-owned company, it is very important to us to maintain close relationships and treat each other with trust. We put people first.

We are committed to the well-being of our employees, identify with the expectations of our customers, and show personal commitment to mutual success.



"We have installed gear units, motors and drive controllers from STOBER in nearly all our systems. STOBER supports us in new projects from the first stroke of a pencil in the design phase until commissioning. Our years of cooperation are shaped by openness and honesty and emanate a rather special spirit. The technical consulting, the support—that is real, experienced partnership"

- Jürgen Leicht, Managing Partner of Leicht Stanzautomation.



Working together. Worldwide. Successfully.

With an eye to the future, STOBER is facing the challenges of digitalization and investing in integrated solutions and a strong global production, sales and service presence. STOBER China was founded at the end of 2019. As a result, we are present in more than 40 countries around in the world with eleven subsidiaries and 80 service partners.



**STOBER drives
Systems technology
Taicang, China.**



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1 Selection tool

1.1 Asynchronous geared motors



Product chapter

C

F

Chapter number

[2]

[3]

Technical data

P_N	0.12 – 30 kW	0.12 – 7.5 kW
i	2 – 274	4.3 – 547
M_{2N}	2.3 – 8677 Nm	5.1 – 1338 Nm
η_{get}	96 – 97 %	96 – 97 %

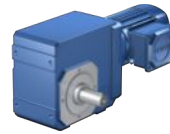
An explanation of the formula symbols can be found in the chapter [▶ 13.1](#).

Features

Power density	★☆☆☆☆	★☆☆☆☆
Price category	€	€
Shaft load	★☆☆☆☆	★☆☆☆☆
Smooth operation	★☆☆☆☆	★☆☆☆☆
Torsional stiffness	★☆☆☆☆	★☆☆☆☆
Mass moment of inertia	★★★★★	★★★★★
Key	★☆☆☆☆ good ★★★★★ excellent € Economy €€€€€ Premium	
Shaft design		
Solid shaft with feather key	✓	✓
Solid shaft without feather key	C0 – C5: ✓ Starting at C6: Request	
Hollow shaft with keyway		✓
Hollow shaft with shrink ring		✓
Bearing design		
Standard	✓	✓
Maintenance-free	C0 – C5: ✓	✓

1 Selection tool

1.1 Asynchronous geared motors



Product chapter

K

Chapter number

[4]

Technical data

P_N	0.12 – 30 kW
i	4 – 381
M_{2N}	6.5 – 13970 Nm
η_{get}	94 – 97 %

An explanation of the formula symbols can be found in the chapter [▶ 13.1](#).

Features

Power density	★★☆☆☆
Price category	€€
Shaft load	★★★★☆
Smooth operation	★★★★☆
Torsional stiffness	★★☆☆☆
Mass moment of inertia	★★★★★
Key	★★☆☆☆ good ★★★★★ excellent € Economy €€€€€ Premium
Shaft design	
Solid shaft with feather key	✓
Solid shaft without feather key	K1 – K4: ✓ Starting at K5: Request
Solid shaft on both sides	✓
Hollow shaft with keyway	✓
Hollow shaft with shrink ring	✓
Bearing design	
Standard	✓
Maintenance-free	K1 – K4: ✓

1 Selection tool

1.2 Asynchronous motors



Product chapter

IE3D

Chapter number

[5]

Technical data

n_2	1400 – 1480 rpm
P_N	0.12 – 30 kW
M_N	0.82 – 194 Nm
I_N	0.35 – 54 A

An explanation of the formula symbols can be found in the chapter [▶ 13.1](#).

Features

Efficiency	★★★★☆
Price category	€€
Key	★☆☆☆☆ good ★★★★★ excellent € Economy €€€€€ Premium
Shaft design	
Direct attachment onto STOBER gear units	✓
IEC design	✓
Encoder	
Incremental encoders	✓
SSI multi-turn absolute encoders ¹	✓
Electrical connection	
Terminal box	✓
Cooling	
Self-ventilation	✓
Forced ventilation	✓
Brake	
Spring-loaded brake	✓
Marks and test symbols	
CE	✓
cURus	✓
EISA CC number including cURus	Request

¹ only in combination with forced ventilation

1 Selection tool

1.3 Drive controllers



SC6



SI6



SD6

Product chapter

Chapter number

[▶ 6](#)

[▶ 7](#)

[▶ 8](#)

Technical data

	SC6	SI6	SD6
$I_{2N,PU}$	4.5 – 19 A	5 – 50 A	2.3 – 85 A
$I_{2N,PU}$	4 – 15 A	4.5 – 40 A	1.7 – 60 A
I_{2maxPU}	9.5 – 39.9 A	10.5 – 105 A	4.2 – 153 A
I_{2maxPU}	10 – 37.5 A	11.3 – 100 A	4.3 – 150 A

An explanation of the formula symbols can be found in the chapter [▶ 13.1](#).

Features

Optimal application area			
Number of axes	1 – 4	> 4	1 – 8
Application	Drive Based	CiA 402, PROFIdrive	Drive Based Synchronous
Motor types			
Lean motors	✓	✓	
Asynchronous motors	✓	✓	✓
Synchronous servo motors	✓	✓	✓
Linear motors			✓
Torque motors	✓	✓	✓
Encoder interfaces			
EnDat 2.2 digital	✓	✓	✓
Incremental	✓	✓	✓
SSI	✓	✓	✓
Resolver	✓	✓	(✓)
Pulse/direction signals	✓	✓	(✓)
EnDat 2.1 sin/cos			(✓)
Sin/cos			(✓)
EnDat 3 (OCS)	✓	✓	
(✓): Terminal module required			
Communication			
Isochronic system bus (IGB motion bus)			✓
CANopen			(✓)
EtherCAT	✓	✓	(✓)
PROFINET	✓	✓	(✓)
(✓): Communication module required			

1 Selection tool

1.3 Drive controllers



SC6



SI6



SD6

Product chapter

Chapter number

[▶ 6](#)

[▶ 7](#)

[▶ 8](#)

Features

Motor temperature sensor

PTC thermistor	✓	✓	✓
Pt1000 temperature sensor	(✓)	(✓)	✓
(✓): OCS required			

Safety functions

STO, SS1: SIL 3, PL e (cat. 4)	(✓)	(✓)	(✓)
SS2, SLS, SBC, SBT, SDI, SLI: SIL 3, PL e (cat. 4)			(✓)
(✓): Safety module required			

Terminals

			IO6	RI6	XI6
Digital inputs	8	8	(5)	(5)	(13)
Digital outputs	—	—	(2)	(2)	(10)
Analog inputs	—	—	(2)	(2)	(3)
Analog outputs	—	—	(2)	(2)	(2)
Expanded encoder support	—	—	—	(✓)	—

(x): Terminal module required

Features

Multi-axis drive system		✓	
Stand-alone	✓		✓
One Cable Solution (OCS)	✓	✓	
Double-axis controller available	✓	✓	
Live firmware update	✓	✓	✓
Display and keyboard			✓
Removable data storage	✓	✓	✓
DC link connection	✓	✓	✓

Applications

Torque/force mode	✓	✓	✓
Velocity mode	✓	✓	✓
Positioning mode	✓	✓	✓
Master/slave mode			✓
Interpolating mode	✓	✓	✓

Conformity

cULus	✓	✓	✓
CE	✓	✓	✓
UKCA	(In preparation)	(In preparation)	(In preparation)

1 Selection tool

1.3 Drive controllers



SDS 5000



FDS 5000

Product chapter

Chapter number

[9]

[10]

Technical data

$I_{2N,PU}$	2.3 – 85 A	1.3 – 16 A
$I_{2N,PU}$	1.7 – 60 A	1 – 10 A
I_{2maxPU}	4.2 – 153 A	2.4 – 28.8 A
I_{2maxPU}	4.3 – 150 A	2.5 – 25 A

An explanation of the formula symbols can be found in the chapter [\[13.1 \]](#).

Features

Optimal application area

Number of axes	1 – 8	1 – 4
Application	Drive Based Synchronous	Drive Based

Motor types

Asynchronous motors	✓	✓
Synchronous servo motors	✓	

Encoder interfaces

EnDat 2.1/2.2 digital	✓	
Incremental	✓	✓
SSI	✓	
Resolver	(✓)	
Pulse/direction signals	(✓)	✓
EnDat 2.1 sin/cos	(✓)	

(✓): Terminal module required

Communication

Isochronic system bus (IGB motion bus)	✓	
CANopen	(✓)	(✓)
EtherCAT	(✓)	(✓)
PROFINET	(✓)	(✓)
PROFIBUS DP	(✓)	(✓)

(✓): Communication module required

Motor temperature sensor

PTC thermistor	✓	✓
Pt1000 temperature sensor	✓	✓

1 Selection tool

1.3 Drive controllers



SDS 5000



FDS 5000

Product chapter

Chapter number

[9]

[10]

Features

Safety functions

STO, SS1: SIL 3, PL e (cat. 3)

(✓)

(✓)

(✓): Safety module required

Terminals

SEA 5001

REA 5001

XEA 5001

Base unit

LEA 5001

Digital inputs

(5)

(5)

(13)

5

(8)

Digital outputs

(2)

(2)

(10)

2

(8)

Analog inputs

(2)

(2)

(3)

2

—

Analog outputs

(2)

(2)

(2)

2

—

Expanded encoder support

—

(✓)

—

—

—

(x): Terminal module required

Features

Stand-alone

✓

✓

Live firmware update

✓

Display and keyboard

✓

✓

Removable data storage

✓

✓

DC link connection

✓

✓

Applications

Torque/force mode

✓

✓

Velocity mode

✓

✓

Positioning mode

✓

✓

Master/slave mode

✓

✓

Electronic cam disk

✓

✓

Conformity

cULus

✓

✓

CE

✓

✓

UKCA

(In preparation)

(In preparation)

1 Selection tool

1.4 Connection method



Product chapter

Cables

Chapter number

[11]

Encoder cables

Design	Motor plug connector size
	con.23
speedtec quick lock	✓
Encoder	Motor plug connector size
	con.23
Incremental (HTL)	✓
SSI	✓

Encoder	Supply cores	Pilot cores	Cable Ø	Bending radius 1 (min.)	Bending radius 2 (min.)
Incremental (HTL)	2 × 0.25 mm ²	3 × 2 × 0.14 mm ²	Max. 6.8 mm	68.0 mm	34.0 mm
SSI	2 × 0.25 mm ²	3 × 2 × 0.14 mm ²	Max. 6.8 mm	68.0 mm	34.0 mm

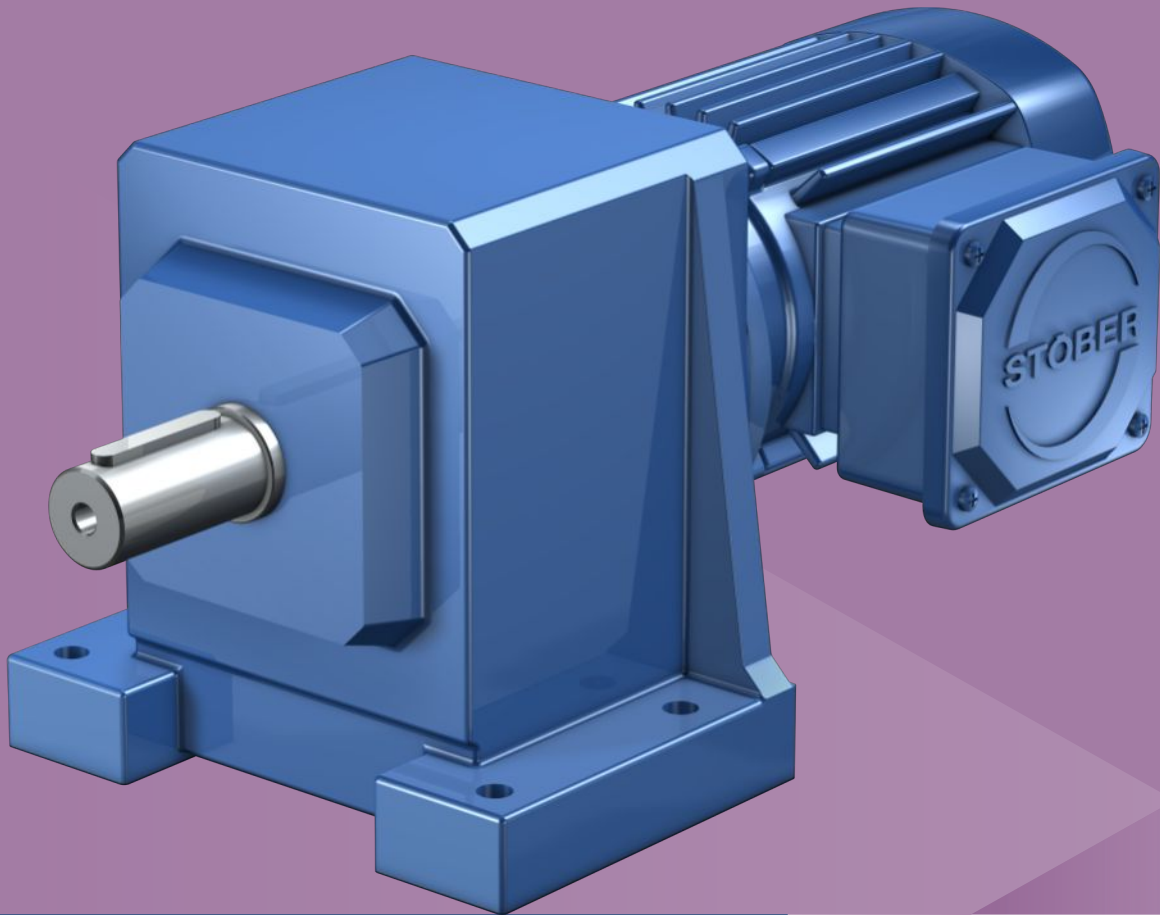
Bending radius: 1 = free to move, 2 = fixed installation

Other	
Torsional stress	± 30°/m
Bending resistance	✓
Resistant to oil and chemicals	✓

2 C helical geared motors

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2 Helical geared motors

C

2.1 Overview

Compact helical geared motors

Features

Power density	★☆☆☆☆
Backlash	★★★★☆
Price category	€
Shaft load	★★★★☆
Smooth operation	★★★★☆
Torsional stiffness	★★★★☆
Mass moment of inertia	★★★★★
Helical gearing	✓
Maintenance-free (C0 – C5)	✓
FKM seal ring at the input	✓
Reinforced output bearing	✓ (on request)
Energy efficiency class IE3 in accordance with EN 60034-30-1	✓

Key ★☆☆☆☆ good | ★★★★★ excellent

€ Economy | €€€€€ Premium

Technical data

P_N	0.12 – 30 kW
i	2 – 274
M_{2N}	2.3 – 8677 Nm
η_{get}	96 – 97 %

2.2 Selection tables

The technical data specified in the selection tables applies to:

- Installation altitudes up to 1000 m above sea level
- Surrounding temperatures from 0 °C to 40 °C
- Drives with self-ventilated motors
- Weight specification for mounting position EL1, housing design N

You can receive asynchronous geared motors with low output speed on request.

Asynchronous geared motors are ideal for operation on a drive controller (87 Hz). More information can be found in chapter [▶ 5.6.2](#)

For all other technical data, refer to <https://configurator.stoeber.de/en-US/>.

An explanation of the formula symbols can be found in the chapter [▶ 13.1](#).

n_2 50 Hz [rpm]	S	n_2 87 Hz [rpm]	S	M_{2N} [Nm]	Type	m [kg]	i	i_{exakt}	J_1 [kgcm ²]
P_N (50 Hz) = 0,12 kW, P_N (87 Hz) = 0,21 kW									
7.6	0.83	13	0.83	144	C103_1840 IE3D063K04	20	183.7	2021/11	4.0
10	1.1	18	1.1	108	C103_1370 IE3D063K04	20	137.3	10575/77	4.1
13	1.4	22	1.4	87	C103_1110 IE3D063K04	20	111.1	1222/11	4.1
15	1.7	26	1.7	72	C103_0920 IE3D063K04	20	92.13	16215/176	4.1
17	1.9	30	1.9	64	C103_0820 IE3D063K04	20	81.64	31349/384	4.1
20	1.1	35	1.1	56	C002_0700 IE3D063K04	12	69.88	559/8	4.0
20	2.1	34	2.1	56	C102_0700 IE3D063K04	17	70.46	775/11	4.0
22	1.2	39	1.2	50	C002_0620 IE3D063K04	12	62.35	1247/20	4.0
22	2.4	39	2.4	50	C102_0620 IE3D063K04	17	62.43	4495/72	4.0
25	1.3	43	1.3	45	C002_0560 IE3D063K04	12	55.97	2015/36	4.0
25	2.7	43	2.7	45	C102_0560 IE3D063K04	17	56.36	620/11	4.0
28	1.5	49	1.5	40	C002_0500 IE3D063K04	12	49.94	899/18	4.0
28	3.0	49	3.0	40	C102_0500 IE3D063K04	17	49.94	899/18	4.0
30	1.6	52	1.6	37	C002_0470 IE3D063K04	12	46.82	7865/168	4.0
30	3.2	52	3.2	37	C102_0470 IE3D063K04	17	46.91	516/11	4.1
34	1.8	58	1.8	33	C002_0420 IE3D063K04	12	41.77	3509/84	4.0
34	3.6	58	3.6	33	C102_0420 IE3D063K04	17	41.57	1247/30	4.1
40	2.2	69	2.2	28	C002_0350 IE3D063K04	12	35.03	1261/36	4.0
45	2.4	78	2.4	25	C002_0310 IE3D063K04	12	31.26	2813/90	4.0
50	2.7	87	2.7	22	C002_0280 IE3D063K04	12	27.99	2015/72	4.1
56	3.0	97	3.0	20	C002_0250 IE3D063K04	12	24.97	899/36	4.1
60	3.3	104	3.3	18	C002_0230 IE3D063K04	12	23.21	325/14	4.1
68	3.6	117	3.6	16	C002_0210 IE3D063K04	12	20.71	145/7	4.1
80	4.3	138	4.3	14	C002_0175 IE3D063K04	12	17.53	3575/204	4.1
90	4.8	155	4.8	12	C002_0155 IE3D063K04	12	15.64	1595/102	4.1
99	5.4	172	5.4	11	C002_0140 IE3D063K04	12	14.08	169/12	4.2
111	6.0	193	6.0	10	C002_0125 IE3D063K04	12	12.57	377/30	4.2
121	6.5	210	6.5	9.2	C002_0115 IE3D063K04	12	11.54	3185/276	4.2
136	7.3	235	7.3	8.2	C002_0105 IE3D063K04	12	10.30	1421/138	4.2
152	7.3	263	7.3	7.3	C002_0092 IE3D063K04	12	9.228	1495/162	4.3
170	7.3	294	7.3	6.6	C002_0082 IE3D063K04	12	8.235	667/81	4.3
181	6.9	314	6.9	6.1	C002_0077 IE3D063K04	12	7.714	54/7	4.1
222	7.3	385	7.3	5.0	C002_0063 IE3D063K04	12	6.300	2035/323	4.1
240	7.3	416	7.3	4.6	C002_0058 IE3D063K04	12	5.824	99/17	4.1
277	7.3	479	7.3	4.0	C002_0051 IE3D063K04	12	5.063	481/95	4.2
299	7.3	518	7.3	3.7	C002_0047 IE3D063K04	12	4.680	117/25	4.2
337	7.3	584	7.3	3.3	C002_0041 IE3D063K04	12	4.149	1813/437	4.3
365	7.3	632	7.3	3.1	C002_0038 IE3D063K04	12	3.835	441/115	4.3
422	7.3	731	7.3	2.6	C002_0033 IE3D063K04	12	3.318	1702/513	4.4
456	7.3	791	7.3	2.4	C002_0031 IE3D063K04	12	3.067	46/15	4.4
P_N (50 Hz) = 0,18 kW, P_N (87 Hz) = 0,31 kW									
7.7	0.94	13	0.94	212	C203_1830 IE3D063M04	27	183.4	99029/540	5.1
10	1.3	18	1.3	159	C203_1380 IE3D063M04	27	137.8	16121/117	5.1
13	0.93	22	0.93	129	C103_1110 IE3D063M04	21	111.1	1222/11	5.1
13	1.6	22	1.6	128	C203_1110 IE3D063M04	27	110.6	191149/1728	5.1
15	1.1	27	1.1	107	C103_0920 IE3D063M04	21	92.13	16215/176	5.1
15	1.9	27	1.9	107	C203_0920 IE3D063M04	27	92.40	29939/324	5.1
17	1.3	30	1.3	94	C103_0820 IE3D063M04	21	81.64	31349/384	5.1
18	2.1	30	2.1	93	C203_0810 IE3D063M04	27	80.62	11609/144	5.1

2.2 Selection tables 2 C helical geared motors

n_2 50 Hz [rpm]	S	n_2 87 Hz [rpm]	S	M_{2N} [Nm]	Type	m [kg]	i	i_{exakt}	J_1 [kgcm ²]
P_N (50 Hz) = 0,18 kW, P_N (87 Hz) = 0,31 kW									
20	1.5	35	1.5	83	C102_0700 IE3D063M04	18	70.46	775/11	5.0
20	2.4	35	2.4	83	C202_0700 IE3D063M04	22	70.32	7595/108	5.1
23	0.82	39	0.82	73	C002_0620 IE3D063M04	13	62.35	1247/20	5.0
23	1.6	39	1.6	73	C102_0620 IE3D063M04	18	62.43	4495/72	5.0
23	2.6	40	2.6	72	C202_0610 IE3D063M04	22	61.35	2945/48	5.1
25	0.91	44	0.91	66	C002_0560 IE3D063M04	13	55.97	2015/36	5.0
25	1.8	43	1.8	66	C102_0560 IE3D063M04	18	56.36	620/11	5.0
28	1.0	49	1.0	59	C002_0500 IE3D063M04	13	49.94	899/18	5.0
28	2.0	49	2.0	59	C102_0500 IE3D063M04	18	49.94	899/18	5.0
30	1.1	52	1.1	55	C002_0470 IE3D063M04	13	46.82	7865/168	5.0
30	2.2	52	2.2	55	C102_0470 IE3D063M04	18	46.91	516/11	5.1
34	1.2	59	1.2	49	C002_0420 IE3D063M04	13	41.77	3509/84	5.0
34	2.5	59	2.5	49	C102_0420 IE3D063M04	18	41.57	1247/30	5.1
40	1.5	70	1.5	41	C002_0350 IE3D063M04	13	35.03	1261/36	5.0
40	2.9	70	2.9	41	C102_0350 IE3D063M04	18	35.07	2700/77	5.1
45	1.6	78	1.6	37	C002_0310 IE3D063M04	13	31.26	2813/90	5.0
46	3.3	79	3.3	36	C102_0310 IE3D063M04	18	31.07	435/14	5.1
51	1.8	88	1.8	33	C002_0280 IE3D063M04	13	27.99	2015/72	5.1
57	2.0	98	2.0	29	C002_0250 IE3D063M04	13	24.97	899/36	5.1
60	4.3	104	4.3	28	C102_0240 IE3D063M04	18	23.52	1035/44	5.2
61	2.2	106	2.2	27	C002_0230 IE3D063M04	13	23.21	325/14	5.1
68	2.5	118	2.5	24	C002_0210 IE3D063M04	13	20.71	145/7	5.1
81	2.9	140	2.9	21	C002_0175 IE3D063M04	13	17.53	3575/204	5.1
90	3.3	157	3.3	18	C002_0155 IE3D063M04	13	15.64	1595/102	5.1
100	3.6	174	3.6	17	C002_0140 IE3D063M04	13	14.08	169/12	5.2
113	4.1	195	4.1	15	C002_0125 IE3D063M04	13	12.57	377/30	5.2
123	4.4	212	4.4	14	C002_0115 IE3D063M04	13	11.54	3185/276	5.2
137	5.0	238	4.9	12	C002_0105 IE3D063M04	13	10.30	1421/138	5.2
153	5.0	266	5.0	11	C002_0092 IE3D063M04	13	9.228	1495/162	5.3
172	5.0	298	5.0	9.7	C002_0082 IE3D063M04	13	8.235	667/81	5.3
182	5.0	314	5.0	9.2	C102_0078 IE3D063M04	18	7.796	3243/416	5.2
183	4.7	318	4.7	9.1	C002_0077 IE3D063M04	13	7.714	54/7	5.1
225	5.0	389	5.0	7.4	C002_0063 IE3D063M04	13	6.300	2035/323	5.1
241	5.0	417	5.0	6.9	C102_0059 IE3D063M04	18	5.875	47/8	5.4
243	5.0	421	5.0	6.8	C002_0058 IE3D063M04	13	5.824	99/17	5.1
279	5.0	484	5.0	5.9	C002_0051 IE3D063M04	13	5.063	481/95	5.2
302	5.0	524	5.0	5.5	C002_0047 IE3D063M04	13	4.680	117/25	5.2
338	5.0	585	5.0	4.9	C102_0042 IE3D063M04	18	4.189	377/90	5.7
341	5.0	591	5.0	4.9	C002_0041 IE3D063M04	13	4.149	1813/437	5.3
364	5.0	631	5.0	4.6	C102_0039 IE3D063M04	18	3.883	1363/351	5.7
369	5.0	639	5.0	4.5	C002_0038 IE3D063M04	13	3.835	441/115	5.3
426	5.0	739	5.0	3.9	C002_0033 IE3D063M04	13	3.318	1702/513	5.4
461	5.0	799	5.0	3.6	C002_0031 IE3D063M04	13	3.067	46/15	5.4
709	5.0	1227	5.0	2.3	C002_0020 IE3D063M04	13	1.997	1480/741	5.7
P_N (50 Hz) = 0,25 kW, P_N (87 Hz) = 0,43 kW									
5.2	0.80	9.1	0.80	437	C303_2740 IE3D071K04	34	273.7	26273/96	8.8
6.5	1.0	11	1.0	351	C303_2200 IE3D071K04	34	219.9	58045/264	8.8
7.8	1.2	14	1.2	292	C303_1830 IE3D071K04	34	182.8	1645/9	8.8
10	0.91	18	0.91	220	C203_1380 IE3D071K04	30	137.8	16121/117	8.8
10	1.6	18	1.6	219	C303_1370 IE3D071K04	34	137.2	59267/432	8.8
13	1.1	22	1.1	177	C203_1110 IE3D071K04	30	110.6	191149/1728	8.8
13	2.0	23	2.0	175	C303_1100 IE3D071K04	34	109.6	94705/864	8.8
16	0.82	27	0.82	147	C103_0920 IE3D071K04	24	92.13	16215/176	8.8
15	1.4	27	1.4	148	C203_0920 IE3D071K04	30	92.40	29939/324	8.8
16	2.4	27	2.4	147	C303_0920 IE3D071K04	34	91.93	39715/432	8.8
18	0.92	30	0.92	130	C103_0820 IE3D071K04	24	81.64	31349/384	8.8
18	1.6	31	1.6	129	C203_0810 IE3D071K04	30	80.62	11609/144	8.8
18	2.7	30	2.7	130	C303_0810 IE3D071K04	34	81.47	1222/15	8.8
20	1.1	35	1.1	114	C102_0700 IE3D071K04	21	70.46	775/11	8.7
20	1.8	35	1.8	114	C202_0700 IE3D071K04	25	70.32	7595/108	8.8
23	1.2	40	1.2	101	C102_0620 IE3D071K04	21	62.43	4495/72	8.7
23	1.9	40	1.9	99	C202_0610 IE3D071K04	25	61.35	2945/48	8.8
25	1.3	44	1.3	91	C102_0560 IE3D071K04	21	56.36	620/11	8.7
29	1.5	50	1.5	81	C102_0500 IE3D071K04	21	49.94	899/18	8.7
30	1.6	53	1.6	76	C102_0470 IE3D071K04	21	46.91	516/11	8.8

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 0,25 kW, P_N (87 Hz) = 0,43 kW									
34	0.89	59	0.89	68	C002_0420 IE3D071K04	16	41.77	3509/84	8.7
34	1.8	60	1.8	67	C102_0420 IE3D071K04	21	41.57	1247/30	8.8
41	1.1	71	1.1	57	C002_0350 IE3D071K04	16	35.03	1261/36	8.7
41	2.1	71	2.1	57	C102_0350 IE3D071K04	21	35.07	2700/77	8.8
46	1.2	79	1.2	51	C002_0310 IE3D071K04	16	31.26	2813/90	8.7
46	2.4	80	2.4	50	C102_0310 IE3D071K04	21	31.07	435/14	8.8
51	1.3	89	1.3	45	C002_0280 IE3D071K04	16	27.99	2015/72	8.8
57	1.5	99	1.5	40	C002_0250 IE3D071K04	16	24.97	899/36	8.8
61	3.1	105	3.1	38	C102_0240 IE3D071K04	21	23.52	1035/44	8.9
62	1.6	107	1.6	38	C002_0230 IE3D071K04	16	23.21	325/14	8.8
69	1.8	120	1.8	34	C002_0210 IE3D071K04	16	20.71	145/7	8.8
69	3.6	119	3.6	34	C102_0210 IE3D071K04	21	20.84	667/32	8.9
82	2.1	141	2.1	28	C002_0175 IE3D071K04	16	17.53	3575/204	8.8
91	2.4	158	2.4	25	C002_0155 IE3D071K04	16	15.64	1595/102	8.8
102	2.6	176	2.6	23	C002_0140 IE3D071K04	16	14.08	169/12	8.9
114	2.9	197	2.9	20	C002_0125 IE3D071K04	16	12.57	377/30	8.9
124	3.2	215	3.2	19	C002_0115 IE3D071K04	16	11.54	3185/276	8.9
139	3.6	241	3.6	17	C002_0105 IE3D071K04	16	10.30	1421/138	8.9
155	3.6	268	3.6	15	C002_0092 IE3D071K04	16	9.228	1495/162	9.0
174	3.6	301	3.6	13	C002_0082 IE3D071K04	16	8.235	667/81	9.0
183	3.6	318	3.6	13	C102_0078 IE3D071K04	21	7.796	3243/416	8.9
185	3.4	321	3.4	12	C002_0077 IE3D071K04	16	7.714	54/7	8.8
227	3.6	393	3.6	10	C002_0063 IE3D071K04	16	6.300	2035/323	8.8
243	3.6	422	3.6	9.5	C102_0059 IE3D071K04	21	5.875	47/8	9.1
246	3.6	425	3.6	9.4	C002_0058 IE3D071K04	16	5.824	99/17	8.8
282	3.6	489	3.6	8.2	C002_0051 IE3D071K04	16	5.063	481/95	8.9
306	3.6	529	3.6	7.6	C002_0047 IE3D071K04	16	4.680	117/25	8.9
341	3.6	591	3.6	6.8	C102_0042 IE3D071K04	21	4.189	377/90	9.4
345	3.6	597	3.6	6.7	C002_0041 IE3D071K04	16	4.149	1813/437	9.0
368	3.6	638	3.6	6.3	C102_0039 IE3D071K04	21	3.883	1363/351	9.4
373	3.6	646	3.6	6.2	C002_0038 IE3D071K04	16	3.835	441/115	9.0
431	3.6	746	3.6	5.4	C002_0033 IE3D071K04	16	3.318	1702/513	9.1
466	3.6	808	3.6	5.0	C002_0031 IE3D071K04	16	3.067	46/15	9.1
716	3.6	1240	3.6	3.2	C002_0020 IE3D071K04	16	1.997	1480/741	9.4
P_N (50 Hz) = 0,37 kW, P_N (87 Hz) = 0,64 kW									
7.8	0.80	14	0.80	437	C303_1830 IE3D071L04	35	182.8	1645/9	11
10	1.1	18	1.1	328	C303_1370 IE3D071L04	35	137.2	59267/432	11
13	1.3	23	1.3	262	C303_1100 IE3D071L04	35	109.6	94705/864	11
15	0.91	27	0.91	221	C203_0920 IE3D071L04	31	92.40	29939/324	11
16	1.6	27	1.6	220	C303_0920 IE3D071L04	35	91.93	39715/432	11
18	1.0	31	1.0	193	C203_0810 IE3D071L04	31	80.62	11609/144	11
18	1.8	30	1.8	195	C303_0810 IE3D071L04	35	81.47	1222/15	11
20	1.2	35	1.2	171	C202_0700 IE3D071L04	26	70.32	7595/108	11
23	1.3	40	1.3	149	C202_0610 IE3D071L04	26	61.35	2945/48	11
25	0.88	44	0.88	137	C102_0560 IE3D071L04	22	56.36	620/11	11
29	0.99	50	0.99	121	C102_0500 IE3D071L04	22	49.94	899/18	11
30	1.1	53	1.1	114	C102_0470 IE3D071L04	22	46.91	516/11	11
34	1.2	60	1.2	101	C102_0420 IE3D071L04	22	41.57	1247/30	11
41	1.4	71	1.4	85	C102_0350 IE3D071L04	22	35.07	2700/77	11
46	1.6	80	1.6	75	C102_0310 IE3D071L04	22	31.07	435/14	11
51	0.88	89	0.88	68	C002_0280 IE3D071L04	17	27.99	2015/72	11
57	0.99	99	0.99	61	C002_0250 IE3D071L04	17	24.97	899/36	11
61	2.1	105	2.1	57	C102_0240 IE3D071L04	22	23.52	1035/44	11
62	1.1	107	1.1	56	C002_0230 IE3D071L04	17	23.21	325/14	11
69	1.2	120	1.2	50	C002_0210 IE3D071L04	17	20.71	145/7	11
69	2.4	119	2.4	51	C102_0210 IE3D071L04	22	20.84	667/32	11
82	1.4	141	1.4	42	C002_0175 IE3D071L04	17	17.53	3575/204	11
81	2.4	140	2.4	43	C102_0175 IE3D071L04	22	17.73	195/11	11
91	1.6	158	1.6	38	C002_0155 IE3D071L04	17	15.64	1595/102	11
91	2.4	158	2.4	38	C102_0155 IE3D071L04	22	15.71	377/24	11
102	1.8	176	1.8	34	C002_0140 IE3D071L04	17	14.08	169/12	11
114	2.0	197	2.0	30	C002_0125 IE3D071L04	17	12.57	377/30	11
124	2.1	215	2.1	28	C002_0115 IE3D071L04	17	11.54	3185/276	11
139	2.4	241	2.4	25	C002_0105 IE3D071L04	17	10.30	1421/138	11
155	2.4	268	2.4	22	C002_0092 IE3D071L04	17	9.228	1495/162	11

2.2 Selection tables 2 C helical geared motors

n_2 50 Hz [rpm]	S	n_2 87 Hz [rpm]	S	M_{2N} [Nm]	Type	m [kg]	i	i_{exakt}	J_1 [kgcm ²]
P_N (50 Hz) = 0,37 kW, P_N (87 Hz) = 0,64 kW									
174	2.4	301	2.4	20	C002_0082 IE3D071L04	17	8.235	667/81	11
183	2.4	318	2.4	19	C102_0078 IE3D071L04	22	7.796	3243/416	11
185	2.3	321	2.3	19	C002_0077 IE3D071L04	17	7.714	54/7	11
227	2.4	393	2.4	15	C002_0063 IE3D071L04	17	6.300	2035/323	11
243	2.4	422	2.4	14	C102_0059 IE3D071L04	22	5.875	47/8	11
246	2.4	425	2.4	14	C002_0058 IE3D071L04	17	5.824	99/17	11
282	2.4	489	2.4	12	C002_0051 IE3D071L04	17	5.063	481/95	11
306	2.4	529	2.4	11	C002_0047 IE3D071L04	17	4.680	117/25	11
341	2.4	591	2.4	10	C102_0042 IE3D071L04	22	4.189	377/90	11
345	2.4	597	2.4	10	C002_0041 IE3D071L04	17	4.149	1813/437	11
368	2.4	638	2.4	9.4	C102_0039 IE3D071L04	22	3.883	1363/351	11
373	2.4	646	2.4	9.3	C002_0038 IE3D071L04	17	3.835	441/115	11
431	2.4	746	2.4	8.0	C002_0033 IE3D071L04	17	3.318	1702/513	11
466	2.4	808	2.4	7.4	C002_0031 IE3D071L04	17	3.067	46/15	11
716	2.4	1240	2.4	4.8	C002_0020 IE3D071L04	17	1.997	1480/741	11
P_N (50 Hz) = 0,55 kW, P_N (87 Hz) = 0,95 kW									
5.3	0.85	9.2	0.85	944	C503_2710 IE3D080K04	60	270.5	58435/216	21
5.4	1.4	9.4	1.4	929	C613_2660 IE3D080K04	80	266.4	7192/27	21
6.7	1.1	12	1.1	753	C503_2160 IE3D080K04	60	215.9	1943/9	21
6.8	1.7	12	1.7	744	C613_2130 IE3D080K04	80	213.1	28768/135	21
8.0	1.3	14	1.3	630	C503_1810 IE3D080K04	60	180.6	8671/48	21
8.0	0.87	14	0.87	630	C403_1800 IE3D080K04	49	180.4	1624/9	21
8.2	2.1	14	2.1	612	C613_1750 IE3D080K04	80	175.3	7888/45	21
11	1.2	19	1.2	470	C403_1350 IE3D080K04	49	134.6	1885/14	21
11	1.7	18	1.7	472	C503_1350 IE3D080K04	60	135.3	406/3	21
11	2.8	18	2.8	471	C613_1350 IE3D080K04	80	134.8	15776/117	21
13	2.1	23	2.1	379	C503_1090 IE3D080K04	60	108.6	31291/288	21
13	0.93	23	0.93	378	C303_1080 IE3D080K04	39	108.2	11687/108	21
13	1.5	23	1.5	376	C403_1080 IE3D080K04	49	107.7	754/7	21
14	3.5	24	3.5	370	C613_1060 IE3D080K04	80	106.1	3712/35	21
16	1.1	27	1.1	317	C303_0910 IE3D080K04	39	90.76	4901/54	21
16	1.7	28	1.7	315	C403_0900 IE3D080K04	49	90.32	8671/96	21
16	2.5	28	2.5	315	C503_0900 IE3D080K04	60	90.32	8671/96	21
18	2.0	31	2.0	282	C403_0810 IE3D080K04	49	80.81	42021/520	21
18	2.8	31	2.8	281	C503_0810 IE3D080K04	60	80.60	19343/240	21
18	1.2	31	1.2	281	C303_0800 IE3D080K04	39	80.43	6032/75	21
19	3.5	33	3.5	265	C613_0760 IE3D080K04	80	75.81	5307/70	21
21	1.4	36	1.4	247	C302_0700 IE3D080K04	35	69.88	559/8	21
21	2.2	36	2.2	247	C402_0700 IE3D080K04	45	69.88	559/8	21
23	2.3	40	2.3	221	C402_0630 IE3D080K04	45	62.52	8127/130	21
23	1.5	40	1.5	219	C302_0620 IE3D080K04	35	61.92	1548/25	21
23	3.2	40	3.2	221	C502_0620 IE3D080K04	56	62.43	4495/72	21
26	1.0	44	1.0	200	C202_0560 IE3D080K04	29	56.42	1862/33	21
26	1.8	44	1.8	199	C302_0560 IE3D080K04	35	56.14	1235/22	21
26	2.8	44	2.8	199	C402_0560 IE3D080K04	45	56.10	9425/168	21
29	2.0	50	2.0	176	C302_0500 IE3D080K04	35	49.75	2736/55	21
29	3.1	50	3.1	178	C402_0500 IE3D080K04	45	50.19	1305/26	21
29	1.1	51	1.1	174	C202_0490 IE3D080K04	29	49.23	1083/22	21
31	1.2	53	1.2	166	C202_0470 IE3D080K04	29	46.82	2107/45	21
31	2.1	53	2.1	165	C302_0470 IE3D080K04	35	46.67	140/3	21
35	0.82	60	0.82	147	C102_0420 IE3D080K04	25	41.57	1247/30	21
34	3.7	60	3.7	148	C402_0420 IE3D080K04	45	41.75	7056/169	21
35	1.4	61	1.4	145	C202_0410 IE3D080K04	29	40.85	817/20	21
35	2.4	60	2.4	146	C302_0410 IE3D080K04	35	41.35	2688/65	21
41	0.97	71	0.97	124	C102_0350 IE3D080K04	25	35.07	2700/77	21
41	1.6	71	1.6	125	C202_0350 IE3D080K04	29	35.18	1372/39	21
41	2.8	71	2.8	124	C302_0350 IE3D080K04	35	35.03	1261/36	21
46	1.1	80	1.1	110	C102_0310 IE3D080K04	25	31.07	435/14	21
47	1.8	81	1.8	109	C202_0310 IE3D080K04	29	30.69	399/13	21
46	3.2	80	3.2	110	C302_0310 IE3D080K04	35	31.04	776/25	21
51	1.2	88	1.2	100	C102_0280 IE3D080K04	25	28.36	312/11	21
51	2.0	88	2.0	100	C202_0280 IE3D080K04	29	28.24	4067/144	21
57	1.3	99	1.3	89	C102_0250 IE3D080K04	25	25.13	377/15	21
58	2.3	101	2.3	87	C202_0250 IE3D080K04	29	24.64	1577/64	21
61	1.4	106	1.4	83	C102_0240 IE3D080K04	25	23.52	1035/44	21

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 0,55 kW, P_N (87 Hz) = 0,95 kW									
61	2.4	106	2.4	84	C202_0240 IE3D080K04	29	23.59	637/27	21
61	4.2	106	4.2	83	C302_0230 IE3D080K04	35	23.47	845/36	21
70	0.82	120	0.82	73	C002_0210 IE3D080K04	21	20.71	145/7	21
69	1.6	120	1.6	74	C102_0210 IE3D080K04	25	20.84	667/32	21
70	2.7	121	2.7	73	C202_0210 IE3D080K04	29	20.58	247/12	21
82	0.97	142	0.97	62	C002_0175 IE3D080K04	21	17.53	3575/204	21
81	1.9	141	1.9	63	C102_0175 IE3D080K04	25	17.73	195/11	21
82	3.2	142	3.2	62	C202_0175 IE3D080K04	29	17.52	3626/207	21
92	1.1	160	1.1	55	C002_0155 IE3D080K04	21	15.64	1595/102	21
92	2.2	159	2.2	56	C102_0155 IE3D080K04	25	15.71	377/24	21
102	1.2	177	1.2	50	C002_0140 IE3D080K04	21	14.08	169/12	21
102	2.4	177	2.4	50	C102_0140 IE3D080K04	25	14.06	2010/143	21
115	1.3	198	1.3	44	C002_0125 IE3D080K04	21	12.57	377/30	21
116	2.7	200	2.7	44	C102_0125 IE3D080K04	25	12.46	1943/156	21
122	4.8	212	4.8	42	C202_0120 IE3D080K04	29	11.76	294/25	22
125	1.5	216	1.5	41	C002_0115 IE3D080K04	21	11.54	3185/276	21
123	2.9	213	2.9	41	C102_0115 IE3D080K04	25	11.72	1160/99	21
140	1.6	242	1.6	36	C002_0105 IE3D080K04	21	10.30	1421/138	21
139	3.3	240	3.3	37	C102_0105 IE3D080K04	25	10.38	841/81	21
154	3.6	267	3.5	33	C102_0093 IE3D080K04	25	9.326	3180/341	21
156	1.8	270	1.8	33	C002_0092 IE3D080K04	21	9.228	1495/162	21
174	4.1	302	3.8	29	C102_0083 IE3D080K04	25	8.263	1537/186	21
175	2.1	303	1.9	29	C002_0082 IE3D080K04	21	8.235	667/81	21
185	4.0	320	3.3	28	C102_0078 IE3D080K04	25	7.796	3243/416	21
187	2.0	323	1.7	27	C002_0077 IE3D080K04	21	7.714	54/7	21
229	2.3	396	1.9	22	C002_0063 IE3D080K04	21	6.300	2035/323	21
245	4.8	425	4.0	21	C102_0059 IE3D080K04	25	5.875	47/8	21
247	2.4	428	2.0	21	C002_0058 IE3D080K04	21	5.824	99/17	21
284	2.6	493	2.2	18	C002_0051 IE3D080K04	21	5.063	481/95	21
287	5.3	496	4.5	18	C102_0050 IE3D080K04	25	5.025	201/40	21
308	2.8	533	2.3	17	C002_0047 IE3D080K04	21	4.680	117/25	21
344	6.0	595	5.0	15	C102_0042 IE3D080K04	25	4.189	377/90	21
347	3.0	601	2.5	15	C002_0041 IE3D080K04	21	4.149	1813/437	21
371	6.3	642	5.3	14	C102_0039 IE3D080K04	25	3.883	1363/351	21
375	3.2	650	2.7	14	C002_0038 IE3D080K04	21	3.835	441/115	21
434	3.5	752	2.9	12	C002_0033 IE3D080K04	21	3.318	1702/513	21
470	3.7	813	3.1	11	C002_0031 IE3D080K04	21	3.067	46/15	21
520	3.9	901	3.3	9.8	C002_0028 IE3D080K04	21	2.769	36/13	21
661	6.6	1146	6.6	7.7	C102_0022 IE3D080K04	25	2.177	468/215	23
721	4.9	1249	4.1	7.1	C002_0020 IE3D080K04	21	1.997	1480/741	21
P_N (50 Hz) = 0,75 kW, P_N (87 Hz) = 1,30 kW									
5.4	1.0	9.4	1.0	1273	C613_2660 IE3D080L04	83	266.4	7192/27	26
6.8	1.3	12	1.3	1019	C613_2130 IE3D080L04	83	213.1	28768/135	26
8.0	0.93	14	0.93	863	C503_1810 IE3D080L04	63	180.6	8671/48	26
8.2	1.6	14	1.6	838	C613_1750 IE3D080L04	83	175.3	7888/45	26
11	0.86	19	0.86	644	C403_1350 IE3D080L04	52	134.6	1885/14	26
11	1.2	18	1.2	647	C503_1350 IE3D080L04	63	135.3	406/3	26
11	2.0	19	2.0	645	C613_1350 IE3D080L04	83	134.8	15776/117	26
13	1.5	23	1.5	519	C503_1090 IE3D080L04	63	108.6	31291/288	26
13	1.1	23	1.1	515	C403_1080 IE3D080L04	52	107.7	754/7	26
14	2.5	24	2.5	507	C613_1060 IE3D080L04	83	106.1	3712/35	27
16	0.81	28	0.81	434	C303_0910 IE3D080L04	41	90.76	4901/54	26
16	1.3	28	1.3	432	C403_0900 IE3D080L04	52	90.32	8671/96	26
16	1.9	28	1.9	432	C503_0900 IE3D080L04	63	90.32	8671/96	26
18	1.4	31	1.4	386	C403_0810 IE3D080L04	52	80.81	42021/520	26
18	2.1	31	2.1	385	C503_0810 IE3D080L04	63	80.60	19343/240	26
18	0.91	31	0.91	384	C303_0800 IE3D080L04	41	80.43	6032/75	26
19	2.5	33	2.5	362	C613_0760 IE3D080L04	83	75.81	5307/70	27
21	1.0	36	1.0	339	C302_0700 IE3D080L04	37	69.88	559/8	26
21	1.6	36	1.6	339	C402_0700 IE3D080L04	47	69.88	559/8	26
21	2.4	36	2.4	339	C502_0700 IE3D080L04	59	69.97	10075/144	26
23	1.7	40	1.7	303	C402_0630 IE3D080L04	47	62.52	8127/130	26
23	1.1	40	1.1	300	C302_0620 IE3D080L04	37	61.92	1548/25	26
23	2.4	40	2.4	303	C502_0620 IE3D080L04	59	62.43	4495/72	26
26	1.3	45	1.3	272	C302_0560 IE3D080L04	37	56.14	1235/22	26

2.2 Selection tables 2 C helical geared motors

n ₂ 50 Hz [rpm]	S	n ₂ 87 Hz [rpm]	S	M _{2N} [Nm]	Type	m [kg]	i	i _{exakt}	J ₁ [kgcm ²]
P _N (50 Hz) = 0,75 kW, P _N (87 Hz) = 1,30 kW									
26	2.0	45	2.0	272	C402_0560 IE3D080L04	47	56.10	9425/168	26
29	1.5	50	1.5	241	C302_0500 IE3D080L04	37	49.75	2736/55	26
29	2.3	50	2.3	243	C402_0500 IE3D080L04	47	50.19	1305/26	26
29	0.84	51	0.84	239	C202_0490 IE3D080L04	32	49.23	1083/22	26
31	0.88	53	0.88	227	C202_0470 IE3D080L04	32	46.82	2107/45	26
31	1.5	54	1.5	226	C302_0470 IE3D080L04	37	46.67	140/3	26
31	2.4	54	2.4	226	C402_0470 IE3D080L04	47	46.67	140/3	27
35	2.7	60	2.7	202	C402_0420 IE3D080L04	47	41.75	7056/169	27
35	1.0	61	1.0	198	C202_0410 IE3D080L04	32	40.85	817/20	26
35	1.7	61	1.7	201	C302_0410 IE3D080L04	37	41.35	2688/65	26
41	1.2	71	1.2	171	C202_0350 IE3D080L04	32	35.18	1372/39	26
41	2.1	71	2.1	170	C302_0350 IE3D080L04	37	35.03	1261/36	26
47	1.3	82	1.3	149	C202_0310 IE3D080L04	32	30.69	399/13	26
47	2.3	81	2.3	151	C302_0310 IE3D080L04	37	31.04	776/25	26
51	0.87	88	0.87	138	C102_0280 IE3D080L04	28	28.36	312/11	26
51	1.5	89	1.5	137	C202_0280 IE3D080L04	32	28.24	4067/144	26
52	2.6	89	2.6	136	C302_0280 IE3D080L04	37	27.99	2015/72	27
57	0.98	100	0.98	122	C102_0250 IE3D080L04	28	25.13	377/15	26
59	1.7	102	1.7	120	C202_0250 IE3D080L04	32	24.64	1577/64	26
58	2.9	101	2.9	120	C302_0250 IE3D080L04	37	24.80	124/5	27
61	1.1	106	1.1	114	C102_0240 IE3D080L04	28	23.52	1035/44	26
61	1.7	106	1.7	114	C202_0240 IE3D080L04	32	23.59	637/27	26
62	3.1	107	3.1	114	C302_0230 IE3D080L04	37	23.47	845/36	27
69	1.2	120	1.2	101	C102_0210 IE3D080L04	28	20.84	667/32	26
70	2.0	122	2.0	100	C202_0210 IE3D080L04	32	20.58	247/12	26
82	1.4	141	1.4	86	C102_0175 IE3D080L04	28	17.73	195/11	26
82	2.4	143	2.4	85	C202_0175 IE3D080L04	32	17.52	3626/207	27
92	1.6	159	1.6	76	C102_0155 IE3D080L04	28	15.71	377/24	26
95	2.7	164	2.7	74	C202_0155 IE3D080L04	32	15.28	703/46	27
103	0.88	178	0.88	68	C002_0140 IE3D080L04	23	14.08	169/12	26
103	1.8	178	1.8	68	C102_0140 IE3D080L04	28	14.06	2010/143	26
102	2.9	177	2.9	68	C202_0140 IE3D080L04	32	14.12	3430/243	27
115	0.98	199	0.98	61	C002_0125 IE3D080L04	23	12.57	377/30	26
116	2.0	201	2.0	60	C102_0125 IE3D080L04	28	12.46	1943/156	26
117	3.3	203	3.3	60	C202_0125 IE3D080L04	32	12.32	665/54	27
123	3.5	213	3.5	57	C202_0120 IE3D080L04	32	11.76	294/25	27
125	1.1	217	1.1	56	C002_0115 IE3D080L04	23	11.54	3185/276	26
123	2.1	214	2.1	57	C102_0115 IE3D080L04	28	11.72	1160/99	27
140	1.2	243	1.2	50	C002_0105 IE3D080L04	23	10.30	1421/138	26
139	2.4	241	2.4	50	C102_0105 IE3D080L04	28	10.38	841/81	27
155	2.7	268	2.6	45	C102_0093 IE3D080L04	28	9.326	3180/341	27
157	1.3	271	1.3	45	C002_0092 IE3D080L04	23	9.228	1495/162	26
175	3.0	303	2.8	40	C102_0083 IE3D080L04	28	8.263	1537/186	27
175	1.5	304	1.4	40	C002_0082 IE3D080L04	23	8.235	667/81	26
185	2.9	321	2.4	38	C102_0078 IE3D080L04	28	7.796	3243/416	26
187	1.5	324	1.2	37	C002_0077 IE3D080L04	23	7.714	54/7	26
229	1.7	397	1.4	31	C002_0063 IE3D080L04	23	6.300	2035/323	26
228	3.3	395	2.8	31	C102_0063 IE3D080L04	28	6.338	507/80	26
246	3.5	426	2.9	28	C102_0059 IE3D080L04	28	5.875	47/8	26
248	1.8	430	1.5	28	C002_0058 IE3D080L04	23	5.824	99/17	26
250	4.8	432	4.5	28	C202_0058 IE3D080L04	32	5.791	666/115	27
285	1.9	494	1.6	25	C002_0051 IE3D080L04	23	5.063	481/95	26
285	4.8	493	4.8	25	C202_0051 IE3D080L04	32	5.072	350/69	27
288	3.9	498	3.3	24	C102_0050 IE3D080L04	28	5.025	201/40	27
309	2.0	535	1.7	23	C002_0047 IE3D080L04	23	4.680	117/25	26
345	4.4	597	3.7	20	C102_0042 IE3D080L04	28	4.189	377/90	27
348	2.2	603	1.9	20	C002_0041 IE3D080L04	23	4.149	1813/437	26
372	4.6	645	3.9	19	C102_0039 IE3D080L04	28	3.883	1363/351	27
377	2.3	653	2.0	19	C002_0038 IE3D080L04	23	3.835	441/115	26
436	2.5	754	2.2	16	C002_0033 IE3D080L04	23	3.318	1702/513	26
471	2.7	816	2.3	15	C002_0031 IE3D080L04	23	3.067	46/15	26
522	2.9	904	2.4	13	C002_0028 IE3D080L04	23	2.769	36/13	26
664	4.8	1150	4.8	11	C102_0022 IE3D080L04	28	2.177	468/215	28
724	3.6	1253	3.0	9.7	C002_0020 IE3D080L04	23	1.997	1480/741	27

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 1,10 kW, P_N (87 Hz) = 1,91 kW									
6.8	0.87	12	0.87	1487	C613_2130 IE3D090S04	88	213.1	28768/135	40
8.2	1.1	14	1.1	1223	C613_1750 IE3D090S04	88	175.3	7888/45	40
11	0.85	18	0.85	944	C503_1350 IE3D090S04	68	135.3	406/3	40
11	1.4	18	1.4	941	C613_1350 IE3D090S04	88	134.8	15776/117	40
13	1.1	23	1.1	758	C503_1090 IE3D090S04	68	108.6	31291/288	40
14	1.7	24	1.7	740	C613_1060 IE3D090S04	88	106.1	3712/35	41
16	0.87	28	0.87	630	C403_0900 IE3D090S04	57	90.32	8671/96	40
16	1.3	28	1.3	630	C503_0900 IE3D090S04	68	90.32	8671/96	40
18	0.98	31	0.98	564	C403_0810 IE3D090S04	57	80.81	42021/520	40
18	1.4	31	1.4	562	C503_0810 IE3D090S04	68	80.60	19343/240	40
19	1.7	33	1.7	529	C613_0760 IE3D090S04	88	75.81	5307/70	41
21	1.1	36	1.1	495	C402_0700 IE3D090S04	53	69.88	559/8	40
21	1.6	36	1.6	495	C502_0700 IE3D090S04	64	69.97	10075/144	40
23	1.1	40	1.1	443	C402_0630 IE3D090S04	53	62.52	8127/130	40
23	1.6	40	1.6	442	C502_0620 IE3D090S04	64	62.43	4495/72	40
26	0.88	44	0.88	397	C302_0560 IE3D090S04	43	56.14	1235/22	40
26	1.4	44	1.4	397	C402_0560 IE3D090S04	53	56.10	9425/168	40
26	2.0	45	2.0	395	C502_0560 IE3D090S04	64	55.83	335/6	41
29	0.99	50	0.99	352	C302_0500 IE3D090S04	43	49.75	2736/55	40
29	1.5	50	1.5	355	C402_0500 IE3D090S04	53	50.19	1305/26	40
29	2.3	50	2.3	353	C502_0500 IE3D090S04	64	49.82	1943/39	41
31	1.1	53	1.1	330	C302_0470 IE3D090S04	43	46.67	140/3	40
31	1.7	53	1.7	330	C402_0470 IE3D090S04	53	46.67	140/3	41
34	1.9	60	1.9	296	C402_0420 IE3D090S04	53	41.75	7056/169	41
35	1.2	60	1.2	293	C302_0410 IE3D090S04	43	41.35	2688/65	40
41	0.80	71	0.80	249	C202_0350 IE3D090S04	37	35.18	1372/39	40
41	1.4	71	1.4	248	C302_0350 IE3D090S04	43	35.03	1261/36	40
41	2.2	72	2.2	247	C402_0350 IE3D090S04	53	34.82	975/28	41
47	0.92	81	0.92	217	C202_0310 IE3D090S04	37	30.69	399/13	40
46	1.6	80	1.6	220	C302_0310 IE3D090S04	43	31.04	776/25	40
46	2.5	80	2.5	221	C402_0310 IE3D090S04	53	31.15	405/13	41
51	1.0	88	1.0	200	C202_0280 IE3D090S04	37	28.24	4067/144	40
51	1.8	89	1.8	198	C302_0280 IE3D090S04	43	27.99	2015/72	41
58	1.1	101	1.1	174	C202_0250 IE3D090S04	37	24.64	1577/64	40
58	2.0	101	2.0	176	C302_0250 IE3D090S04	43	24.80	124/5	41
61	1.2	106	1.2	167	C202_0240 IE3D090S04	37	23.59	637/27	40
61	2.1	106	2.1	166	C302_0230 IE3D090S04	43	23.47	845/36	41
69	0.81	120	0.81	148	C102_0210 IE3D090S04	33	20.84	667/32	40
70	1.4	121	1.4	146	C202_0210 IE3D090S04	37	20.58	247/12	40
69	2.4	120	2.4	147	C302_0210 IE3D090S04	43	20.80	104/5	41
81	0.96	141	0.96	126	C102_0175 IE3D090S04	33	17.73	195/11	40
82	1.6	142	1.6	124	C202_0175 IE3D090S04	37	17.52	3626/207	41
92	1.1	159	1.1	111	C102_0155 IE3D090S04	33	15.71	377/24	40
94	1.8	163	1.8	108	C202_0155 IE3D090S04	37	15.28	703/46	41
102	1.2	177	1.2	100	C102_0140 IE3D090S04	33	14.06	2010/143	40
102	2.0	177	2.0	100	C202_0140 IE3D090S04	37	14.12	3430/243	41
116	1.4	200	1.4	88	C102_0125 IE3D090S04	33	12.46	1943/156	40
117	2.3	203	2.3	87	C202_0125 IE3D090S04	37	12.32	665/54	41
122	2.4	212	2.4	83	C202_0120 IE3D090S04	37	11.76	294/25	41
123	1.4	213	1.4	83	C102_0115 IE3D090S04	33	11.72	1160/99	41
140	0.82	242	0.82	73	C002_0105 IE3D090S04	29	10.30	1421/138	40
139	1.6	240	1.6	74	C102_0105 IE3D090S04	33	10.38	841/81	41
140	2.8	243	2.7	73	C202_0105 IE3D090S04	37	10.26	513/50	41
154	1.8	267	1.7	66	C102_0093 IE3D090S04	33	9.326	3180/341	41
156	0.92	270	0.88	65	C002_0092 IE3D090S04	29	9.228	1495/162	40
174	2.1	302	1.9	59	C102_0083 IE3D090S04	33	8.263	1537/186	41
175	1.0	303	0.95	58	C002_0082 IE3D090S04	29	8.235	667/81	40
185	2.0	320	1.7	55	C102_0078 IE3D090S04	33	7.796	3243/416	40
185	3.0	320	2.5	55	C202_0078 IE3D090S04	37	7.800	39/5	41
187	1.0	323	0.84	55	C002_0077 IE3D090S04	29	7.714	54/7	40
229	1.1	396	0.96	45	C002_0063 IE3D090S04	29	6.300	2035/323	40
227	2.3	394	1.9	45	C102_0063 IE3D090S04	33	6.338	507/80	40
245	2.4	425	2.0	42	C102_0059 IE3D090S04	33	5.875	47/8	40
247	1.2	428	1.0	41	C002_0058 IE3D090S04	29	5.824	99/17	40
249	3.3	431	3.1	41	C202_0058 IE3D090S04	37	5.791	666/115	41

2.2 Selection tables 2 C helical geared motors

n_2 50 Hz [rpm]	S	n_2 87 Hz [rpm]	S	M_{2N} [Nm]	Type	m [kg]	i	i_{exakt}	J_1 [kgcm ²]
P_N (50 Hz) = 1,10 kW, P_N (87 Hz) = 1,91 kW									
284	1.3	493	1.1	36	C002_0051 IE3D090S04	29	5.063	481/95	40
284	3.3	492	3.3	36	C202_0051 IE3D090S04	37	5.072	350/69	41
287	2.6	496	2.2	36	C102_0050 IE3D090S04	33	5.025	201/40	41
308	1.4	533	1.2	33	C002_0047 IE3D090S04	29	4.680	117/25	40
309	2.8	535	2.3	33	C102_0047 IE3D090S04	33	4.658	3149/676	41
344	3.0	595	2.5	30	C102_0042 IE3D090S04	33	4.189	377/90	41
347	1.5	601	1.3	29	C002_0041 IE3D090S04	29	4.149	1813/437	40
371	3.1	642	2.7	27	C102_0039 IE3D090S04	33	3.883	1363/351	41
375	1.6	650	1.3	27	C002_0038 IE3D090S04	29	3.835	441/115	40
434	1.7	752	1.5	23	C002_0033 IE3D090S04	29	3.318	1702/513	40
432	3.3	748	2.9	24	C102_0033 IE3D090S04	33	3.334	2067/620	41
470	1.8	813	1.6	22	C002_0031 IE3D090S04	29	3.067	46/15	40
466	3.3	807	3.1	22	C102_0031 IE3D090S04	33	3.091	2491/806	41
520	2.0	901	1.7	20	C002_0028 IE3D090S04	29	2.769	36/13	40
661	3.3	1146	3.3	15	C102_0022 IE3D090S04	33	2.177	468/215	42
721	2.4	1249	2.1	14	C002_0020 IE3D090S04	29	1.997	1480/741	41
P_N (50 Hz) = 1,50 kW, P_N (87 Hz) = 2,60 kW									
11	1.0	19	1.0	1263	C613_1350 IE3D090LX04	97	134.8	15776/117	58
14	1.3	24	1.3	994	C613_1060 IE3D090LX04	97	106.1	3712/35	59
16	0.95	28	0.95	846	C503_0900 IE3D090LX04	77	90.32	8671/96	58
18	1.1	31	1.1	755	C503_0810 IE3D090LX04	77	80.60	19343/240	58
19	1.3	33	1.3	710	C613_0760 IE3D090LX04	97	75.81	5307/70	59
21	0.83	36	0.83	664	C402_0700 IE3D090LX04	61	69.88	559/8	58
21	1.2	36	1.2	665	C502_0700 IE3D090LX04	73	69.97	10075/144	58
23	0.84	40	0.84	594	C402_0630 IE3D090LX04	61	62.52	8127/130	58
23	1.2	40	1.2	593	C502_0620 IE3D090LX04	73	62.43	4495/72	58
26	1.0	45	1.0	533	C402_0560 IE3D090LX04	61	56.10	9425/168	58
26	1.5	45	1.5	531	C502_0560 IE3D090LX04	73	55.83	335/6	59
29	1.2	50	1.2	477	C402_0500 IE3D090LX04	61	50.19	1305/26	58
29	1.7	51	1.7	474	C502_0500 IE3D090LX04	73	49.82	1943/39	59
31	1.2	54	1.2	444	C402_0470 IE3D090LX04	61	46.67	140/3	59
35	1.4	60	1.4	397	C402_0420 IE3D090LX04	61	41.75	7056/169	59
35	0.89	61	0.89	393	C302_0410 IE3D090LX04	51	41.35	2688/65	58
42	1.1	72	1.1	333	C302_0350 IE3D090LX04	51	35.03	1261/36	58
42	1.7	72	1.7	331	C402_0350 IE3D090LX04	61	34.82	975/28	59
47	1.2	81	1.2	295	C302_0310 IE3D090LX04	51	31.04	776/25	58
47	1.9	81	1.9	296	C402_0310 IE3D090LX04	61	31.15	405/13	59
52	1.3	90	1.3	266	C302_0280 IE3D090LX04	51	27.99	2015/72	59
59	0.85	102	0.85	234	C202_0250 IE3D090LX04	46	24.64	1577/64	58
59	1.5	102	1.5	236	C302_0250 IE3D090LX04	51	24.80	124/5	59
62	0.89	107	0.89	224	C202_0240 IE3D090LX04	46	23.59	637/27	58
62	1.6	107	1.6	223	C302_0230 IE3D090LX04	51	23.47	845/36	59
71	1.0	122	1.0	196	C202_0210 IE3D090LX04	46	20.58	247/12	58
70	1.8	121	1.8	198	C302_0210 IE3D090LX04	51	20.80	104/5	59
83	1.2	144	1.2	167	C202_0175 IE3D090LX04	46	17.52	3626/207	59
93	0.80	160	0.80	149	C102_0155 IE3D090LX04	42	15.71	377/24	58
95	1.4	165	1.4	145	C202_0155 IE3D090LX04	46	15.28	703/46	59
104	0.90	179	0.90	134	C102_0140 IE3D090LX04	42	14.06	2010/143	58
103	1.5	179	1.5	134	C202_0140 IE3D090LX04	46	14.12	3430/243	59
117	1.0	202	1.0	118	C102_0125 IE3D090LX04	42	12.46	1943/156	58
118	1.7	205	1.7	117	C202_0125 IE3D090LX04	46	12.32	665/54	59
124	1.8	214	1.8	112	C202_0120 IE3D090LX04	46	11.76	294/25	59
124	1.1	215	1.1	111	C102_0115 IE3D090LX04	42	11.72	1160/99	59
140	1.2	243	1.2	99	C102_0105 IE3D090LX04	42	10.38	841/81	59
142	2.1	246	2.0	98	C202_0105 IE3D090LX04	46	10.26	513/50	59
156	1.4	270	1.3	89	C102_0093 IE3D090LX04	42	9.326	3180/341	59
176	1.5	305	1.4	79	C102_0083 IE3D090LX04	42	8.263	1537/186	59
187	1.5	323	1.2	74	C102_0078 IE3D090LX04	42	7.796	3243/416	58
187	2.2	323	1.9	74	C202_0078 IE3D090LX04	46	7.800	39/5	59
231	0.85	-	-	60	C002_0063 IE3D090LX04	37	6.300	2035/323	58
230	1.7	398	1.4	60	C102_0063 IE3D090LX04	42	6.338	507/80	58
231	2.5	400	2.2	60	C202_0063 IE3D090LX04	46	6.295	3330/529	59
248	1.8	429	1.5	56	C102_0059 IE3D090LX04	42	5.875	47/8	58
250	0.89	-	-	55	C002_0058 IE3D090LX04	37	5.824	99/17	58
251	2.4	435	2.3	55	C202_0058 IE3D090LX04	46	5.791	666/115	59

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 1,50 kW, P_N (87 Hz) = 2,60 kW									
287	0.98	498	0.83	48	C002_0051 IE3D090LX04	37	5.063	481/95	58
287	2.5	497	2.5	48	C202_0051 IE3D090LX04	46	5.072	350/69	59
290	2.0	502	1.7	48	C102_0050 IE3D090LX04	42	5.025	201/40	59
311	1.0	538	0.87	44	C002_0047 IE3D090LX04	37	4.680	117/25	58
312	2.1	541	1.8	44	C102_0047 IE3D090LX04	42	4.658	3149/676	59
347	2.2	602	1.9	40	C102_0042 IE3D090LX04	42	4.189	377/90	59
351	1.1	607	0.95	39	C002_0041 IE3D090LX04	37	4.149	1813/437	58
375	2.3	649	2.0	37	C102_0039 IE3D090LX04	42	3.883	1363/351	59
379	1.2	657	1.0	36	C002_0038 IE3D090LX04	37	3.835	441/115	58
439	1.3	760	1.1	32	C002_0033 IE3D090LX04	37	3.318	1702/513	58
436	2.5	756	2.2	32	C102_0033 IE3D090LX04	42	3.334	2067/620	59
474	1.4	822	1.2	29	C002_0031 IE3D090LX04	37	3.067	46/15	58
471	2.5	815	2.3	29	C102_0031 IE3D090LX04	42	3.091	2491/806	59
525	1.5	910	1.2	26	C002_0028 IE3D090LX04	37	2.769	36/13	58
668	2.4	1158	2.4	21	C102_0022 IE3D090LX04	42	2.177	468/215	60
729	1.8	1262	1.5	19	C002_0020 IE3D090LX04	37	1.997	1480/741	59
721	2.4	1249	2.4	19	C102_0020 IE3D090LX04	42	2.018	1128/559	60
P_N (50 Hz) = 2,20 kW, P_N (87 Hz) = 3,81 kW									
5.4	0.96	9.3	0.96	3740	C813_2700 IE3D100KX04	210	269.8	7285/27	111
6.8	1.2	12	1.2	2940	C813_2120 IE3D100KX04	210	212.1	8272/39	111
8.1	1.5	14	1.4	2472	C813_1780 IE3D100KX04	210	178.4	6956/39	111
10	1.9	18	1.7	1918	C813_1380 IE3D100KX04	210	138.4	2491/18	112
11	1.1	18	1.1	1904	C713_1370 IE3D100KX04	151	137.3	10575/77	111
11	1.3	19	1.1	1835	C713_1320 IE3D100KX04	151	132.4	33887/256	111
11	0.82	20	0.82	1759	C613_1270 IE3D100KX04	111	126.9	48739/384	111
13	2.2	23	2.0	1491	C813_1080 IE3D100KX04	210	107.6	4841/45	112
13	0.87	23	0.87	1489	C613_1070 IE3D100KX04	111	107.4	752/7	111
15	1.7	25	1.4	1374	C713_0990 IE3D100KX04	151	99.14	6345/64	111
15	1.1	26	1.1	1353	C613_0980 IE3D100KX04	111	97.63	243695/2496	111
16	2.2	28	2.2	1259	C813_0910 IE3D100KX04	210	90.82	18800/207	113
16	1.1	28	1.1	1231	C613_0890 IE3D100KX04	111	88.78	799/9	111
18	2.0	31	1.7	1122	C713_0810 IE3D100KX04	151	80.97	20727/256	111
18	2.2	32	2.0	1100	C813_0790 IE3D100KX04	210	79.34	285619/3600	112
19	1.4	33	1.4	1065	C613_0770 IE3D100KX04	111	76.80	8601/112	111
21	2.0	36	2.0	978	C712_0700 IE3D100KX04	137	69.55	765/11	112
21	1.3	36	1.3	969	C612_0690 IE3D100KX04	102	68.89	620/9	111
23	1.6	40	1.6	880	C613_0630 IE3D100KX04	111	63.46	48739/768	111
26	2.4	44	2.4	799	C712_0570 IE3D100KX04	137	56.82	625/11	113
26	1.0	45	1.0	785	C502_0560 IE3D100KX04	87	55.83	335/6	111
26	1.7	46	1.7	775	C612_0550 IE3D100KX04	102	55.11	496/9	112
29	1.1	50	1.1	701	C502_0500 IE3D100KX04	87	49.82	1943/39	111
29	2.1	51	2.0	683	C613_0490 IE3D100KX04	111	49.28	31537/640	111
31	0.84	54	0.84	656	C402_0470 IE3D100KX04	75	46.67	140/3	111
31	1.2	54	1.2	657	C502_0470 IE3D100KX04	87	46.72	1495/32	111
32	2.0	55	2.0	638	C612_0450 IE3D100KX04	102	45.33	136/3	112
35	0.94	60	0.94	587	C402_0420 IE3D100KX04	75	41.75	7056/169	111
35	1.4	60	1.4	586	C502_0420 IE3D100KX04	87	41.69	667/16	111
35	2.4	61	2.4	577	C712_0410 IE3D100KX04	137	41.02	2625/64	113
37	2.2	64	2.2	554	C612_0390 IE3D100KX04	102	39.40	1891/48	112
42	1.1	72	1.1	490	C402_0350 IE3D100KX04	75	34.82	975/28	111
41	1.6	72	1.6	492	C502_0350 IE3D100KX04	87	35.00	35/1	112
42	2.7	72	2.7	490	C612_0350 IE3D100KX04	102	34.87	1360/39	114
45	2.5	78	2.5	456	C612_0320 IE3D100KX04	102	32.41	1037/32	112
47	0.80	81	0.80	437	C302_0310 IE3D100KX04	65	31.04	776/25	110
47	1.3	81	1.3	438	C402_0310 IE3D100KX04	75	31.15	405/13	111
46	1.8	80	1.8	439	C502_0310 IE3D100KX04	87	31.23	406/13	112
52	0.89	90	0.89	394	C302_0280 IE3D100KX04	65	27.99	2015/72	111
52	1.4	90	1.4	392	C402_0280 IE3D100KX04	75	27.86	195/7	111
52	2.0	89	2.0	395	C502_0280 IE3D100KX04	87	28.10	5395/192	112
53	3.3	92	3.3	386	C612_0270 IE3D100KX04	102	27.43	192/7	115
58	1.0	101	1.0	349	C302_0250 IE3D100KX04	65	24.80	124/5	111
58	1.6	101	1.6	351	C402_0250 IE3D100KX04	75	24.92	324/13	111
58	2.3	100	2.3	353	C502_0250 IE3D100KX04	87	25.07	2407/96	112
62	1.1	107	1.1	330	C302_0230 IE3D100KX04	65	23.47	845/36	111
62	1.7	108	1.7	329	C402_0230 IE3D100KX04	75	23.36	1495/64	112

2.2 Selection tables 2 C helical geared motors

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 2,20 kW, P_N (87 Hz) = 3,81 kW									
62	2.4	108	2.4	329	C502_0230 IE3D100KX04	87	23.36	1495/64	113
70	1.2	121	1.2	293	C302_0210 IE3D100KX04	65	20.80	104/5	111
69	1.9	120	1.9	294	C402_0210 IE3D100KX04	75	20.90	4347/208	112
70	2.7	120	2.7	293	C502_0210 IE3D100KX04	87	20.84	667/32	113
74	3.3	128	3.3	276	C612_0195 IE3D100KX04	102	19.61	549/28	115
83	0.81	143	0.81	246	C202_0175 IE3D100KX04	60	17.52	3626/207	111
83	1.4	143	1.4	247	C302_0175 IE3D100KX04	65	17.54	1105/63	111
82	2.2	143	2.2	248	C402_0175 IE3D100KX04	75	17.60	845/48	112
92	2.5	159	2.5	222	C402_0160 IE3D100KX04	75	15.75	63/4	113
95	0.93	164	0.93	215	C202_0155 IE3D100KX04	60	15.28	703/46	111
93	1.6	162	1.6	219	C302_0155 IE3D100KX04	65	15.54	544/35	111
103	1.0	178	1.0	199	C202_0140 IE3D100KX04	60	14.12	3430/243	111
104	1.8	179	1.7	197	C302_0140 IE3D100KX04	65	13.99	2015/144	111
104	2.8	179	2.8	197	C402_0140 IE3D100KX04	75	13.99	2015/144	113
118	1.2	204	1.2	173	C202_0125 IE3D100KX04	60	12.32	665/54	111
117	2.0	203	1.9	174	C302_0125 IE3D100KX04	65	12.40	62/5	112
123	1.2	214	1.2	165	C202_0120 IE3D100KX04	60	11.76	294/25	111
125	2.1	216	1.9	163	C302_0115 IE3D100KX04	65	11.61	325/28	112
140	0.82	242	0.82	146	C102_0105 IE3D100KX04	56	10.38	841/81	111
141	1.4	245	1.4	144	C202_0105 IE3D100KX04	60	10.26	513/50	111
141	2.4	244	2.1	145	C302_0105 IE3D100KX04	65	10.29	72/7	112
154	1.5	268	1.4	132	C202_0094 IE3D100KX04	60	9.387	2450/261	111
155	0.92	269	0.88	131	C102_0093 IE3D100KX04	56	9.326	3180/341	111
156	2.7	270	2.2	131	C302_0093 IE3D100KX04	65	9.310	3575/384	113
175	1.0	304	0.95	116	C102_0083 IE3D100KX04	56	8.263	1537/186	111
176	2.9	304	2.4	116	C302_0083 IE3D100KX04	65	8.250	33/4	113
177	1.7	307	1.6	115	C202_0082 IE3D100KX04	60	8.190	475/58	112
186	1.0	322	0.84	110	C102_0078 IE3D100KX04	56	7.796	3243/416	110
186	1.5	322	1.3	110	C202_0078 IE3D100KX04	60	7.800	39/5	111
185	2.5	320	2.1	110	C302_0078 IE3D100KX04	65	7.841	494/63	111
229	1.1	396	0.96	89	C102_0063 IE3D100KX04	56	6.338	507/80	110
230	1.8	399	1.5	89	C202_0063 IE3D100KX04	60	6.295	3330/529	111
230	2.9	398	2.4	89	C302_0063 IE3D100KX04	65	6.314	221/35	111
247	1.2	427	1.0	83	C102_0059 IE3D100KX04	56	5.875	47/8	110
247	3.0	429	2.5	82	C302_0059 IE3D100KX04	65	5.859	2584/441	111
250	1.9	434	1.6	81	C202_0058 IE3D100KX04	60	5.791	666/115	111
286	2.0	495	1.7	71	C202_0051 IE3D100KX04	60	5.072	350/69	111
289	1.3	500	1.1	71	C102_0050 IE3D100KX04	56	5.025	201/40	111
288	3.3	499	2.8	71	C302_0050 IE3D100KX04	65	5.038	403/80	112
311	1.4	539	1.2	66	C102_0047 IE3D100KX04	56	4.658	3149/676	111
311	2.1	538	1.8	66	C202_0047 IE3D100KX04	60	4.667	14/3	111
313	4.1	543	4.1	65	C502_0046 IE3D100KX04	87	4.629	162/35	118
346	1.5	600	1.3	59	C102_0042 IE3D100KX04	56	4.189	377/90	111
343	2.3	594	1.9	59	C202_0042 IE3D100KX04	60	4.226	486/115	111
373	1.6	647	1.3	55	C102_0039 IE3D100KX04	56	3.883	1363/351	111
373	2.4	646	2.0	55	C202_0039 IE3D100KX04	60	3.888	486/125	111
430	2.7	745	2.2	47	C202_0034 IE3D100KX04	60	3.373	2250/667	112
435	1.8	753	1.5	47	C102_0033 IE3D100KX04	56	3.334	2067/620	111
469	1.8	813	1.6	43	C102_0031 IE3D100KX04	56	3.091	2491/806	111
467	2.8	809	2.4	44	C202_0031 IE3D100KX04	60	3.103	90/29	112
539	3.1	934	2.6	38	C202_0027 IE3D100KX04	60	2.690	495/184	113
562	2.1	973	1.8	36	C102_0026 IE3D100KX04	56	2.582	1911/740	111
586	3.3	1015	2.8	35	C202_0025 IE3D100KX04	60	2.475	99/40	113
606	2.2	1049	1.8	34	C102_0024 IE3D100KX04	56	2.394	2303/962	111
666	2.3	1154	2.0	31	C102_0022 IE3D100KX04	56	2.177	468/215	112
719	2.4	1245	2.1	28	C102_0020 IE3D100KX04	56	2.018	1128/559	112
P_N (50 Hz) = 3,00 kW, P_N (87 Hz) = 5,20 kW									
6.8	0.90	12	0.88	4015	C813_2120 IE3D100LX04	215	212.1	8272/39	131
8.1	1.1	14	1.0	3376	C813_1780 IE3D100LX04	215	178.4	6956/39	131
10	1.4	18	1.2	2620	C813_1380 IE3D100LX04	215	138.4	2491/18	132
11	0.96	19	0.84	2506	C713_1320 IE3D100LX04	156	132.4	33887/256	131
13	1.6	23	1.5	2036	C813_1080 IE3D100LX04	215	107.6	4841/45	132
15	1.3	25	1.1	1877	C713_0990 IE3D100LX04	156	99.14	6345/64	131
16	1.6	28	1.6	1719	C813_0910 IE3D100LX04	215	90.82	18800/207	133
18	1.5	31	1.2	1533	C713_0810 IE3D100LX04	156	80.97	20727/256	131

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 3,00 kW, P_N (87 Hz) = 5,20 kW									
18	1.6	32	1.5	1502	C813_0790 IE3D100LX04	215	79.34	285619/3600	132
19	1.0	33	1.0	1454	C613_0770 IE3D100LX04	116	76.80	8601/112	131
21	1.5	36	1.5	1336	C712_0700 IE3D100LX04	142	69.55	765/11	132
21	0.98	36	0.98	1323	C612_0690 IE3D100LX04	107	68.89	620/9	131
23	1.2	40	1.2	1201	C613_0630 IE3D100LX04	116	63.46	48739/768	131
26	1.8	44	1.8	1091	C712_0570 IE3D100LX04	142	56.82	625/11	133
26	1.2	46	1.2	1058	C612_0550 IE3D100LX04	107	55.11	496/9	132
29	0.84	50	0.84	957	C502_0500 IE3D100LX04	92	49.82	1943/39	131
29	1.6	51	1.5	933	C613_0490 IE3D100LX04	116	49.28	31537/640	131
31	0.89	54	0.89	897	C502_0470 IE3D100LX04	92	46.72	1495/32	131
32	1.5	55	1.5	871	C612_0450 IE3D100LX04	107	45.33	136/3	132
35	1.0	60	1.0	801	C502_0420 IE3D100LX04	92	41.69	667/16	131
35	1.8	61	1.8	788	C712_0410 IE3D100LX04	142	41.02	2625/64	133
37	1.6	64	1.6	757	C612_0390 IE3D100LX04	107	39.40	1891/48	132
42	0.82	72	0.82	669	C402_0350 IE3D100LX04	80	34.82	975/28	131
41	1.2	72	1.2	672	C502_0350 IE3D100LX04	92	35.00	35/1	132
42	1.9	72	1.9	670	C612_0350 IE3D100LX04	107	34.87	1360/39	134
41	2.3	72	2.3	673	C712_0350 IE3D100LX04	142	35.07	2700/77	138
45	1.8	78	1.8	622	C612_0320 IE3D100LX04	107	32.41	1037/32	132
47	0.92	81	0.92	598	C402_0310 IE3D100LX04	80	31.15	405/13	131
46	1.3	80	1.3	600	C502_0310 IE3D100LX04	92	31.23	406/13	132
52	1.0	90	1.0	535	C402_0280 IE3D100LX04	80	27.86	195/7	131
52	1.5	89	1.5	540	C502_0280 IE3D100LX04	92	28.10	5395/192	132
53	2.4	92	2.4	527	C612_0270 IE3D100LX04	107	27.43	192/7	135
58	1.1	101	1.1	479	C402_0250 IE3D100LX04	80	24.92	324/13	131
58	1.7	100	1.7	482	C502_0250 IE3D100LX04	92	25.07	2407/96	132
58	2.1	101	2.1	479	C612_0250 IE3D100LX04	107	24.93	5185/208	134
62	1.2	108	1.2	449	C402_0230 IE3D100LX04	80	23.36	1495/64	132
62	1.8	108	1.8	449	C502_0230 IE3D100LX04	92	23.36	1495/64	133
70	0.88	121	0.88	399	C302_0210 IE3D100LX04	70	20.80	104/5	131
69	1.4	120	1.4	401	C402_0210 IE3D100LX04	80	20.90	4347/208	132
70	2.0	120	2.0	400	C502_0210 IE3D100LX04	92	20.84	667/32	133
74	2.4	128	2.4	377	C612_0195 IE3D100LX04	107	19.61	549/28	135
83	1.0	143	1.0	337	C302_0175 IE3D100LX04	70	17.54	1105/63	131
82	1.6	143	1.6	338	C402_0175 IE3D100LX04	80	17.60	845/48	132
92	1.8	159	1.8	302	C402_0160 IE3D100LX04	80	15.75	63/4	133
93	1.2	162	1.2	299	C302_0155 IE3D100LX04	70	15.54	544/35	131
104	1.3	179	1.3	269	C302_0140 IE3D100LX04	70	13.99	2015/144	131
104	2.0	179	2.0	269	C402_0140 IE3D100LX04	80	13.99	2015/144	133
118	0.85	204	0.85	237	C202_0125 IE3D100LX04	65	12.32	665/54	131
117	1.5	203	1.4	238	C302_0125 IE3D100LX04	70	12.40	62/5	132
116	2.3	201	2.3	240	C402_0125 IE3D100LX04	80	12.52	651/52	133
123	0.89	214	0.89	226	C202_0120 IE3D100LX04	65	11.76	294/25	131
125	1.6	216	1.4	223	C302_0115 IE3D100LX04	70	11.61	325/28	132
125	2.5	216	2.4	223	C402_0115 IE3D100LX04	80	11.64	1885/162	134
141	1.0	245	0.99	197	C202_0105 IE3D100LX04	65	10.26	513/50	131
141	1.8	244	1.5	198	C302_0105 IE3D100LX04	70	10.29	72/7	132
139	2.8	241	2.6	200	C402_0105 IE3D100LX04	80	10.41	406/39	134
154	1.1	268	1.1	180	C202_0094 IE3D100LX04	65	9.387	2450/261	131
156	2.0	270	1.6	179	C302_0093 IE3D100LX04	70	9.310	3575/384	133
176	2.1	304	1.8	158	C302_0083 IE3D100LX04	70	8.250	33/4	133
177	1.3	307	1.2	157	C202_0082 IE3D100LX04	65	8.190	475/58	132
186	1.1	322	0.94	150	C202_0078 IE3D100LX04	65	7.800	39/5	131
185	1.8	320	1.5	151	C302_0078 IE3D100LX04	70	7.841	494/63	131
186	2.4	321	2.2	150	C402_0078 IE3D100LX04	80	7.816	2001/256	132
229	0.84	-	-	122	C102_0063 IE3D100LX04	61	6.338	507/80	130
230	1.3	399	1.1	121	C202_0063 IE3D100LX04	65	6.295	3330/529	131
230	2.1	398	1.8	121	C302_0063 IE3D100LX04	70	6.314	221/35	131
247	0.88	-	-	113	C102_0059 IE3D100LX04	61	5.875	47/8	130
247	2.2	429	1.9	113	C302_0059 IE3D100LX04	70	5.859	2584/441	131
250	1.4	434	1.1	111	C202_0058 IE3D100LX04	65	5.791	666/115	131
286	1.5	495	1.3	97	C202_0051 IE3D100LX04	65	5.072	350/69	131
289	0.98	500	0.82	97	C102_0050 IE3D100LX04	61	5.025	201/40	131
288	2.4	499	2.1	97	C302_0050 IE3D100LX04	70	5.038	403/80	132
311	1.0	539	0.87	89	C102_0047 IE3D100LX04	61	4.658	3149/676	131

2.2 Selection tables 2 C helical geared motors

n_2 50 Hz [rpm]	S	n_2 87 Hz [rpm]	S	M_{2N} [Nm]	Type	m [kg]	i	i_{exakt}	J_1 [kgcm ²]
P_N (50 Hz) = 3,00 kW, P_N (87 Hz) = 5,20 kW									
311	1.6	538	1.3	90	C202_0047 IE3D100LX04	65	4.667	14/3	131
310	2.6	537	2.2	90	C302_0047 IE3D100LX04	70	4.675	589/126	132
313	3.0	543	3.0	89	C502_0046 IE3D100LX04	92	4.629	162/35	138
346	1.1	600	0.93	80	C102_0042 IE3D100LX04	61	4.189	377/90	131
343	1.7	594	1.4	81	C202_0042 IE3D100LX04	65	4.226	486/115	131
347	2.8	601	2.3	80	C302_0042 IE3D100LX04	70	4.179	117/28	133
373	1.2	647	0.98	75	C102_0039 IE3D100LX04	61	3.883	1363/351	131
373	1.8	646	1.5	75	C202_0039 IE3D100LX04	65	3.888	486/125	131
374	2.9	648	2.4	74	C302_0039 IE3D100LX04	70	3.878	190/49	133
430	1.9	745	1.6	65	C202_0034 IE3D100LX04	65	3.373	2250/667	132
433	3.0	749	2.7	64	C302_0034 IE3D100LX04	70	3.352	429/128	133
435	1.3	753	1.1	64	C102_0033 IE3D100LX04	61	3.334	2067/620	131
469	1.4	813	1.1	59	C102_0031 IE3D100LX04	61	3.091	2491/806	131
467	2.1	809	1.7	60	C202_0031 IE3D100LX04	65	3.103	90/29	132
539	2.3	934	1.9	52	C202_0027 IE3D100LX04	65	2.690	495/184	133
562	1.5	973	1.3	50	C102_0026 IE3D100LX04	61	2.582	1911/740	131
586	2.4	1015	2.0	48	C202_0025 IE3D100LX04	65	2.475	99/40	133
606	1.6	1049	1.4	46	C102_0024 IE3D100LX04	61	2.394	2303/962	131
666	1.7	1154	1.4	42	C102_0022 IE3D100LX04	61	2.177	468/215	132
664	2.6	1150	2.2	42	C202_0022 IE3D100LX04	65	2.184	2160/989	134
719	1.8	1245	1.5	39	C102_0020 IE3D100LX04	61	2.018	1128/559	132
722	2.7	1250	2.3	39	C202_0020 IE3D100LX04	65	2.009	432/215	134
P_N (50 Hz) = 4,00 kW, P_N (87 Hz) = 6,93 kW									
8.2	0.81	–	–	4450	C813_1780 IE3D112M04	221	178.4	6956/39	171
11	1.0	18	0.93	3453	C813_1380 IE3D112M04	221	138.4	2491/18	172
14	1.2	24	1.1	2684	C813_1080 IE3D112M04	221	107.6	4841/45	172
15	0.95	26	0.80	2474	C713_0990 IE3D112M04	162	99.14	6345/64	171
16	1.2	28	1.2	2266	C813_0910 IE3D112M04	221	90.82	18800/207	173
18	1.1	31	0.93	2020	C713_0810 IE3D112M04	162	80.97	20727/256	171
18	1.2	32	1.1	1980	C813_0790 IE3D112M04	221	79.34	285619/3600	172
21	1.1	36	1.1	1761	C712_0700 IE3D112M04	148	69.55	765/11	172
23	0.92	40	0.92	1583	C613_0630 IE3D112M04	122	63.46	48739/768	171
26	1.3	45	1.3	1438	C712_0570 IE3D112M04	148	56.82	625/11	173
27	0.93	46	0.93	1395	C612_0550 IE3D112M04	113	55.11	496/9	172
30	1.2	51	1.1	1230	C613_0490 IE3D112M04	122	49.28	31537/640	171
32	1.1	56	1.1	1148	C612_0450 IE3D112M04	113	45.33	136/3	172
36	1.3	62	1.3	1038	C712_0410 IE3D112M04	148	41.02	2625/64	173
37	1.2	64	1.2	997	C612_0390 IE3D112M04	113	39.40	1891/48	172
42	0.90	72	0.90	886	C502_0350 IE3D112M04	98	35.00	35/1	172
42	1.5	73	1.5	883	C612_0350 IE3D112M04	113	34.87	1360/39	174
42	1.8	72	1.8	888	C712_0350 IE3D112M04	148	35.07	2700/77	178
45	1.4	78	1.4	820	C612_0320 IE3D112M04	113	32.41	1037/32	172
47	1.0	81	1.0	791	C502_0310 IE3D112M04	98	31.23	406/13	172
52	1.1	90	1.1	711	C502_0280 IE3D112M04	98	28.10	5395/192	172
53	1.8	93	1.8	694	C612_0270 IE3D112M04	113	27.43	192/7	175
59	0.87	102	0.87	631	C402_0250 IE3D112M04	86	24.92	324/13	171
58	1.3	101	1.3	635	C502_0250 IE3D112M04	98	25.07	2407/96	172
59	1.6	102	1.6	631	C612_0250 IE3D112M04	113	24.93	5185/208	174
58	1.8	100	1.8	641	C712_0250 IE3D112M04	148	25.31	405/16	178
63	0.93	109	0.93	591	C402_0230 IE3D112M04	86	23.36	1495/64	172
63	1.4	109	1.4	591	C502_0230 IE3D112M04	98	23.36	1495/64	173
70	1.0	121	1.0	529	C402_0210 IE3D112M04	86	20.90	4347/208	172
70	1.5	122	1.5	528	C502_0210 IE3D112M04	98	20.84	667/32	173
75	1.8	129	1.8	496	C612_0195 IE3D112M04	113	19.61	549/28	175
83	1.2	144	1.2	446	C402_0175 IE3D112M04	86	17.60	845/48	172
93	1.4	161	1.4	399	C402_0160 IE3D112M04	86	15.75	63/4	173
94	0.89	163	0.89	394	C302_0155 IE3D112M04	76	15.54	544/35	171
105	0.99	181	0.95	354	C302_0140 IE3D112M04	76	13.99	2015/144	171
105	1.6	181	1.6	354	C402_0140 IE3D112M04	86	13.99	2015/144	173
105	2.3	182	2.3	353	C502_0140 IE3D112M04	98	13.93	195/14	176
118	1.1	205	1.0	314	C302_0125 IE3D112M04	76	12.40	62/5	172
117	1.7	203	1.7	317	C402_0125 IE3D112M04	86	12.52	651/52	173
118	2.3	204	2.3	315	C502_0125 IE3D112M04	98	12.43	87/7	176
126	1.2	219	1.1	294	C302_0115 IE3D112M04	76	11.61	325/28	172
126	1.9	218	1.8	295	C402_0115 IE3D112M04	86	11.64	1885/162	174

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 4,00 kW, P_N (87 Hz) = 6,93 kW									
142	1.3	247	1.2	260	C302_0105 IE3D112M04	76	10.29	72/7	172
141	2.1	244	1.9	264	C402_0105 IE3D112M04	86	10.41	406/39	174
156	0.84	–	–	238	C202_0094 IE3D112M04	71	9.387	2450/261	171
157	1.5	273	1.2	236	C302_0093 IE3D112M04	76	9.310	3575/384	173
178	1.6	308	1.4	209	C302_0083 IE3D112M04	76	8.250	33/4	173
179	0.97	310	0.88	207	C202_0082 IE3D112M04	71	8.190	475/58	172
188	0.84	–	–	197	C202_0078 IE3D112M04	71	7.800	39/5	171
187	1.4	324	1.2	199	C302_0078 IE3D112M04	76	7.841	494/63	171
187	1.8	325	1.7	198	C402_0078 IE3D112M04	86	7.816	2001/256	172
189	2.0	327	2.0	197	C502_0078 IE3D112M04	98	7.763	621/80	174
233	0.97	403	0.82	159	C202_0063 IE3D112M04	71	6.295	3330/529	171
232	1.6	402	1.3	160	C302_0063 IE3D112M04	76	6.314	221/35	171
250	1.7	433	1.4	148	C302_0059 IE3D112M04	76	5.859	2584/441	171
249	2.1	431	2.0	149	C402_0059 IE3D112M04	86	5.891	377/64	173
253	1.0	438	0.87	147	C202_0058 IE3D112M04	71	5.791	666/115	171
289	1.1	500	0.95	128	C202_0051 IE3D112M04	71	5.072	350/69	171
291	1.8	504	1.6	128	C302_0050 IE3D112M04	76	5.038	403/80	172
314	1.2	544	1.0	118	C202_0047 IE3D112M04	71	4.667	14/3	171
313	1.9	543	1.6	118	C302_0047 IE3D112M04	76	4.675	589/126	172
313	2.3	542	2.3	119	C402_0047 IE3D112M04	86	4.682	899/192	175
316	2.3	548	2.3	117	C502_0046 IE3D112M04	98	4.629	162/35	178
350	0.84	–	–	106	C102_0042 IE3D112M04	67	4.189	377/90	171
347	1.3	600	1.1	107	C202_0042 IE3D112M04	71	4.226	486/115	171
351	2.1	607	1.8	106	C302_0042 IE3D112M04	76	4.179	117/28	173
377	0.88	–	–	98	C102_0039 IE3D112M04	67	3.883	1363/351	171
377	1.3	653	1.1	98	C202_0039 IE3D112M04	71	3.888	486/125	171
378	2.2	654	1.9	98	C302_0039 IE3D112M04	76	3.878	190/49	173
434	1.5	752	1.2	85	C202_0034 IE3D112M04	71	3.373	2250/667	172
437	2.3	757	2.0	85	C302_0034 IE3D112M04	76	3.352	429/128	173
439	0.97	761	0.82	84	C102_0033 IE3D112M04	67	3.334	2067/620	171
474	1.0	821	0.86	78	C102_0031 IE3D112M04	67	3.091	2491/806	171
472	1.6	818	1.3	79	C202_0031 IE3D112M04	71	3.103	90/29	172
471	2.3	816	2.2	79	C302_0031 IE3D112M04	76	3.110	1045/336	174
545	1.7	943	1.4	68	C202_0027 IE3D112M04	71	2.690	495/184	173
567	1.2	983	0.97	65	C102_0026 IE3D112M04	67	2.582	1911/740	171
592	1.8	1025	1.5	63	C202_0025 IE3D112M04	71	2.475	99/40	173
612	1.2	1060	1.0	61	C102_0024 IE3D112M04	67	2.394	2303/962	171
673	1.3	1166	1.1	55	C102_0022 IE3D112M04	67	2.177	468/215	172
671	2.0	1162	1.7	55	C202_0022 IE3D112M04	71	2.184	2160/989	174
726	1.4	1257	1.1	51	C102_0020 IE3D112M04	67	2.018	1128/559	172
729	2.1	1263	1.8	51	C202_0020 IE3D112M04	71	2.009	432/215	174
P_N (50 Hz) = 5,50 kW, P_N (87 Hz) = 9,53 kW									
6.8	0.81	12	0.81	7412	C913_2150 IE3D132SX04	361	215.4	3015/14	353
8.3	0.99	14	0.99	6061	C913_1760 IE3D132SX04	361	176.1	34515/196	354
11	0.94	20	0.92	4458	C813_1300 IE3D132SX04	255	129.5	58941/455	352
13	1.6	23	1.6	3801	C913_1100 IE3D132SX04	361	110.4	21645/196	356
14	0.99	24	0.99	3646	C813_1060 IE3D132SX04	255	105.9	3708/35	353
15	1.2	25	1.1	3459	C813_1010 IE3D132SX04	255	100.5	28143/280	353
16	1.2	28	1.2	3078	C813_0890 IE3D132SX04	255	89.44	14400/161	354
18	0.88	32	0.88	2744	C713_0800 IE3D132SX04	196	79.73	5103/64	352
19	1.6	32	1.4	2689	C813_0780 IE3D132SX04	255	78.13	54693/700	353
19	1.9	33	1.6	2675	C913_0780 IE3D132SX04	361	77.73	60939/784	356
21	1.5	37	1.5	2406	C812_0690 IE3D132SX04	242	68.89	620/9	356
22	1.8	38	1.6	2270	C813_0660 IE3D132SX04	255	65.96	10620/161	354
23	1.1	39	1.1	2221	C713_0650 IE3D132SX04	196	64.55	4131/64	353
26	1.0	45	1.0	1984	C712_0570 IE3D132SX04	182	56.82	625/11	353
27	1.9	47	1.9	1891	C812_0540 IE3D132SX04	242	54.15	704/13	359
29	1.4	50	1.4	1750	C713_0510 IE3D132SX04	196	50.85	18711/368	353
30	2.2	52	1.9	1692	C813_0490 IE3D132SX04	255	49.18	49914/1015	355
31	1.2	54	1.2	1635	C712_0470 IE3D132SX04	182	46.82	515/11	355
32	2.3	56	2.3	1590	C812_0460 IE3D132SX04	242	45.54	592/13	362
32	0.82	56	0.82	1583	C612_0450 IE3D132SX04	147	45.33	136/3	352
36	1.5	62	1.5	1432	C712_0410 IE3D132SX04	182	41.02	2625/64	353
37	2.6	64	2.6	1395	C812_0400 IE3D132SX04	242	39.94	2596/65	359
42	1.1	73	1.1	1218	C612_0350 IE3D132SX04	147	34.87	1360/39	354

2.2 Selection tables 2 C helical geared motors

n_2 50 Hz [rpm]	S	n_2 87 Hz [rpm]	S	M_{2N} [Nm]	Type	m [kg]	i	i_{exakt}	J_1 [kgcm ²]
P_N (50 Hz) = 5,50 kW, P_N (87 Hz) = 9,53 kW									
42	1.6	72	1.6	1224	C712_0350 IE3D132SX04	182	35.07	2700/77	358
41	2.9	72	2.9	1234	C812_0350 IE3D132SX04	242	35.33	106/3	368
43	2.0	75	2.0	1180	C712_0340 IE3D132SX04	182	33.80	2163/64	355
45	1.3	78	1.3	1132	C612_0320 IE3D132SX04	147	32.41	1037/32	352
51	2.0	89	2.0	1000	C712_0290 IE3D132SX04	182	28.64	315/11	360
52	0.82	90	0.82	981	C502_0280 IE3D132SX04	132	28.10	5395/192	352
53	1.4	93	1.4	958	C612_0270 IE3D132SX04	147	27.43	192/7	355
53	3.5	92	3.5	959	C812_0270 IE3D132SX04	242	27.47	412/15	376
56	3.0	97	3.0	910	C812_0260 IE3D132SX04	242	26.06	3127/120	368
58	0.91	101	0.91	876	C502_0250 IE3D132SX04	132	25.07	2407/96	352
59	1.7	102	1.6	870	C612_0250 IE3D132SX04	147	24.93	5185/208	354
58	2.7	100	2.7	884	C712_0250 IE3D132SX04	182	25.31	405/16	358
63	0.98	109	0.98	816	C502_0230 IE3D132SX04	132	23.36	1495/64	353
65	1.6	112	1.6	792	C612_0230 IE3D132SX04	147	22.67	68/3	357
63	2.5	109	2.5	810	C712_0230 IE3D132SX04	182	23.18	255/11	364
70	1.1	122	1.1	728	C502_0210 IE3D132SX04	132	20.84	667/32	353
71	3.1	123	3.1	722	C712_0210 IE3D132SX04	182	20.67	1323/64	361
72	3.5	125	3.5	707	C812_0200 IE3D132SX04	242	20.26	6077/300	377
75	2.1	129	1.9	685	C612_0195 IE3D132SX04	147	19.61	549/28	355
80	3.1	139	3.1	638	C712_0185 IE3D132SX04	182	18.26	420/23	371
83	0.90	144	0.90	615	C402_0175 IE3D132SX04	120	17.60	845/48	352
83	1.3	144	1.3	615	C502_0175 IE3D132SX04	132	17.60	845/48	355
83	2.1	144	2.1	615	C612_0175 IE3D132SX04	147	17.60	88/5	360
86	3.8	148	3.8	597	C812_0170 IE3D132SX04	242	17.10	1180/69	385
88	3.7	152	3.5	584	C712_0165 IE3D132SX04	182	16.73	1071/64	365
93	1.0	161	1.0	550	C402_0160 IE3D132SX04	120	15.75	63/4	353
90	2.6	157	2.2	566	C612_0160 IE3D132SX04	147	16.20	1037/64	357
93	1.5	162	1.5	549	C502_0155 IE3D132SX04	132	15.71	377/24	355
105	1.1	181	1.1	489	C402_0140 IE3D132SX04	120	13.99	2015/144	353
105	1.6	182	1.6	486	C502_0140 IE3D132SX04	132	13.93	195/14	356
104	2.6	179	2.4	494	C612_0140 IE3D132SX04	147	14.15	976/69	364
107	4.2	185	4.0	479	C712_0135 IE3D132SX04	182	13.73	4380/319	380
111	4.0	192	4.0	460	C712_0130 IE3D132SX04	182	13.18	4851/368	372
118	0.81	–	–	433	C302_0125 IE3D132SX04	110	12.40	62/5	352
117	1.3	203	1.2	437	C402_0125 IE3D132SX04	120	12.52	651/52	353
118	1.8	204	1.8	434	C502_0125 IE3D132SX04	132	12.43	87/7	356
116	3.0	202	2.6	439	C612_0125 IE3D132SX04	147	12.58	2013/160	361
126	0.86	–	–	405	C302_0115 IE3D132SX04	110	11.61	325/28	352
126	1.4	218	1.3	406	C402_0115 IE3D132SX04	120	11.64	1885/162	354
126	2.0	218	2.0	406	C502_0115 IE3D132SX04	132	11.64	1885/162	358
128	3.2	221	2.7	400	C612_0115 IE3D132SX04	147	11.46	928/81	368
142	0.97	247	0.85	359	C302_0105 IE3D132SX04	110	10.29	72/7	352
141	1.5	244	1.4	364	C402_0105 IE3D132SX04	120	10.41	406/39	354
141	2.2	244	2.1	363	C502_0105 IE3D132SX04	132	10.38	841/81	358
145	3.5	251	3.0	353	C612_0100 IE3D132SX04	147	10.11	3721/368	365
148	4.4	256	4.4	346	C712_0099 IE3D132SX04	182	9.912	4599/464	381
157	1.1	273	0.91	325	C302_0093 IE3D132SX04	110	9.310	3575/384	353
158	1.7	274	1.5	323	C402_0093 IE3D132SX04	120	9.261	3445/372	356
158	2.5	274	2.3	323	C502_0093 IE3D132SX04	132	9.261	3445/372	361
161	3.8	278	3.2	318	C612_0091 IE3D132SX04	147	9.118	848/93	373
178	1.2	308	0.98	288	C302_0083 IE3D132SX04	110	8.250	33/4	353
177	1.9	306	1.6	289	C402_0083 IE3D132SX04	120	8.285	3339/403	356
177	2.8	307	2.5	289	C502_0083 IE3D132SX04	132	8.263	1537/186	361
179	4.1	310	3.4	286	C612_0082 IE3D132SX04	147	8.190	1769/216	369
187	1.0	324	0.84	274	C302_0078 IE3D132SX04	110	7.841	494/63	351
187	1.5	325	1.2	273	C402_0078 IE3D132SX04	120	7.816	2001/256	352
189	2.3	327	1.9	271	C502_0078 IE3D132SX04	132	7.763	621/80	354
225	4.4	389	4.0	228	C612_0065 IE3D132SX04	147	6.518	3233/496	376
232	1.2	402	0.97	220	C302_0063 IE3D132SX04	110	6.314	221/35	351
250	1.2	433	1.0	205	C302_0059 IE3D132SX04	110	5.859	2584/441	351
249	1.8	431	1.5	206	C402_0059 IE3D132SX04	120	5.891	377/64	353
250	2.7	434	2.3	204	C502_0059 IE3D132SX04	132	5.850	117/20	356
291	1.3	504	1.1	176	C302_0050 IE3D132SX04	110	5.038	403/80	352
313	1.4	543	1.2	163	C302_0047 IE3D132SX04	110	4.675	589/126	352
313	2.0	542	1.7	163	C402_0047 IE3D132SX04	120	4.682	899/192	355

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 5,50 kW, P_N (87 Hz) = 9,53 kW									
316	3.2	548	2.7	162	C502_0046 IE3D132SX04	132	4.629	162/35	358
351	1.5	607	1.3	146	C302_0042 IE3D132SX04	110	4.179	117/28	353
378	1.6	654	1.3	135	C302_0039 IE3D132SX04	110	3.878	190/49	353
376	2.3	652	2.0	136	C402_0039 IE3D132SX04	120	3.894	841/216	356
437	1.8	757	1.5	117	C302_0034 IE3D132SX04	110	3.352	429/128	353
471	1.8	816	1.6	109	C302_0031 IE3D132SX04	110	3.110	1045/336	354
473	2.7	819	2.3	108	C402_0031 IE3D132SX04	120	3.099	1537/496	358
542	2.0	938	1.7	94	C302_0027 IE3D132SX04	110	2.705	1677/620	355
584	2.1	1011	1.8	88	C302_0025 IE3D132SX04	110	2.510	1634/651	355
673	2.3	1166	2.0	76	C302_0022 IE3D132SX04	110	2.177	468/215	357
725	2.5	1256	2.1	71	C302_0020 IE3D132SX04	110	2.020	608/301	357
P_N (50 Hz) = 7,50 kW, P_N (87 Hz) = 12,99 kW									
13	1.2	23	1.2	5173	C913_1100 IE3D132MX04	359	110.4	21645/196	356
15	0.89	25	0.83	4708	C813_1010 IE3D132MX04	253	100.5	28143/280	353
16	0.86	28	0.86	4190	C813_0890 IE3D132MX04	253	89.44	14400/161	354
19	1.1	33	1.0	3660	C813_0780 IE3D132MX04	253	78.13	54693/700	353
19	1.4	33	1.2	3641	C913_0780 IE3D132MX04	359	77.73	60939/784	356
21	1.1	37	1.1	3274	C812_0690 IE3D132MX04	240	68.89	620/9	356
22	1.4	39	1.1	3090	C813_0660 IE3D132MX04	253	65.96	10620/161	354
27	1.4	47	1.4	2574	C812_0540 IE3D132MX04	240	54.15	704/13	359
29	1.0	50	1.0	2382	C713_0510 IE3D132MX04	194	50.85	18711/368	353
30	1.6	52	1.4	2304	C813_0490 IE3D132MX04	253	49.18	49914/1015	355
31	0.90	54	0.90	2225	C712_0470 IE3D132MX04	180	46.82	515/11	355
32	1.7	56	1.7	2164	C812_0460 IE3D132MX04	240	45.54	592/13	362
36	1.1	62	1.1	1949	C712_0410 IE3D132MX04	180	41.02	2625/64	353
37	1.9	64	1.9	1898	C812_0400 IE3D132MX04	240	39.94	2596/65	359
42	1.2	73	1.2	1667	C712_0350 IE3D132MX04	180	35.07	2700/77	358
42	2.1	72	2.1	1679	C812_0350 IE3D132MX04	240	35.33	106/3	368
43	1.5	75	1.5	1606	C712_0340 IE3D132MX04	180	33.80	2163/64	355
44	1.9	76	1.9	1596	C812_0340 IE3D132MX04	240	33.59	2183/65	362
45	0.94	79	0.94	1540	C612_0320 IE3D132MX04	145	32.41	1037/32	352
51	1.5	89	1.5	1361	C712_0290 IE3D132MX04	180	28.64	315/11	360
54	1.0	93	1.0	1304	C612_0270 IE3D132MX04	145	27.43	192/7	355
54	2.6	93	2.6	1306	C812_0270 IE3D132MX04	240	27.47	412/15	376
56	2.2	98	2.2	1239	C812_0260 IE3D132MX04	240	26.06	3127/120	368
59	1.2	102	1.2	1185	C612_0250 IE3D132MX04	145	24.93	5185/208	354
58	2.0	101	2.0	1203	C712_0250 IE3D132MX04	180	25.31	405/16	358
65	1.2	112	1.2	1077	C612_0230 IE3D132MX04	145	22.67	68/3	357
63	1.8	110	1.8	1102	C712_0230 IE3D132MX04	180	23.18	255/11	364
63	2.8	110	2.8	1102	C812_0230 IE3D132MX04	240	23.19	1600/69	384
71	0.81	122	0.81	991	C502_0210 IE3D132MX04	130	20.84	667/32	353
71	2.3	123	2.2	983	C712_0210 IE3D132MX04	180	20.67	1323/64	361
73	2.6	126	2.6	963	C812_0200 IE3D132MX04	240	20.26	6077/300	377
75	1.6	130	1.4	932	C612_0195 IE3D132MX04	145	19.61	549/28	355
80	2.3	139	2.3	868	C712_0185 IE3D132MX04	180	18.26	420/23	371
84	0.96	145	0.96	837	C502_0175 IE3D132MX04	130	17.60	845/48	355
84	1.6	145	1.5	837	C612_0175 IE3D132MX04	145	17.60	88/5	360
85	3.2	147	3.2	822	C812_0175 IE3D132MX04	240	17.29	1504/87	401
86	2.8	149	2.8	813	C812_0170 IE3D132MX04	240	17.10	1180/69	385
88	2.7	152	2.6	795	C712_0165 IE3D132MX04	180	16.73	1071/64	365
91	1.9	157	1.6	770	C612_0160 IE3D132MX04	145	16.20	1037/64	357
94	1.1	162	1.1	747	C502_0155 IE3D132MX04	130	15.71	377/24	355
105	0.83	182	0.83	665	C402_0140 IE3D132MX04	118	13.99	2015/144	353
106	1.2	183	1.2	662	C502_0140 IE3D132MX04	130	13.93	195/14	356
104	1.9	180	1.7	672	C612_0140 IE3D132MX04	145	14.15	976/69	364
107	3.1	185	2.9	653	C712_0135 IE3D132MX04	180	13.73	4380/319	380
112	2.9	193	2.9	627	C712_0130 IE3D132MX04	180	13.18	4851/368	372
117	0.92	203	0.92	595	C402_0125 IE3D132MX04	118	12.52	651/52	353
118	1.4	205	1.4	591	C502_0125 IE3D132MX04	130	12.43	87/7	356
117	2.2	202	1.9	598	C612_0125 IE3D132MX04	145	12.58	2013/160	361
126	0.99	219	0.96	553	C402_0115 IE3D132MX04	118	11.64	1885/162	354
126	1.4	219	1.4	553	C502_0115 IE3D132MX04	130	11.64	1885/162	358
128	2.4	222	2.0	545	C612_0115 IE3D132MX04	145	11.46	928/81	368
141	1.1	245	1.0	495	C402_0105 IE3D132MX04	118	10.41	406/39	354
142	1.6	245	1.6	494	C502_0105 IE3D132MX04	130	10.38	841/81	358

2.2 Selection tables 2 C helical geared motors

n_2 50 Hz [rpm]	S	n_2 87 Hz [rpm]	S	M_{2N} [Nm]	Type	m [kg]	i	i_{exakt}	J_1 [kgcm ²]
P_N (50 Hz) = 7,50 kW, P_N (87 Hz) = 12,99 kW									
145	2.6	252	2.2	481	C612_0100 IE3D132MX04	145	10.11	3721/368	365
148	3.3	257	3.3	471	C712_0099 IE3D132MX04	180	9.912	4599/464	381
159	1.3	275	1.1	440	C402_0093 IE3D132MX04	118	9.261	3445/372	356
159	1.8	275	1.7	440	C502_0093 IE3D132MX04	130	9.261	3445/372	361
161	2.8	279	2.3	433	C612_0091 IE3D132MX04	145	9.118	848/93	373
178	0.86	-	-	392	C302_0083 IE3D132MX04	108	8.250	33/4	353
177	1.4	307	1.2	394	C402_0083 IE3D132MX04	118	8.285	3339/403	356
178	2.0	308	1.8	393	C502_0083 IE3D132MX04	130	8.263	1537/186	361
179	3.0	311	2.5	389	C612_0082 IE3D132MX04	145	8.190	1769/216	369
188	1.1	326	0.90	371	C402_0078 IE3D132MX04	118	7.816	2001/256	352
189	1.7	328	1.4	369	C502_0078 IE3D132MX04	130	7.763	621/80	354
226	3.3	391	2.9	310	C612_0065 IE3D132MX04	145	6.518	3233/496	376
233	0.85	-	-	300	C302_0063 IE3D132MX04	108	6.314	221/35	351
251	0.89	-	-	278	C302_0059 IE3D132MX04	108	5.859	2584/441	351
250	1.3	432	1.1	280	C402_0059 IE3D132MX04	118	5.891	377/64	353
251	2.0	435	1.7	278	C502_0059 IE3D132MX04	130	5.850	117/20	356
292	0.98	505	0.83	239	C302_0050 IE3D132MX04	108	5.038	403/80	352
314	1.0	545	0.87	222	C302_0047 IE3D132MX04	108	4.675	589/126	352
314	1.5	544	1.3	223	C402_0047 IE3D132MX04	118	4.682	899/192	355
318	2.3	550	2.0	220	C502_0046 IE3D132MX04	130	4.629	162/35	358
352	1.1	609	0.94	199	C302_0042 IE3D132MX04	108	4.179	117/28	353
379	1.2	657	0.99	184	C302_0039 IE3D132MX04	108	3.878	190/49	353
378	1.7	654	1.4	185	C402_0039 IE3D132MX04	118	3.894	841/216	356
380	2.6	658	2.2	184	C502_0039 IE3D132MX04	130	3.867	58/15	361
439	1.3	760	1.1	159	C302_0034 IE3D132MX04	108	3.352	429/128	353
473	1.4	819	1.1	148	C302_0031 IE3D132MX04	108	3.110	1045/336	354
474	2.0	822	1.7	147	C402_0031 IE3D132MX04	118	3.099	1537/496	358
478	3.1	827	2.6	146	C502_0031 IE3D132MX04	130	3.077	477/155	365
543	1.5	941	1.3	129	C302_0027 IE3D132MX04	108	2.705	1677/620	355
586	1.6	1014	1.3	119	C302_0025 IE3D132MX04	108	2.510	1634/651	355
599	2.3	-	-	117	C402_0025 IE3D132MX04	118	2.456	609/248	362
675	1.7	1170	1.5	103	C302_0022 IE3D132MX04	108	2.177	468/215	357
728	1.8	1260	1.5	96	C302_0020 IE3D132MX04	108	2.020	608/301	357
747	2.7	-	-	94	C402_0020 IE3D132MX04	118	1.968	551/280	367
P_N (50 Hz) = 11,00 kW, P_N (87 Hz) = 19,05 kW									
12	0.81	20	0.81	8677	C913_1260 IE3D160MX04	376	126.1	183549/1456	435
15	1.0	26	1.0	6843	C913_0990 IE3D160MX04	376	99.42	20679/208	436
16	0.95	28	0.95	6316	C913_0920 IE3D160MX04	376	91.76	8075/88	438
19	1.2	32	1.2	5442	C913_0790 IE3D160MX04	376	79.06	115107/1456	437
21	1.1	36	1.1	4886	C912_0700 IE3D160MX04	347	69.97	10075/144	443
23	1.2	39	1.2	4446	C913_0650 IE3D160MX04	376	64.59	295545/4576	438
26	1.2	45	1.2	3899	C912_0560 IE3D160MX04	347	55.83	335/6	449
27	0.95	47	0.95	3782	C812_0540 IE3D160MX04	257	54.15	704/13	439
32	1.1	56	1.1	3180	C812_0460 IE3D160MX04	257	45.54	592/13	442
37	1.3	64	1.3	2789	C812_0400 IE3D160MX04	257	39.94	2596/65	439
37	1.2	65	1.2	2745	C912_0390 IE3D160MX04	347	39.30	4087/104	450
42	0.82	72	0.82	2449	C712_0350 IE3D160MX04	197	35.07	2700/77	438
41	1.5	72	1.5	2468	C812_0350 IE3D160MX04	257	35.33	106/3	448
43	1.0	75	1.0	2360	C712_0340 IE3D160MX04	197	33.80	2163/64	435
44	1.3	76	1.3	2346	C812_0340 IE3D160MX04	257	33.59	2183/65	442
51	1.0	89	1.0	2000	C712_0290 IE3D160MX04	197	28.64	315/11	440
53	1.8	92	1.8	1918	C812_0270 IE3D160MX04	257	27.47	412/15	456
56	1.5	97	1.5	1820	C812_0260 IE3D160MX04	257	26.06	3127/120	448
59	0.83	102	0.81	1741	C612_0250 IE3D160MX04	162	24.93	5185/208	434
58	1.4	100	1.3	1768	C712_0250 IE3D160MX04	197	25.31	405/16	438
65	0.82	112	0.82	1583	C612_0230 IE3D160MX04	162	22.67	68/3	437
63	1.2	109	1.2	1619	C712_0230 IE3D160MX04	197	23.18	255/11	444
63	1.9	109	1.9	1619	C812_0230 IE3D160MX04	257	23.19	1600/69	464
71	1.6	123	1.5	1444	C712_0210 IE3D160MX04	197	20.67	1323/64	441
72	1.8	125	1.8	1415	C812_0200 IE3D160MX04	257	20.26	6077/300	457
75	1.1	129	0.96	1369	C612_0195 IE3D160MX04	162	19.61	549/28	435
80	1.6	139	1.6	1275	C712_0185 IE3D160MX04	197	18.26	420/23	451
83	1.1	144	1.0	1229	C612_0175 IE3D160MX04	162	17.60	88/5	440
85	2.2	147	2.2	1207	C812_0175 IE3D160MX04	257	17.29	1504/87	481
86	1.9	148	1.9	1194	C812_0170 IE3D160MX04	257	17.10	1180/69	465

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 11,00 kW, P_N (87 Hz) = 19,05 kW									
88	1.9	152	1.8	1169	C712_0165 IE3D160MX04	197	16.73	1071/64	445
90	1.3	157	1.1	1132	C612_0160 IE3D160MX04	162	16.20	1037/64	437
105	0.82	182	0.82	973	C502_0140 IE3D160MX04	147	13.93	195/14	436
104	1.3	179	1.2	988	C612_0140 IE3D160MX04	162	14.15	976/69	444
107	2.1	185	2.0	959	C712_0135 IE3D160MX04	197	13.73	4380/319	460
111	2.0	192	2.0	921	C712_0130 IE3D160MX04	197	13.18	4851/368	452
118	0.92	204	0.92	868	C502_0125 IE3D160MX04	147	12.43	87/7	436
116	1.5	202	1.3	879	C612_0125 IE3D160MX04	162	12.58	2013/160	441
115	2.2	199	2.2	890	C812_0125 IE3D160MX04	257	12.75	5546/435	484
126	0.98	218	0.98	813	C502_0115 IE3D160MX04	147	11.64	1885/162	438
128	1.6	221	1.4	800	C612_0115 IE3D160MX04	162	11.46	928/81	448
141	1.1	244	1.1	725	C502_0105 IE3D160MX04	147	10.38	841/81	438
145	1.8	251	1.5	706	C612_0100 IE3D160MX04	162	10.11	3721/368	445
148	2.2	256	2.2	692	C712_0099 IE3D160MX04	197	9.912	4599/464	461
158	1.2	274	1.1	647	C502_0093 IE3D160MX04	147	9.261	3445/372	441
161	1.9	278	1.6	637	C612_0091 IE3D160MX04	162	9.118	848/93	453
177	1.4	307	1.2	577	C502_0083 IE3D160MX04	147	8.263	1537/186	441
179	2.0	310	1.7	572	C612_0082 IE3D160MX04	162	8.190	1769/216	449
189	1.1	327	0.96	542	C502_0078 IE3D160MX04	147	7.763	621/80	434
225	2.2	389	2.0	455	C612_0065 IE3D160MX04	162	6.518	3233/496	456
250	1.4	434	1.2	409	C502_0059 IE3D160MX04	147	5.850	117/20	436
316	1.6	548	1.3	323	C502_0046 IE3D160MX04	147	4.629	162/35	438
379	1.8	656	1.5	270	C502_0039 IE3D160MX04	147	3.867	58/15	441
476	2.1	825	1.8	215	C502_0031 IE3D160MX04	147	3.077	477/155	445
741	2.2	-	-	138	C502_0020 IE3D160MX04	147	1.976	81/41	460
P_N (50 Hz) = 15,00 kW, P_N (87 Hz) = 25,98 kW									
19	0.93	32	0.91	7331	C913_0790 IE3D160LX04	436	79.06	115107/1456	1157
21	0.84	37	0.84	6583	C912_0700 IE3D160LX04	407	69.97	10075/144	1163
23	0.93	40	0.93	5989	C913_0650 IE3D160LX04	436	64.59	295545/4576	1158
26	0.89	46	0.89	5253	C912_0560 IE3D160LX04	407	55.83	335/6	1169
32	0.84	56	0.84	4285	C812_0460 IE3D160LX04	317	45.54	592/13	1162
37	0.98	64	0.98	3758	C812_0400 IE3D160LX04	317	39.94	2596/65	1159
38	0.89	65	0.89	3698	C912_0390 IE3D160LX04	407	39.30	4087/104	1170
42	1.1	72	1.1	3324	C812_0350 IE3D160LX04	317	35.33	106/3	1168
44	0.98	76	0.98	3160	C812_0340 IE3D160LX04	317	33.59	2183/65	1162
54	1.3	93	1.3	2584	C812_0270 IE3D160LX04	317	27.47	412/15	1176
57	1.1	98	1.1	2452	C812_0260 IE3D160LX04	317	26.06	3127/120	1168
58	1.0	101	0.99	2382	C712_0250 IE3D160LX04	257	25.31	405/16	1158
64	0.92	110	0.92	2181	C712_0230 IE3D160LX04	257	23.18	255/11	1164
64	1.4	110	1.4	2182	C812_0230 IE3D160LX04	317	23.19	1600/69	1184
71	1.2	124	1.1	1945	C712_0210 IE3D160LX04	257	20.67	1323/64	1161
73	1.3	126	1.3	1906	C812_0200 IE3D160LX04	317	20.26	6077/300	1177
81	1.2	140	1.2	1718	C712_0185 IE3D160LX04	257	18.26	420/23	1171
85	1.6	148	1.6	1627	C812_0175 IE3D160LX04	317	17.29	1504/87	1201
86	1.4	149	1.4	1609	C812_0170 IE3D160LX04	317	17.10	1180/69	1185
88	1.4	153	1.3	1575	C712_0165 IE3D160LX04	257	16.73	1071/64	1165
91	0.95	158	0.81	1525	C612_0160 IE3D160LX04	222	16.20	1037/64	1157
104	0.98	181	0.88	1331	C612_0140 IE3D160LX04	222	14.15	976/69	1164
107	1.5	186	1.5	1292	C712_0135 IE3D160LX04	257	13.73	4380/319	1180
112	1.5	194	1.5	1240	C712_0130 IE3D160LX04	257	13.18	4851/368	1172
117	1.1	203	0.95	1184	C612_0125 IE3D160LX04	222	12.58	2013/160	1161
116	1.6	200	1.6	1200	C812_0125 IE3D160LX04	317	12.75	5546/435	1204
129	1.2	223	1.0	1078	C612_0115 IE3D160LX04	222	11.46	928/81	1168
142	0.82	-	-	977	C502_0105 IE3D160LX04	207	10.38	841/81	1158
146	1.3	253	1.1	951	C612_0100 IE3D160LX04	222	10.11	3721/368	1165
149	1.7	258	1.7	933	C712_0099 IE3D160LX04	257	9.912	4599/464	1181
159	0.92	276	0.85	871	C502_0093 IE3D160LX04	207	9.261	3445/372	1161
162	1.4	280	1.2	858	C612_0091 IE3D160LX04	222	9.118	848/93	1173
179	1.0	309	0.92	777	C502_0083 IE3D160LX04	207	8.263	1537/186	1161
180	1.5	312	1.3	771	C612_0082 IE3D160LX04	222	8.190	1769/216	1169
190	0.84	-	-	730	C502_0078 IE3D160LX04	207	7.763	621/80	1154
226	1.7	392	1.5	613	C612_0065 IE3D160LX04	222	6.518	3233/496	1176
252	1.0	437	0.86	550	C502_0059 IE3D160LX04	207	5.850	117/20	1156
319	1.2	552	1.0	436	C502_0046 IE3D160LX04	207	4.629	162/35	1158
381	1.3	661	1.1	364	C502_0039 IE3D160LX04	207	3.867	58/15	1161

2.2 Selection tables 2 C helical geared motors

n_2 50 Hz [rpm]	S	n_2 87 Hz [rpm]	S	M_{2N} [Nm]	Type	m [kg]	i	i_{exakt}	J_1 [kgcm ²]
P_N (50 Hz) = 15,00 kW, P_N (87 Hz) = 25,98 kW									
479	1.6	830	1.3	290	C502_0031 IE3D160LX04	207	3.077	477/155	1165
746	1.7	–	–	186	C502_0020 IE3D160LX04	207	1.976	81/41	1180
P_N (50 Hz) = 18,50 kW, P_N (87 Hz) = 32,04 kW									
23	0.95	40	0.85	7409	C913_0650 IE3D180MX04	431	64.59	295545/4576	1158
26	0.92	46	0.92	6499	C912_0560 IE3D180MX04	402	55.83	335/6	1169
32	1.1	56	1.1	5314	C912_0460 IE3D180MX04	402	45.66	3835/84	1177
38	1.3	65	1.3	4574	C912_0390 IE3D180MX04	402	39.30	4087/104	1170
42	0.88	72	0.88	4113	C812_0350 IE3D180MX04	312	35.33	106/3	1168
44	1.1	76	1.1	3909	C812_0340 IE3D180MX04	312	33.59	2183/65	1162
46	1.8	80	1.8	3740	C912_0320 IE3D180MX04	402	32.13	3599/112	1178
52	1.8	89	1.8	3333	C912_0290 IE3D180MX04	402	28.63	2405/84	1206
54	1.1	93	1.1	3197	C812_0270 IE3D180MX04	312	27.47	412/15	1176
57	1.4	98	1.3	3033	C812_0260 IE3D180MX04	312	26.06	3127/120	1168
64	1.3	110	1.3	2699	C812_0230 IE3D180MX04	312	23.19	1600/69	1184
71	1.0	124	0.92	2406	C712_0210 IE3D180MX04	252	20.67	1323/64	1161
73	1.8	126	1.5	2358	C812_0200 IE3D180MX04	312	20.26	6077/300	1177
73	2.4	127	2.4	2346	C912_0200 IE3D180MX04	402	20.15	2257/112	1210
81	0.94	140	0.94	2126	C712_0185 IE3D180MX04	252	18.26	420/23	1171
85	1.8	148	1.7	2012	C812_0175 IE3D180MX04	312	17.29	1504/87	1201
86	2.0	149	1.7	1991	C812_0170 IE3D180MX04	312	17.10	1180/69	1185
88	1.2	153	1.1	1948	C712_0165 IE3D180MX04	252	16.73	1071/64	1165
107	2.2	186	2.0	1602	C812_0140 IE3D180MX04	312	13.76	1280/93	1219
107	1.3	186	1.2	1598	C712_0135 IE3D180MX04	252	13.73	4380/319	1180
112	1.5	194	1.2	1534	C712_0130 IE3D180MX04	252	13.18	4851/368	1172
117	0.91	–	–	1464	C612_0125 IE3D180MX04	217	12.58	2013/160	1161
116	2.4	200	2.1	1484	C812_0125 IE3D180MX04	312	12.75	5546/435	1204
125	1.5	217	1.3	1369	C712_0120 IE3D180MX04	252	11.76	1035/88	1186
129	0.97	223	0.82	1334	C612_0115 IE3D180MX04	217	11.46	928/81	1168
146	1.1	253	0.89	1177	C612_0100 IE3D180MX04	217	10.11	3721/368	1165
145	2.5	252	2.4	1182	C812_0100 IE3D180MX04	312	10.15	944/93	1224
149	1.8	258	1.5	1154	C712_0099 IE3D180MX04	252	9.912	4599/464	1181
162	1.1	280	0.96	1061	C612_0091 IE3D180MX04	217	9.118	848/93	1173
163	2.5	–	–	1053	C812_0090 IE3D180MX04	312	9.043	208/23	1271
174	2.0	301	1.7	988	C712_0085 IE3D180MX04	252	8.490	4347/512	1188
180	1.2	312	1.0	953	C612_0082 IE3D180MX04	217	8.190	1769/216	1169
200	2.2	–	–	856	C712_0074 IE3D180MX04	252	7.357	3480/473	1215
207	1.3	–	–	828	C612_0071 IE3D180MX04	217	7.111	64/9	1182
221	2.5	–	–	776	C812_0067 IE3D180MX04	312	6.670	767/115	1282
226	1.4	392	1.2	759	C612_0065 IE3D180MX04	217	6.518	3233/496	1176
252	1.5	–	–	681	C612_0059 IE3D180MX04	217	5.854	240/41	1191
278	2.5	–	–	618	C712_0053 IE3D180MX04	252	5.311	1827/344	1221
290	1.7	–	–	592	C612_0051 IE3D180MX04	217	5.083	61/12	1186
346	2.5	–	–	496	C712_0043 IE3D180MX04	252	4.259	477/112	1246
353	1.9	–	–	487	C612_0042 IE3D180MX04	217	4.184	2745/656	1197
746	1.7	–	–	230	C502_0020 IE3D180MX04	202	1.976	81/41	1180
P_N (50 Hz) = 22,00 kW, P_N (87 Hz) = 38,11 kW									
32	0.95	56	0.95	6289	C912_0460 IE3D180LX04	448	45.66	3835/84	1707
38	1.1	65	1.1	5413	C912_0390 IE3D180LX04	448	39.30	4087/104	1700
44	0.91	76	0.91	4626	C812_0340 IE3D180LX04	358	33.59	2183/65	1692
46	1.5	80	1.5	4426	C912_0320 IE3D180LX04	448	32.13	3599/112	1708
52	1.5	89	1.5	3944	C912_0290 IE3D180LX04	448	28.63	2405/84	1736
54	0.95	93	0.95	3783	C812_0270 IE3D180LX04	358	27.47	412/15	1706
57	1.2	98	1.1	3589	C812_0260 IE3D180LX04	358	26.06	3127/120	1698
64	1.1	110	1.1	3194	C812_0230 IE3D180LX04	358	23.19	1600/69	1714
71	0.84	–	–	2847	C712_0210 IE3D180LX04	298	20.67	1323/64	1691
73	1.5	126	1.3	2790	C812_0200 IE3D180LX04	358	20.26	6077/300	1707
73	2.0	127	2.0	2776	C912_0200 IE3D180LX04	448	20.15	2257/112	1740
85	1.5	148	1.4	2381	C812_0175 IE3D180LX04	358	17.29	1504/87	1731
86	1.7	149	1.4	2355	C812_0170 IE3D180LX04	358	17.10	1180/69	1715
88	1.0	153	0.89	2305	C712_0165 IE3D180LX04	298	16.73	1071/64	1695
107	1.9	186	1.7	1896	C812_0140 IE3D180LX04	358	13.76	1280/93	1749
107	1.1	186	1.0	1891	C712_0135 IE3D180LX04	298	13.73	4380/319	1710
112	1.2	194	1.0	1816	C712_0130 IE3D180LX04	298	13.18	4851/368	1702
116	2.1	200	1.7	1756	C812_0125 IE3D180LX04	358	12.75	5546/435	1734
125	1.2	217	1.1	1620	C712_0120 IE3D180LX04	298	11.76	1035/88	1716

n_2 50 Hz [rpm]	S	n_2 87 Hz [rpm]	S	M_{2N} [Nm]	Type	m [kg]	i	i_{exakt}	J_1 [kgcm ²]
P_N (50 Hz) = 22,00 kW, P_N (87 Hz) = 38,11 kW									
129	0.82	–	–	1578	C612_0115 IE3D180LX04	263	11.46	928/81	1698
146	0.89	–	–	1393	C612_0100 IE3D180LX04	263	10.11	3721/368	1695
145	2.1	252	2.0	1398	C812_0100 IE3D180LX04	358	10.15	944/93	1754
149	1.5	258	1.3	1365	C712_0099 IE3D180LX04	298	9.912	4599/464	1711
162	0.96	280	0.81	1256	C612_0091 IE3D180LX04	263	9.118	848/93	1703
163	2.1	–	–	1246	C812_0090 IE3D180LX04	358	9.043	208/23	1801
174	1.7	301	1.4	1169	C712_0085 IE3D180LX04	298	8.490	4347/512	1718
180	1.0	312	0.87	1128	C612_0082 IE3D180LX04	263	8.190	1769/216	1699
200	1.8	–	–	1013	C712_0074 IE3D180LX04	298	7.357	3480/473	1745
207	1.1	–	–	979	C612_0071 IE3D180LX04	263	7.111	64/9	1712
221	2.1	–	–	919	C812_0067 IE3D180LX04	358	6.670	767/115	1812
226	1.2	392	1.0	898	C612_0065 IE3D180LX04	263	6.518	3233/496	1706
252	1.3	–	–	806	C612_0059 IE3D180LX04	263	5.854	240/41	1721
278	2.1	–	–	732	C712_0053 IE3D180LX04	298	5.311	1827/344	1751
290	1.4	–	–	700	C612_0051 IE3D180LX04	263	5.083	61/12	1716
346	2.1	–	–	587	C712_0043 IE3D180LX04	298	4.259	477/112	1776
353	1.6	–	–	576	C612_0042 IE3D180LX04	263	4.184	2745/656	1727
746	1.4	–	–	272	C502_0020 IE3D180LX04	248	1.976	81/41	1710
P_N (50 Hz) = 30,00 kW, P_N (87 Hz) = 51,96 kW									
41	0.89	–	–	6775	C912_0360 IE3D200LX04	546	36.01	7345/204	3170
46	1.2	–	–	6047	C912_0320 IE3D200LX04	546	32.13	3599/112	3158
52	1.1	–	–	5388	C912_0290 IE3D200LX04	546	28.63	2405/84	3186
58	1.5	–	–	4769	C912_0250 IE3D200LX04	546	25.34	6893/272	3172
63	1.4	–	–	4402	C912_0230 IE3D200LX04	546	23.39	6175/264	3207
73	1.8	–	–	3792	C912_0200 IE3D200LX04	546	20.15	2257/112	3190
84	1.8	–	–	3321	C912_0175 IE3D200LX04	546	17.65	6565/372	3243
90	2.3	–	–	3098	C912_0165 IE3D200LX04	546	16.46	5795/352	3212
108	1.4	–	–	2590	C812_0140 IE3D200LX04	456	13.76	1280/93	3199
119	3.0	–	–	2337	C912_0125 IE3D200LX04	546	12.42	6161/496	3251
126	2.7	–	–	2216	C912_0120 IE3D200LX04	546	11.78	1625/138	3322
146	1.8	–	–	1910	C812_0100 IE3D200LX04	456	10.15	944/93	3204
164	1.9	–	–	1702	C812_0090 IE3D200LX04	456	9.043	208/23	3251
179	3.3	–	–	1560	C912_0083 IE3D200LX04	546	8.288	1525/184	3341
222	2.3	–	–	1255	C812_0067 IE3D200LX04	456	6.670	767/115	3262
350	3.1	–	–	795	C812_0042 IE3D200LX04	456	4.225	1711/405	3374

2.3 Dimensional drawings

In this chapter you can find the dimensions of the geared motors.

There is a dimensional drawing for every possible shaft/housing design, each with the tables for gear unit dimensions, motor dimensions and geared motor dimensions.

Dimensions can exceed the specifications of ISO 2768-mK due to casting tolerances or accumulation of individual tolerances.

We reserve the right to make dimensional changes due to ongoing technical development.

You can download 3D models of our standard drives at <https://configurator.stoeber.de/en-US/>.

Tolerances

Axis height in accordance with DIN 747	Tolerance
Up to 50 mm	-0.4 mm
Up to 250 mm	-0.5 mm
Up to 630 mm	-0.6 mm

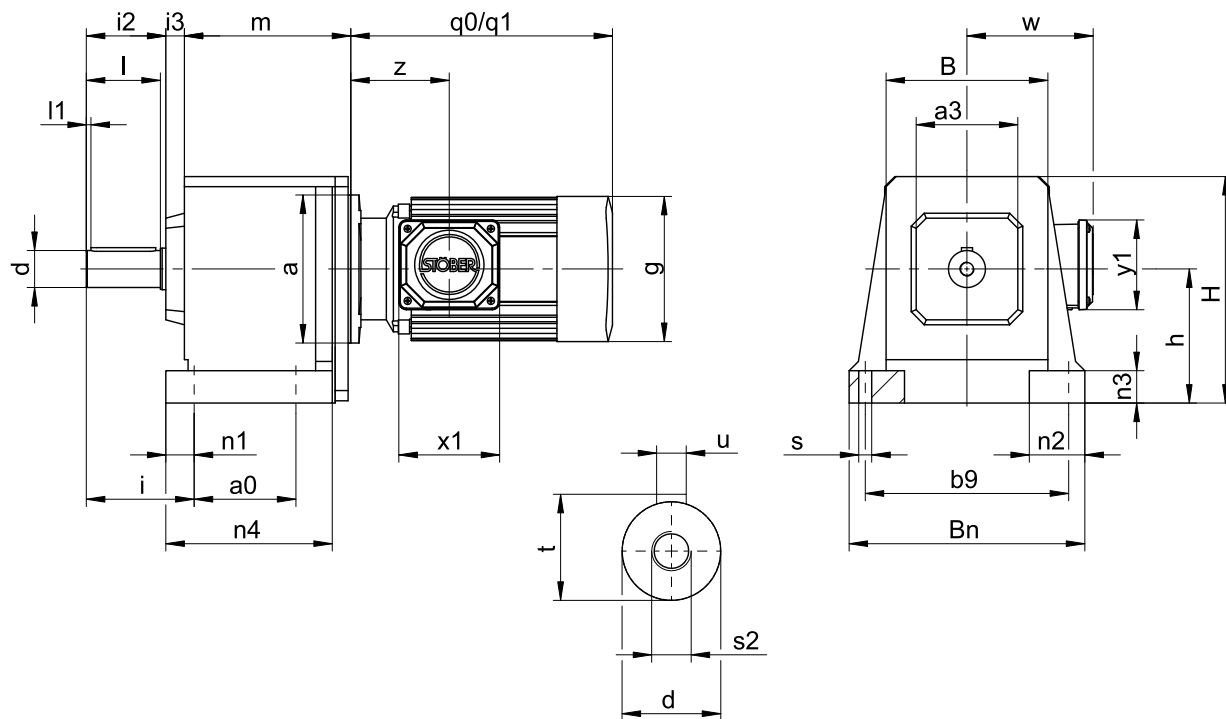
Solid shaft	Tolerance
Shaft \varnothing fit \leq 50 mm	DIN 748-1, ISO k6
Shaft \varnothing fit $>$ 50 mm	DIN 748-1, ISO m6
Feather keys	DIN 6885-1, high form A

Flange	Pilot tolerance
Up to 300 mm	ISO j6
Starting at 350 mm	ISO h6

Centering holes in solid shafts in accordance with DIN 332-2, DR shape

Thread size	M4	M5	M6	M8	M10	M12	M16	M20	M24
Thread depth [mm]	10	12.5	16	19	22	28	36	42	50

2.3.1 Solid shaft design with feather key, N housing design (base)



q_0 Applies to motors without brake.

q_1 Applies to motors with brake.

C203, C303, C612, C613: Motor and gear unit are sometimes non-coaxial.

Options: C0 – C5 also available with solid shaft without feather key; on request starting at C6.

Dimensions of gear units

Type	a_0	a_3	b_9	B	B_n	$\varnothing d$	h	H	i	i_2	i_3	l	l_1	n_1	n_2	n_3	n_4	$\varnothing s$	s_2	t	u
C0	62	60	110	92	132	20 _{k6}	82	144	55	44	13	40	3	11	35	20	95.0	7	M6	22.5	A6×6×32
C1	70	80	150	124	176	25 _{k6}	102	177	67	54	15	50	5	13	42	25	117.5	9	M10	28.0	A8×7×40
C2	85	95	170	138	200	30 _{k6}	115	195	79	65	21	60	5	14	50	30	134.5	11	M10	33.0	A8×7×50
C3	105	95	185	150	215	30 _{k6}	130	215	79	65	20	60	5	14	50	30	153.5	11	M10	33.0	A8×7×50
C4	110	110	220	175	255	40 _{k6}	145	245	105	86	20	80	5	19	60	35	180.0	14	M16	43.0	A12×8×70
C5	130	130	245	192	290	40 _{k6}	170	290	108	86	21	80	5	22	70	40	197.0	18	M16	43.0	A12×8×70
C6	215	177	245	225	300	50 _{k6}	200	315	130	106	47	100	5	25	75	40	265.0	18	M16	53.5	A14×9×90
C7	235	192	300	265	365	60 _{m6}	235	375	163	127	58	120	5	25	90	50	285.0	18	M20	64.0	A18×11×100
C8	300	223	340	310	435	70 _{m6}	290	450	190	148	70	140	5	29	95	55	360.0	22	M20	74.5	A20×12×125
C9	340	277	400	365	510	90 _{m6}	340	530	222	178	78	170	5	34	110	60	410.0	26	M24	95.0	A25×14×140

Dimensions of motors

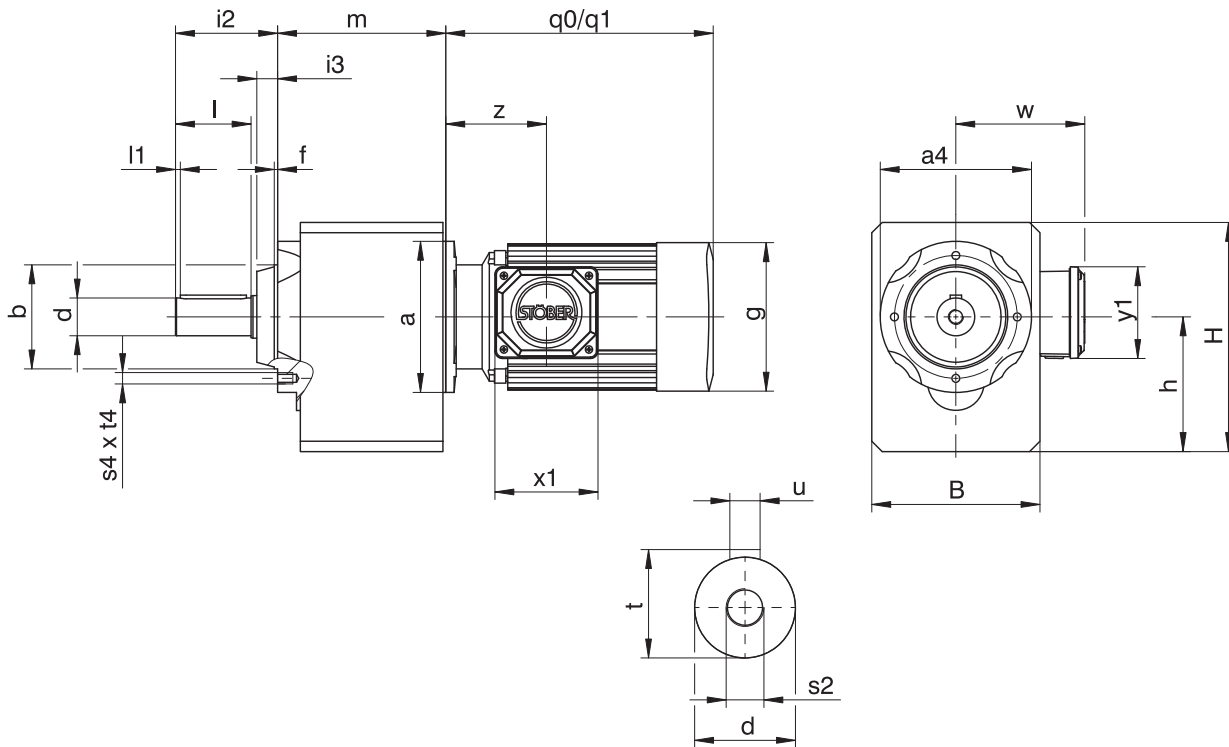
Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5
IE3D160MX04	313	526	641	199	166.5	193.5	138.0
IE3D160LX04	313	549	627	242	166.5	193.5	138.0
IE3D180MX04	313	549	677	242	166.5	193.5	178.0
IE3D180LX04	351	601	748	260	166.5	193.5	178.0
IE3D200LX04	390	729	878	298	207.0	209.0	242.0

Dimensions of geared motors

Type	IE3D063		IE3D071		IE3D080		IE3D090		IE3D100	
	a	m	a	m	a	m	a	m	a	m
C002	∅140	97.5	∅140	97.5	∅160	101.5	∅160	101.5	-	-
C102	∅140	118.0	∅140	118.0	∅160	122.0	∅160	122.0	∅200	124.0
C103	∅140	155.0	∅140	155.0	-	-	-	-	-	-
C202	∅140	129.0	∅140	129.0	∅160	133.0	∅160	133.0	∅200	135.0
C203	∅140	166.0	∅140	166.0	-	-	-	-	-	-
C302	-	-	-	-	∅160	152.5	∅160	152.5	∅200	154.5
C303	-	-	∅140	185.5	∅160	195.5	-	-	-	-
C402	-	-	-	-	∅160	180.0	∅160	180.0	∅200	182.0
C403	-	-	-	-	∅160	223.0	∅160	223.0	-	-
C502	-	-	-	-	∅160	200.0	∅160	200.0	∅200	202.0
C503	-	-	-	-	∅160	243.0	∅160	243.0	-	-
C612	-	-	-	-	-	-	-	-	∅200	180.0
C613	-	-	-	-	∅160	222.0	∅160	222.0	∅200	242.0
C712	-	-	-	-	-	-	-	-	∅200	201.0
C713	-	-	-	-	-	-	-	-	∅200	262.0
C813	-	-	-	-	-	-	-	-	∅200	296.0

Type	IE3D112		IE3D132		IE3D160		IE3D180		IE3D200	
	a	m	a	m	a	m	a	m	a	m
C102	∅200	124.0	-	-	-	-	-	-	-	-
C202	∅200	135.0	-	-	-	-	-	-	-	-
C302	∅200	154.5	∅250	157.5	-	-	-	-	-	-
C402	∅200	182.0	∅250	185.0	-	-	-	-	-	-
C502	∅200	202.0	∅250	205.0	∅300	219.0	∅300	219.0	-	-
C612	∅200	180.0	∅250	183.0	∅300	196.0	∅300	196.0	-	-
C613	∅200	242.0	-	-	-	-	-	-	-	-
C712	∅200	201.0	∅250	203.0	∅300	216.0	∅300	216.0	-	-
C713	∅200	262.0	∅250	274.0	-	-	-	-	-	-
C812	-	-	∅250	237.0	∅300	250.0	∅300	250.0	∅350	273.0
C813	∅200	296.0	∅250	308.0	-	-	-	-	-	-
C912	-	-	-	-	∅300	279.0	∅300	279.0	∅350	302.0
C913	-	-	∅250	337.0	∅300	362.0	∅300	362.0	-	-

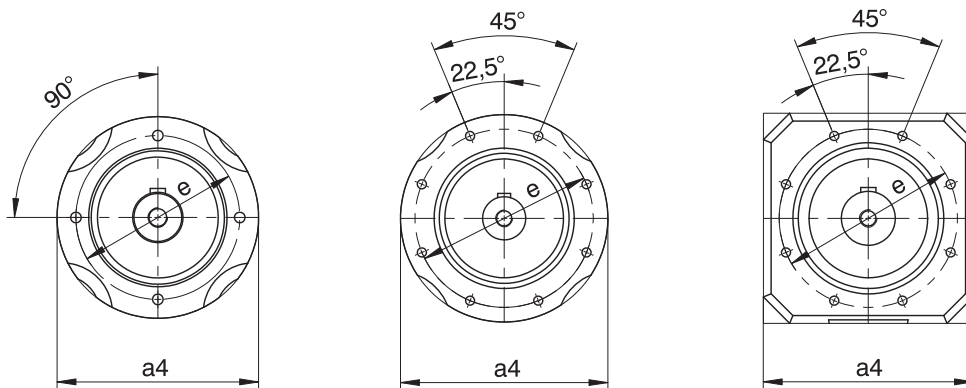
2.3.2 Solid shaft design with feather key, G housing design (pitch circle diameter)



C0 - C4

C5

C6 - C9



q0 Applies to motors without brake.

q1 Applies to motors with brake.

C203, C303, C612, C613: Motor and gear unit are sometimes non-coaxial.

Options: C0 - C5 also available with solid shaft without feather key; on request starting at C6.

Dimensions of gear units

Type	a4	Øb	B	Ød	Øe	f	h	H	i2	i3	l	l1	s2	s4	t	t4	u
C0	Ø87	55 _{j6}	97	20 _{k6}	75	3.0	79.0	141.0	58	14	40	3	M6	M6	22.5	10	A6×6×32
C1	Ø120	80 _{j6}	130	25 _{k6}	100	3.0	100.0	175.0	71	17	50	5	M10	M6	28.0	13	A8×7×40
C2	Ø140	95 _{j6}	142	30 _{k6}	115	3.0	112.0	192.0	87	22	60	5	M10	M8	33.0	13	A8×7×50
C3	Ø140	95 _{j6}	154	30 _{k6}	115	3.0	127.0	212.0	87	22	60	5	M10	M8	33.0	13	A8×7×50
C4	Ø160	110 _{j6}	178	40 _{k6}	130	3.5	142.5	242.5	108	22	80	5	M16	M10	43.0	16	A12×8×70
C5	Ø192	130 _{j6}	195	40 _{k6}	165	3.5	166.0	286.0	109	23	80	5	M16	M10	43.0	16	A12×8×70
C6	□180	140 _{j6}	225	50 _{k6}	165	5.0	195.0	310.0	136	30	100	5	M16	M10	53.5	16	A14×9×90
C7	□195	155 _{j6}	265	60 _{m6}	185	8.0	231.0	371.0	164	37	120	5	M20	M12	64.0	19	A18×11×100
C8	□226	185 _{j6}	310	70 _{m6}	215	5.0	285.0	445.0	185	37	140	5	M20	M12	74.5	19	A20×12×125
C9	□280	230 _{j6}	365	90 _{m6}	265	5.0	334.0	524.0	220	42	170	5	M24	M16	95.0	26	A25×14×140

Dimensions of motors

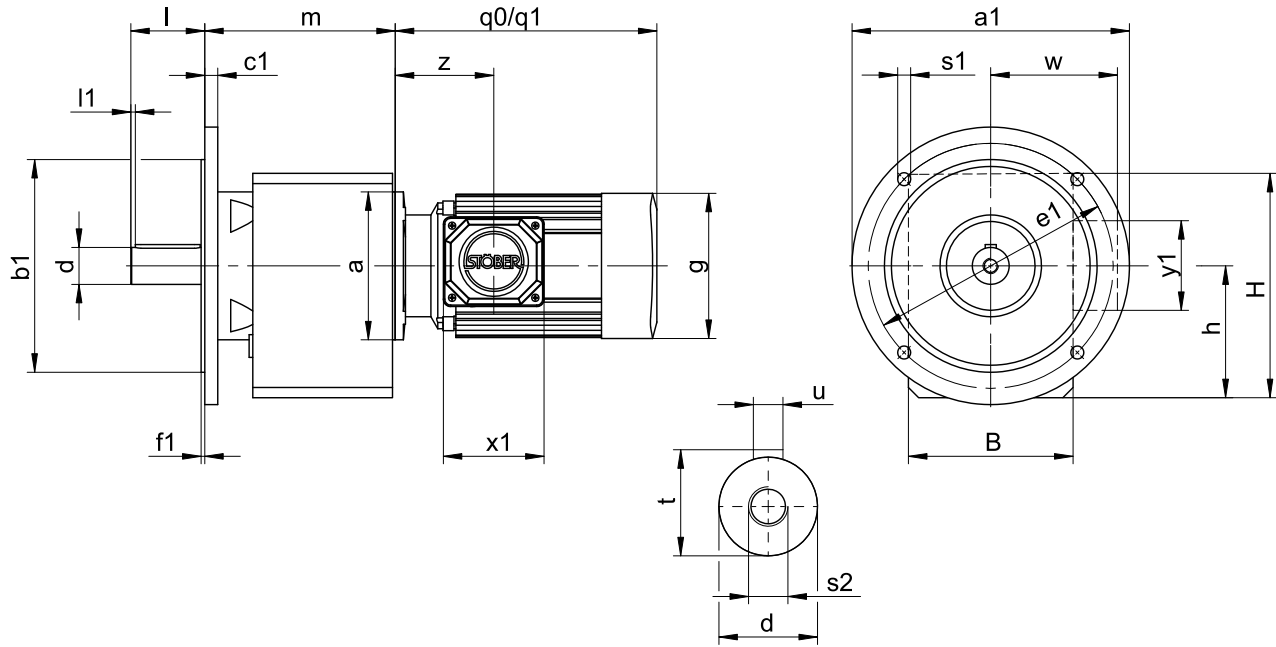
Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5
IE3D160MX04	313	526	641	199	166.5	193.5	138.0
IE3D160LX04	313	549	627	242	166.5	193.5	138.0
IE3D180MX04	313	549	677	242	166.5	193.5	178.0
IE3D180LX04	351	601	748	260	166.5	193.5	178.0
IE3D200LX04	390	729	878	298	207.0	209.0	242.0

Dimensions of geared motors

Type	IE3D063		IE3D071		IE3D080		IE3D090		IE3D100	
	a	m	a	m	a	m	a	m	a	m
C002	∅140	96	∅140	96	∅160	100	∅160	100	-	-
C102	∅140	116	∅140	116	∅160	120	∅160	120	∅200	122
C103	∅140	153	∅140	153	-	-	-	-	-	-
C202	∅140	128	∅140	128	∅160	132	∅160	132	∅200	134
C203	∅140	165	∅140	165	-	-	-	-	-	-
C302	-	-	-	-	∅160	151	∅160	151	∅200	153
C303	-	-	∅140	184	∅160	194	-	-	-	-
C402	-	-	-	-	∅160	178	∅160	178	∅200	180
C403	-	-	-	-	∅160	221	∅160	221	-	-
C502	-	-	-	-	∅160	198	∅160	198	∅200	200
C503	-	-	-	-	∅160	241	∅160	241	-	-
C612	-	-	-	-	-	-	-	-	∅200	197
C613	-	-	-	-	∅160	239	∅160	239	∅200	259
C712	-	-	-	-	-	-	-	-	∅200	222
C713	-	-	-	-	-	-	-	-	∅200	283
C813	-	-	-	-	-	-	-	-	∅200	329

Type	IE3D112		IE3D132		IE3D160		IE3D180		IE3D200	
	a	m	a	m	a	m	a	m	a	m
C102	∅200	122	-	-	-	-	-	-	-	-
C202	∅200	134	-	-	-	-	-	-	-	-
C302	∅200	153	∅250	156	-	-	-	-	-	-
C402	∅200	180	∅250	183	-	-	-	-	-	-
C502	∅200	200	∅250	203	∅300	217	∅300	217	-	-
C612	∅200	197	∅250	200	∅300	213	∅300	213	-	-
C613	∅200	259	-	-	-	-	-	-	-	-
C712	∅200	222	∅250	224	∅300	237	∅300	237	-	-
C713	∅200	283	∅250	295	-	-	-	-	-	-
C812	-	-	∅250	270	∅300	283	∅300	283	∅350	306
C813	∅200	329	∅250	341	-	-	-	-	-	-
C912	-	-	-	-	∅300	315	∅300	315	∅350	338
C913	-	-	∅250	373	∅300	398	∅300	398	-	-

2.3.3 Solid shaft design with feather key, F housing design (round flange)



$q0$ Applies to motors without brake.

$q1$ Applies to motors with brake.

C203, C303, C612, C613: Motor and gear unit are sometimes non-coaxial.

Options: C0 – C5 also available with solid shaft without feather key; on request starting at C6.

Dimensions of gear units

Type	$\varnothing a1$	$\varnothing b1$	B	$c1$	$\varnothing d$	$\varnothing e1$	$f1$	h	H	l	l1	$\varnothing s1$	s2	t	u
C0	160	110 _{f6}	97	10	20 _{k6}	130	3.0	79.0	141.0	40	3	9	M6	22.5	A6×6×32
C1	200	130 _{f6}	130	12	25 _{k6}	165	3.5	100.0	175.0	50	5	11	M10	28.0	A8×7×40
C2	200	130 _{f6}	142	12	30 _{k6}	165	3.5	112.0	192.0	60	5	11	M10	33.0	A8×7×50
C3	250	180 _{f6}	154	12	30 _{k6}	215	4.0	127.0	212.0	60	5	14	M10	33.0	A8×7×50
C4	250	180 _{f6}	178	14	40 _{k6}	215	4.0	142.5	242.5	80	5	14	M16	43.0	A12×8×70
C5	300	230 _{f6}	195	16	40 _{k6}	265	4.0	166.0	286.0	80	5	14	M16	43.0	A12×8×70
C6	300	230 _{f6}	225	17	50 _{k6}	265	4.0	195.0	310.0	100	5	14	M16	53.5	A14×9×90
C7	350	250 _{h6}	265	18	60 _{m6}	300	5.0	231.0	371.0	120	5	18	M20	64.0	A18×11×100
C8	400	300 _{h6}	310	20	70 _{m6}	350	5.0	285.0	445.0	140	5	18	M20	74.5	A20×12×125
C9	450	350 _{h6}	365	23	90 _{m6}	400	5.0	334.0	524.0	170	5	18	M24	95.0	A25×14×140

Dimensions of additional round flanges

Type	$\varnothing a1$	$\varnothing b1$	$c1$	$\varnothing e1$	$f1$	$\varnothing s1$
C0	120	80 _{f6}	10	100	3.0	7
C0	140	95 _{f6}	10	115	3.0	9
C1	140	95 _{f6}	8	115	3.5	9
C1	160	110 _{f6}	10	130	3.5	9
C2	160	110 _{f6}	10	130	3.5	9
C2	250	180 _{f6}	12	215	4.0	14
C3	160	110 _{f6}	10	130	3.5	9
C3	200	130 _{f6}	12	165	3.5	11
C4	200	130 _{f6}	14	165	3.5	11
C4	300	230 _{f6}	14	265	4.0	14
C5	250	180 _{f6}	14	215	4.0	14
C8	350	250 _{h6}	18	300	5.0	18
C8	450	350 _{h6}	20	400	5.0	18

Dimensions of motors

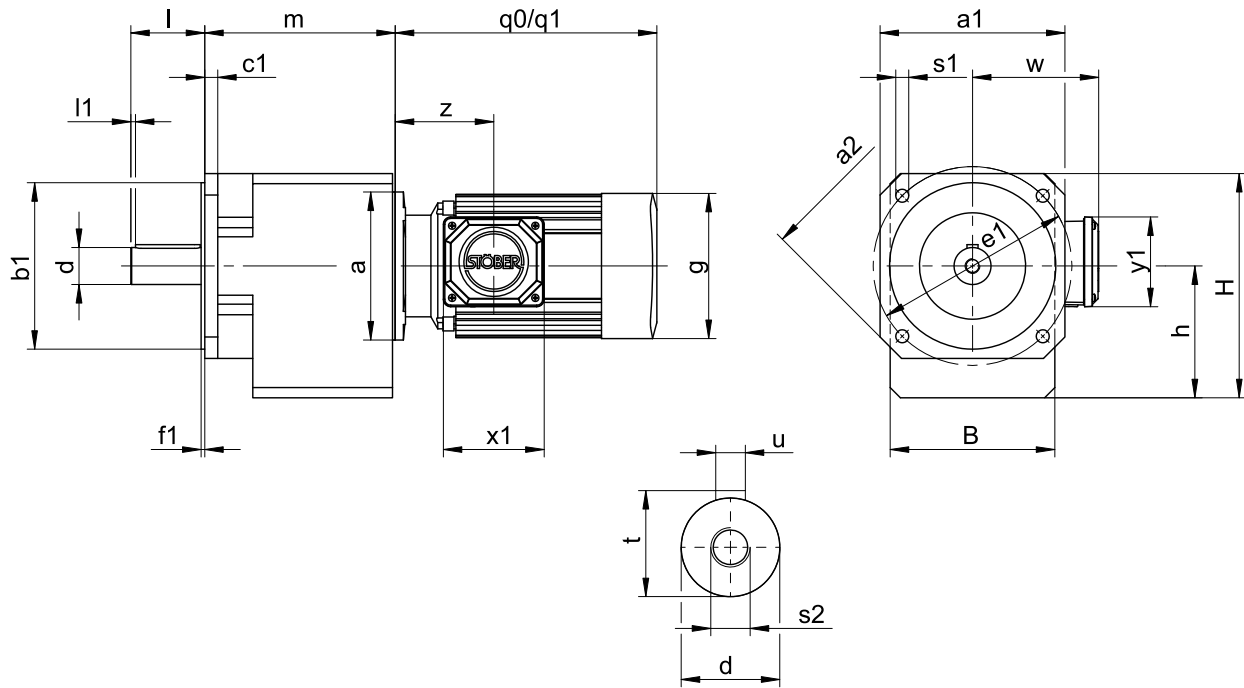
Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5
IE3D160MX04	313	526	641	199	166.5	193.5	138.0
IE3D160LX04	313	549	627	242	166.5	193.5	138.0
IE3D180MX04	313	549	677	242	166.5	193.5	178.0
IE3D180LX04	351	601	748	260	166.5	193.5	178.0
IE3D200LX04	390	729	878	298	207.0	209.0	242.0

Dimensions of geared motors

Type	IE3D063		IE3D071		IE3D080		IE3D090		IE3D100	
	a	m	a	m	a	m	a	m	a	m
C002	∅140	114	∅140	114	∅160	118	∅160	118	-	-
C102	∅140	137	∅140	137	∅160	141	∅160	141	∅200	143
C103	∅140	174	∅140	174	-	-	-	-	-	-
C202	∅140	155	∅140	155	∅160	159	∅160	159	∅200	161
C203	∅140	192	∅140	192	-	-	-	-	-	-
C302	-	-	-	-	∅160	178	∅160	178	∅200	180
C303	-	-	∅140	211	∅160	221	-	-	-	-
C402	-	-	-	-	∅160	206	∅160	206	∅200	208
C403	-	-	-	-	∅160	249	∅160	249	-	-
C502	-	-	-	-	∅160	227	∅160	227	∅200	229
C503	-	-	-	-	∅160	270	∅160	270	-	-
C612	-	-	-	-	-	-	-	-	∅200	233
C613	-	-	-	-	∅160	275	∅160	275	∅200	295
C712	-	-	-	-	-	-	-	-	∅200	266
C713	-	-	-	-	-	-	-	-	∅200	327
C813	-	-	-	-	-	-	-	-	∅200	374

Type	IE3D112		IE3D132		IE3D160		IE3D180		IE3D200	
	a	m	a	m	a	m	a	m	a	m
C102	∅200	143	-	-	-	-	-	-	-	-
C202	∅200	161	-	-	-	-	-	-	-	-
C302	∅200	180	∅250	183	-	-	-	-	-	-
C402	∅200	208	∅250	211	-	-	-	-	-	-
C502	∅200	229	∅250	232	∅300	246	∅300	246	-	-
C612	∅200	233	∅250	236	∅300	249	∅300	249	-	-
C613	∅200	295	-	-	-	-	-	-	-	-
C712	∅200	266	∅250	268	∅300	281	∅300	281	-	-
C713	∅200	327	∅250	339	-	-	-	-	-	-
C812	-	-	∅250	315	∅300	328	∅300	328	∅350	351
C813	∅200	374	∅250	386	-	-	-	-	-	-
C912	-	-	-	-	∅300	365	∅300	365	∅350	388
C913	-	-	∅250	423	∅300	448	∅300	448	-	-

2.3.4 Solid shaft design with feather key, Q housing design (square flange)



q_0 Applies to motors without brake.

q_1 Applies to motors with brake.

C203, C303, C612, C613: Motor and gear unit are sometimes non-coaxial.

Options: C0 – C5 also available with solid shaft without feather key; on request starting at C6.

Dimensions of gear units

Type	$\square a_1$	$\square a_2$	$\varnothing b_1$	B	c_1	$\varnothing d$	$\varnothing e_1$	f_1	h	H	l	l_1	$\varnothing s_1$	s2	t	u
C0	124	160	110_{β}	97	9	$20_{\kappa 6}$	130	3.0	79.0	141.0	40	3	9	M6	22.5	A6×6×32
C1	145	192	130_{β}	130	11	$25_{\kappa 6}$	165	3.5	100.0	175.0	50	5	11	M10	28.0	A8×7×40
C2	145	192	130_{β}	142	11	$30_{\kappa 6}$	165	3.5	112.0	192.0	60	5	11	M10	33.0	A8×7×50
C3	200	250	180_{β}	154	14	$30_{\kappa 6}$	215	4.0	127.0	212.0	60	5	14	M10	33.0	A8×7×50
C4	200	250	180_{β}	178	14	$40_{\kappa 6}$	215	4.0	142.5	242.5	80	5	14	M16	43.0	A12×8×70

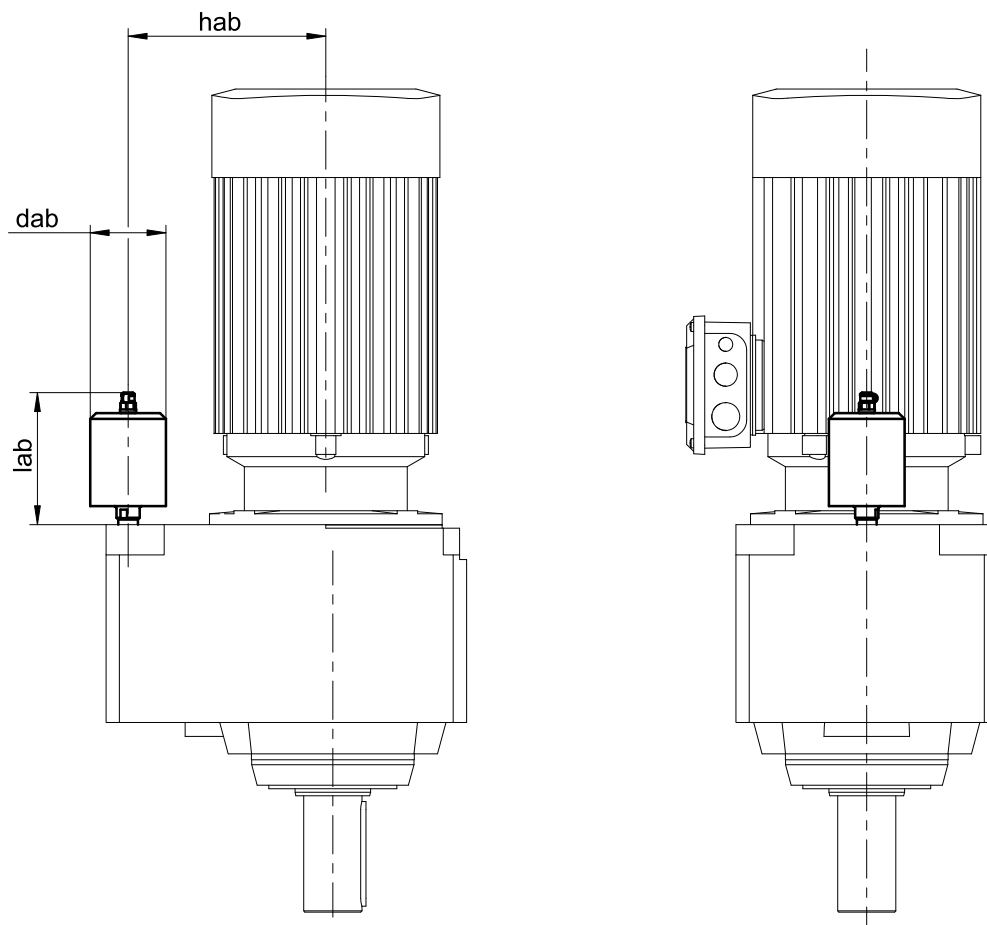
Dimensions of motors

Type	g	q_0	q_1	w	x_1	y_1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5

Dimensions of geared motors

Type	IE3D063		IE3D071		IE3D080		IE3D090		IE3D100		IE3D112		IE3D132	
	a	m	a	m	a	m	a	m	a	m	a	m	a	m
C002	∅140	114	∅140	114	∅160	118	∅160	118	-	-	-	-	-	-
C102	∅140	137	∅140	137	∅160	141	∅160	141	∅200	143	∅200	143	-	-
C103	∅140	174	∅140	174	-	-	-	-	-	-	-	-	-	-
C202	∅140	155	∅140	155	∅160	159	∅160	159	∅200	161	∅200	161	-	-
C203	∅140	192	∅140	192	-	-	-	-	-	-	-	-	-	-
C302	-	-	-	-	∅160	178	∅160	178	∅200	180	∅200	180	∅250	183
C303	-	-	∅140	211	∅160	221	-	-	-	-	-	-	-	-
C402	-	-	-	-	∅160	206	∅160	206	∅200	208	∅200	208	∅250	211
C403	-	-	-	-	∅160	249	∅160	249	-	-	-	-	-	-

2.3.5 Oil expansion tank



Dimensions

Type	IE3D100			IE3D112			IE3D132			IE3D160			IE3D180			IE3D200		
	dab	hab	lab	dab	hab	lab	dab	hab	lab	dab	hab	lab	dab	hab	lab	dab	hab	lab
C612	65	170	114.5	65	170	114.5	65	170	115.5	65	214	191.5	65	214	191.5	-	-	-
C712	73	205	129.5	73	205	129.5	73	205	129.5	73	205	129.5	73	205	129.5	-	-	-
C812	-	-	-	-	-	-	73	255	129.5	73	255	129.5	73	255	129.5	73	255	129.5
C912	-	-	-	-	-	-	-	-	-	73	305	126.0	73	305	126.0	73	305	112.0

More information can be found in the chapter [▶ 2.6.3](#)

2.4 Type designation

This chapter shows you an explanation of the type designation with the associated options.

Additional ordering information not included in the type designation can be found at the end of the chapter.

Example code

C	2	0	2	N	0280	IE3D080L04
---	---	---	---	---	------	------------

Explanation

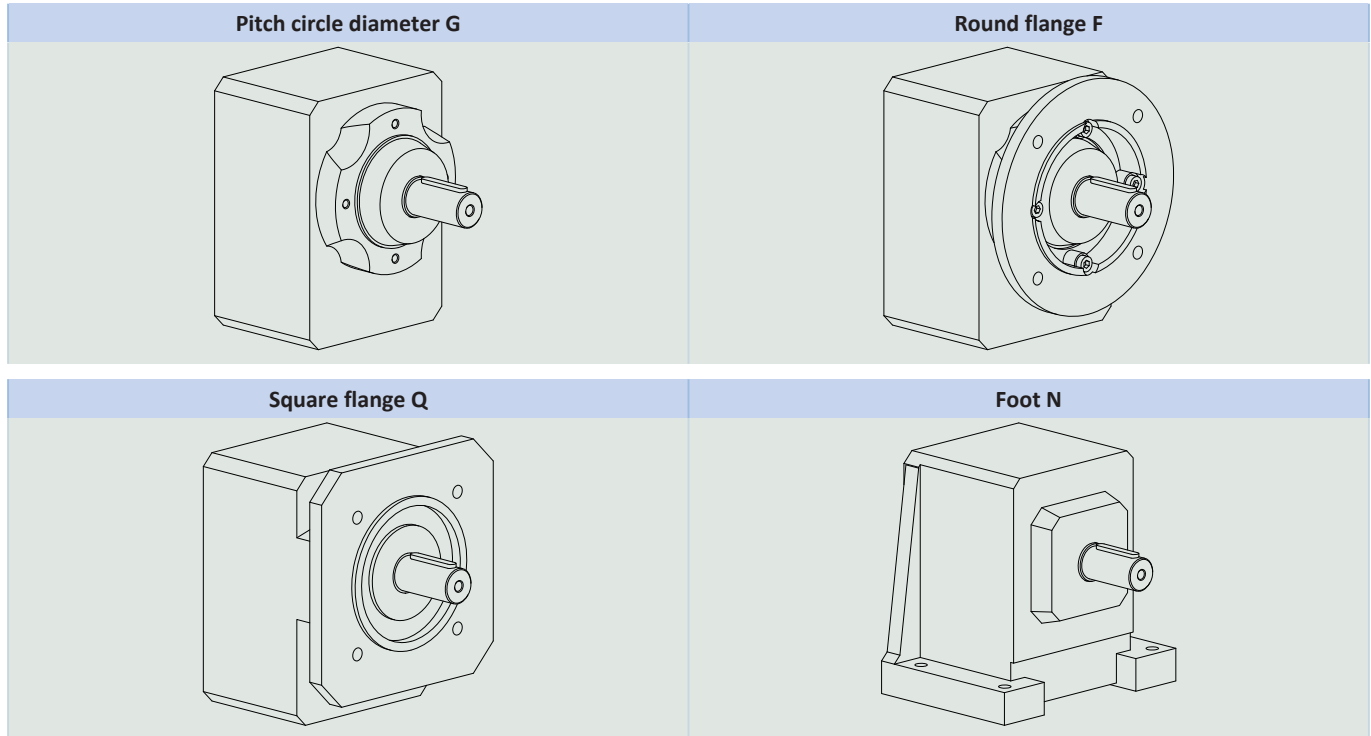
Code	Designation	Design
C	Type	Helical gear unit
2	Size	2 (example)
0	Generation	Generation 0
1		Generation 1
2	Stages	Two-stage
3		Three-stage
G	Housing	Pitch circle diameter
F		Round flange
Q		Square flange
N		Foot
0280	Transmission ratio (i x 10 rounded)	i = 28.24 (example)
IE3D080	Motor	IE3D asynchronous motor
L04		

To complete the type designation, also specify the following in your order:

- A detailed type designation of the motor, see the chapter [\[5.4\]](#)
- The mounting position, see the chapter [\[2.5.4\]](#)
- The position of the terminal box, see the chapter [\[2.5.6\]](#)
- Oil expansion tank (recommended for gear units in mounting position EL5), see the chapter [\[2.6.3\]](#)
- Standard or reinforced output bearing

2.5 Product description

2.5.1 Housing design



	G	F	Q	N
C0	✓	✓	✓	✓
C1	✓	✓	✓	✓
C2	✓	✓	✓	✓
C3	✓	✓	✓	✓
C4	✓	✓	✓	✓
C5	✓	✓	-	✓
C6	✓	✓	-	✓
C7	✓	✓	-	✓
C8	✓	✓	-	✓
C9	✓	✓	-	✓

2.5.2 Shaft design

Gear units in sizes C0 – C9 come standard with a solid shaft with feather key.

Gear units in sizes C0 – C5 can be ordered with the option of a solid shaft without feather key. Only upon request starting at size C6.

2.5.3 Installation conditions

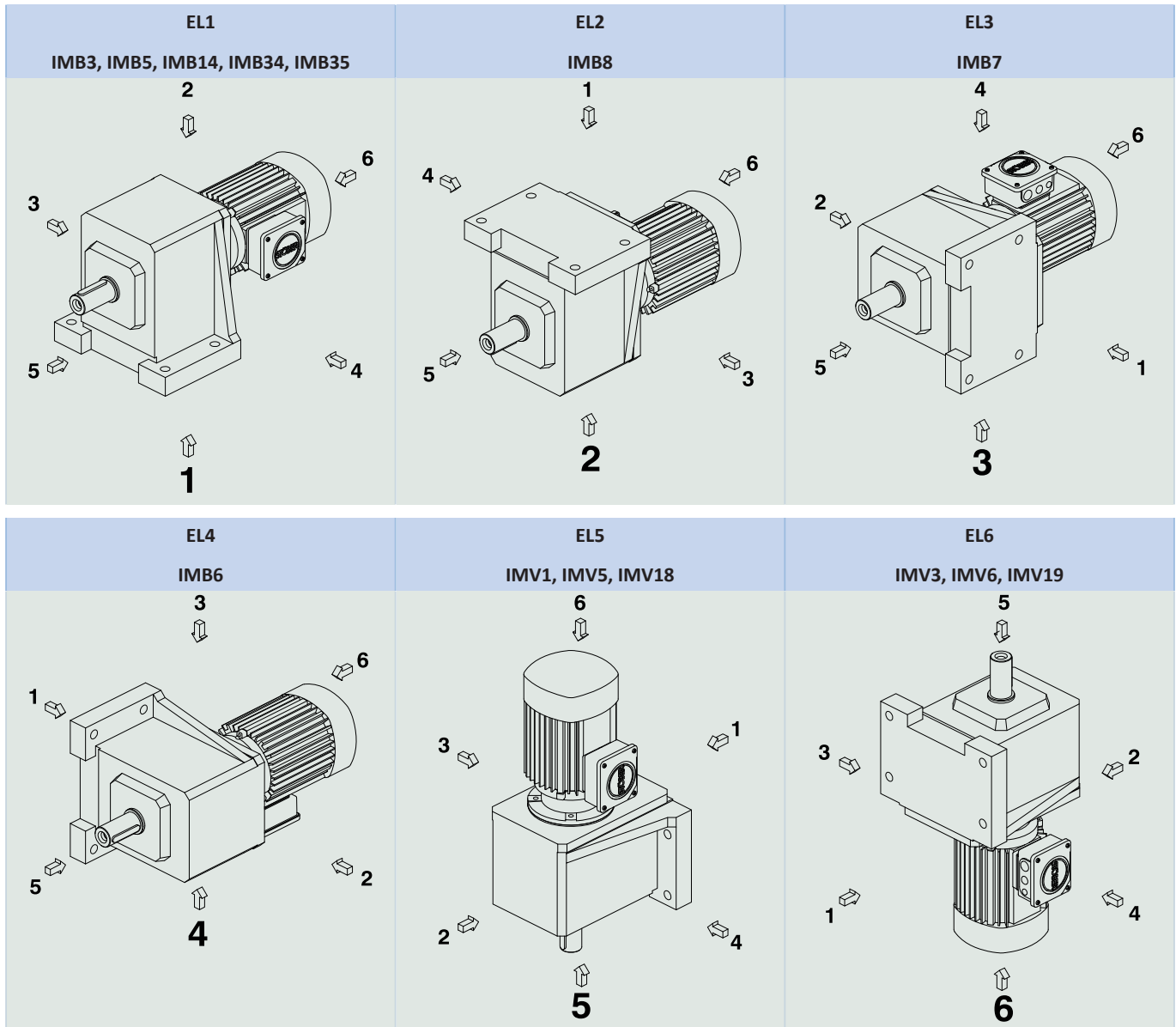
Fastening the gear units on the machine side using the pitch circle diameter

The specified torques and forces only apply when gear units are fastened on the machine side using screws of strength class 10.9. In addition, the gear housings must be adjusted at the pilot. The machine-side fit must be H7.

2.5.4 Mounting positions

The following table shows the standard mounting positions.

The numbers identify the gear unit sides. The mounting position is defined by the gear side facing downwards.



Since the lubricant filling volume of the gear unit depends on the mounting position, the mounting position must be specified when ordering.

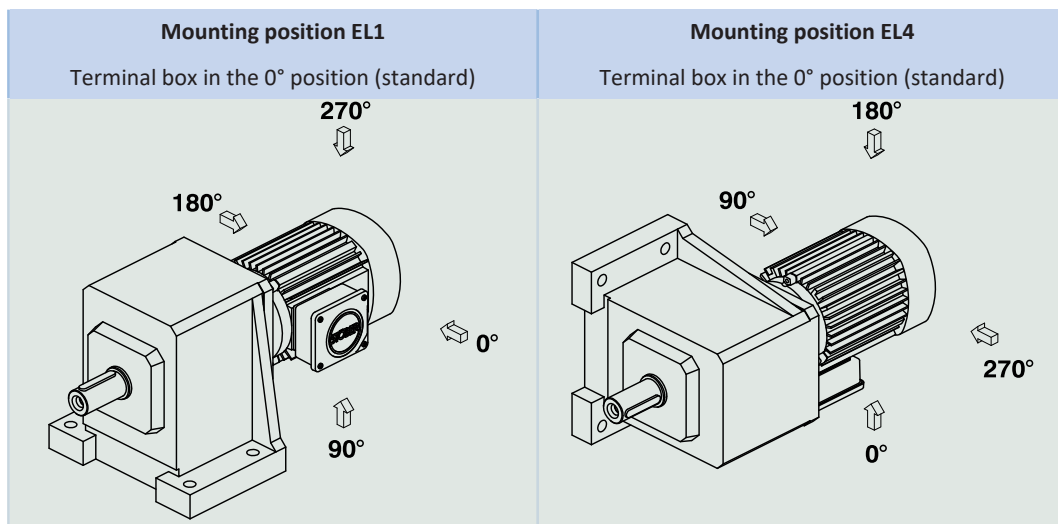
2.5.5 Lubricants

STOBER fills the gear units with the amount and type of lubricant specified on the nameplate. The filling volume and the structure of the gear units depend on the mounting position.

Only install the gear units in the intended mounting position! Reposition the gear units only after consulting STOBER. Otherwise, STOBER assumes no liability for the gear units.

You will receive lubricants for use in the food industry upon request.

2.5.6 Position of the terminal box



Indicate variations for your geared motor in the order.

Note that the terminal box position rotates along with the geared motor if the geared motor rotates to another mounting position.

2.5.7 Other product features

Feature	Value
Max. permitted gear unit temperature (on the surface of the gear unit)	≤ 80 °C
Paint	RAL 7001 Silver gray Optional selection of various RAL colors.
(ATEX) Directive 2014/34/EU	You can get asynchronous motors for use in potentially explosive atmospheres on request.
Efficiency:	
η_{get} two-stage	97%
η_{get} three-stage	96%
Protection class	IP56

2.5.8 Losses due to splashing

Increased losses due to splashing can occur in individual cases under certain operating conditions. These can lead to oil leakage or unacceptably high operating temperatures.

Please coordinate with STOBER to determine a suitable course of action if:

- The surrounding temperature is under -10 °C or over +40 °C
- The gear unit type meets the following conditions:

Type	Mounting position	n_{1N} [rpm]	ED	i
C6, C7	EL5, EL6	> 2500	> 60%, > 20 min	< 10
C8, C9	EL5, EL6	> 2000	> 60%, > 20 min	< 10

2.5.9 Maintenance

The instructions for maintenance can be found in the operating manual, ID 443027_en, at <http://www.stoeb.de/en/downloads/>. Enter the ID of the documentation in the Search... field.

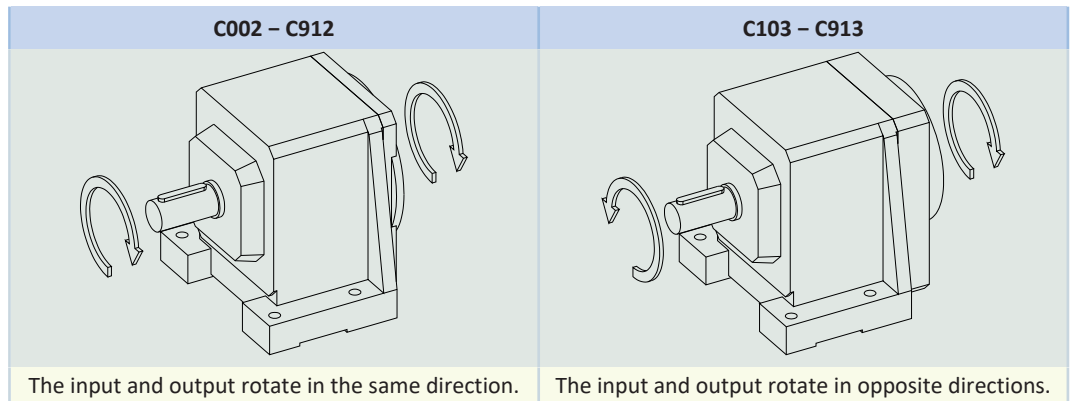
Ventilation

Air release valves are fitted as a standard feature and independently of installation position for gear unit sizes C6 to C9.

For the position and dimensions of the air release valve, refer to the 3D model.

Download the 3D model at <https://configurator.stoeb.de/en-US/>.

2.5.10 Direction of rotation



The pictures show mounting position EL1.

2.6 Project configuration

Project your drives using the information in this chapter. In doing so, observe the limit conditions in this chapter to ensure a safe design.

An explanation of the formula symbols can be found in Chapter [▶ 13.1](#)

Determine the following for your application:

- The actual torque M_{2N^*}
- The actual speed n_{2^*}
- The operating mode operating factor fB_{op}
- The runtime operating factor fB_t
- The motor operating factor fB_{mot}
- The duty cycle ED in %

$$ED = \frac{t_{op}}{T} \cdot 100\%$$

For the S4 and S8 operating mode:

- The mass moment of inertia J_{2^*}

$$J_{1^*} = \frac{J_{2^*}}{i^2}$$

Calculate the motor rating necessary for your application:

$$P_{N^*} = \frac{M_{2N^*} \cdot n_{2^*} \cdot fB_{mot}}{9550}$$

Using the determined values and the calculated motor rating, select a suitable drive from the selection table.


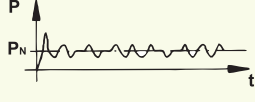
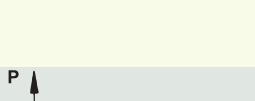
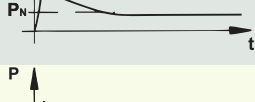
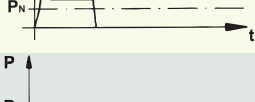
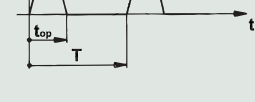
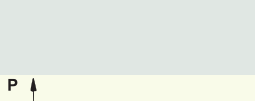
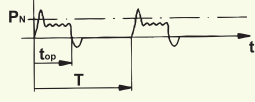
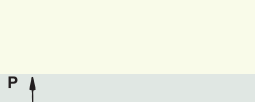
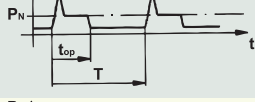
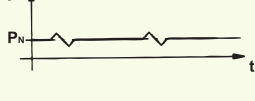
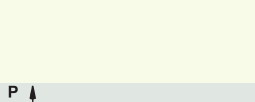
Then check the following conditions:

$$M_{2N^*} \cdot fB_{op} \cdot fB_t < M_{2N} \cdot S$$

$$P_{N^*} < P_N$$

Operating factors

Run time	fB_t
Daily runtime ≤ 8 h	1.00
Daily runtime ≤ 16 h	1.15
Daily runtime ≤ 24 h	1.20

Operating mode	Characteristic output curve	ED	fB _{op}	fB _{mot}
S1 Continuous operation with soft start <ul style="list-style-type: none"> Start time up to 30 s 		100 %	1.00	1.00
S1 Continuous operation with normal start <ul style="list-style-type: none"> Asynchronous motors with direct switch-on or dynamic loading Start time up to 30 s 		100 %	1.25	1.00
S1 Continuous operation with high-load start <ul style="list-style-type: none"> Start time up to 30 s 		100 %	1.25	1.25
S2 brief operation <ul style="list-style-type: none"> Operating time t_{op} ≤ 3 minutes 		≤ 30 %	0.75	0.75
S3 Periodic cyclic operation <ul style="list-style-type: none"> Cycle time T ≤ 10 minutes Cyclic operation with braking motor Low additional flywheel weights J_{1*} < 0,5 · J₁ 		≤ 25 %	0.70	0.70
		≤ 40 %	1.00	1.00
		≤ 60 %	1.25	1.25
S4 Periodic cyclic operation with the effect of the start-up process <ul style="list-style-type: none"> Cycle time T ≤ 10 minutes Cyclic operation with braking motor Larger additional flywheel weights 		40 %	J _{1*} ≤ J ₁ : 1.40 J _{1*} ~ 3 · J ₁ : 1.60	1.40
S6 Uninterrupted periodic operation 	100 %	1.25	1.00	
S6 Uninterrupted periodic operation with short-term loading <ul style="list-style-type: none"> Low speeds Low additional flywheel weights J_{1*} < 0,5 · J₁ 		100 %	1.40	1.00
S6 Uninterrupted periodic operation with impact loading <ul style="list-style-type: none"> High speeds Large additional flywheel weights 		100 %	1.60	1.25
S8 Uninterrupted periodic operation <ul style="list-style-type: none"> With load changes With speed changes 		100 %	J _{1*} ≤ J ₁ : 1.40 J _{1*} ~ 3 · J ₁ : 1.60	J _{1*} ≤ J ₁ : 1.25 J _{1*} ~ 3 · J ₁ : 1.40
S9 Non-periodic operation <ul style="list-style-type: none"> With load changes With speed changes 		100 %	J _{1*} ≤ J ₁ : 1.40 J _{1*} ~ 3 · J ₁ : 1.60	J _{1*} ≤ J ₁ : 1.25 J _{1*} ~ 3 · J ₁ : 1.40
S10 Operation with individual constant loads 	100 %	1.00	1.00	

Tab. 1: Operating factors for operating modes S1 to S10

2.6.1 Permitted shaft loads for the output shaft

The values specified in the tables apply to the permitted shaft loads:

- For shaft dimensions in accordance with the catalog
- For output speeds $n_{2m^*} \leq 20$ rpm ($F_{2axN} = F_{2ax20}$; $F_{2radN} = F_{2rad20}$; $M_{2kN} = M_{2k20}$)
- Only if radial forces on the gear unit are stabilized by its pilots for the pitch circle diameter and flange housing design

Permitted shaft loads

Type	z_2 [mm]	F_{2ax20} [N]	F_{2rad20} [N]	$F_{2rad,acc}$ [N]	M_{2k20} [Nm]	$M_{2k,acc}$ [Nm]
C0	20.0	500	1900	1900	80	80
C1	30.0	850	3400	3400	190	190
C2	30.0	1050	4200	4200	260	260
C3	30.0	1400	5650	5650	350	350
C4	35.0	2400	9700	9700	750	750
C5	42.0	3000	11000	11000	900	900
C6	40.0	4000	16000	16000	1500	1500
C7	45.0	5500	22000	22000	2400	2400
C8	50.0	7500	30000	30000	3700	3700
C9	55.0	9500	37000	37000	5200	5200

For other output speeds, download diagrams at <https://configurator.stoeber.de/en-US/>.

The following applies to output speeds $n_{2m^*} > 20$ rpm:

$$F_{2axN} = \frac{F_{2ax20}}{\sqrt[3]{\frac{n_{2m^*}}{20 \text{ rpm}}}} \quad F_{2radN} = \frac{F_{2rad20}}{\sqrt[3]{\frac{n_{2m^*}}{20 \text{ rpm}}}} \quad M_{2kN} = \frac{M_{2k20}}{\sqrt[3]{\frac{n_{2m^*}}{20 \text{ rpm}}}}$$

The values for F_{2ax20} , F_{2rad20} and M_{2k20} can be found in the table "Permitted shaft loads" in this chapter.

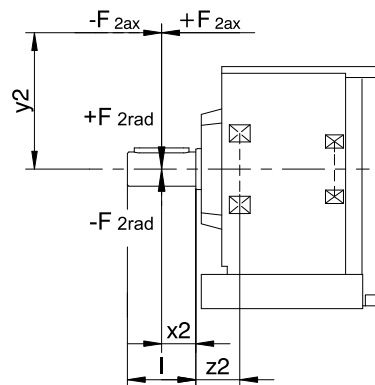


Fig. 1: Force application points

The specified values for F_{2rad20} and $F_{2rad,acc}$ refer to an application of force at the center of the output shaft: $x_2 = l/2$.

Shaft dimensions can be found in the "Dimensional drawings" chapter.

The following applies to other force application points:

$$M_{2k,acc^*} = \frac{2 \cdot F_{2ax^*} \cdot y_2 + F_{2rad,acc^*} \cdot (x_2 + z_2)}{1000}$$

For applications with multiple axial and/or radial forces, you must add the forces as vectors.

In the event of EMERGENCY OFF operation (max. 1000 load changes), you can multiply the permitted forces and torques for F_{2ax20} , F_{2rad20} and M_{2k20} by a factor of two.

Also note the calculation for equivalent values:

$$M_{2k,eq^*} = \sqrt[3]{\frac{|n_{2m,1^*}| \cdot t_{1^*} \cdot |M_{2k,acc,1^*}|^3 + \dots + |n_{2m,n^*}| \cdot t_{n^*} \cdot |M_{2k,acc,n^*}|^3}{|n_{2m,1^*}| \cdot t_{1^*} + \dots + |n_{2m,n^*}| \cdot t_{n^*}}}$$

$$F_{2rad,eq^*} = \sqrt[3]{\frac{|n_{2m,1^*}| \cdot t_{1^*} \cdot |F_{2rad,acc,1^*}|^3 + \dots + |n_{2m,n^*}| \cdot t_{n^*} \cdot |F_{2rad,acc,n^*}|^3}{|n_{2m,1^*}| \cdot t_{1^*} + \dots + |n_{2m,n^*}| \cdot t_{n^*}}}$$

2.6.2 Radial shaft seal rings

Leak-proofness

Our gear units are equipped with high-quality radial shaft seal rings and checked for leaks. However, a leak cannot be fully ruled out over the length of use of a gear unit. If you use a gear unit with goods incompatible with the lubricant, you must take measures to prevent direct contact with the gear unit lubricant in case of a leak.

2.6.3 Oil expansion tank

The gear units have a higher fill level in mounting position EL5. The oil expansion tank prevents oil from escaping out of the gear unit.

Notes

- We recommend using an oil expansion tank in mounting position EL5 (additional cost) for fast running gear units with an input speed $n_1 > 1750$ rpm and gear ratios $i < 20$.
- It is not possible to use an oil expansion tank if the terminal box is at 90°!
- The oil expansion tank can only be used with certain sizes; see the chapter [▶ 2.3.5](#)

2.7 Additional documentation

Additional documentation related to the product can be found at

<http://www.stoeber.de/en/downloads/>

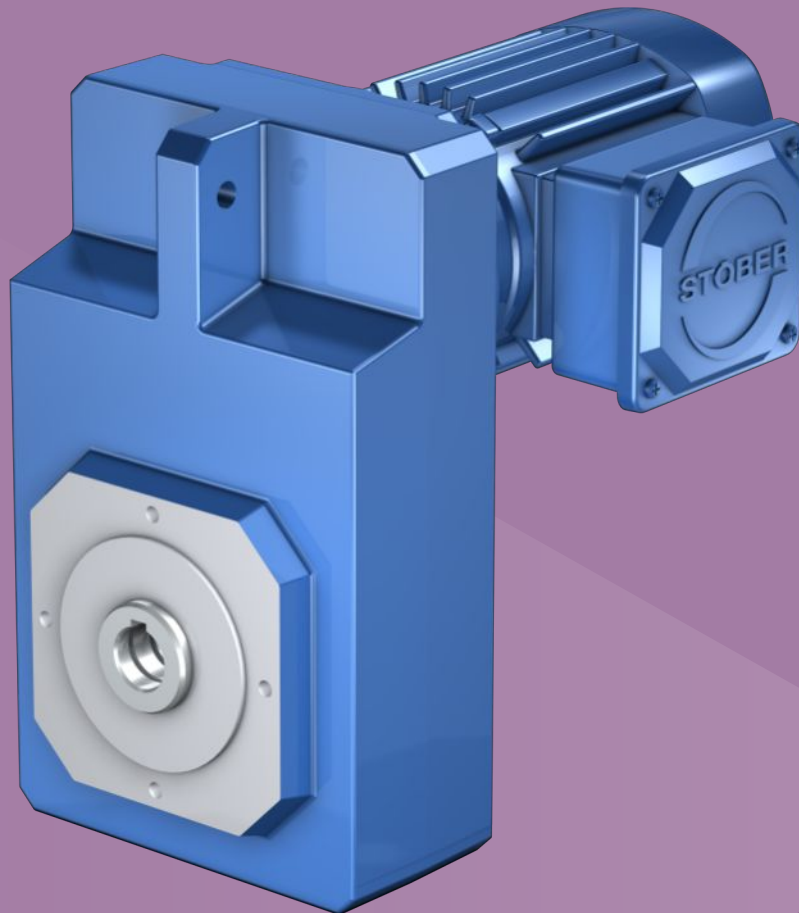
Enter the ID of the documentation in the Search field.

Documentation	ID
Operating manual for C/F/K/S gear units and gear motors	443027_en

3 F offset helical geared motors

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3

Offset helical geared motors

F

3.1 Overview

Offset helical geared motors with large axial distances

Features

Power density	★☆☆☆☆
Backlash	★★★★☆
Price category	€
Shaft load	★★★★☆
Smooth operation	★★★★☆
Torsional stiffness	★★☆☆☆
Mass moment of inertia	★★★★★
Helical gearing	✓
Maintenance-free	✓
FKM seal ring at the input	✓
Large axial distances, suitable for confined situations	✓
Energy efficiency class IE3 in accordance with EN 60034-30-1	✓

Key ★☆☆☆☆ good | ★★★★★ excellent

€ Economy | €€€€€ Premium

Technical data

P_N	0.12 – 7.5 kW
i	4.3 – 547
M_{2N}	5.1 – 1338 Nm
η_{get}	96 – 97 %

3.2 Selection tables

The technical data specified in the selection tables applies to:

- Installation altitudes up to 1000 m above sea level
- Surrounding temperatures from 0 °C to 40 °C
- Drives with self-ventilated motors
- Weight specification for mounting position EL1, housing design G

You can receive asynchronous geared motors with low output speed on request.

Asynchronous geared motors are ideal for operation on a drive controller (87 Hz). More information can be found in chapter [▶ 5.6.2](#)

For all other technical data, refer to <https://configurator.stoeber.de/en-US/>.

An explanation of the formula symbols can be found in the chapter [▶ 13.1](#).

n_2 50 Hz [rpm]	S	n_2 87 Hz [rpm]	S	M_{2N} [Nm]	Type	m [kg]	i	i_{exakt}	J_1 [kgcm ²]
P_N (50 Hz) = 0,12 kW, P_N (87 Hz) = 0,21 kW									
10	1.1	17	1.1	111	F102_1400 IE3D063K04	18	139.8	559/4	4.0
13	1.3	22	1.3	89	F102_1120 IE3D063K04	18	111.9	2015/18	4.0
15	1.6	26	1.6	74	F102_0940 IE3D063K04	18	93.63	7865/84	4.0
20	2.2	35	2.2	56	F102_0700 IE3D063K04	18	70.06	1261/18	4.0
25	2.7	43	2.7	45	F102_0560 IE3D063K04	18	55.97	2015/36	4.1
30	3.2	52	3.2	37	F102_0460 IE3D063K04	18	46.43	325/7	4.1
40	4.3	69	4.2	28	F102_0350 IE3D063K04	18	35.05	3575/102	4.1
50	5.4	86	4.8	22	F102_0280 IE3D063K04	18	28.17	169/6	4.2
61	6.5	105	5.5	18	F102_0230 IE3D063K04	18	23.08	3185/138	4.2
76	7.3	131	6.4	15	F102_0185 IE3D063K04	18	18.46	1495/81	4.3
103	7.3	178	7.3	11	F102_0135 IE3D063K04	18	13.59	231/17	4.2
128	7.3	222	7.3	8.7	F102_0110 IE3D063K04	18	10.92	273/25	4.3
156	7.3	271	7.3	7.1	F102_0089 IE3D063K04	18	8.948	1029/115	4.4
P_N (50 Hz) = 0,18 kW, P_N (87 Hz) = 0,31 kW									
3.9	0.94	6.7	0.94	424	F303_3670 IE3D063M04	39	366.8	99029/270	5.1
5.1	1.3	8.9	1.3	319	F303_2760 IE3D063M04	39	275.6	32242/117	5.1
6.4	0.93	11	0.93	257	F203_2220 IE3D063M04	29	222.2	2444/11	5.1
6.4	1.6	11	1.6	256	F303_2210 IE3D063M04	39	221.2	191149/864	5.1
7.7	1.9	13	1.9	214	F303_1850 IE3D063M04	39	184.8	29939/162	5.1
7.7	1.1	13	1.1	213	F203_1840 IE3D063M04	29	184.3	16215/88	5.1
10	1.5	17	1.5	165	F202_1410 IE3D063M04	27	140.9	1550/11	5.0
10	2.4	17	2.4	165	F302_1410 IE3D063M04	34	140.6	7595/54	5.1
13	1.8	22	1.8	132	F202_1130 IE3D063M04	27	112.7	1240/11	5.1
13	0.91	22	0.91	131	F102_1120 IE3D063M04	18	111.9	2015/18	5.0
15	1.1	26	1.1	110	F102_0940 IE3D063M04	18	93.63	7865/84	5.0
15	2.2	26	2.2	110	F202_0940 IE3D063M04	27	93.82	1032/11	5.1
20	1.5	35	1.5	82	F102_0700 IE3D063M04	18	70.06	1261/18	5.0
20	2.9	35	2.9	82	F202_0700 IE3D063M04	27	70.13	5400/77	5.1
25	1.8	44	1.8	66	F102_0560 IE3D063M04	18	55.97	2015/36	5.1
30	4.3	52	4.3	55	F202_0470 IE3D063M04	27	47.05	1035/22	5.2
30	2.2	53	2.2	54	F102_0460 IE3D063M04	18	46.43	325/7	5.1
40	2.9	70	2.8	41	F102_0350 IE3D063M04	18	35.05	3575/102	5.1
50	3.6	87	3.3	33	F102_0280 IE3D063M04	18	28.17	169/6	5.2
61	4.4	106	3.7	27	F102_0230 IE3D063M04	18	23.08	3185/138	5.2
77	5.0	133	4.3	22	F102_0185 IE3D063M04	18	18.46	1495/81	5.3
104	5.0	180	5.0	16	F102_0135 IE3D063M04	18	13.59	231/17	5.2
130	5.0	224	5.0	13	F102_0110 IE3D063M04	18	10.92	273/25	5.3
158	5.0	274	5.0	11	F102_0089 IE3D063M04	18	8.948	1029/115	5.4
198	5.0	342	5.0	8.4	F102_0072 IE3D063M04	18	7.156	322/45	5.6
328	5.0	569	5.0	5.1	F102_0043 IE3D063M04	18	4.308	56/13	6.5
P_N (50 Hz) = 0,25 kW, P_N (87 Hz) = 0,43 kW									
2.6	0.80	4.5	0.80	874	F403_5470 IE3D071K04	49	547.4	26273/48	8.8
3.3	1.0	5.6	1.0	702	F403_4400 IE3D071K04	49	439.7	58045/132	8.8
3.9	1.2	6.8	1.2	584	F403_3660 IE3D071K04	49	365.6	3290/9	8.8
5.2	0.91	9.0	0.91	440	F303_2760 IE3D071K04	42	275.6	32242/117	8.8
5.2	1.6	9.0	1.6	438	F403_2740 IE3D071K04	49	274.4	59267/216	8.8
6.5	1.1	11	1.1	353	F303_2210 IE3D071K04	42	221.2	191149/864	8.8
6.5	2.0	11	2.0	350	F403_2190 IE3D071K04	49	219.2	94705/432	8.8
7.7	1.4	13	1.4	295	F303_1850 IE3D071K04	42	184.8	29939/162	8.8

3.2 Selection tables 3 F offset helical geared motors

n_2 50 Hz [rpm]	S	n_2 87 Hz [rpm]	S	M_{2N} [Nm]	Type	m [kg]	i	i_{exakt}	J_1 [kgcm ²]
P_N (50 Hz) = 0,25 kW, P_N (87 Hz) = 0,43 kW									
7.8	0.82	13	0.82	294	F203_1840 IE3D071K04	32	184.3	16215/88	8.8
7.8	2.4	13	2.4	294	F403_1840 IE3D071K04	49	183.9	39715/216	8.8
10	1.1	18	1.1	228	F202_1410 IE3D071K04	29	140.9	1550/11	8.7
10	1.8	18	1.8	228	F302_1410 IE3D071K04	37	140.6	7595/54	8.8
13	1.3	22	1.3	183	F202_1130 IE3D071K04	29	112.7	1240/11	8.8
15	1.6	26	1.6	152	F202_0940 IE3D071K04	29	93.82	1032/11	8.8
20	1.1	35	1.1	113	F102_0700 IE3D071K04	21	70.06	1261/18	8.7
20	2.1	35	2.1	114	F202_0700 IE3D071K04	29	70.13	5400/77	8.8
26	1.3	44	1.3	91	F102_0560 IE3D071K04	21	55.97	2015/36	8.8
30	3.1	53	3.1	76	F202_0470 IE3D071K04	29	47.05	1035/22	8.9
31	1.6	53	1.6	75	F102_0460 IE3D071K04	21	46.43	325/7	8.8
41	2.1	71	2.0	57	F102_0350 IE3D071K04	21	35.05	3575/102	8.8
51	2.6	88	2.4	46	F102_0280 IE3D071K04	21	28.17	169/6	8.9
62	3.2	107	2.7	37	F102_0230 IE3D071K04	21	23.08	3185/138	8.9
77	3.6	134	3.1	30	F102_0185 IE3D071K04	21	18.46	1495/81	9.0
105	3.6	182	3.6	22	F102_0135 IE3D071K04	21	13.59	231/17	8.9
131	3.6	227	3.6	18	F102_0110 IE3D071K04	21	10.92	273/25	9.0
159	3.6	275	3.6	15	F202_0090 IE3D071K04	29	9.006	3161/351	10
160	3.6	277	3.6	14	F102_0089 IE3D071K04	21	8.948	1029/115	9.1
200	3.6	346	3.6	12	F102_0072 IE3D071K04	21	7.156	322/45	9.3
332	3.6	575	3.6	7.0	F102_0043 IE3D071K04	21	4.308	56/13	10
P_N (50 Hz) = 0,37 kW, P_N (87 Hz) = 0,64 kW									
3.9	0.80	6.8	0.80	874	F403_3660 IE3D071L04	51	365.6	3290/9	11
5.2	1.1	9.0	1.1	656	F403_2740 IE3D071L04	51	274.4	59267/216	11
6.5	1.3	11	1.3	524	F403_2190 IE3D071L04	51	219.2	94705/432	11
7.7	0.91	13	0.91	442	F303_1850 IE3D071L04	43	184.8	29939/162	11
7.8	1.6	13	1.6	439	F403_1840 IE3D071L04	51	183.9	39715/216	11
10	1.2	18	1.2	341	F302_1410 IE3D071L04	38	140.6	7595/54	11
13	0.88	22	0.88	273	F202_1130 IE3D071L04	30	112.7	1240/11	11
15	1.1	26	1.1	228	F202_0940 IE3D071L04	30	93.82	1032/11	11
20	1.4	35	1.4	170	F202_0700 IE3D071L04	30	70.13	5400/77	11
26	0.88	44	0.88	136	F102_0560 IE3D071L04	22	55.97	2015/36	11
30	2.1	53	2.1	114	F202_0470 IE3D071L04	30	47.05	1035/22	11
31	1.1	53	1.1	113	F102_0460 IE3D071L04	22	46.43	325/7	11
41	1.4	71	1.4	85	F102_0350 IE3D071L04	22	35.05	3575/102	11
40	2.4	70	2.4	86	F202_0350 IE3D071L04	30	35.46	390/11	11
51	1.8	88	1.6	68	F102_0280 IE3D071L04	22	28.17	169/6	11
62	2.1	107	1.8	56	F102_0230 IE3D071L04	22	23.08	3185/138	11
77	2.4	134	2.1	45	F102_0185 IE3D071L04	22	18.46	1495/81	11
105	2.4	182	2.4	33	F102_0135 IE3D071L04	22	13.59	231/17	11
131	2.4	227	2.4	26	F102_0110 IE3D071L04	22	10.92	273/25	11
159	2.4	275	2.4	22	F202_0090 IE3D071L04	30	9.006	3161/351	12
160	2.4	277	2.4	22	F102_0089 IE3D071L04	22	8.948	1029/115	11
200	2.4	346	2.4	17	F102_0072 IE3D071L04	22	7.156	322/45	11
332	2.4	575	2.4	10	F102_0043 IE3D071L04	22	4.308	56/13	12
P_N (50 Hz) = 0,55 kW, P_N (87 Hz) = 0,95 kW									
4.0	0.87	6.9	0.87	1259	F603_3610 IE3D080K04	81	360.9	3248/9	21
5.3	1.2	9.3	1.2	940	F603_2690 IE3D080K04	81	269.3	1885/7	21
6.7	0.93	12	0.93	755	F403_2160 IE3D080K04	54	216.4	11687/54	21
6.7	1.5	12	1.5	752	F603_2150 IE3D080K04	81	215.4	1508/7	21
7.9	1.1	14	1.1	633	F403_1820 IE3D080K04	54	181.5	4901/27	21
8.0	1.7	14	1.7	630	F603_1810 IE3D080K04	81	180.6	8671/48	21
10	1.4	18	1.4	495	F402_1400 IE3D080K04	50	139.8	559/4	21
10	2.2	18	2.2	495	F602_1400 IE3D080K04	77	139.8	559/4	21
13	1.0	22	1.0	400	F302_1130 IE3D080K04	42	112.8	3724/33	21
13	1.8	22	1.8	398	F402_1120 IE3D080K04	50	112.3	1235/11	21
13	2.8	22	2.8	397	F602_1120 IE3D080K04	77	112.2	9425/84	21
15	1.2	27	1.2	332	F302_0940 IE3D080K04	42	93.64	4214/45	21
15	2.1	27	2.1	330	F402_0930 IE3D080K04	50	93.33	280/3	21
21	0.97	36	0.97	248	F202_0700 IE3D080K04	34	70.13	5400/77	21
20	1.6	35	1.6	249	F302_0700 IE3D080K04	42	70.36	2744/39	21
21	2.8	36	2.8	248	F402_0700 IE3D080K04	50	70.06	1261/18	21
25	1.2	44	1.2	201	F202_0570 IE3D080K04	34	56.73	624/11	21
25	2.0	44	2.0	200	F302_0560 IE3D080K04	42	56.49	4067/72	21
31	1.4	53	1.4	167	F202_0470 IE3D080K04	34	47.05	1035/22	21

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 0,55 kW, P_N (87 Hz) = 0,95 kW									
31	2.4	53	2.4	167	F302_0470 IE3D080K04	42	47.19	1274/27	21
41	0.97	71	0.94	124	F102_0350 IE3D080K04	26	35.05	3575/102	21
41	1.9	70	1.9	126	F202_0350 IE3D080K04	34	35.46	390/11	21
41	3.2	71	3.1	124	F302_0350 IE3D080K04	42	35.03	7252/207	21
51	1.2	89	1.1	100	F102_0280 IE3D080K04	26	28.17	169/6	21
51	2.4	89	2.2	100	F202_0280 IE3D080K04	34	28.11	4020/143	21
61	4.8	106	4.1	83	F302_0240 IE3D080K04	42	23.52	588/25	22
62	1.5	108	1.2	82	F102_0230 IE3D080K04	26	23.08	3185/138	21
61	2.9	106	2.4	83	F202_0230 IE3D080K04	34	23.43	2320/99	21
78	1.7	135	1.4	65	F102_0185 IE3D080K04	26	18.46	1495/81	21
77	3.4	134	2.8	66	F202_0185 IE3D080K04	34	18.65	6360/341	22
106	2.1	184	1.8	48	F102_0135 IE3D080K04	26	13.59	231/17	21
132	2.4	228	2.0	39	F102_0110 IE3D080K04	26	10.92	273/25	21
160	5.5	277	4.6	32	F202_0090 IE3D080K04	34	9.006	3161/351	22
161	2.8	279	2.3	32	F102_0089 IE3D080K04	26	8.948	1029/115	21
201	3.2	349	2.7	25	F102_0072 IE3D080K04	26	7.156	322/45	21
223	3.4	386	2.9	23	F102_0065 IE3D080K04	26	6.462	84/13	21
308	6.6	533	6.6	17	F202_0047 IE3D080K04	34	4.680	2616/559	25
334	4.5	579	3.8	15	F102_0043 IE3D080K04	26	4.308	56/13	22
P_N (50 Hz) = 0,75 kW, P_N (87 Hz) = 1,30 kW									
5.4	0.86	9.3	0.86	1287	F603_2690 IE3D080L04	84	269.3	1885/7	26
6.7	1.1	12	1.1	1030	F603_2150 IE3D080L04	84	215.4	1508/7	26
8.0	0.81	14	0.81	868	F403_1820 IE3D080L04	57	181.5	4901/27	26
8.0	1.3	14	1.3	863	F603_1810 IE3D080L04	84	180.6	8671/48	26
10	1.0	18	1.0	678	F402_1400 IE3D080L04	52	139.8	559/4	26
10	1.6	18	1.6	678	F602_1400 IE3D080L04	79	139.8	559/4	26
13	1.3	22	1.3	545	F402_1120 IE3D080L04	52	112.3	1235/11	26
13	2.0	22	2.0	544	F602_1120 IE3D080L04	79	112.2	9425/84	26
15	0.88	27	0.88	454	F302_0940 IE3D080L04	44	93.64	4214/45	26
15	1.5	27	1.5	453	F402_0930 IE3D080L04	52	93.33	280/3	26
15	2.4	27	2.4	453	F602_0930 IE3D080L04	79	93.33	280/3	27
21	1.2	36	1.2	341	F302_0700 IE3D080L04	44	70.36	2744/39	26
21	2.1	36	2.1	340	F402_0700 IE3D080L04	52	70.06	1261/18	26
25	0.87	44	0.87	275	F202_0570 IE3D080L04	36	56.73	624/11	26
26	1.5	44	1.5	274	F302_0560 IE3D080L04	44	56.49	4067/72	26
26	2.6	45	2.6	271	F402_0560 IE3D080L04	52	55.97	2015/36	27
31	1.1	53	1.1	228	F202_0470 IE3D080L04	36	47.05	1035/22	26
31	1.7	53	1.7	229	F302_0470 IE3D080L04	44	47.19	1274/27	26
31	3.1	53	3.1	228	F402_0470 IE3D080L04	52	46.94	845/18	27
41	1.4	71	1.4	172	F202_0350 IE3D080L04	36	35.46	390/11	26
41	2.4	71	2.3	170	F302_0350 IE3D080L04	44	35.03	7252/207	27
51	0.88	–	–	137	F102_0280 IE3D080L04	28	28.17	169/6	26
51	1.8	89	1.6	136	F202_0280 IE3D080L04	36	28.11	4020/143	27
51	2.9	89	2.6	137	F302_0280 IE3D080L04	44	28.23	6860/243	27
61	3.5	106	3.0	114	F302_0240 IE3D080L04	44	23.52	588/25	27
63	1.1	108	0.90	112	F102_0230 IE3D080L04	28	23.08	3185/138	26
62	2.1	107	1.8	114	F202_0230 IE3D080L04	36	23.43	2320/99	27
78	1.2	136	1.0	90	F102_0185 IE3D080L04	28	18.46	1495/81	26
77	2.5	134	2.1	90	F202_0185 IE3D080L04	36	18.65	6360/341	27
106	1.5	184	1.3	66	F102_0135 IE3D080L04	28	13.59	231/17	26
106	3.0	184	2.6	66	F202_0135 IE3D080L04	36	13.63	109/8	27
132	1.8	229	1.5	53	F102_0110 IE3D080L04	28	10.92	273/25	26
134	3.5	232	3.0	52	F202_0110 IE3D080L04	36	10.80	7303/676	27
160	4.0	278	3.4	44	F202_0090 IE3D080L04	36	9.006	3161/351	27
161	2.0	280	1.7	43	F102_0089 IE3D080L04	28	8.948	1029/115	26
202	2.3	350	2.0	35	F102_0072 IE3D080L04	28	7.156	322/45	27
224	2.5	387	2.1	31	F102_0065 IE3D080L04	28	6.462	84/13	27
309	4.8	535	4.8	23	F202_0047 IE3D080L04	36	4.680	2616/559	30
335	3.3	581	2.8	21	F102_0043 IE3D080L04	28	4.308	56/13	28
P_N (50 Hz) = 1,10 kW, P_N (87 Hz) = 1,91 kW									
8.0	0.87	14	0.87	1261	F603_1810 IE3D090S04	89	180.6	8671/48	40
10	1.1	18	1.1	990	F602_1400 IE3D090S04	85	139.8	559/4	40
13	0.88	22	0.88	795	F402_1120 IE3D090S04	58	112.3	1235/11	40
13	1.4	22	1.4	795	F602_1120 IE3D090S04	85	112.2	9425/84	40
15	1.1	27	1.1	661	F402_0930 IE3D090S04	58	93.33	280/3	40

3.2 Selection tables 3 F offset helical geared motors

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 1,10 kW, P_N (87 Hz) = 1,91 kW									
15	1.7	27	1.7	661	F602_0930 IE3D090S04	85	93.33	280/3	41
20	0.80	35	0.80	498	F302_0700 IE3D090S04	50	70.36	2744/39	40
21	1.4	36	1.4	496	F402_0700 IE3D090S04	58	70.06	1261/18	40
21	2.2	36	2.2	493	F602_0700 IE3D090S04	85	69.64	975/14	41
25	1.0	44	1.0	400	F302_0560 IE3D090S04	50	56.49	4067/72	40
26	1.8	45	1.8	396	F402_0560 IE3D090S04	58	55.97	2015/36	41
31	1.2	53	1.2	334	F302_0470 IE3D090S04	50	47.19	1274/27	40
31	2.1	53	2.1	332	F402_0470 IE3D090S04	58	46.94	845/18	41
41	0.96	70	0.93	251	F202_0350 IE3D090S04	42	35.46	390/11	40
41	1.6	71	1.6	248	F302_0350 IE3D090S04	50	35.03	7252/207	41
51	1.2	89	1.1	199	F202_0280 IE3D090S04	42	28.11	4020/143	41
51	2.0	88	1.8	200	F302_0280 IE3D090S04	50	28.23	6860/243	41
61	2.4	106	2.0	167	F302_0240 IE3D090S04	50	23.52	588/25	41
61	1.4	106	1.2	166	F202_0230 IE3D090S04	42	23.43	2320/99	41
78	0.85	–	–	131	F102_0185 IE3D090S04	34	18.46	1495/81	40
77	1.7	134	1.4	132	F202_0185 IE3D090S04	42	18.65	6360/341	41
106	1.0	184	0.88	96	F102_0135 IE3D090S04	34	13.59	231/17	40
106	2.1	183	1.8	96	F202_0135 IE3D090S04	42	13.63	109/8	41
132	1.2	228	1.0	77	F102_0110 IE3D090S04	34	10.92	273/25	40
133	2.4	231	2.0	76	F202_0110 IE3D090S04	42	10.80	7303/676	41
160	2.7	277	2.3	64	F202_0090 IE3D090S04	42	9.006	3161/351	41
161	1.4	279	1.2	63	F102_0089 IE3D090S04	34	8.948	1029/115	40
201	1.6	349	1.4	51	F102_0072 IE3D090S04	34	7.156	322/45	41
201	3.2	348	2.7	51	F202_0072 IE3D090S04	42	7.167	5777/806	42
223	1.7	386	1.4	46	F102_0065 IE3D090S04	34	6.462	84/13	41
308	3.3	533	3.3	33	F202_0047 IE3D090S04	42	4.680	2616/559	44
334	2.2	579	1.9	31	F102_0043 IE3D090S04	34	4.308	56/13	42
P_N (50 Hz) = 1,50 kW, P_N (87 Hz) = 2,60 kW									
10	0.83	18	0.83	1328	F602_1400 IE3D090LX04	93	139.8	559/4	58
13	1.0	22	1.0	1067	F602_1120 IE3D090LX04	93	112.2	9425/84	58
16	1.2	27	1.2	887	F602_0930 IE3D090LX04	93	93.33	280/3	59
21	1.1	36	1.1	666	F402_0700 IE3D090LX04	66	70.06	1261/18	58
21	1.7	36	1.7	662	F602_0700 IE3D090LX04	93	69.64	975/14	59
26	1.3	45	1.3	532	F402_0560 IE3D090LX04	66	55.97	2015/36	59
31	0.89	53	0.89	449	F302_0470 IE3D090LX04	58	47.19	1274/27	58
31	1.6	54	1.6	446	F402_0470 IE3D090LX04	66	46.94	845/18	59
42	1.2	72	1.2	333	F302_0350 IE3D090LX04	58	35.03	7252/207	59
52	0.90	90	0.81	267	F202_0280 IE3D090LX04	50	28.11	4020/143	59
52	1.5	89	1.3	268	F302_0280 IE3D090LX04	58	28.23	6860/243	59
62	1.8	107	1.5	224	F302_0240 IE3D090LX04	58	23.52	588/25	59
62	1.1	108	0.91	223	F202_0230 IE3D090LX04	50	23.43	2320/99	59
78	1.3	135	1.1	177	F202_0185 IE3D090LX04	50	18.65	6360/341	59
107	1.5	185	1.3	130	F202_0135 IE3D090LX04	50	13.63	109/8	59
109	2.4	188	2.2	127	F302_0135 IE3D090LX04	58	13.38	7696/575	59
133	0.90	–	–	104	F102_0110 IE3D090LX04	42	10.92	273/25	58
135	1.8	233	1.5	103	F202_0110 IE3D090LX04	50	10.80	7303/676	59
135	2.5	234	2.5	103	F302_0110 IE3D090LX04	58	10.79	1456/135	60
162	2.0	280	1.7	86	F202_0090 IE3D090LX04	50	9.006	3161/351	59
163	1.0	282	0.87	85	F102_0089 IE3D090LX04	42	8.948	1029/115	58
203	1.2	352	1.0	68	F102_0072 IE3D090LX04	42	7.156	322/45	59
203	2.4	352	2.0	68	F202_0072 IE3D090LX04	50	7.167	5777/806	60
225	1.3	390	1.1	61	F102_0065 IE3D090LX04	42	6.462	84/13	59
311	2.4	538	2.4	44	F202_0047 IE3D090LX04	50	4.680	2616/559	62
338	1.7	585	1.4	41	F102_0043 IE3D090LX04	42	4.308	56/13	60
P_N (50 Hz) = 2,20 kW, P_N (87 Hz) = 3,81 kW									
16	0.84	27	0.84	1313	F602_0930 IE3D100KX04	107	93.33	280/3	111
21	1.1	36	1.1	980	F602_0700 IE3D100KX04	107	69.64	975/14	111
26	0.89	45	0.89	787	F402_0560 IE3D100KX04	80	55.97	2015/36	111
26	1.4	45	1.4	784	F602_0560 IE3D100KX04	107	55.71	390/7	111
31	1.1	53	1.1	660	F402_0470 IE3D100KX04	80	46.94	845/18	111
31	1.7	54	1.7	657	F602_0470 IE3D100KX04	107	46.72	1495/32	112
41	0.81	–	–	493	F302_0350 IE3D100KX04	72	35.03	7252/207	111
41	1.4	72	1.3	493	F402_0350 IE3D100KX04	80	35.08	2210/63	111
41	2.2	71	2.2	495	F602_0350 IE3D100KX04	107	35.21	845/24	113
51	1.0	89	0.90	397	F302_0280 IE3D100KX04	72	28.23	6860/243	111

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 2,20 kW, P_N (87 Hz) = 3,81 kW									
52	1.8	90	1.5	394	F402_0280 IE3D100KX04	80	27.99	2015/72	112
52	2.8	90	2.5	394	F602_0280 IE3D100KX04	107	27.99	2015/72	114
62	1.2	107	1.0	331	F302_0240 IE3D100KX04	72	23.52	588/25	111
62	2.0	108	1.7	327	F402_0230 IE3D100KX04	80	23.21	325/14	112
77	1.4	134	1.2	264	F302_0190 IE3D100KX04	72	18.77	4900/261	112
78	0.85	–	–	262	F202_0185 IE3D100KX04	64	18.65	6360/341	111
78	2.3	135	2.0	262	F402_0185 IE3D100KX04	80	18.62	3575/192	113
106	1.0	184	0.88	192	F202_0135 IE3D100KX04	64	13.63	109/8	111
108	1.8	188	1.5	188	F302_0135 IE3D100KX04	72	13.38	7696/575	111
107	2.9	185	2.4	191	F402_0135 IE3D100KX04	80	13.57	5984/441	112
134	1.2	232	1.0	152	F202_0110 IE3D100KX04	64	10.80	7303/676	111
134	2.0	233	1.7	152	F302_0110 IE3D100KX04	72	10.79	1456/135	112
161	1.4	279	1.2	127	F202_0090 IE3D100KX04	64	9.006	3161/351	111
161	2.3	279	1.9	126	F302_0090 IE3D100KX04	72	8.986	5616/625	113
202	1.6	350	1.4	101	F202_0072 IE3D100KX04	64	7.167	5777/806	112
202	2.7	350	2.3	101	F302_0072 IE3D100KX04	72	7.172	208/29	114
253	3.1	439	2.6	80	F302_0057 IE3D100KX04	72	5.720	143/25	116
261	1.9	452	1.6	78	F202_0056 IE3D100KX04	64	5.552	5341/962	113
310	2.1	537	1.8	66	F202_0047 IE3D100KX04	64	4.680	2616/559	114
312	3.6	541	3.0	65	F302_0046 IE3D100KX04	72	4.644	4992/1075	118
P_N (50 Hz) = 3,00 kW, P_N (87 Hz) = 5,20 kW									
21	0.82	36	0.82	1338	F602_0700 IE3D100LX04	112	69.64	975/14	131
26	1.0	45	1.0	1070	F602_0560 IE3D100LX04	112	55.71	390/7	131
31	1.2	54	1.2	897	F602_0470 IE3D100LX04	112	46.72	1495/32	132
41	1.0	72	0.95	674	F402_0350 IE3D100LX04	85	35.08	2210/63	131
41	1.6	71	1.6	676	F602_0350 IE3D100LX04	112	35.21	845/24	133
52	1.3	90	1.1	537	F402_0280 IE3D100LX04	85	27.99	2015/72	132
52	2.0	90	1.8	537	F602_0280 IE3D100LX04	112	27.99	2015/72	134
62	0.89	–	–	452	F302_0240 IE3D100LX04	77	23.52	588/25	131
62	1.5	108	1.2	446	F402_0230 IE3D100LX04	85	23.21	325/14	132
62	2.5	108	2.1	447	F602_0230 IE3D100LX04	112	23.27	1885/81	135
77	1.0	134	0.87	361	F302_0190 IE3D100LX04	77	18.77	4900/261	132
78	1.7	135	1.4	358	F402_0185 IE3D100LX04	85	18.62	3575/192	133
108	1.3	188	1.1	257	F302_0135 IE3D100LX04	77	13.38	7696/575	131
107	2.1	185	1.8	261	F402_0135 IE3D100LX04	85	13.57	5984/441	132
134	0.89	–	–	207	F202_0110 IE3D100LX04	69	10.80	7303/676	131
134	1.5	233	1.3	207	F302_0110 IE3D100LX04	77	10.79	1456/135	132
134	2.5	232	2.1	208	F402_0110 IE3D100LX04	85	10.83	682/63	133
161	1.0	279	0.85	173	F202_0090 IE3D100LX04	69	9.006	3161/351	131
161	1.7	279	1.4	173	F302_0090 IE3D100LX04	77	8.986	5616/625	133
161	2.8	280	2.3	172	F402_0090 IE3D100LX04	85	8.980	440/49	135
202	1.2	350	0.99	138	F202_0072 IE3D100LX04	69	7.167	5777/806	132
202	2.0	350	1.6	138	F302_0072 IE3D100LX04	77	7.172	208/29	134
201	3.0	349	2.7	138	F402_0072 IE3D100LX04	85	7.202	605/84	137
253	2.3	439	1.9	110	F302_0057 IE3D100LX04	77	5.720	143/25	136
261	1.4	452	1.2	107	F202_0056 IE3D100LX04	69	5.552	5341/962	133
310	1.6	537	1.3	90	F202_0047 IE3D100LX04	69	4.680	2616/559	134
312	2.6	541	2.2	89	F302_0046 IE3D100LX04	77	4.644	4992/1075	138
P_N (50 Hz) = 4,00 kW, P_N (87 Hz) = 6,93 kW									
31	0.93	54	0.93	1183	F602_0470 IE3D112M04	118	46.72	1495/32	172
42	1.2	72	1.2	891	F602_0350 IE3D112M04	118	35.21	845/24	173
52	0.99	91	0.83	709	F402_0280 IE3D112M04	91	27.99	2015/72	172
52	1.6	91	1.4	709	F602_0280 IE3D112M04	118	27.99	2015/72	174
63	1.1	109	0.94	588	F402_0230 IE3D112M04	91	23.21	325/14	172
63	1.9	109	1.6	589	F602_0230 IE3D112M04	118	23.27	1885/81	175
79	1.3	136	1.1	471	F402_0185 IE3D112M04	91	18.62	3575/192	173
109	0.98	190	0.83	339	F302_0135 IE3D112M04	83	13.38	7696/575	171
108	1.6	187	1.4	344	F402_0135 IE3D112M04	91	13.57	5984/441	172
108	2.1	186	2.1	345	F602_0135 IE3D112M04	118	13.61	871/64	175
136	1.1	235	0.95	273	F302_0110 IE3D112M04	83	10.79	1456/135	172
135	1.9	234	1.6	274	F402_0110 IE3D112M04	91	10.83	682/63	173
135	2.3	235	2.3	274	F602_0110 IE3D112M04	118	10.82	2077/192	178
163	1.3	282	1.1	227	F302_0090 IE3D112M04	83	8.986	5616/625	173
163	2.1	283	1.8	227	F402_0090 IE3D112M04	91	8.980	440/49	175
204	0.89	–	–	181	F202_0072 IE3D112M04	75	7.167	5777/806	172

3.2 Selection tables 3 F offset helical geared motors

n_2 50 Hz [rpm]	S	n_2 87 Hz [rpm]	S	M_{2N} [Nm]	Type	m [kg]	i	i_{exakt}	J_1 [kgcm ²]
P_N (50 Hz) = 4,00 kW, P_N (87 Hz) = 6,93 kW									
204	1.5	354	1.3	182	F302_0072 IE3D112M04	83	7.172	208/29	174
203	2.3	352	2.1	182	F402_0072 IE3D112M04	91	7.202	605/84	177
256	1.7	444	1.5	145	F302_0057 IE3D112M04	83	5.720	143/25	176
264	1.1	457	0.89	141	F202_0056 IE3D112M04	75	5.552	5341/962	173
313	1.2	542	1.0	118	F202_0047 IE3D112M04	75	4.680	2616/559	174
315	2.0	546	1.7	118	F302_0046 IE3D112M04	83	4.644	4992/1075	178
P_N (50 Hz) = 5,50 kW, P_N (87 Hz) = 9,53 kW									
42	0.90	72	0.87	1229	F602_0350 IE3D132SX04	152	35.21	845/24	353
52	1.1	91	1.0	977	F602_0280 IE3D132SX04	152	27.99	2015/72	354
63	0.81	–	–	811	F402_0230 IE3D132SX04	125	23.21	325/14	352
63	1.4	109	1.1	813	F602_0230 IE3D132SX04	152	23.27	1885/81	355
79	0.94	–	–	650	F402_0185 IE3D132SX04	125	18.62	3575/192	353
79	1.6	137	1.3	647	F602_0185 IE3D132SX04	152	18.52	3445/186	358
108	1.2	187	0.98	474	F402_0135 IE3D132SX04	125	13.57	5984/441	352
108	1.9	186	1.6	475	F602_0135 IE3D132SX04	152	13.61	871/64	355
135	1.3	234	1.1	378	F402_0110 IE3D132SX04	125	10.83	682/63	353
135	2.3	235	1.9	378	F602_0110 IE3D132SX04	152	10.82	2077/192	358
163	1.5	283	1.3	314	F402_0090 IE3D132SX04	125	8.980	440/49	355
163	2.6	282	2.2	314	F602_0090 IE3D132SX04	152	8.995	1943/216	361
203	1.8	352	1.5	251	F402_0072 IE3D132SX04	125	7.202	605/84	357
205	3.0	354	2.5	250	F602_0072 IE3D132SX04	152	7.159	3551/496	366
252	2.0	437	1.7	203	F402_0058 IE3D132SX04	125	5.813	3784/651	360
258	3.5	–	–	198	F602_0057 IE3D132SX04	152	5.673	1407/248	374
313	2.4	542	2.0	163	F402_0047 IE3D132SX04	125	4.678	1408/301	365
322	4.0	–	–	159	F602_0045 IE3D132SX04	152	4.546	1273/280	386
P_N (50 Hz) = 7,50 kW, P_N (87 Hz) = 12,99 kW									
53	0.83	–	–	1330	F602_0280 IE3D132MX04	150	27.99	2015/72	354
63	0.99	109	0.84	1106	F602_0230 IE3D132MX04	150	23.27	1885/81	355
79	1.2	137	0.98	880	F602_0185 IE3D132MX04	150	18.52	3445/186	358
108	0.85	–	–	645	F402_0135 IE3D132MX04	123	13.57	5984/441	352
108	1.4	187	1.2	647	F602_0135 IE3D132MX04	150	13.61	871/64	355
136	0.99	235	0.84	515	F402_0110 IE3D132MX04	123	10.83	682/63	353
136	1.7	235	1.4	514	F602_0110 IE3D132MX04	150	10.82	2077/192	358
164	1.1	284	0.95	427	F402_0090 IE3D132MX04	123	8.980	440/49	355
163	1.9	283	1.6	428	F602_0090 IE3D132MX04	150	8.995	1943/216	361
204	1.3	354	1.1	342	F402_0072 IE3D132MX04	123	7.202	605/84	357
205	2.2	356	1.8	340	F602_0072 IE3D132MX04	150	7.159	3551/496	366
253	1.5	438	1.3	276	F402_0058 IE3D132MX04	123	5.813	3784/651	360
259	2.5	–	–	270	F602_0057 IE3D132MX04	150	5.673	1407/248	374
314	1.7	544	1.5	222	F402_0047 IE3D132MX04	123	4.678	1408/301	365
323	3.0	–	–	216	F602_0045 IE3D132MX04	150	4.546	1273/280	386

3.3 Dimensional drawings

In this chapter you can find the dimensions of the geared motors.

There is a dimensional drawing for every possible shaft/housing design, each with the tables for gear unit dimensions, motor dimensions and geared motor dimensions.

Dimensions can exceed the specifications of ISO 2768-mK due to casting tolerances or accumulation of individual tolerances.

We reserve the right to make dimensional changes due to ongoing technical development.

You can download 3D models of our standard drives at <https://configurator.stoeber.de/en-US/>.

Tolerances

Axis height in accordance with DIN 747	Tolerance
Up to 50 mm	-0.4 mm
Up to 250 mm	-0.5 mm
Up to 630 mm	-0.6 mm

Solid shaft	Tolerance
Shaft \varnothing fit \leq 50 mm	DIN 748-1, ISO k6
Shaft \varnothing fit $>$ 50 mm	DIN 748-1, ISO m6
Feather keys	DIN 6885-1, high form A

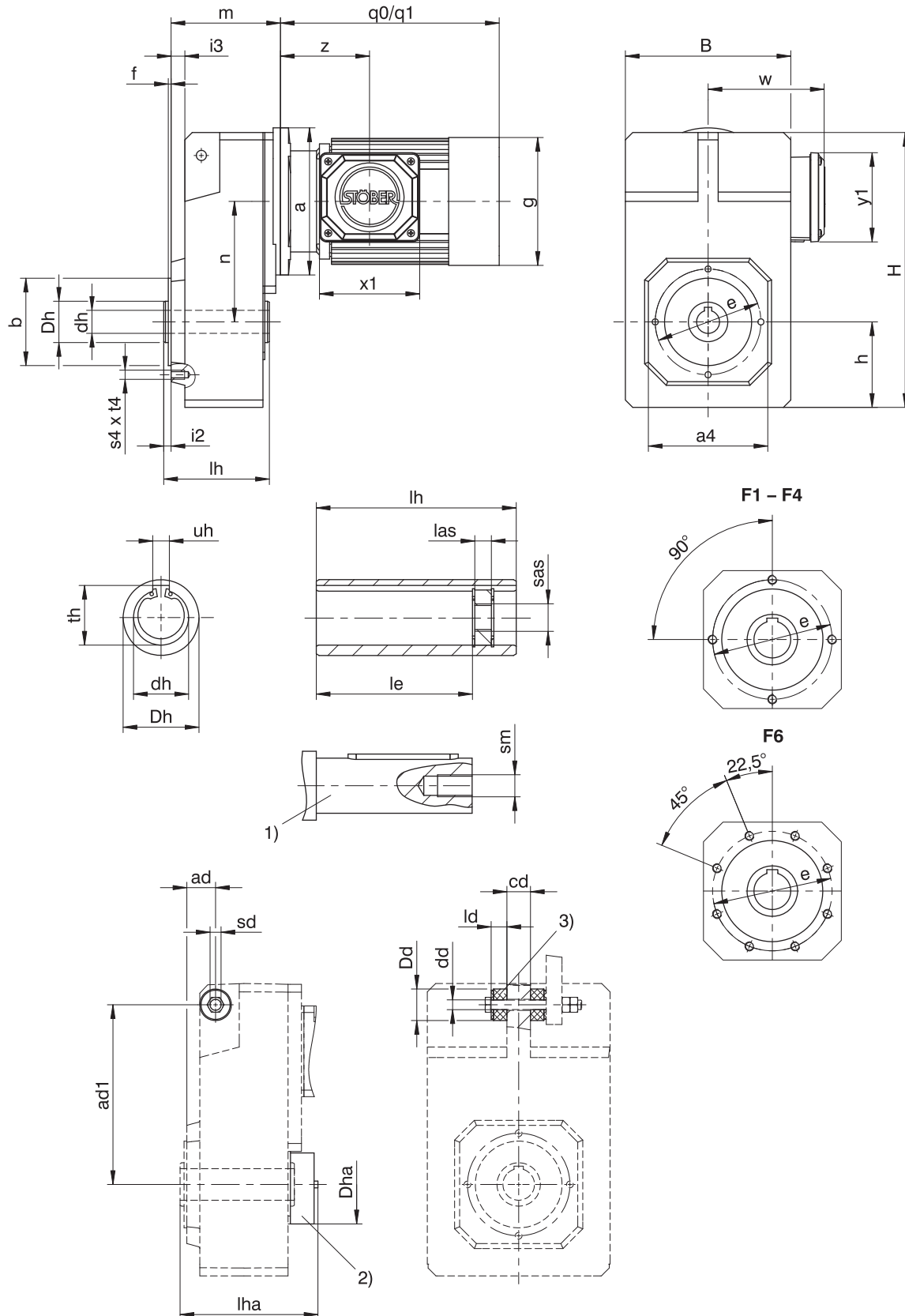
Hollow shaft	Tolerance
Hollow shaft hole fit	ISO H7
Feather keys	DIN 6885-1, high form

Flange	Pilot tolerance
Up to 300 mm	ISO j6
Starting at 350 mm	ISO h6

Centering holes in solid shafts in accordance with DIN 332-2, DR shape

Thread size	M4	M5	M6	M8	M10	M12	M16	M20	M24
Thread depth [mm]	10	12.5	16	19	22	28	36	42	50

3.3.1 A shaft design (hollow shaft), G housing design (pitch circle diameter)



- | | | | |
|----|---|----|-------------------------------|
| q0 | Applies to motors without brake. | q1 | Applies to motors with brake. |
| 1) | The length of the machine shaft must be at least 2.2 x $\varnothing dh$ and the length of the feather key must be at least 2 x $\varnothing dh$. | 2) | Cover (optional) |
| 3) | Rubber buffer for torque arm bracket (optional). Dimension $\varnothing Dd$ = outer diameter of the rubber buffer when not tensioned. | | |

Dimensions of gear units

Type	□a4	ad	ad1	Øb	B	cd	Ødd	Ødh	ØDd	ØDh	ØDha	Øe	f	h	H	i2	i3	ld	le	lh	las	lha	s4	sd	sm	sas	t4	th	uh
F1	100	28.5	150	70 _{js}	145	20	11 ^{+0.5}	20 ^{H7}	30	35	70	85	2.5	74	238.0	6.5	12.5	15	73	95	12	112	M8	M10	M6	M8	13	22.8	6 ^{JS9}
F2	130	32.0	181	95 _{js}	180	22	11 ^{+0.5}	25 ^{H7}	30	45	82	115	3.0	93	299.0	8.0	15.0	15	92	115	12	132	M8	M10	M10	M12	13	28.3	8 ^{JS9}
F3	150	36.5	205	110 _{js}	206	30	14 ^{+0.5}	30 ^{H7}	37	50	88	130	3.5	106	335.5	8.5	16.5	20	103	130	12	157	M10	M12	M10	M12	16	33.3	8 ^{JS9}
F4	150	36.5	228	110 _{js}	230	30	14 ^{+0.5}	40 ^{H7}	37	55	100	130	3.5	116	370.0	8.5	16.5	20	114	145	12	175	M10	M12	M16	M20	16	43.3	12 ^{JS9}
F6	180	44.5	270	130 _{js}	265	35	22 ^{+0.5}	50 ^{H7}	60	70	115	165	3.5	137	433.0	10.5	20.5	30	143	180	12	194	M10	M20	M16	M20	16	53.8	14 ^{JS9}

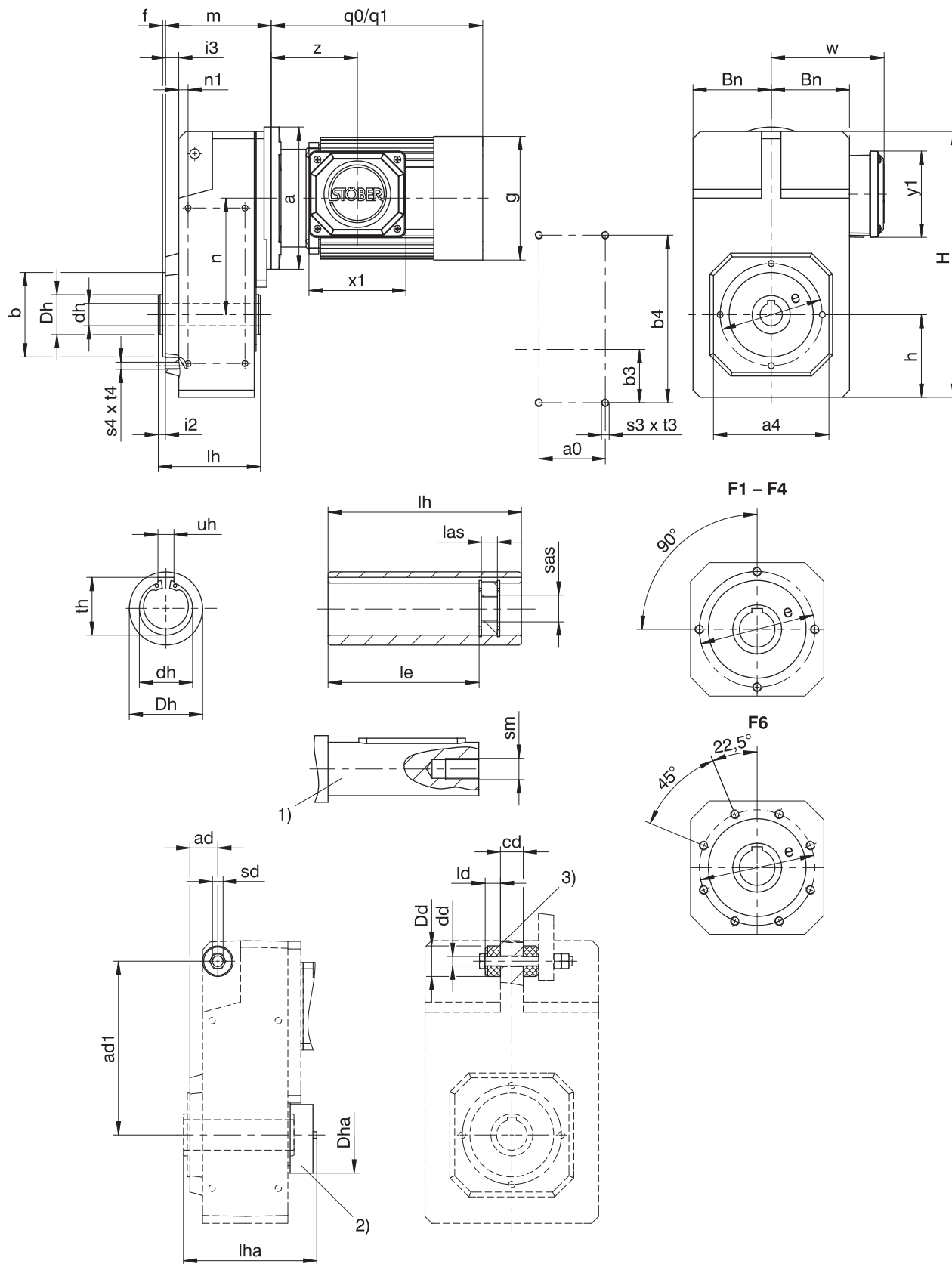
Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100			IE3D112			IE3D132		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
F102	Ø140	97.5	102.0	Ø140	97.5	102.0	Ø160	101.5	102.0	Ø160	101.5	102.0	-	-	-	-	-	-	-	-	-
F202	Ø140	115.0	131.0	Ø140	115.0	131.0	Ø160	119.0	131.0	Ø160	119.0	131.0	Ø200	121.0	131.0	Ø200	121.0	131.0	-	-	-
F203	Ø140	152.0	131.0	Ø140	152.0	131.0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
F302	Ø140	129.5	149.5	Ø140	129.5	149.5	Ø160	133.5	149.5	Ø160	133.5	149.5	Ø200	135.5	149.5	Ø200	135.5	149.5	-	-	-
F303	Ø140	166.5	149.5	Ø140	166.5	149.5	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
F402	-	-	-	-	-	-	Ø160	148.5	169.0	Ø160	148.5	169.0	Ø200	150.5	169.0	Ø200	150.5	169.0	Ø250	153.5	169.0
F403	-	-	-	Ø140	181.5	169.0	Ø160	191.5	132.0	-	-	-	-	-	-	-	-	-	-	-	-
F602	-	-	-	-	-	-	Ø160	179.5	196.0	Ø160	179.5	196.0	Ø200	181.5	196.0	Ø200	181.5	196.0	Ø250	184.5	196.0
F603	-	-	-	-	-	-	Ø160	222.5	196.0	Ø160	222.5	196.0	-	-	-	-	-	-	-	-	-

3.3.2 A shaft design (hollow shaft), GN housing design (pitch circle diameter + side fastening)



- | | | | |
|-------|---|-------|-------------------------------|
| q_0 | Applies to motors without brake. | q_1 | Applies to motors with brake. |
| 1) | The length of the machine shaft must be at least $2.2 \times \varnothing dh$ and the length of the feather key must be at least $2 \times \varnothing dh$. | 2) | Cover (optional) |
| 3) | Rubber buffer for torque arm bracket (optional). Dimension $\varnothing D_d$ = outer diameter of the rubber buffer when not tensioned. | | |

Dimensions of gear units

Type	a0	□a4	ad	ad1	Øb	b3	b4	Bn	cd	Ødd	Ødh	ØDd	ØDh	ØDha	Øe	f	h	H
F1	50	100	28.5	150	70 _{f6}	40	140	71	20	11 ^{+0.5}	20 ^{H7}	30	35	70	85	2.5	74	238.0
F2	64	130	32.0	181	95 _{f6}	55	175	88	22	11 ^{+0.5}	25 ^{H7}	30	45	82	115	3.0	93	299.0
F3	72	150	36.5	205	110 _{f6}	60	200	102	30	14 ^{+0.5}	30 ^{H7}	37	50	88	130	3.5	106	335.5
F4	87	150	36.5	228	110 _{f6}	70	220	114	30	14 ^{+0.5}	40 ^{H7}	37	55	100	130	3.5	116	370.0
F6	108	180	44.5	270	130 _{f6}	85	270	131	35	22 ^{+0.5}	50 ^{H7}	60	70	115	165	3.5	137	433.0

Type	i2	i3	ld	le	lh	las	lha	n1	s3	s4	sd	sm	sas	t3	t4	th	uh
F1	6.5	12.5	15	73	95	12	112	10.0	M6	M8	M10	M6	M8	11	13	22.8	6 ^{JS9}
F2	8.0	15.0	15	92	115	12	132	10.5	M8	M8	M10	M10	M12	13	13	28.3	8 ^{JS9}
F3	8.5	16.5	20	103	130	12	157	12.5	M10	M10	M12	M10	M12	16	16	33.3	8 ^{JS9}
F4	8.5	16.5	20	114	145	12	175	12.5	M10	M10	M12	M16	M20	16	16	43.3	12 ^{JS9}
F6	10.5	20.5	30	143	180	12	194	15.5	M12	M10	M20	M16	M20	19	16	53.8	14 ^{JS9}

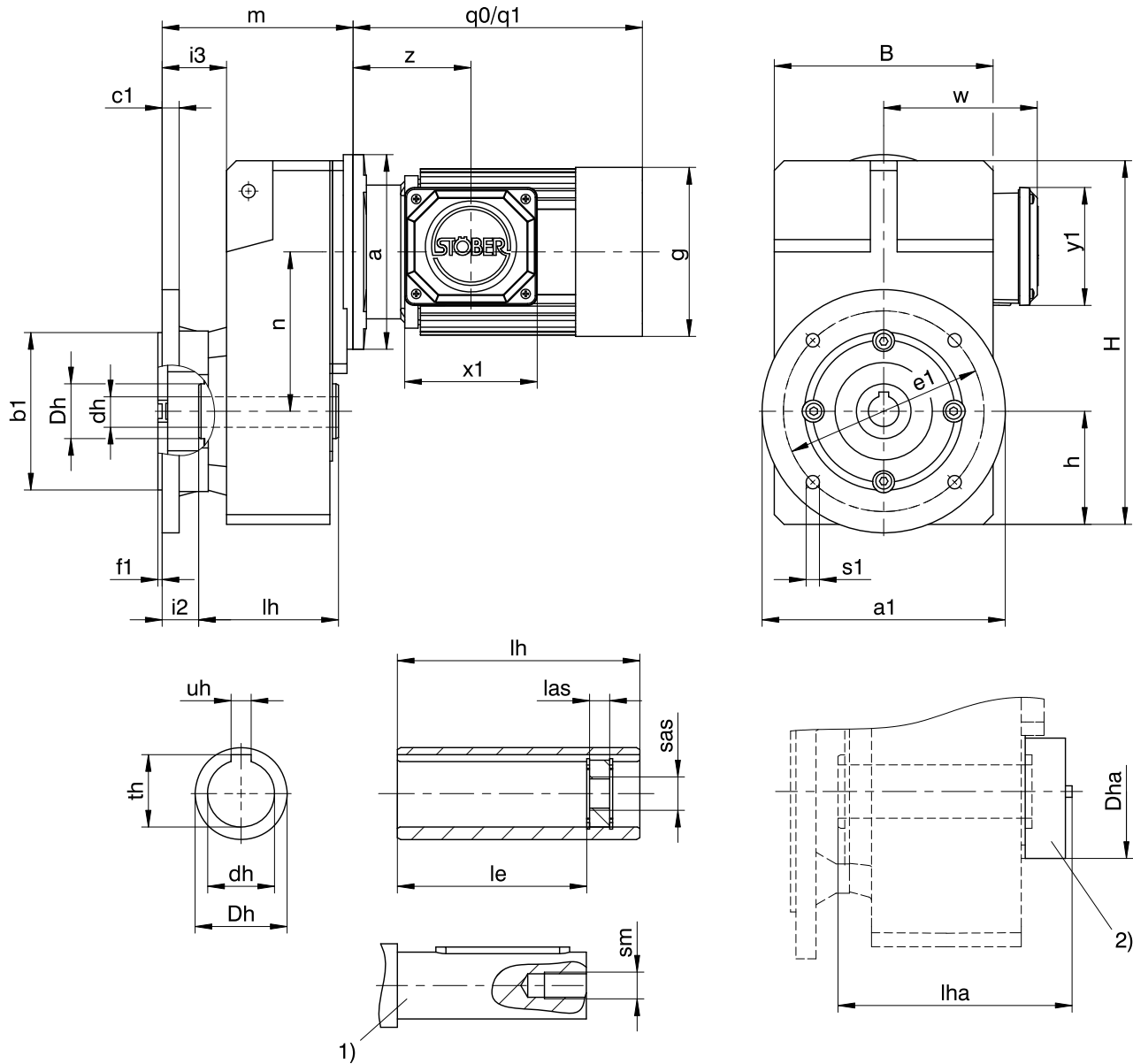
Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100			IE3D112			IE3D132		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
F102	Ø140	97.5	102.0	Ø140	97.5	102.0	Ø160	101.5	102.0	Ø160	101.5	102.0	-	-	-	-	-	-	-	-	-
F202	Ø140	115.0	131.0	Ø140	115.0	131.0	Ø160	119.0	131.0	Ø160	119.0	131.0	Ø200	121.0	131.0	Ø200	121.0	131.0	-	-	-
F203	Ø140	152.0	131.0	Ø140	152.0	131.0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
F302	Ø140	129.5	149.5	Ø140	129.5	149.5	Ø160	133.5	149.5	Ø160	133.5	149.5	Ø200	135.5	149.5	Ø200	135.5	149.5	-	-	-
F303	Ø140	166.5	149.5	Ø140	166.5	149.5	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
F402	-	-	-	-	-	-	Ø160	148.5	169.0	Ø160	148.5	169.0	Ø200	150.5	169.0	Ø200	150.5	169.0	Ø250	153.5	169.0
F403	-	-	-	Ø140	181.5	169.0	Ø160	191.5	132.0	-	-	-	-	-	-	-	-	-	-	-	-
F602	-	-	-	-	-	-	Ø160	179.5	196.0	Ø160	179.5	196.0	Ø200	181.5	196.0	Ø200	181.5	196.0	Ø250	184.5	196.0
F603	-	-	-	-	-	-	Ø160	222.5	196.0	Ø160	222.5	196.0	-	-	-	-	-	-	-	-	-

3.3.3 A shaft design (hollow shaft), F housing design (round flange)



q0 Applies to motors without brake.

q1 Applies to motors with brake.

1) The length of the machine shaft must be at least 2.2 x $\varnothing dh$ and the length of the feather key must be at least 2 x $\varnothing dh$.

2) Cover (optional)

Dimensions of gear units

Type	$\varnothing a1$	$\varnothing b1$	B	c1	$\varnothing dh$	$\varnothing Dh$	$\varnothing Dha$	$\varnothing e1$	f1	h	H	i2	i3	le	lh	las	lha	$\varnothing s1$	sm	sas	th	uh
F1	160	110 _{f6}	145	10	20 ^{H7}	35	70	130	3.5	74	238.0	25.5	44.5	73	95	12	112	9	M6	M8	22.8	6 ^{JS9}
F2	200	130 _{f6}	180	14	25 ^{H7}	45	82	165	3.5	93	299.0	30.0	53.0	92	115	12	132	11	M10	M12	28.3	8 ^{JS9}
F3	250	180 _{f6}	206	15	30 ^{H7}	50	88	215	4.0	106	335.5	31.5	56.5	103	130	12	157	14	M10	M12	33.3	8 ^{JS9}
F4	250	180 _{f6}	230	15	40 ^{H7}	55	100	215	4.0	116	370.0	31.5	56.5	114	145	12	175	14	M16	M20	43.3	12 ^{JS9}
F6	300	230 _{f6}	265	17	50 ^{H7}	70	115	265	4.0	137	433.0	29.5	60.5	143	180	12	194	14	M16	M20	53.8	14 ^{JS9}

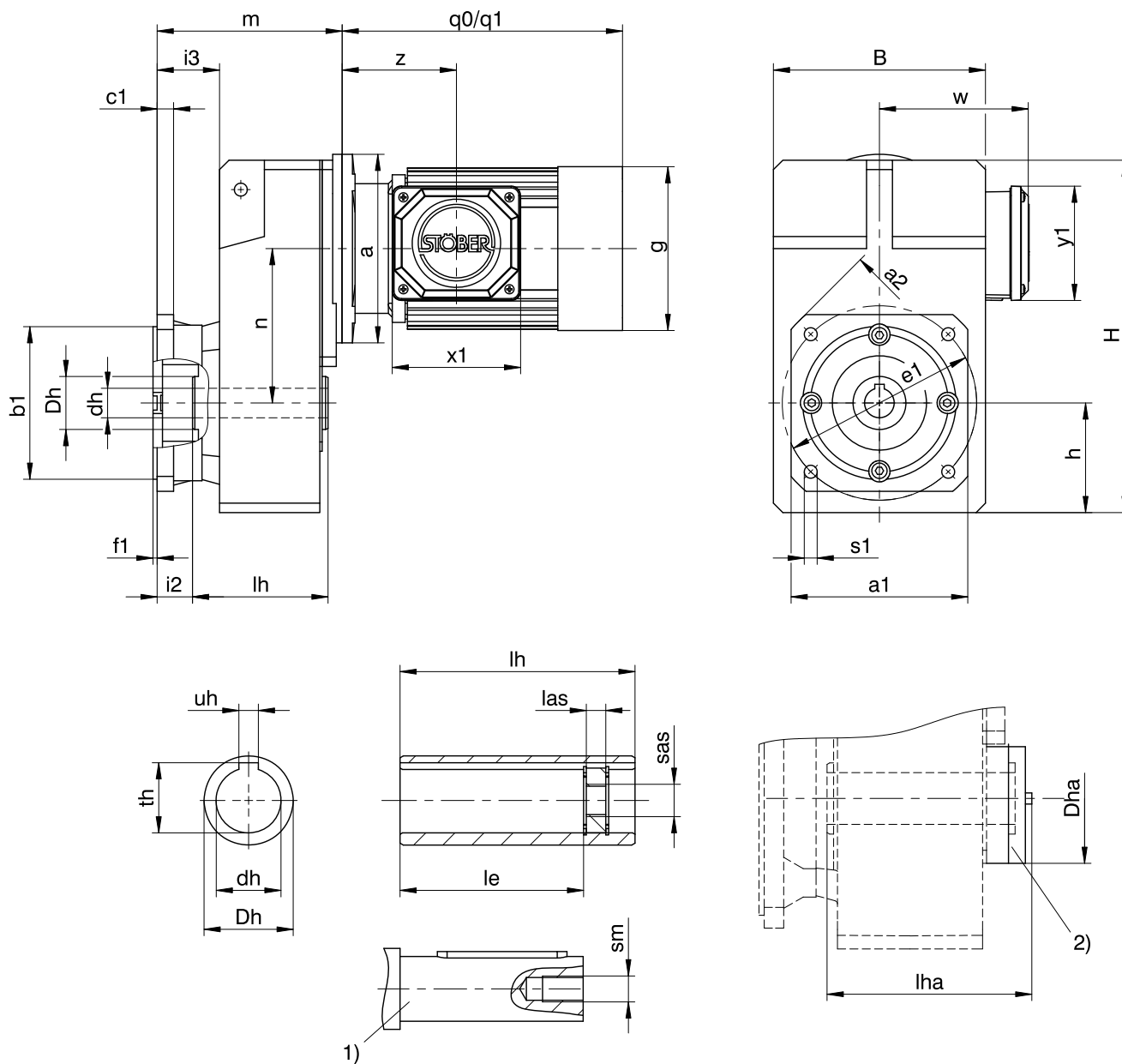
Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100			IE3D112			IE3D132			
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	
F102	∅140	129.5	102.0	∅140	129.5	102.0	∅160	133.5	102.0	∅160	133.5	102.0	-	-	-	-	-	-	-	-	-	-
F202	∅140	153.0	131.0	∅140	153.0	131.0	∅160	157.0	131.0	∅160	157.0	131.0	∅200	159.0	131.0	∅200	159.0	131.0	-	-	-	-
F203	∅140	190.0	131.0	∅140	190.0	131.0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
F302	∅140	169.5	149.5	∅140	169.5	149.5	∅160	173.5	149.5	∅160	173.5	149.5	∅200	175.5	149.5	∅200	175.5	149.5	-	-	-	-
F303	∅140	206.5	149.5	∅140	206.5	149.5	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
F402	-	-	-	-	-	-	∅160	188.5	169.0	∅160	188.5	169.0	∅200	190.5	169.0	∅200	190.5	169.0	∅250	193.5	169.0	-
F403	-	-	-	∅140	221.5	169.0	∅160	231.5	132.0	-	-	-	-	-	-	-	-	-	-	-	-	-
F602	-	-	-	-	-	-	∅160	219.5	196.0	∅160	219.5	196.0	∅200	221.5	196.0	∅200	221.5	196.0	∅250	224.5	196.0	-
F603	-	-	-	-	-	-	∅160	262.5	196.0	∅160	262.5	196.0	-	-	-	-	-	-	-	-	-	-

3.3.4 A shaft design (hollow shaft), Q housing design (square flange)



q0 Applies to motors without brake.

q1 Applies to motors with brake.

1) The length of the machine shaft must be at least 2.2 x $\varnothing dh$ and the length of the feather key must be at least 2 x $\varnothing dh$.

2) Cover (optional)

Dimensions of gear units

Type	□a1	□a2	∅b1	B	c1	∅dh	∅Dh	∅Dha	∅e1	f1	h	H	i2	i3	le	lh	las	lha	∅s1	sm	sas	th	uh
F1	125	160	110 _{f8}	145	10	20 ^{H7}	35	70	130	3.5	74	238.0	25.5	44.5	73	95	12	112	9	M6	M8	22.8	6 ^{JS9}
F2	150	195	130 _{f8}	180	14	25 ^{H7}	45	82	165	3.5	93	299.0	30.0	53.0	92	115	12	132	11	M10	M12	28.3	8 ^{JS9}
F3	200	260	180 _{f8}	206	15	30 ^{H7}	50	88	215	4.0	106	335.5	31.5	56.5	103	130	12	157	14	M10	M12	33.3	8 ^{JS9}
F4	200	260	180 _{f8}	230	15	40 ^{H7}	55	100	215	4.0	116	370.0	31.5	56.5	114	145	12	175	14	M16	M20	43.3	12 ^{JS9}
F6	250	325	230 _{f8}	265	17	50 ^{H7}	70	115	265	4.0	137	433.0	29.5	60.5	143	180	12	194	14	M16	M20	53.8	14 ^{JS9}

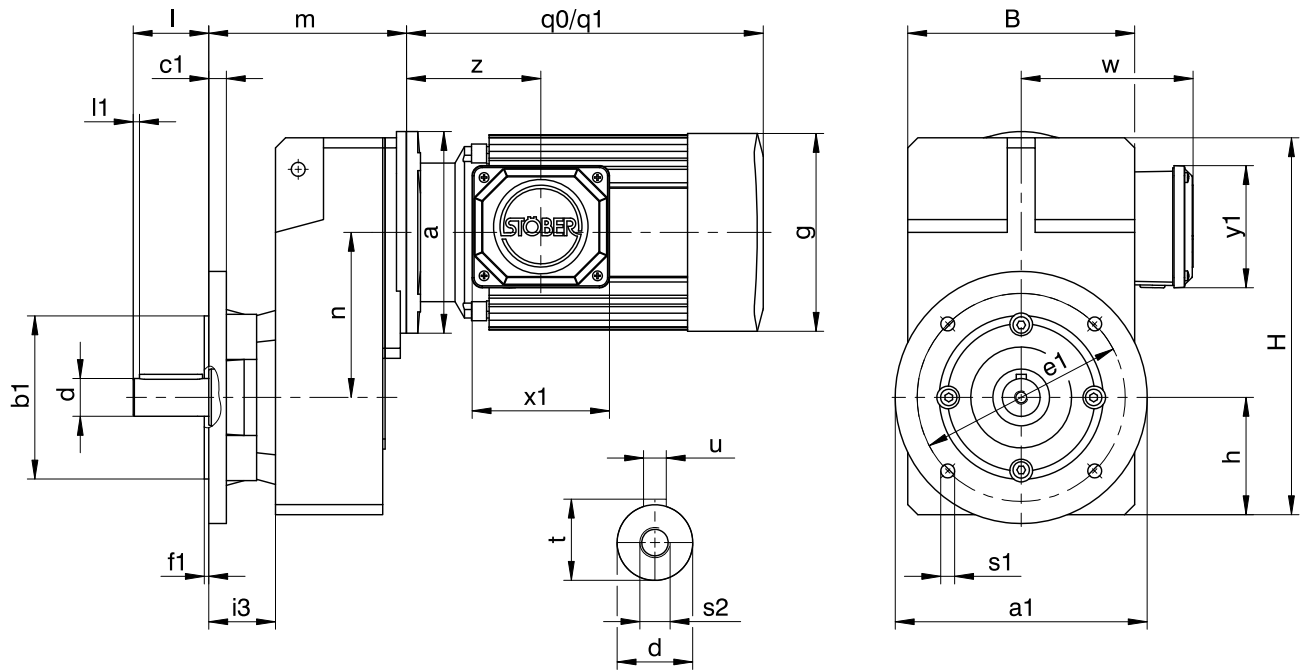
Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100			IE3D112			IE3D132			
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	
F102	∅140	129.5	102.0	∅140	129.5	102.0	∅160	133.5	102.0	∅160	133.5	102.0	-	-	-	-	-	-	-	-	-	-
F202	∅140	153.0	131.0	∅140	153.0	131.0	∅160	157.0	131.0	∅160	157.0	131.0	∅200	159.0	131.0	∅200	159.0	131.0	-	-	-	-
F203	∅140	190.0	131.0	∅140	190.0	131.0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
F302	∅140	169.5	149.5	∅140	169.5	149.5	∅160	173.5	149.5	∅160	173.5	149.5	∅200	175.5	149.5	∅200	175.5	149.5	-	-	-	-
F303	∅140	206.5	149.5	∅140	206.5	149.5	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
F402	-	-	-	-	-	-	∅160	188.5	169.0	∅160	188.5	169.0	∅200	190.5	169.0	∅200	190.5	169.0	∅250	193.5	169.0	-
F403	-	-	-	∅140	221.5	169.0	∅160	231.5	132.0	-	-	-	-	-	-	-	-	-	-	-	-	-
F602	-	-	-	-	-	-	∅160	219.5	196.0	∅160	219.5	196.0	∅200	221.5	196.0	∅200	221.5	196.0	∅250	224.5	196.0	-
F603	-	-	-	-	-	-	∅160	262.5	196.0	∅160	262.5	196.0	-	-	-	-	-	-	-	-	-	-

3.3.5 V shaft design (solid shaft), F housing design (round flange)



q0 Applies to motors without brake.

q1 Applies to motors with brake.

Dimensions of gear units

Type	Øa1	Øb1	B	c1	Ød	Øe1	f1	h	H	i3	l	l1	Øs1	s2	t	u
F1	160	110 _{js}	145	10	25 _{ks}	130	3.5	74	238.0	44.5	50	5	9	M10	28.0	A8×7×40
F2	200	130 _{js}	180	14	30 _{ks}	165	3.5	93	299.0	53.0	60	5	11	M10	33.0	A8×7×50
F3	250	180 _{js}	206	15	35 _{ks}	215	4.0	106	335.5	56.5	70	5	14	M12	38.0	A10×8×60
F4	250	180 _{js}	230	15	40 _{ks}	215	4.0	116	370.0	56.5	80	5	14	M16	43.0	A12×8×70
F6	300	230 _{js}	265	17	50 _{ks}	265	4.0	137	433.0	60.5	100	5	14	M16	53.5	A14×9×90

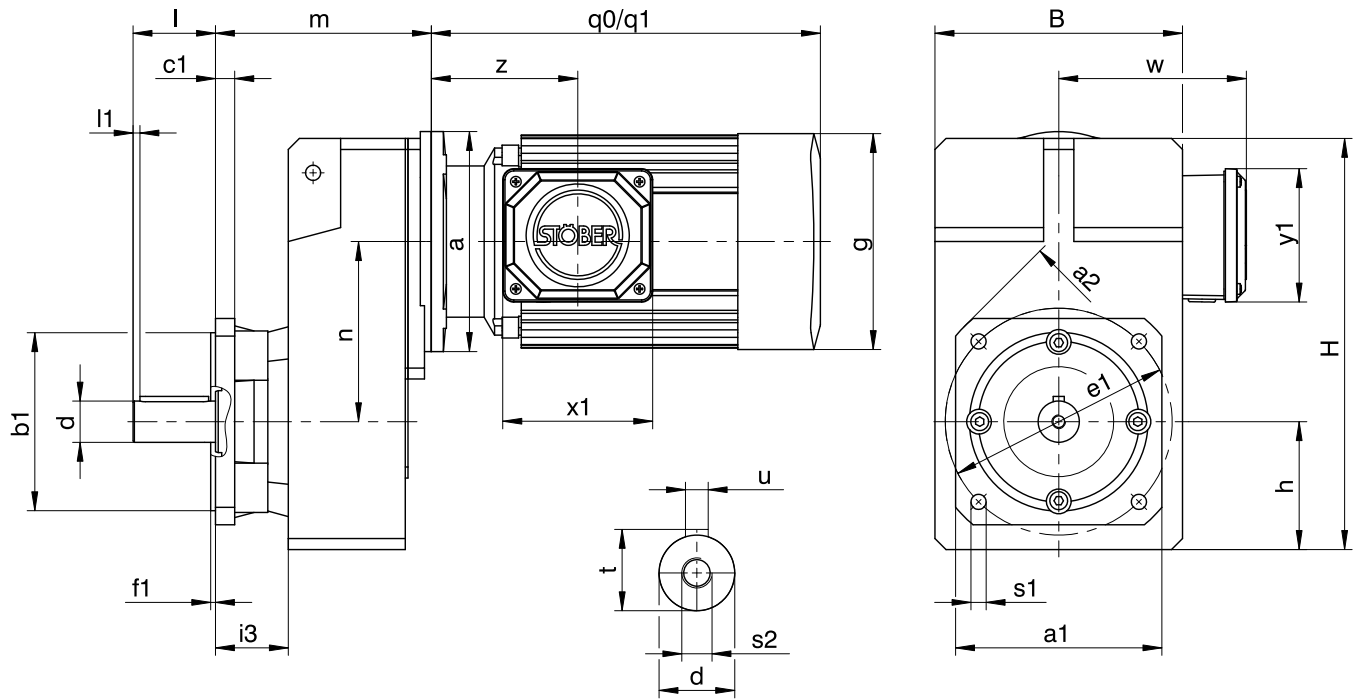
Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100			IE3D112			IE3D132			
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	
F102	Ø140	129.5	102.0	Ø140	129.5	102.0	Ø160	133.5	102.0	Ø160	133.5	102.0	-	-	-	-	-	-	-	-	-	-
F202	Ø140	153.0	131.0	Ø140	153.0	131.0	Ø160	157.0	131.0	Ø160	157.0	131.0	Ø200	159.0	131.0	Ø200	159.0	131.0	-	-	-	-
F203	Ø140	190.0	131.0	Ø140	190.0	131.0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
F302	Ø140	169.5	149.5	Ø140	169.5	149.5	Ø160	173.5	149.5	Ø160	173.5	149.5	Ø200	175.5	149.5	Ø200	175.5	149.5	-	-	-	-
F303	Ø140	206.5	149.5	Ø140	206.5	149.5	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
F402	-	-	-	-	-	-	Ø160	188.5	169.0	Ø160	188.5	169.0	Ø200	190.5	169.0	Ø200	190.5	169.0	Ø250	193.5	169.0	-
F403	-	-	-	Ø140	221.5	169.0	Ø160	231.5	132.0	-	-	-	-	-	-	-	-	-	-	-	-	-
F602	-	-	-	-	-	-	Ø160	219.5	196.0	Ø160	219.5	196.0	Ø200	221.5	196.0	Ø200	221.5	196.0	Ø250	224.5	196.0	-
F603	-	-	-	-	-	-	Ø160	262.5	196.0	Ø160	262.5	196.0	-	-	-	-	-	-	-	-	-	-

3.3.6 V shaft design (solid shaft), Q housing design (square flange)



q0 Applies to motors without brake.

q1 Applies to motors with brake.

Dimensions of gear units

Type	□a1	□a2	∅b1	c1	B	∅d	∅e1	f1	h	H	i3	l	l1	∅s1	s2	t	u
F1	125	160	110 _{f6}	10	145	25 _{k6}	130	3.5	74	238.0	44.5	50	5	9	M10	28.0	A8×7×40
F2	150	195	130 _{f6}	14	180	30 _{k6}	165	3.5	93	299.0	53.0	60	5	11	M10	33.0	A8×7×50
F3	200	260	180 _{f6}	15	206	35 _{k6}	215	4.0	106	335.5	56.5	70	5	14	M12	38.0	A10×8×60
F4	200	260	180 _{f6}	15	230	40 _{k6}	215	4.0	116	370.0	56.5	80	5	14	M16	43.0	A12×8×70
F6	250	325	230 _{f6}	17	265	50 _{k6}	265	4.0	137	433.0	60.5	100	5	14	M16	53.5	A14×9×90

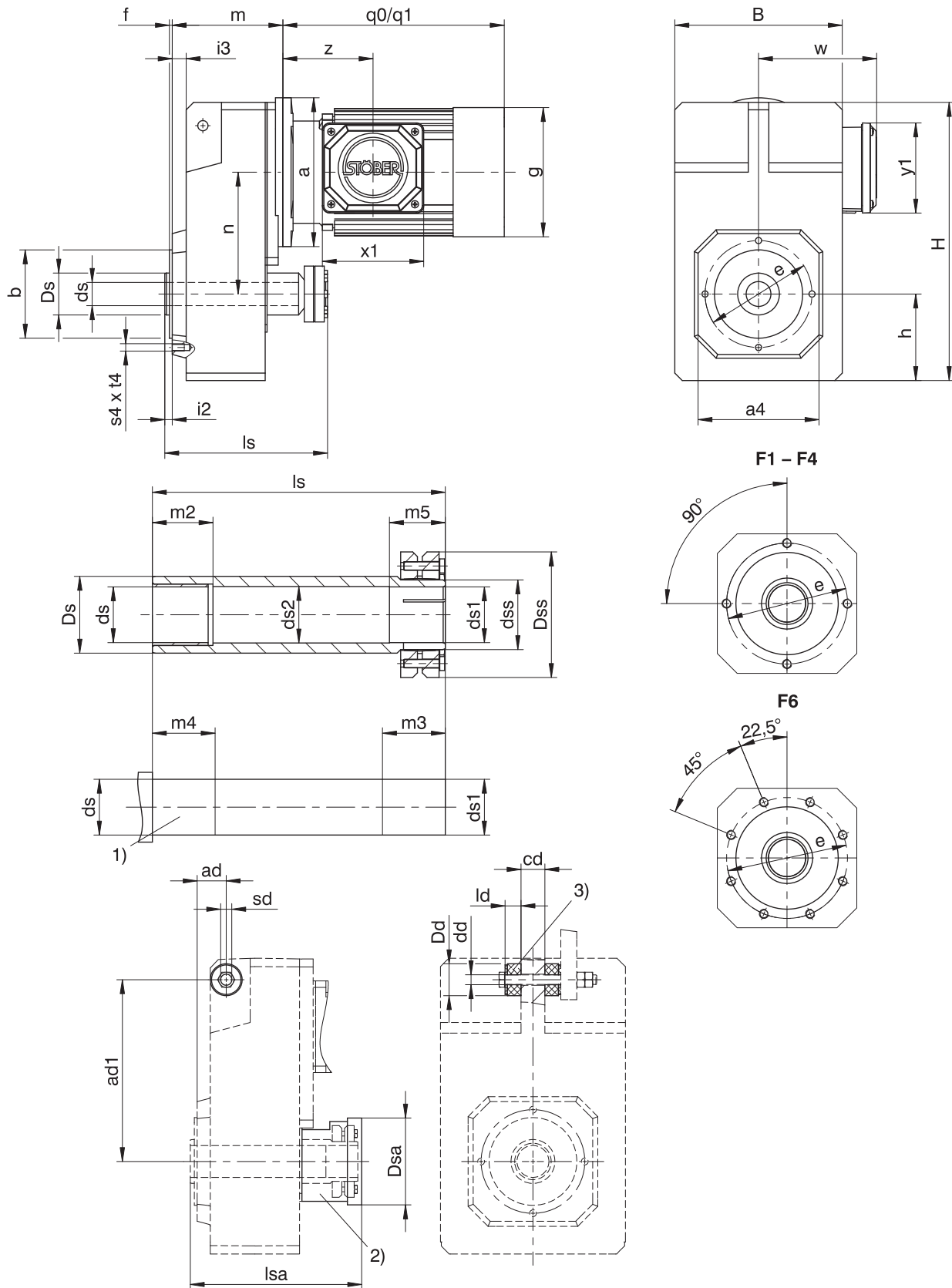
Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100			IE3D112			IE3D132		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
F102	∅140	129.5	102.0	∅140	129.5	102.0	∅160	133.5	102.0	∅160	133.5	102.0	-	-	-	-	-	-	-	-	-
F202	∅140	153.0	131.0	∅140	153.0	131.0	∅160	157.0	131.0	∅160	157.0	131.0	∅200	159.0	131.0	∅200	159.0	131.0	-	-	-
F203	∅140	190.0	131.0	∅140	190.0	131.0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
F302	∅140	169.5	149.5	∅140	169.5	149.5	∅160	173.5	149.5	∅160	173.5	149.5	∅200	175.5	149.5	∅200	175.5	149.5	-	-	-
F303	∅140	206.5	149.5	∅140	206.5	149.5	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
F402	-	-	-	-	-	-	∅160	188.5	169.0	∅160	188.5	169.0	∅200	190.5	169.0	∅200	190.5	169.0	∅250	193.5	169.0
F403	-	-	-	∅140	221.5	169.0	∅160	231.5	132.0	-	-	-	-	-	-	-	-	-	-	-	-
F602	-	-	-	-	-	-	∅160	219.5	196.0	∅160	219.5	196.0	∅200	221.5	196.0	∅200	221.5	196.0	∅250	224.5	196.0
F603	-	-	-	-	-	-	∅160	262.5	196.0	∅160	262.5	196.0	-	-	-	-	-	-	-	-	-

3.3.7 S shaft design (hollow shaft with shrink disk), G housing design (pitch circle diameter)



- | | | | |
|----|--|----|-------------------------------|
| q0 | Applies to motors without brake. | q1 | Applies to motors with brake. |
| 1) | Machine shaft: The dimension l_s must meet or exceed the specified value. | 2) | Cover (optional) |
| 3) | Rubber buffer for torque arm bracket (optional). Dimension $\varnothing D_d$ = outer diameter of the rubber buffer when not tensioned. | | |

Dimensions of gear units

Type	a4	ad	ad1	Øb	B	cd	Ødd	Øds	Øds1	Øds2	Ødss	ØDd	ØDs	ØDsa	ØDss	Øe	f	h	H	i2	i3	ld	ls	lsa	m2	m3	m4	m5	s4	sd	t4
F1	100	28.5	150	70 _f	145	20	11 ^{+0.5}	20 _{h9}	20 _{h9} ^{H7}	20.5	24	30	35	63	50	85	2.5	74	238.0	6.5	12.5	15	146	150	20	31	25	26	M8	M10	13
F2	130	32.0	181	95 _f	180	22	11 ^{+0.5}	25 _{h9}	25 _{h9} ^{H7}	25.5	30	30	45	73	60	115	3.0	93	299.0	8.0	15.0	15	175	180	20	37	25	32	M8	M10	13
F3	150	36.5	205	110 _f	206	30	14 ^{+0.5}	30 _{h9}	30 _{h9} ^{H7}	30.5	36	37	50	83	72	130	3.5	106	335.5	8.5	16.5	20	192	196	25	37	30	32	M10	M12	16
F4	150	36.5	228	110 _f	230	30	14 ^{+0.5}	40 _{h9}	40 _{h9} ^{H7}	40.5	50	37	55	108	90	130	3.5	116	370.0	8.5	16.5	20	210	215	40	45	45	40	M10	M12	16
F6	180	44.5	270	130 _f	265	35	22 ^{+0.5}	50 _{h9}	50 _{h9} ^{H7}	50.5	62	60	70	128	106	165	3.5	137	433.0	10.5	20.5	30	248	251	40	47	45	42	M10	M20	16

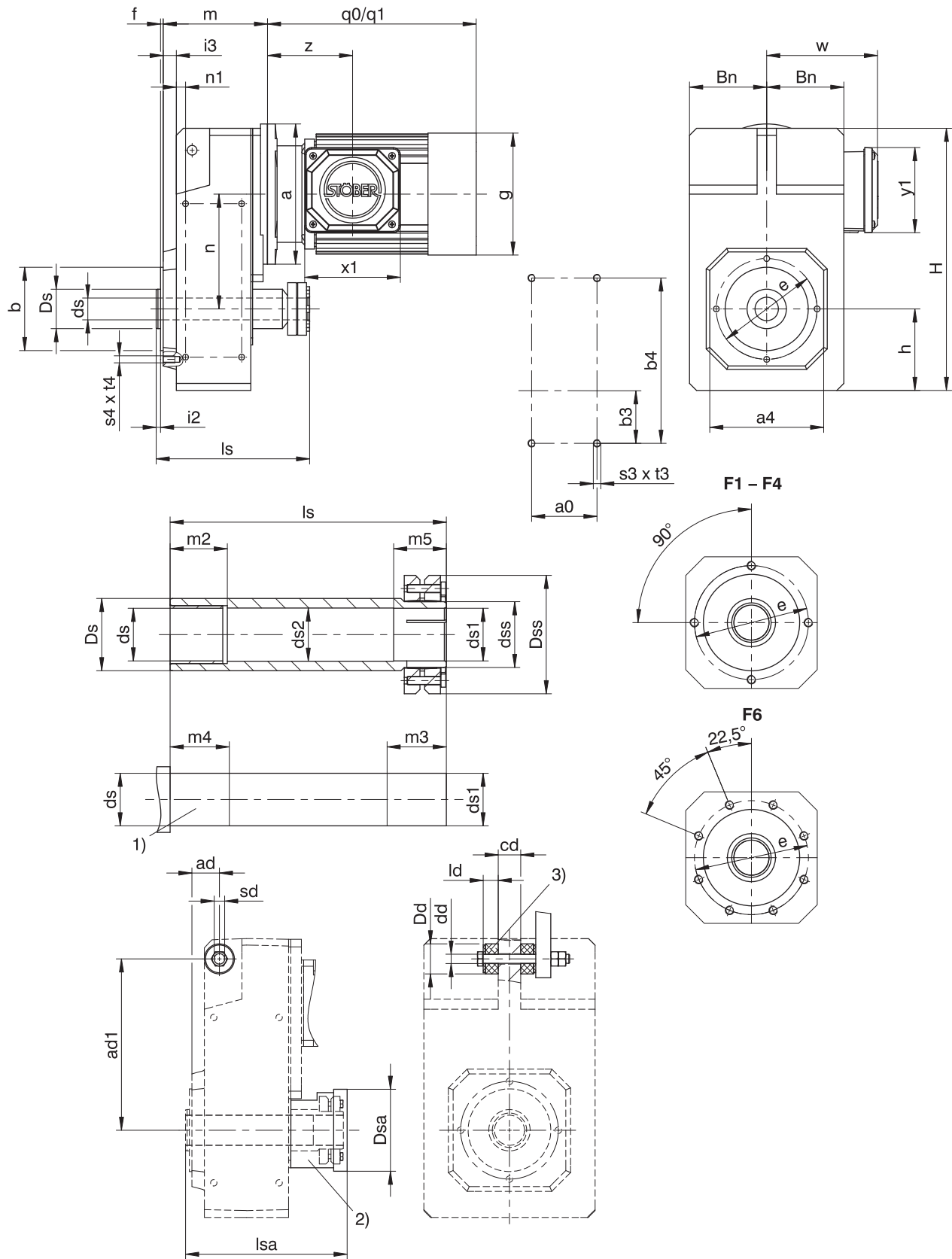
Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100			IE3D112			IE3D132		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
F102	Ø140	97.5	102.0	Ø140	97.5	102.0	Ø160	101.5	102.0	Ø160	101.5	102.0	-	-	-	-	-	-	-	-	-
F202	Ø140	115.0	131.0	Ø140	115.0	131.0	Ø160	119.0	131.0	Ø160	119.0	131.0	Ø200	121.0	131.0	Ø200	121.0	131.0	-	-	-
F203	Ø140	152.0	131.0	Ø140	152.0	131.0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
F302	Ø140	129.5	149.5	Ø140	129.5	149.5	Ø160	133.5	149.5	Ø160	133.5	149.5	Ø200	135.5	149.5	Ø200	135.5	149.5	-	-	-
F303	Ø140	166.5	149.5	Ø140	166.5	149.5	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
F402	-	-	-	-	-	-	Ø160	148.5	169.0	Ø160	148.5	169.0	Ø200	150.5	169.0	Ø200	150.5	169.0	Ø250	153.5	169.0
F403	-	-	-	Ø140	181.5	169.0	Ø160	191.5	132.0	-	-	-	-	-	-	-	-	-	-	-	-
F602	-	-	-	-	-	-	Ø160	179.5	196.0	Ø160	179.5	196.0	Ø200	181.5	196.0	Ø200	181.5	196.0	Ø250	184.5	196.0
F603	-	-	-	-	-	-	Ø160	222.5	196.0	Ø160	222.5	196.0	-	-	-	-	-	-	-	-	-

3.3.8 S shaft design (hollow shaft with shrink disk), GN housing design (pitch circle diameter + side fastening)



- | | | | |
|----|--|----|-------------------------------|
| q0 | Applies to motors without brake. | q1 | Applies to motors with brake. |
| 1) | Machine shaft: The dimension l_s must meet or exceed the specified value. | 2) | Cover (optional) |
| 3) | Rubber buffer for torque arm bracket (optional). Dimension $\varnothing D_d$ = outer diameter of the rubber buffer when not tensioned. | | |

Dimensions of gear units

Type	a0	□a4	ad	ad1	Øb	b3	b4	Bn	cd	Ødd	Øds	Øds1	Øds2	Ødss	ØDd	ØDs	ØDsa	ØDss
F1	50	100	28.5	150	70 _{f6}	40	140	71	20	11 ^{+0.5}	20 _{H9}	20 _{H9} ^{H7}	20.5	24	30	63	63	50
F2	64	130	32.0	181	95 _{f6}	55	175	88	22	11 ^{+0.5}	25 _{H9}	25 _{H9} ^{H7}	25.5	30	30	73	73	60
F3	72	150	36.5	205	110 _{f6}	60	200	102	30	14 ^{+0.5}	30 _{H9}	30 _{H9} ^{H7}	30.5	36	37	83	83	72
F4	87	150	36.5	228	110 _{f6}	70	220	114	30	14 ^{+0.5}	40 _{H9}	40 _{H9} ^{H7}	40.5	50	37	108	108	90
F6	108	180	44.5	270	130 _{f6}	85	270	131	35	22 ^{+0.5}	50 _{H9}	50 _{H9} ^{H7}	50.5	62	60	128	128	106

Type	Øe	f	h	H	i2	i3	ld	ls	lsa	n1	m2	m3	m4	m5	s3	s4	sd	t3	t4
F1	85	2.5	74	238.0	6.5	12.5	15	146	150	10	20	31	25	26	M6	M8	M10	11	13
F2	115	3.0	93	299.0	8.0	15.0	15	175	180	10.5	20	37	25	32	M8	M8	M10	13	13
F3	130	3.5	106	335.5	8.5	16.5	20	192	196	12.5	25	37	30	32	M10	M10	M12	16	16
F4	130	3.5	116	370.0	8.5	16.5	20	210	215	12.5	40	45	45	40	M10	M10	M12	16	16
F6	165	3.5	137	433.0	10.5	20.5	30	248	251	15.5	40	47	45	42	M12	M10	M20	19	16

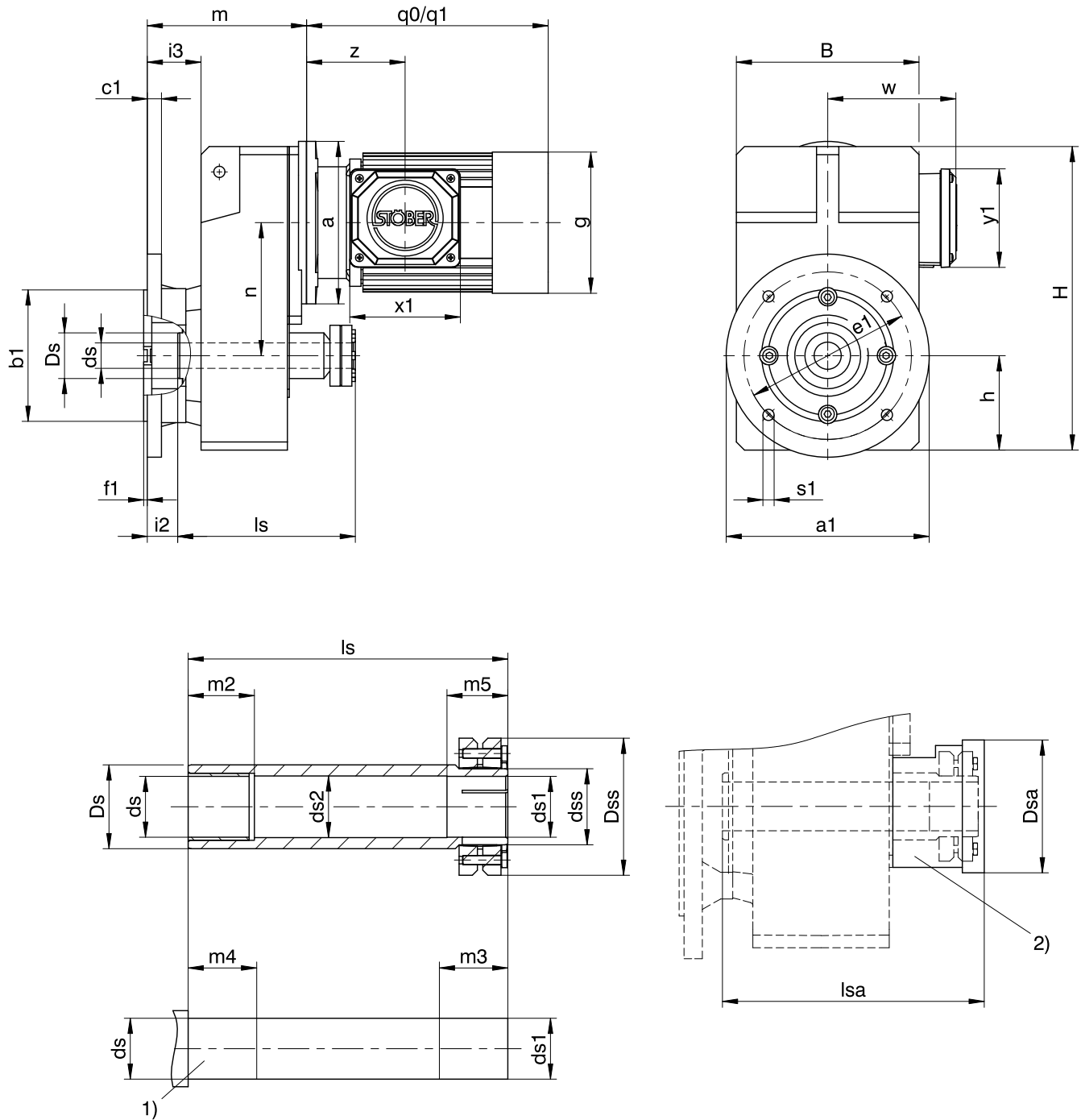
Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100			IE3D112			IE3D132			
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	
F102	Ø140	97.5	102.0	Ø140	97.5	102.0	Ø160	101.5	102.0	Ø160	101.5	102.0	-	-	-	-	-	-	-	-	-	-
F202	Ø140	115.0	131.0	Ø140	115.0	131.0	Ø160	119.0	131.0	Ø160	119.0	131.0	Ø200	121.0	131.0	Ø200	121.0	131.0	-	-	-	-
F203	Ø140	152.0	131.0	Ø140	152.0	131.0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
F302	Ø140	129.5	149.5	Ø140	129.5	149.5	Ø160	133.5	149.5	Ø160	133.5	149.5	Ø200	135.5	149.5	Ø200	135.5	149.5	-	-	-	-
F303	Ø140	166.5	149.5	Ø140	166.5	149.5	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
F402	-	-	-	-	-	-	Ø160	148.5	169.0	Ø160	148.5	169.0	Ø200	150.5	169.0	Ø200	150.5	169.0	Ø250	153.5	169.0	-
F403	-	-	-	Ø140	181.5	169.0	Ø160	191.5	132.0	-	-	-	-	-	-	-	-	-	-	-	-	-
F602	-	-	-	-	-	-	Ø160	179.5	196.0	Ø160	179.5	196.0	Ø200	181.5	196.0	Ø200	181.5	196.0	Ø250	184.5	196.0	-
F603	-	-	-	-	-	-	Ø160	222.5	196.0	Ø160	222.5	196.0	-	-	-	-	-	-	-	-	-	-

3.3.9 S shaft design (hollow shaft with shrink disk), F housing design (round flange)



q0 Applies to motors without brake.

q1 Applies to motors with brake.

1) Machine shaft: The dimension l_s must meet or exceed the specified value.

2) Cover (optional)

Dimensions of gear units

Type	Øa1	Øb1	B	c1	Øds	Øds1	Øds2	Ødss	ØDs	ØDsa	ØDss	Øe1	f1	h	H	i2	i3	ls	lsa	m2	m3	m4	m5	Øs1
F1	160	110 _{f6}	145	10	20 _{h9}	20 _{h9} ^{H7}	20.5	24	35	63	50	130	3.5	74	238.0	25.5	44.5	146	150	20	31	25	26	9
F2	200	130 _{f6}	180	14	25 _{h9}	25 _{h9} ^{H7}	25.5	30	45	73	60	165	3.5	93	299.0	30.0	53.0	175	180	20	37	25	32	11
F3	250	180 _{f6}	206	15	30 _{h9}	30 _{h9} ^{H7}	30.5	36	50	83	72	215	4.0	106	335.5	31.5	56.5	192	196	25	37	30	32	14
F4	250	180 _{f6}	230	15	40 _{h9}	40 _{h9} ^{H7}	40.5	50	55	108	90	215	4.0	116	370.0	31.5	56.5	210	215	40	45	45	40	14
F6	300	230 _{f6}	265	17	50 _{h9}	50 _{h9} ^{H7}	50.5	62	70	128	106	265	4.0	137	433.0	29.5	60.5	248	251	40	47	45	42	14

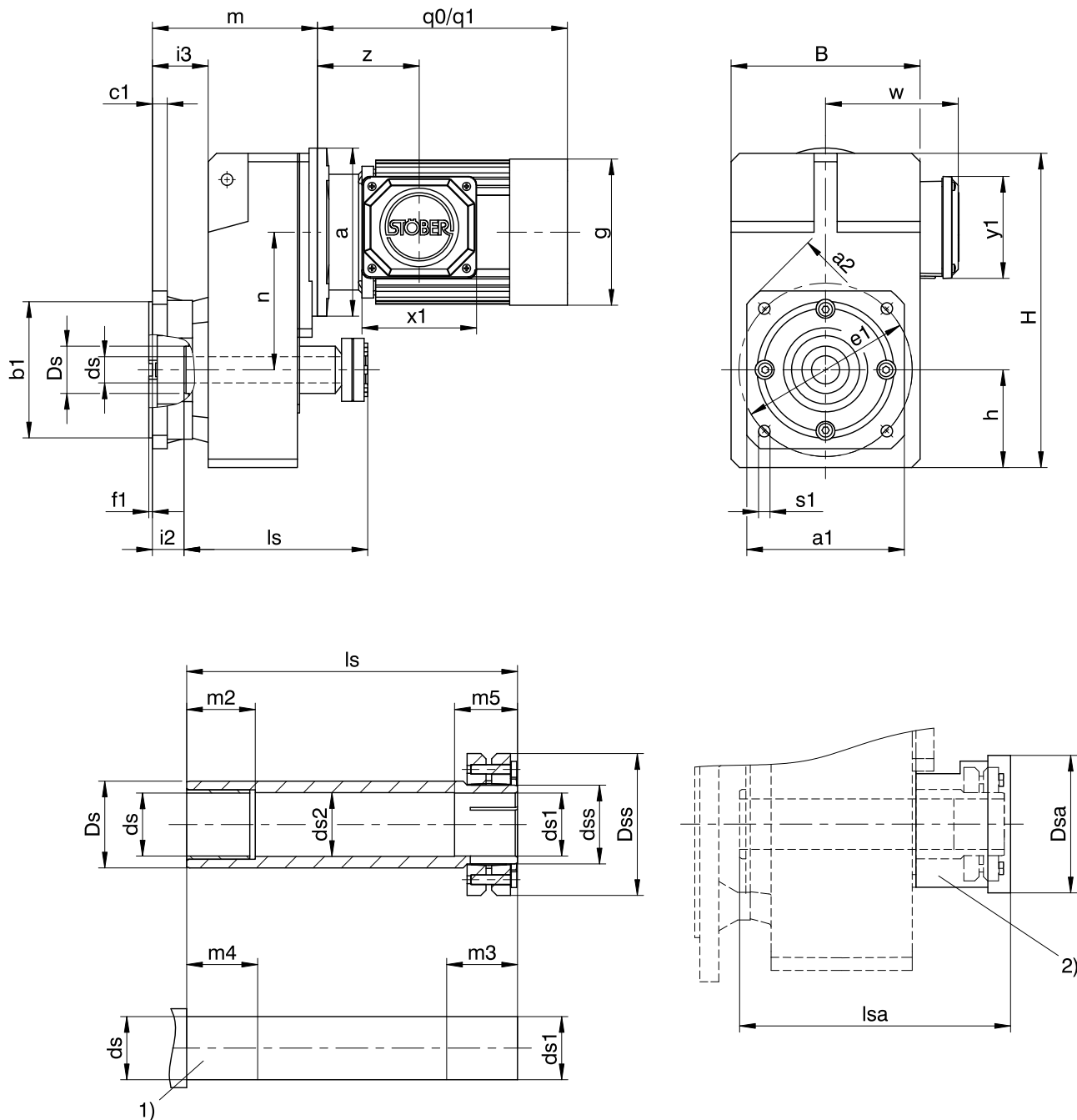
Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100			IE3D112			IE3D132			
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	
F102	Ø140	129.5	102.0	Ø140	129.5	102.0	Ø160	133.5	102.0	Ø160	133.5	102.0	-	-	-	-	-	-	-	-	-	-
F202	Ø140	153.0	131.0	Ø140	153.0	131.0	Ø160	157.0	131.0	Ø160	157.0	131.0	Ø200	159.0	131.0	Ø200	159.0	131.0	-	-	-	-
F203	Ø140	190.0	131.0	Ø140	190.0	131.0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
F302	Ø140	169.5	149.5	Ø140	169.5	149.5	Ø160	173.5	149.5	Ø160	173.5	149.5	Ø200	175.5	149.5	Ø200	175.5	149.5	-	-	-	-
F303	Ø140	206.5	149.5	Ø140	206.5	149.5	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
F402	-	-	-	-	-	-	Ø160	188.5	169.0	Ø160	188.5	169.0	Ø200	190.5	169.0	Ø200	190.5	169.0	Ø250	193.5	169.0	-
F403	-	-	-	Ø140	221.5	169.0	Ø160	231.5	132.0	-	-	-	-	-	-	-	-	-	-	-	-	-
F602	-	-	-	-	-	-	Ø160	219.5	196.0	Ø160	219.5	196.0	Ø200	221.5	196.0	Ø200	221.5	196.0	Ø250	224.5	196.0	-
F603	-	-	-	-	-	-	Ø160	262.5	196.0	Ø160	262.5	196.0	-	-	-	-	-	-	-	-	-	-

3.3.10 S shaft design (hollow shaft with shrink disk), Q housing design (square flange)



q0 Applies to motors without brake.

q1 Applies to motors with brake.

1) Machine shaft: The dimension ls must meet or exceed the specified value.

2) Cover (optional)

Dimensions of gear units

Type	$\square a1$	$\square a2$	$\varnothing b1$	B	c1	$\varnothing ds$	$\varnothing ds1$	$\varnothing ds2$	$\varnothing ds3$	$\varnothing Ds$	$\varnothing Dsa$	$\varnothing Dss$	$\varnothing e1$	f1	h	H	i2	i3	ls	lsa	m2	m3	m4	m5	$\varnothing s1$
F1	125	160	110 _{f6}	145	10	20 _{h9}	20 _{h9} ^{H7}	20.5	24	35	63	50	130	3.5	74	238.0	25.5	44.5	146	150	20	31	25	26	9
F2	150	195	130 _{f6}	180	14	25 _{h9}	25 _{h9} ^{H7}	25.5	30	45	73	60	165	3.5	93	299.0	30.0	53.0	175	180	20	37	25	32	11
F3	200	260	180 _{f6}	206	15	30 _{h9}	30 _{h9} ^{H7}	30.5	36	50	83	72	215	4.0	106	335.5	31.5	56.5	192	196	25	37	30	32	14
F4	200	260	180 _{f6}	230	15	40 _{h9}	40 _{h9} ^{H7}	40.5	50	55	108	90	215	4.0	116	370.0	31.5	56.5	210	215	40	45	45	40	14
F6	250	325	230 _{f6}	265	17	50 _{h9}	50 _{h9} ^{H7}	50.5	62	70	128	106	265	4.0	137	433.0	29.5	60.5	248	251	40	47	45	42	14

Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100			IE3D112			IE3D132		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
F102	∅140	129.5	102.0	∅140	129.5	102.0	∅160	133.5	102.0	∅160	133.5	102.0	-	-	-	-	-	-	-	-	-
F202	∅140	153.0	131.0	∅140	153.0	131.0	∅160	157.0	131.0	∅160	157.0	131.0	∅200	159.0	131.0	∅200	159.0	131.0	-	-	-
F203	∅140	190.0	131.0	∅140	190.0	131.0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
F302	∅140	169.5	149.5	∅140	169.5	149.5	∅160	173.5	149.5	∅160	173.5	149.5	∅200	175.5	149.5	∅200	175.5	149.5	-	-	-
F303	∅140	206.5	149.5	∅140	206.5	149.5	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
F402	-	-	-	-	-	-	∅160	188.5	169.0	∅160	188.5	169.0	∅200	190.5	169.0	∅200	190.5	169.0	∅250	193.5	169.0
F403	-	-	-	∅140	221.5	169.0	∅160	231.5	132.0	-	-	-	-	-	-	-	-	-	-	-	-
F602	-	-	-	-	-	-	∅160	219.5	196.0	∅160	219.5	196.0	∅200	221.5	196.0	∅200	221.5	196.0	∅250	224.5	196.0
F603	-	-	-	-	-	-	∅160	262.5	196.0	∅160	262.5	196.0	-	-	-	-	-	-	-	-	-

3.4 Type designation

This chapter shows you an explanation of the type designation with the associated options.

Additional ordering information not included in the type designation can be found at the end of the chapter.

Example code

F	2	0	2	A	G	0280	IE3D080L04
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Explanation

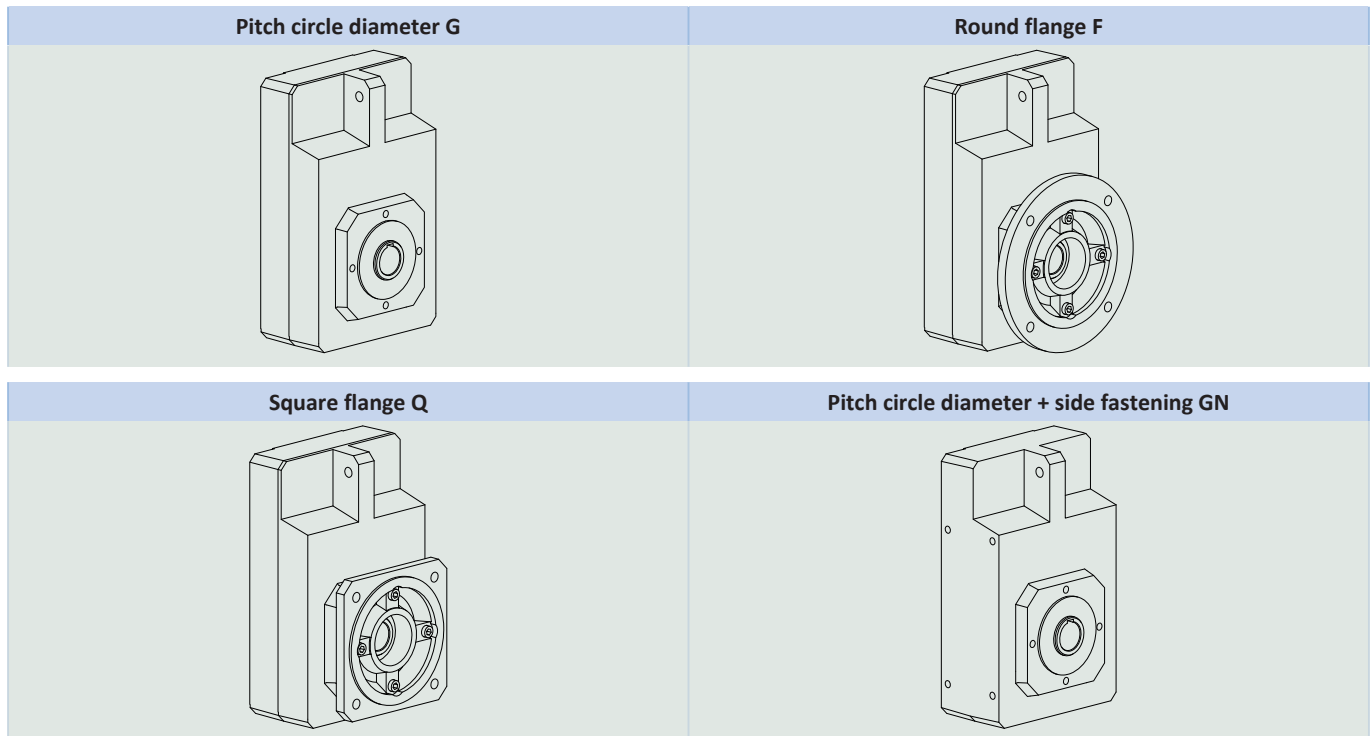
Code	Designation	Design
F	Type	Offset helical gear unit
2	Size	2 (example)
0	Generation	Generation 0
2	Stages	Two-stage
3		Three-stage
A	Shaft	Hollow shaft with keyway
S		Hollow shaft with shrink ring
V		Solid shaft
G	Housing	Pitch circle diameter
F		Round flange
Q		Square flange
GN		Pitch circle diameter + side fastening
0280	Transmission ratio (i x 10 rounded)	i = 28.11 (example)
IE3D080	Motor	IE3D asynchronous motor
L04		

To complete the type designation, also specify the following in your order:

- A detailed type designation of the motor, see the chapter [▶ 5.4](#)
- The mounting position, see the chapter [▶ 3.5.4](#)
- The position of the terminal box, see the chapter [▶ 3.5.6](#)

3.5 Product description

3.5.1 Housing design



	G	F	Q	GN
F1	✓	✓	✓	✓
F2	✓	✓	✓	✓
F3	✓	✓	✓	✓
F4	✓	✓	✓	✓
F6	✓	✓	✓	✓

3.5.2 Combinatorial shaft/housing design

Shaft design	Code	Housing design			
		G	F	Q	GN
Hollow shaft with keyway	A	AG	AF	AQ	AGN
Hollow shaft with shrink ring	S	SG	SF	SQ	SGN
Solid shaft	V	–	VF	VQ	–

3.5.3 Installation conditions

Hollow shaft

The hollow shaft hole tolerance is ISO H7. The tolerance of the machine shaft must be ISO k6.

Take care to align the machine shaft with the gear unit hollow shaft when attaching the gear unit.

Maximum deviation ≤ 0.03 mm.

For simpler assembly and disassembly of the machine shaft, the hollow shafts are equipped with a spiral groove (as a grease deposit).

A hardened, threaded keeper plate is included in the scope of delivery. You also have the option to order the hollow shaft without a keeper plate.

Hollow shaft with shrink ring

The tolerance of the hollow shaft hole is ISO H7.

The machine shaft must be ISO h9.

Select a material for the machine shaft with a permitted surface pressure of $p \geq 325$ N/mm².

Possible materials:

- C45E +QT
- 42CrMo4

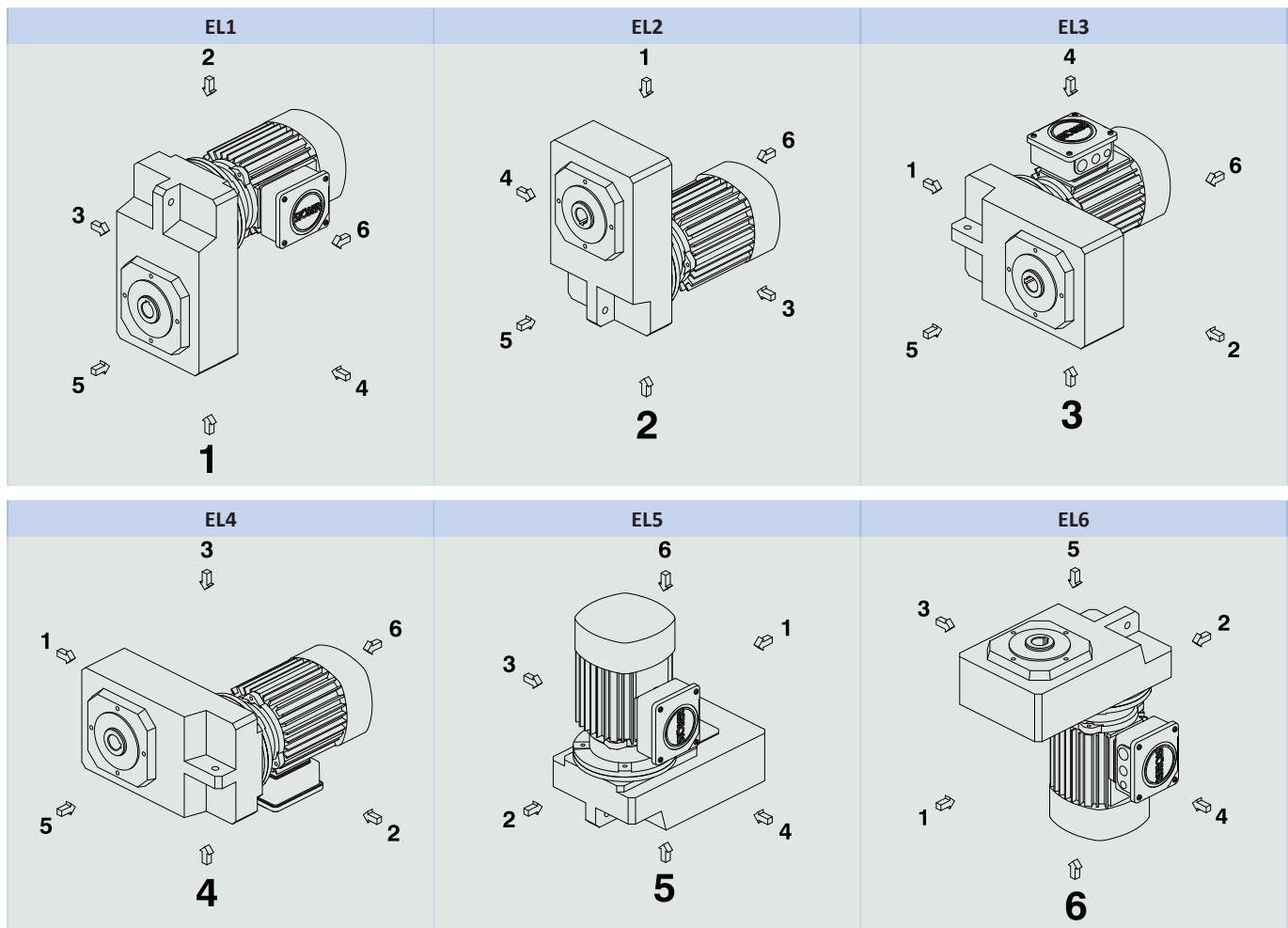
Fastening the gear units on the machine side using the pitch circle diameter

The specified torques and forces only apply when gear units are fastened on the machine side using screws of strength class 10.9. In addition, the gear housings must be adjusted at the pilot. The machine-side fit must be H7.

3.5.4 Mounting positions

The following table shows the standard mounting positions.

The numbers identify the gear unit sides. The mounting position is defined by the gear side facing downwards.



Since the lubricant filling volume of the gear unit depends on the mounting position, the mounting position must be specified when ordering.

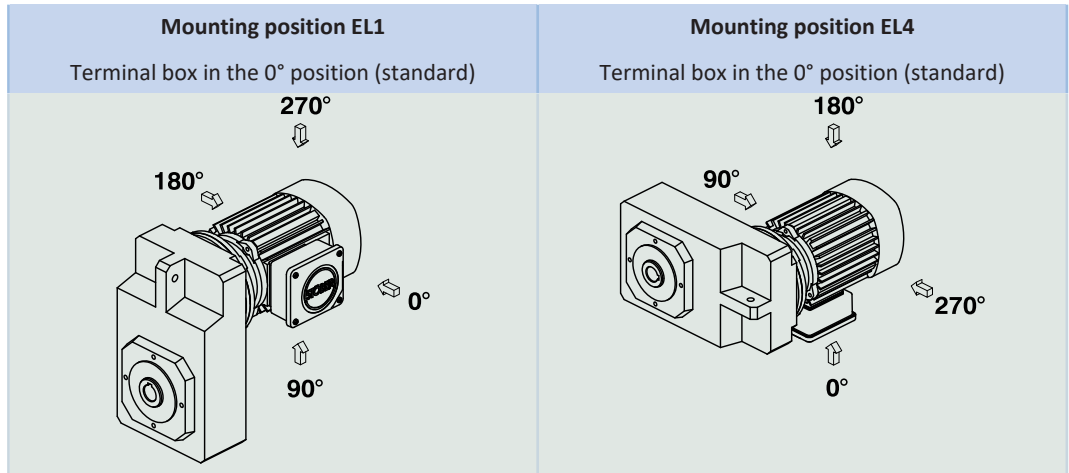
3.5.5 Lubricants

STOBER fills the gear units with the amount and type of lubricant specified on the nameplate. The filling volume and the structure of the gear units depend on the mounting position.

Only install the gear units in the intended mounting position! Reposition the gear units only after consulting STOBER. Otherwise, STOBER assumes no liability for the gear units.

You will receive lubricants for use in the food industry upon request.

3.5.6 Position of the terminal box



Indicate variations for your geared motor in the order.

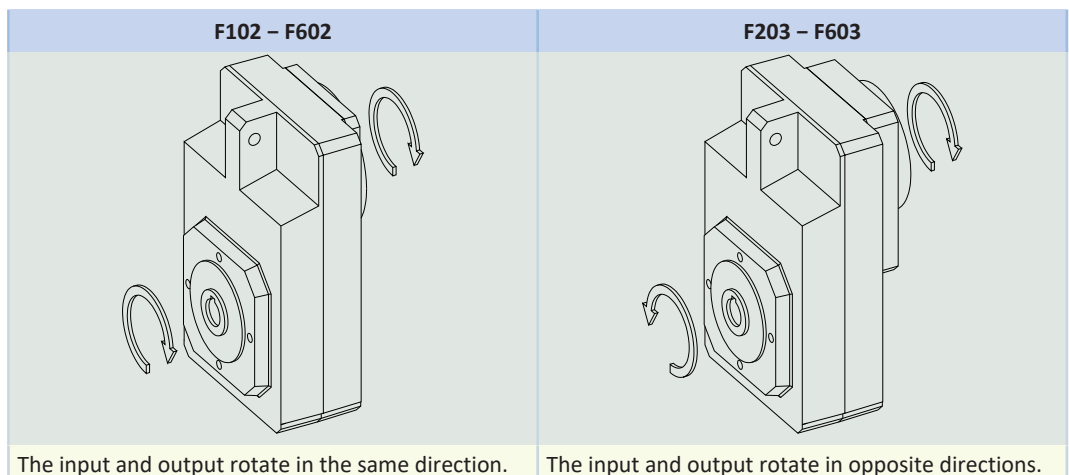
Note that the terminal box position rotates along with the geared motor if the geared motor rotates to another mounting position.

3.5.7 Other product features

Feature	Value
Max. permitted gear unit temperature (on the surface of the gear unit)	≤ 80 °C
Paint	RAL 7001 Silver gray Optional selection of various RAL colors.
(ATEX) Directive 2014/34/EU	You can get asynchronous motors for use in potentially explosive atmospheres on request.
Efficiency:	
η_{get} two-stage	97%
η_{get} three-stage	96%
Protection class	IP56

3.5.8 Direction of rotation

Solid shaft (V), hollow shaft with keyway (A), hollow shaft with shrink ring (S)



The pictures show mounting position EL1.

3.6 Project configuration

Project your drives using the information in this chapter. In doing so, observe the limit conditions in this chapter to ensure a safe design.

An explanation of the formula symbols can be found in Chapter [▶ 13.1](#)

Determine the following for your application:

- The actual torque M_{2N^*}
- The actual speed n_{2^*}
- The operating mode operating factor fB_{op}
- The runtime operating factor fB_t
- The motor operating factor fB_{mot}
- The duty cycle ED in %

$$ED = \frac{t_{op}}{T} \cdot 100\%$$

For the S4 and S8 operating mode:

- The mass moment of inertia J_{2^*}

$$J_{1^*} = \frac{J_{2^*}}{i^2}$$

Calculate the motor rating necessary for your application:

$$P_{N^*} = \frac{M_{2N^*} \cdot n_{2^*} \cdot fB_{mot}}{9550}$$

Using the determined values and the calculated motor rating, select a suitable drive from the selection table.


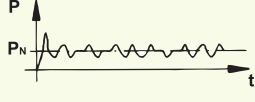

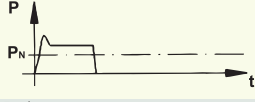
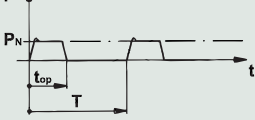
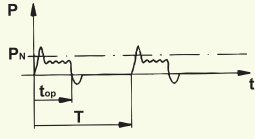
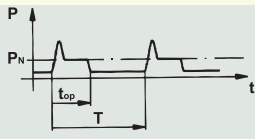
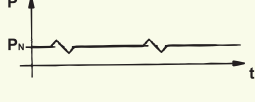
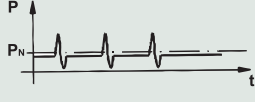
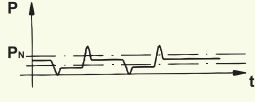
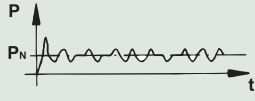
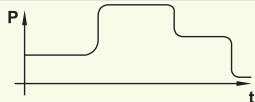
Then check the following conditions:

$$M_{2N^*} \cdot fB_{op} \cdot fB_t < M_{2N} \cdot S$$

$$P_{N^*} < P_N$$

Operating factors

Run time	fB_t
Daily runtime ≤ 8 h	1.00
Daily runtime ≤ 16 h	1.15
Daily runtime ≤ 24 h	1.20

Operating mode	Characteristic output curve	ED	fB _{op}	fB _{mot}
S1 Continuous operation with soft start <ul style="list-style-type: none"> Start time up to 30 s 		100 %	1.00	1.00
S1 Continuous operation with normal start <ul style="list-style-type: none"> Asynchronous motors with direct switch-on or dynamic loading Start time up to 30 s 		100 %	1.25	1.00
S1 Continuous operation with high-load start <ul style="list-style-type: none"> Start time up to 30 s 		100 %	1.25	1.25
S2 brief operation <ul style="list-style-type: none"> Operating time t_{op} ≤ 3 minutes 		≤ 30 %	0.75	0.75
S3 Periodic cyclic operation <ul style="list-style-type: none"> Cycle time T ≤ 10 minutes Cyclic operation with braking motor Low additional flywheel weights J_{1*} < 0,5 · J₁ 		≤ 25 %	0.70	0.70
		≤ 40 %	1.00	1.00
		≤ 60 %	1.25	1.25
S4 Periodic cyclic operation with the effect of the start-up process <ul style="list-style-type: none"> Cycle time T ≤ 10 minutes Cyclic operation with braking motor Larger additional flywheel weights 		40 %	J _{1*} ≤ J ₁ : 1.40 J _{1*} ~ 3 · J ₁ : 1.60	1.40
S6 Uninterrupted periodic operation 	100 %	1.25	1.00	
S6 Uninterrupted periodic operation with short-term loading <ul style="list-style-type: none"> Low speeds Low additional flywheel weights J_{1*} < 0,5 · J₁ 		100 %	1.40	1.00
S6 Uninterrupted periodic operation with impact loading <ul style="list-style-type: none"> High speeds Large additional flywheel weights 		100 %	1.60	1.25
S8 Uninterrupted periodic operation <ul style="list-style-type: none"> With load changes With speed changes 		J _{1*} ≤ J ₁ : 1.40	J _{1*} ≤ J ₁ : 1.25	
		J _{1*} ~ 3 · J ₁ : 1.60	J _{1*} ~ 3 · J ₁ : 1.40	
S9 Non-periodic operation <ul style="list-style-type: none"> With load changes With speed changes 		J _{1*} ≤ J ₁ : 1.40 J _{1*} ~ 3 · J ₁ : 1.60	J _{1*} ≤ J ₁ : 1.25 J _{1*} ~ 3 · J ₁ : 1.40	
S10 Operation with individual constant loads 	100 %	1.00	1.00	

Tab. 1: Operating factors for operating modes S1 to S10

3.6.1 Permitted shaft loads for the output shaft

The values specified in the tables apply to the permitted shaft loads:

- For shaft dimensions in accordance with the catalog
- For output speeds $n_{2m^*} \leq 20$ rpm ($F_{2axN} = F_{2ax20}$; $F_{2radN} = F_{2rad20}$; $M_{2kN} = M_{2k20}$)
- Only if radial forces on the gear unit are stabilized by its pilots for the pitch circle diameter and flange housing design

3.6.1.1 V shaft design

Permitted shaft loads for V shaft design (solid shaft)

Type	z_2 [mm]	F_{2ax20} [N]	F_{2rad20} [N]	$F_{2rad,acc}$ [N]	M_{2k20} [Nm]	$M_{2k,acc}$ [Nm]
F1	35.0	1100	4200	4200	260	260
F2	41.0	1400	5400	5400	400	400
F3	43.0	1900	7500	7500	600	600
F4	44.0	2350	9250	9250	800	800
F6	44.0	3100	12500	12500	1200	1200

For other output speeds, download diagrams at <https://configurator.stoeber.de/en-US/>.

The following applies to output speeds $n_{2m^*} > 20$ rpm:

$$F_{2axN} = \frac{F_{2ax20}}{\sqrt[3]{\frac{n_{2m^*}}{20 \text{ rpm}}}} \quad F_{2radN} = \frac{F_{2rad20}}{\sqrt[3]{\frac{n_{2m^*}}{20 \text{ rpm}}}} \quad M_{2kN} = \frac{M_{2k20}}{\sqrt[3]{\frac{n_{2m^*}}{20 \text{ rpm}}}}$$

The values for F_{2ax20} , F_{2rad20} and M_{2k20} can be found in the table "Permitted shaft loads" in this chapter.

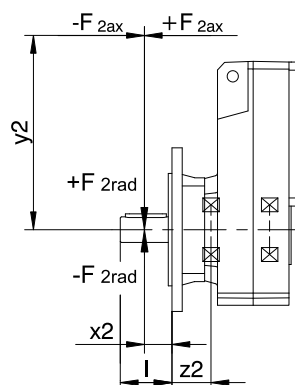


Fig. 1: Force application points for solid shaft

The specified values for F_{2rad20} and $F_{2rad,acc}$ refer to an application of force at the center of the output shaft: $x_2 = l/2$.

Shaft dimensions can be found in the "Dimensional drawings" chapter.

The following applies to other force application points:

$$M_{2k,acc^*} = \frac{2 \cdot F_{2ax^*} \cdot y_2 + F_{2rad,acc^*} \cdot (x_2 + z_2)}{1000}$$

For applications with multiple axial and/or radial forces, you must add the forces as vectors.

In the event of EMERGENCY OFF operation (max. 1000 load changes), you can multiply the permitted forces and torques for F_{2ax20} , F_{2rad20} and M_{2k20} by a factor of two.

Also note the calculation for equivalent values:

$$M_{2k,eq^*} = \sqrt[3]{\frac{|n_{2m,1^*}| \cdot t_{1^*} \cdot |M_{2k,acc,1^*}|^3 + \dots + |n_{2m,n^*}| \cdot t_{n^*} \cdot |M_{2k,acc,n^*}|^3}{|n_{2m,1^*}| \cdot t_{1^*} + \dots + |n_{2m,n^*}| \cdot t_{n^*}}}$$

$$F_{2rad,eq^*} = \sqrt[3]{\frac{|n_{2m,1^*} \cdot t_{1^*} \cdot F_{2rad,acc,1^*}^3 + \dots + |n_{2m,n^*} \cdot t_{n^*} \cdot F_{2rad,acc,n^*}^3|}{|n_{2m,1^*} \cdot t_{1^*} + \dots + |n_{2m,n^*} \cdot t_{n^*}|}}$$

3.6.1.2 A and S shaft design

Permitted shaft loads for A shaft design (hollow shaft with keyway)

Type	z ₂ [mm]	F _{2ax20} [N]	F _{2rad20} [N]	F _{2rad,acc} [N]	M _{2k20} [Nm]	M _{2k,acc} [Nm]
F1	30.0	900	4200	4200	175	175
F2	33.0	1200	5400	5400	250	250
F3	33.0	1350	7500	7500	375	375
F4	39.0	1900	9250	9250	550	550
F6	45.0	2200	12500	12500	800	800

Permitted shaft loads for S shaft design (hollow shaft with shrink ring)

Type	z ₂ [mm]	F _{2ax20} [N]	F _{2rad20} [N]	F _{2rad,acc} [N]	M _{2k20} [Nm]	M _{2k,acc} [Nm]
F1	30.0	900	4200	4200	175	175
F2	33.0	1200	5400	5400	250	250
F3	33.0	1350	7500	7500	375	375
F4	39.0	1900	9250	9250	550	550
F6	45.0	2200	12500	12500	800	800

For other output speeds, download diagrams at <https://configurator.stoeber.de/en-US/>.

The following applies to output speeds n_{2m*} > 20 rpm:

$$F_{2axN} = \frac{F_{2ax20}}{\sqrt[3]{\frac{n_{2m^*}}{20 \text{ rpm}}}} \quad F_{2radN} = \frac{F_{2rad20}}{\sqrt[3]{\frac{n_{2m^*}}{20 \text{ rpm}}}} \quad M_{2kN} = \frac{M_{2k20}}{\sqrt[3]{\frac{n_{2m^*}}{20 \text{ rpm}}}}$$

The values for F_{2ax20}, F_{2rad20} and M_{2k20} can be found in the table "Permitted shaft loads" in this chapter.

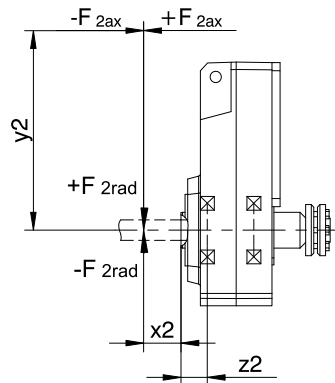


Fig. 2: Force application points for hollow shaft

You can determine the permitted radial forces from the permitted tilting torque M_{2kN} and M_{2k,acc}. The actual radial forces may not exceed the permitted radial forces. The permitted radial forces pertain to the shaft end (x₂ = 0).

$$M_{2k,acc^*} = \frac{2 \cdot F_{2ax^*} \cdot y_2 + F_{2rad,acc^*} \cdot (x_2 + z_2)}{1000}$$

For applications with multiple axial and/or radial forces, you must add the forces as vectors.

In the event of EMERGENCY OFF operation (max. 1000 load changes), you can multiply the permitted forces and torques for F_{2ax20}, F_{2rad20} and M_{2k20} by a factor of two.

Also note the calculation for equivalent values:

$$M_{2k,eq^*} = \sqrt[3]{\frac{|n_{2m,1^*}| \cdot t_{1^*} \cdot |M_{2k,acc,1^*}|^3 + \dots + |n_{2m,n^*}| \cdot t_{n^*} \cdot |M_{2k,acc,n^*}|^3}{|n_{2m,1^*}| \cdot t_{1^*} + \dots + |n_{2m,n^*}| \cdot t_{n^*}}}$$

$$F_{2rad,eq^*} = \sqrt[3]{\frac{|n_{2m,1^*}| \cdot t_{1^*} \cdot |F_{2rad,acc,1^*}|^3 + \dots + |n_{2m,n^*}| \cdot t_{n^*} \cdot |F_{2rad,acc,n^*}|^3}{|n_{2m,1^*}| \cdot t_{1^*} + \dots + |n_{2m,n^*}| \cdot t_{n^*}}}$$

3.6.2 Radial shaft seal rings

Leak-proofness

Our gear units are equipped with high-quality radial shaft seal rings and checked for leaks. However, a leak cannot be fully ruled out over the length of use of a gear unit. If you use a gear unit with goods incompatible with the lubricant, you must take measures to prevent direct contact with the gear unit lubricant in case of a leak.

3.7 Additional documentation

Additional documentation related to the product can be found at <http://www.stoeber.de/en/downloads/>

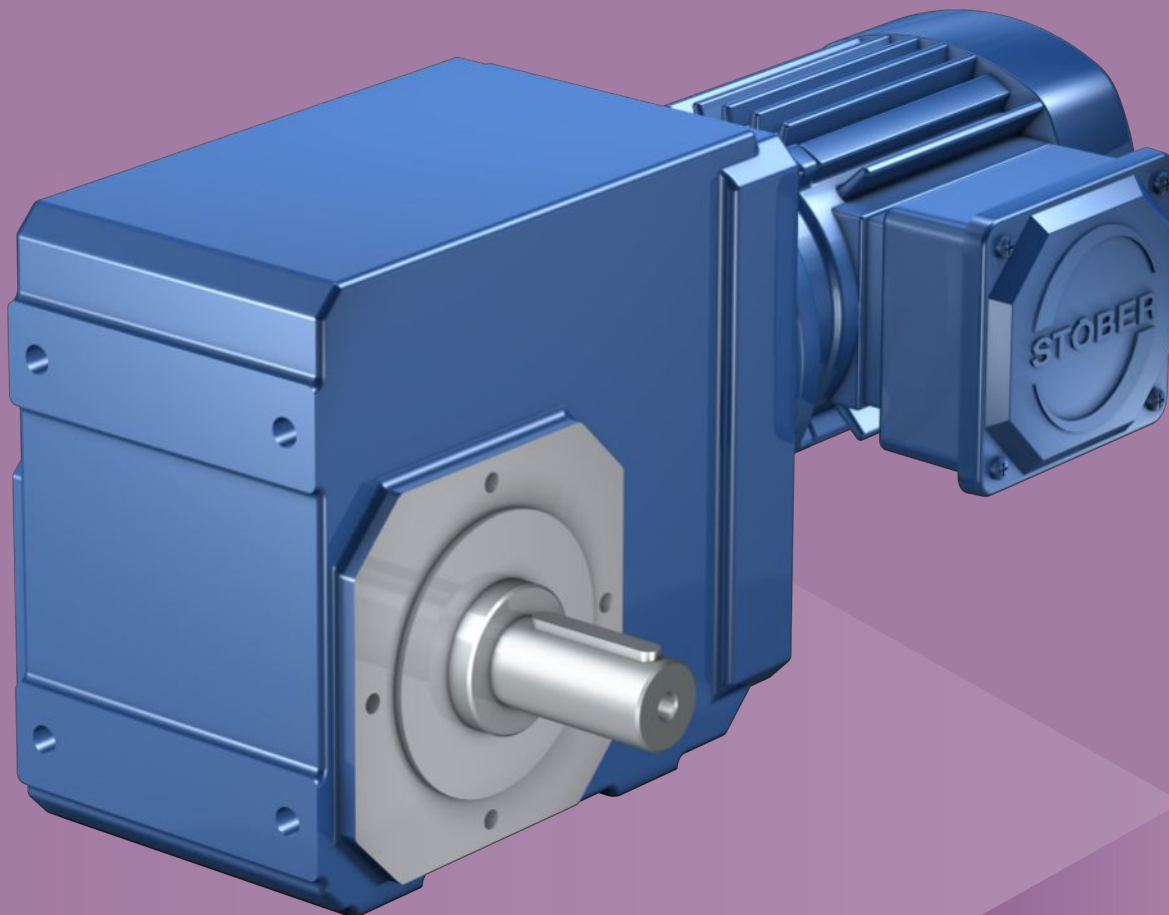
Enter the ID of the documentation in the Search field.

Documentation	ID
Operating manual for C/F/K/S gear units and gear motors	443027_en

4 K helical bevel geared motors

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4

Helical bevel geared motors

K

4.1 Overview

Highly rigid helical-gear right-angle geared motor

Features

- Power density ★★★★★
- Backlash ★★★★★
- Price category €€
- Shaft load ★★★★★
- Smooth operation ★★★★★
- Torsional stiffness ★★★★★
- Mass moment of inertia ★★★★★
- Helical gearing ✓
- Maintenance-free (K1 – K4) ✓
- FKM seal ring at the input ✓
- Reinforced output bearing (K5 – K8) ✓ (on request)
- Energy efficiency class IE3 in accordance with EN 60034-30-1 ✓

Key ★☆☆☆☆ good | ★★★★★ excellent

€ Economy | €€€€€ Premium

Technical data

P_N	0.12 – 30 kW
i	4 – 381
M_{2N}	6.5 – 13970 Nm
η_{get}	94 – 97 %

4.2 Selection tables

The technical data specified in the selection tables applies to:

- Installation altitudes up to 1000 m above sea level
- Surrounding temperatures from 0 °C to 40 °C
- Drives with self-ventilated motors
- Weight specification for mounting position EL1, housing design G

You can receive asynchronous geared motors with low output speed on request.

Asynchronous geared motors are ideal for operation on a drive controller (87 Hz). More information can be found in chapter [▶ 5.6.2](#)

For all other technical data, refer to <https://configurator.stoeber.de/en-US/>.

An explanation of the formula symbols can be found in the chapter [▶ 13.1](#).

n_2 50 Hz [rpm]	S	n_2 87 Hz [rpm]	S	M_{2N} [Nm]	Type	m [kg]	i	i_{exakt}	J_1 [kgcm ²]
P_N (50 Hz) = 0,12 kW, P_N (87 Hz) = 0,21 kW									
20	1.2	35	1.2	56	K102_0700 IE3D063K04	16	70.03	2451/35	4.0
25	1.9	43	1.9	45	K102_0560 IE3D063K04	16	56.10	1178/21	4.0
28	1.2	48	1.2	40	K102_0500 IE3D063K04	16	50.31	5031/100	4.0
30	2.7	52	2.7	37	K102_0470 IE3D063K04	16	46.92	2299/49	4.0
35	1.9	60	1.9	32	K102_0400 IE3D063K04	16	40.30	403/10	4.0
40	4.3	69	4.1	28	K102_0350 IE3D063K04	16	35.11	3686/105	4.0
42	2.7	72	2.7	27	K102_0340 IE3D063K04	16	33.71	4719/140	4.0
50	5.4	86	4.7	22	K102_0280 IE3D063K04	16	28.05	589/21	4.1
56	4.8	96	4.8	20	K102_0250 IE3D063K04	16	25.22	1261/50	4.0
60	6.3	104	5.3	19	K102_0230 IE3D063K04	16	23.27	1140/49	4.1
69	6.0	120	5.9	16	K102_0200 IE3D063K04	16	20.15	403/20	4.1
80	7.3	138	6.4	14	K102_0175 IE3D063K04	16	17.56	2090/119	4.1
84	6.9	145	6.7	13	K102_0165 IE3D063K04	16	16.71	117/7	4.1
P_N (50 Hz) = 0,18 kW, P_N (87 Hz) = 0,31 kW									
6.5	1.0	11	1.0	252	K303_2180 IE3D063M04	34	218.2	38399/176	5.1
7.8	0.96	14	0.96	209	K203_1810 IE3D063M04	27	181.0	86903/480	5.1
7.8	1.6	14	1.6	209	K303_1810 IE3D063M04	34	181.0	86903/480	5.1
10	2.2	18	2.2	157	K303_1360 IE3D063M04	34	136.0	14147/104	5.1
10	1.3	18	1.3	157	K203_1350 IE3D063M04	27	135.3	30315/224	5.1
13	1.6	22	1.6	127	K203_1090 IE3D063M04	27	109.5	26273/240	5.1
13	2.8	22	2.8	126	K303_1090 IE3D063M04	34	109.2	167743/1536	5.1
16	1.9	27	1.9	105	K203_0910 IE3D063M04	27	90.79	46483/512	5.1
16	3.3	27	3.3	106	K303_0910 IE3D063M04	34	91.23	26273/288	5.1
18	2.2	31	2.2	92	K203_0800 IE3D063M04	27	79.62	26273/330	5.1
18	3.8	31	3.3	92	K303_0790 IE3D063M04	34	79.42	167743/2112	5.1
20	0.85	35	0.85	82	K102_0700 IE3D063M04	17	70.03	2451/35	5.0
20	1.6	35	1.6	81	K202_0690 IE3D063M04	24	69.43	6665/96	5.0
20	2.6	35	2.6	81	K302_0690 IE3D063M04	29	69.43	6665/96	5.1
21	2.5	36	2.5	79	K203_0680 IE3D063M04	27	68.42	26273/384	5.1
21	2.6	37	2.6	76	K203_0660 IE3D063M04	27	66.03	46483/704	5.1
25	1.3	44	1.3	66	K102_0560 IE3D063M04	17	56.10	1178/21	5.0
25	2.4	44	2.4	65	K202_0560 IE3D063M04	24	55.54	1333/24	5.1
26	3.2	45	3.2	63	K203_0540 IE3D063M04	27	54.25	135407/2496	5.1
28	0.85	49	0.85	59	K102_0500 IE3D063M04	17	50.31	5031/100	5.0
28	1.6	49	1.6	59	K202_0500 IE3D063M04	24	50.49	6665/132	5.0
28	3.5	49	3.5	58	K203_0500 IE3D063M04	27	49.76	26273/528	5.1
30	1.8	52	1.8	55	K102_0470 IE3D063M04	17	46.92	2299/49	5.0
31	3.7	53	3.7	54	K202_0460 IE3D063M04	24	46.23	1849/40	5.1
31	3.8	54	3.8	52	K102_0450 IE3D063M04	27	45.22	58609/1296	5.1
35	1.3	61	1.3	47	K202_0400 IE3D063M04	17	40.30	403/10	5.0
35	2.4	61	2.4	47	K202_0400 IE3D063M04	24	40.39	1333/33	5.1
36	4.4	62	4.4	46	K203_0390 IE3D063M04	27	39.45	135407/3432	5.1
40	2.9	70	2.8	41	K102_0350 IE3D063M04	17	35.11	3686/105	5.0
42	1.8	73	1.8	40	K102_0340 IE3D063M04	17	33.71	4719/140	5.0
42	3.8	73	3.8	39	K202_0340 IE3D063M04	24	33.62	1849/55	5.1
50	3.6	87	3.2	33	K102_0280 IE3D063M04	17	28.05	589/21	5.1
56	3.2	97	3.2	30	K102_0250 IE3D063M04	17	25.22	1261/50	5.0
61	4.3	105	3.6	27	K102_0230 IE3D063M04	17	23.27	1140/49	5.1
70	4.1	122	4.0	24	K102_0200 IE3D063M04	17	20.15	403/20	5.1

4.2 Selection tables 4 K helical bevel geared motors

n_2 50 Hz [rpm]	S	n_2 87 Hz [rpm]	S	M_{2N} [Nm]	Type	m [kg]	i	i_{exakt}	J_1 [kgcm ²]
P_N (50 Hz) = 0,18 kW, P_N (87 Hz) = 0,31 kW									
81	5.0	140	4.4	21	K102_0175 IE3D063M04	17	17.56	2090/119	5.1
85	4.7	147	4.5	20	K102_0165 IE3D063M04	17	16.71	117/7	5.1
100	5.0	174	5.0	17	K102_0140 IE3D063M04	17	14.11	494/35	5.2
112	5.0	194	5.0	15	K102_0125 IE3D063M04	17	12.62	429/34	5.2
122	5.0	212	5.0	14	K102_0115 IE3D063M04	17	11.57	266/23	5.2
140	5.0	242	5.0	12	K102_0100 IE3D063M04	17	10.14	507/50	5.2
153	5.0	265	5.0	11	K102_0092 IE3D063M04	17	9.249	1748/189	5.3
170	5.0	295	5.0	9.8	K102_0083 IE3D063M04	17	8.309	1911/230	5.3
213	5.0	369	5.0	7.8	K102_0066 IE3D063M04	17	6.644	299/45	5.4
P_N (50 Hz) = 0,25 kW, P_N (87 Hz) = 0,43 kW									
5.3	0.86	9.1	0.86	434	K403_2720 IE3D071K04	50	271.6	86903/320	8.8
6.6	1.2	11	1.2	348	K403_2180 IE3D071K04	50	218.2	38399/176	8.8
7.9	1.2	14	1.2	289	K303_1810 IE3D071K04	37	181.0	86903/480	8.8
7.9	1.8	14	1.8	290	K403_1810 IE3D071K04	50	181.4	14147/78	8.8
11	1.6	18	1.6	217	K303_1360 IE3D071K04	37	136.0	14147/104	8.8
11	2.5	18	2.3	217	K403_1360 IE3D071K04	50	136.1	196037/1440	8.8
11	0.93	18	0.93	216	K203_1350 IE3D071K04	30	135.3	30315/224	8.8
13	1.1	23	1.1	175	K203_1090 IE3D071K04	30	109.5	26273/240	8.8
13	2.0	23	2.0	174	K303_1090 IE3D071K04	37	109.2	167743/1536	8.8
16	1.4	27	1.4	145	K203_0910 IE3D071K04	30	90.79	46483/512	8.8
16	2.4	27	2.4	146	K303_0910 IE3D071K04	37	91.23	26273/288	8.8
18	1.6	31	1.6	127	K203_0800 IE3D071K04	30	79.62	26273/330	8.8
18	2.8	31	2.4	127	K303_0790 IE3D071K04	37	79.42	167743/2112	8.8
21	1.2	36	1.2	112	K202_0690 IE3D071K04	27	69.43	6665/96	8.7
21	1.9	36	1.9	112	K302_0690 IE3D071K04	32	69.43	6665/96	8.8
21	1.8	36	1.8	109	K203_0680 IE3D071K04	30	68.42	26273/384	8.8
21	3.2	37	3.2	108	K303_0680 IE3D071K04	37	67.73	74777/1104	8.8
22	1.9	38	1.9	105	K203_0660 IE3D071K04	30	66.03	46483/704	8.8
22	3.2	37	2.7	106	K303_0660 IE3D071K04	37	66.35	26273/396	8.8
25	0.94	44	0.94	91	K102_0560 IE3D071K04	20	56.10	1178/21	8.7
26	1.8	45	1.8	90	K202_0560 IE3D071K04	27	55.54	1333/24	8.8
26	3.2	45	3.2	87	K303_0550 IE3D071K04	37	54.58	70735/1296	8.8
26	2.3	46	2.3	87	K203_0540 IE3D071K04	30	54.25	135407/2496	8.8
28	1.2	49	1.2	82	K202_0500 IE3D071K04	27	50.49	6665/132	8.7
29	2.5	50	2.5	79	K203_0500 IE3D071K04	30	49.76	26273/528	8.8
29	3.2	50	3.2	79	K303_0490 IE3D071K04	37	49.26	74777/1518	8.8
30	1.3	53	1.3	76	K102_0470 IE3D071K04	20	46.92	2299/49	8.7
31	2.7	54	2.7	75	K202_0460 IE3D071K04	27	46.23	1849/40	8.8
32	2.8	55	2.8	72	K203_0450 IE3D071K04	30	45.22	58609/1296	8.8
35	0.94	61	0.94	65	K102_0400 IE3D071K04	20	40.30	403/10	8.7
35	1.8	61	1.8	65	K202_0400 IE3D071K04	27	40.39	1333/33	8.8
36	3.2	63	3.2	63	K203_0390 IE3D071K04	30	39.45	135407/3432	8.8
41	2.1	71	2.0	57	K102_0350 IE3D071K04	20	35.11	3686/105	8.7
42	1.3	73	1.3	55	K102_0340 IE3D071K04	20	33.71	4719/140	8.7
43	2.8	74	2.8	54	K202_0340 IE3D071K04	27	33.62	1849/55	8.8
51	2.6	88	2.3	45	K102_0280 IE3D071K04	20	28.05	589/21	8.8
57	2.4	98	2.4	41	K102_0250 IE3D071K04	20	25.22	1261/50	8.7
61	3.1	106	2.6	38	K102_0230 IE3D071K04	20	23.27	1140/49	8.8
71	3.0	123	2.9	33	K102_0200 IE3D071K04	20	20.15	403/20	8.8
81	3.6	141	3.2	28	K102_0175 IE3D071K04	20	17.56	2090/119	8.8
85	3.6	147	3.6	27	K202_0170 IE3D071K04	27	16.86	2967/176	9.0
86	3.4	148	3.3	27	K102_0165 IE3D071K04	20	16.71	117/7	8.8
101	3.6	175	3.6	23	K102_0140 IE3D071K04	20	14.11	494/35	8.9
113	3.6	196	3.6	20	K102_0125 IE3D071K04	20	12.62	429/34	8.9
124	3.6	214	3.6	19	K102_0115 IE3D071K04	20	11.57	266/23	8.9
141	3.6	244	3.6	16	K102_0100 IE3D071K04	20	10.14	507/50	8.9
155	3.6	268	3.6	15	K102_0092 IE3D071K04	20	9.249	1748/189	9.0
172	3.6	298	3.6	13	K102_0083 IE3D071K04	20	8.309	1911/230	9.0
215	3.6	373	3.6	11	K102_0066 IE3D071K04	20	6.644	299/45	9.1
257	3.6	445	3.6	9.0	K102_0056 IE3D071K04	20	5.568	1520/273	9.4
358	3.6	619	3.6	6.5	K102_0040 IE3D071K04	20	4.000	4/1	9.6
P_N (50 Hz) = 0,37 kW, P_N (87 Hz) = 0,64 kW									
6.6	0.81	11	0.81	521	K403_2180 IE3D071L04	51	218.2	38399/176	11
7.9	1.2	14	1.2	433	K403_1810 IE3D071L04	51	181.4	14147/78	11
11	1.1	18	1.1	325	K303_1360 IE3D071L04	38	136.0	14147/104	11

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 0,37 kW, P_N (87 Hz) = 0,64 kW									
11	1.7	18	1.5	325	K403_1360 IE3D071L04	51	136.1	196037/1440	11
13	1.3	23	1.3	261	K303_1090 IE3D071L04	38	109.2	167743/1536	11
13	2.1	23	1.8	260	K403_1090 IE3D071L04	51	108.8	62651/576	11
16	0.92	27	0.92	217	K203_0910 IE3D071L04	31	90.79	46483/512	11
16	1.6	27	1.6	218	K303_0910 IE3D071L04	38	91.23	26273/288	11
16	2.1	27	2.0	218	K403_0910 IE3D071L04	51	91.23	26273/288	11
18	1.1	31	1.1	190	K203_0800 IE3D071L04	31	79.62	26273/330	11
18	1.8	31	1.6	190	K303_0790 IE3D071L04	38	79.42	167743/2112	11
18	2.1	31	1.8	189	K403_0790 IE3D071L04	51	79.11	62651/792	11
21	1.3	36	1.3	168	K302_0690 IE3D071L04	33	69.43	6665/96	11
21	1.2	36	1.2	164	K203_0680 IE3D071L04	31	68.42	26273/384	11
21	2.1	37	2.1	162	K303_0680 IE3D071L04	38	67.73	74777/1104	11
22	1.3	38	1.3	158	K203_0660 IE3D071L04	31	66.03	46483/704	11
22	2.1	37	1.8	159	K303_0660 IE3D071L04	38	66.35	26273/396	11
26	1.2	45	1.2	135	K202_0560 IE3D071L04	28	55.54	1333/24	11
26	2.1	45	2.1	130	K303_0550 IE3D071L04	38	54.58	70735/1296	11
26	1.5	46	1.5	130	K203_0540 IE3D071L04	31	54.25	135407/2496	11
29	1.7	50	1.7	119	K203_0500 IE3D071L04	31	49.76	26273/528	11
29	2.1	50	2.1	118	K303_0490 IE3D071L04	38	49.26	74777/1518	11
30	0.89	53	0.89	114	K102_0470 IE3D071L04	21	46.92	2299/49	11
31	1.8	54	1.8	112	K202_0460 IE3D071L04	28	46.23	1849/40	11
32	1.9	55	1.9	108	K203_0450 IE3D071L04	31	45.22	58609/1296	11
35	1.2	61	1.2	98	K202_0400 IE3D071L04	28	40.39	1333/33	11
36	2.1	63	2.1	94	K203_0390 IE3D071L04	31	39.45	135407/3432	11
41	1.4	71	1.3	85	K102_0350 IE3D071L04	21	35.11	3686/105	11
41	2.0	72	2.0	84	K202_0350 IE3D071L04	28	34.55	1935/56	11
42	0.89	73	0.89	82	K102_0340 IE3D071L04	21	33.71	4719/140	11
43	1.8	74	1.8	82	K202_0340 IE3D071L04	28	33.62	1849/55	11
51	1.8	88	1.5	68	K102_0280 IE3D071L04	21	28.05	589/21	11
57	1.6	98	1.6	61	K102_0250 IE3D071L04	21	25.22	1261/50	11
57	2.0	99	2.0	61	K202_0250 IE3D071L04	28	25.13	1935/77	11
61	2.1	106	1.8	56	K102_0230 IE3D071L04	21	23.27	1140/49	11
71	2.0	123	1.9	49	K102_0200 IE3D071L04	21	20.15	403/20	11
81	2.4	141	2.1	43	K102_0175 IE3D071L04	21	17.56	2090/119	11
85	2.4	147	2.4	41	K202_0170 IE3D071L04	28	16.86	2967/176	11
86	2.3	148	2.2	41	K102_0165 IE3D071L04	21	16.71	117/7	11
101	2.4	175	2.4	34	K102_0140 IE3D071L04	21	14.11	494/35	11
113	2.4	196	2.4	31	K102_0125 IE3D071L04	21	12.62	429/34	11
124	2.4	214	2.4	28	K102_0115 IE3D071L04	21	11.57	266/23	11
141	2.4	244	2.4	25	K102_0100 IE3D071L04	21	10.14	507/50	11
155	2.4	268	2.4	22	K102_0092 IE3D071L04	21	9.249	1748/189	11
170	2.4	295	2.4	20	K202_0084 IE3D071L04	28	8.397	2494/297	11
172	2.4	298	2.4	20	K102_0083 IE3D071L04	21	8.309	1911/230	11
215	2.4	373	2.4	16	K102_0066 IE3D071L04	21	6.644	299/45	11
257	2.4	445	2.4	14	K102_0056 IE3D071L04	21	5.568	1520/273	11
358	2.4	619	2.4	9.7	K102_0040 IE3D071L04	21	4.000	4/1	12
P_N (50 Hz) = 0,55 kW, P_N (87 Hz) = 0,95 kW									
3.8	1.4	6.5	1.4	1309	K714_3810 IE3D080K04	114	381.0	195083/512	21
3.9	0.85	6.8	0.85	1267	K614_3690 IE3D080K04	81	368.9	1700009/4608	21
4.2	1.4	7.2	1.4	1182	K714_3440 IE3D080K04	114	344.1	44051/128	21
4.3	0.85	7.5	0.85	1145	K614_3330 IE3D080K04	81	333.2	383873/1152	21
4.7	2.3	8.2	2.1	1047	K714_3050 IE3D080K04	114	304.8	195083/640	21
4.8	0.87	8.3	0.87	1030	K514_3000 IE3D080K04	61	300.0	756059/2520	21
4.9	1.4	8.5	1.4	1011	K614_2940 IE3D080K04	81	294.4	3674213/12480	21
5.2	2.3	9.1	2.1	946	K714_2750 IE3D080K04	114	275.3	44051/160	21
5.3	0.88	9.2	0.88	931	K514_2710 IE3D080K04	61	271.0	24389/90	21
5.4	1.4	9.4	1.4	913	K614_2660 IE3D080K04	81	265.9	829661/3120	21
5.7	2.6	9.9	2.5	861	K714_2510 IE3D080K04	114	250.7	320943/1280	21
5.8	1.1	10	1.1	857	K514_2500 IE3D080K04	61	249.6	729988/2925	21
5.8	1.7	10	1.7	846	K614_2460 IE3D080K04	81	246.3	1261297/5120	21
6.4	2.6	11	2.5	778	K714_2260 IE3D080K04	114	226.5	72471/320	21
6.4	1.2	11	1.2	774	K514_2250 IE3D080K04	61	225.4	659344/2925	21
6.5	1.9	11	1.9	764	K614_2230 IE3D080K04	81	222.5	284809/1280	21
7.5	2.9	13	2.9	662	K714_1930 IE3D080K04	114	192.9	320943/1664	21
7.7	1.4	13	1.4	640	K514_1860 IE3D080K04	61	186.2	26071/140	21

4.2 Selection tables 4 K helical bevel geared motors

n_2 50 Hz [rpm]	S	n_2 87 Hz [rpm]	S	M_{2N} [Nm]	Type	m [kg]	i	i_{exakt}	J_1 [kgcm ²]
P_N (50 Hz) = 0,55 kW, P_N (87 Hz) = 0,95 kW									
7.8	2.3	14	2.3	634	K614_1850 IE3D080K04	81	184.6	383873/2080	21
8.0	0.86	14	0.86	625	K403_1790 IE3D080K04	54	179.1	34916/195	21
8.3	2.9	14	2.9	598	K714_1740 IE3D080K04	114	174.2	72471/416	21
8.6	1.6	15	1.6	578	K514_1680 IE3D080K04	61	168.2	841/5	21
8.6	2.5	15	2.5	573	K614_1670 IE3D080K04	81	166.7	86681/520	21
9.5	3.5	16	3.5	521	K714_1520 IE3D080K04	114	151.7	24273/160	21
9.7	1.8	17	1.8	512	K514_1490 IE3D080K04	61	149.0	26071/175	21
9.7	2.8	17	2.8	509	K614_1480 IE3D080K04	81	148.2	4551637/30720	21
11	3.5	18	3.5	471	K714_1370 IE3D080K04	114	137.0	5481/40	21
11	1.9	19	1.9	462	K514_1350 IE3D080K04	61	134.6	3364/25	21
11	1.2	19	1.2	469	K403_1340 IE3D080K04	54	134.4	120959/900	21
11	3.2	19	3.2	460	K614_1340 IE3D080K04	81	133.8	1027789/7680	21
12	2.1	20	2.1	429	K514_1250 IE3D080K04	61	124.9	599633/4800	21
12	3.4	20	3.4	423	K614_1230 IE3D080K04	81	123.2	1261297/10240	21
13	2.3	22	2.3	388	K514_1130 IE3D080K04	61	112.8	135401/1200	21
13	3.8	22	3.7	382	K614_1110 IE3D080K04	81	111.3	284809/2560	21
13	0.93	23	0.93	376	K303_1080 IE3D080K04	42	107.8	103501/960	21
13	1.5	23	1.5	375	K403_1070 IE3D080K04	54	107.4	38657/360	21
15	2.3	26	2.3	337	K513_0970 IE3D080K04	56	96.64	38657/400	21
15	3.2	26	3.2	333	K613_0950 IE3D080K04	78	95.41	293105/3072	21
15	2.8	26	2.8	323	K514_0940 IE3D080K04	61	94.15	338923/3600	21
16	1.1	28	1.1	314	K303_0900 IE3D080K04	42	90.06	16211/180	21
16	1.8	28	1.8	314	K403_0900 IE3D080K04	54	90.06	16211/180	21
16	2.3	29	2.3	305	K513_0870 IE3D080K04	56	87.29	8729/100	21
17	3.2	29	3.2	301	K613_0860 IE3D080K04	78	86.18	66185/768	21
17	3.1	29	3.1	292	K514_0850 IE3D080K04	61	85.03	76531/900	21
18	1.3	32	1.3	274	K303_0780 IE3D080K04	42	78.41	103501/1320	21
18	2.0	32	2.0	273	K403_0780 IE3D080K04	54	78.10	38657/495	21
19	4.5	33	4.5	266	K613_0760 IE3D080K04	78	76.14	126697/1664	22
21	3.4	36	3.4	245	K513_0700 IE3D080K04	56	70.08	841/12	21
21	1.5	36	1.5	245	K402_0690 IE3D080K04	50	69.34	5547/80	21
21	4.5	36	4.5	240	K613_0690 IE3D080K04	78	68.77	28609/416	22
22	1.5	37	1.5	233	K303_0670 IE3D080K04	42	66.87	46139/690	21
21	2.3	37	2.3	235	K403_0670 IE3D080K04	54	67.30	21199/315	21
22	1.5	38	1.5	229	K303_0650 IE3D080K04	42	65.50	32422/495	21
22	2.4	38	2.4	229	K403_0650 IE3D080K04	54	65.50	32422/495	21
25	4.4	43	4.4	203	K513_0580 IE3D080K04	56	58.30	11368/195	21
26	1.3	45	1.3	197	K302_0560 IE3D080K04	37	55.71	2451/44	21
26	2.1	45	2.1	197	K402_0560 IE3D080K04	50	55.71	2451/44	21
27	1.9	46	1.9	188	K303_0540 IE3D080K04	42	53.88	8729/162	21
27	2.9	46	2.9	187	K403_0540 IE3D080K04	54	53.69	38657/720	21
29	1.5	49	1.5	179	K402_0500 IE3D080K04	50	50.43	5547/110	21
30	2.1	51	2.1	170	K303_0490 IE3D080K04	42	48.63	184556/3795	21
30	5.2	52	5.2	168	K513_0480 IE3D080K04	56	48.16	2697/56	22
31	1.2	54	1.2	164	K202_0460 IE3D080K04	32	46.23	1849/40	21
31	2.1	54	2.1	164	K302_0460 IE3D080K04	37	46.23	1849/40	21
32	2.2	56	2.2	157	K303_0450 IE3D080K04	42	44.89	11223/250	21
33	5.2	57	5.2	152	K513_0440 IE3D080K04	56	43.50	87/2	22
36	1.3	62	1.3	143	K302_0410 IE3D080K04	37	40.51	4902/121	21
36	2.1	62	2.1	143	K402_0410 IE3D080K04	50	40.51	4902/121	21
37	2.6	64	2.6	137	K303_0390 IE3D080K04	42	39.19	34916/891	21
40	2.8	70	2.8	125	K303_0360 IE3D080K04	42	35.83	215/6	21
41	0.97	71	0.91	124	K102_0350 IE3D080K04	24	35.11	3686/105	21
42	1.6	72	1.6	122	K202_0350 IE3D080K04	32	34.55	1935/56	21
41	2.8	72	2.8	123	K302_0350 IE3D080K04	37	34.73	903/26	21
43	1.3	74	1.3	119	K202_0340 IE3D080K04	32	33.62	1849/55	21
43	2.1	74	2.1	119	K302_0340 IE3D080K04	37	33.62	1849/55	21
44	3.1	76	3.0	114	K303_0330 IE3D080K04	42	32.65	44892/1375	21
44	4.1	77	4.1	113	K403_0320 IE3D080K04	54	32.39	2494/77	21
51	1.2	89	1.1	99	K102_0280 IE3D080K04	24	28.05	589/21	21
52	2.0	89	1.9	99	K202_0280 IE3D080K04	32	27.95	559/20	21
57	1.1	99	1.1	89	K102_0250 IE3D080K04	24	25.22	1261/50	21
57	2.2	99	2.0	89	K202_0250 IE3D080K04	32	25.13	1935/77	21
62	1.4	107	1.2	82	K102_0230 IE3D080K04	24	23.27	1140/49	21
62	2.4	108	2.1	82	K202_0230 IE3D080K04	32	23.18	2967/128	21

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 0,55 kW, P_N (87 Hz) = 0,95 kW									
71	1.5	124	1.3	71	K102_0200 IE3D080K04	24	20.15	403/20	21
71	2.8	123	2.3	72	K202_0200 IE3D080K04	32	20.33	1118/55	21
82	1.7	142	1.4	62	K102_0175 IE3D080K04	24	17.56	2090/119	21
82	3.1	143	2.6	62	K202_0175 IE3D080K04	32	17.47	559/32	21
85	3.1	148	2.7	60	K202_0170 IE3D080K04	32	16.86	2967/176	21
86	1.8	149	1.5	59	K102_0165 IE3D080K04	24	16.71	1177/7	21
102	2.0	177	1.7	50	K102_0140 IE3D080K04	24	14.11	494/35	21
104	3.6	180	3.0	49	K202_0140 IE3D080K04	32	13.85	2881/208	21
114	2.1	198	1.8	45	K102_0125 IE3D080K04	24	12.62	429/34	21
125	2.3	216	1.9	41	K102_0115 IE3D080K04	24	11.57	266/23	21
142	2.5	246	2.1	36	K102_0100 IE3D080K04	24	10.14	507/50	21
156	2.6	270	2.2	33	K102_0092 IE3D080K04	24	9.249	1748/189	21
171	5.0	297	4.2	30	K202_0084 IE3D080K04	32	8.397	2494/297	21
173	2.8	300	2.4	29	K102_0083 IE3D080K04	24	8.309	1911/230	21
215	5.8	373	4.9	24	K202_0067 IE3D080K04	32	6.683	2279/341	22
217	3.3	375	2.8	24	K102_0066 IE3D080K04	24	6.644	299/45	21
240	3.5	416	3.0	21	K102_0060 IE3D080K04	24	6.000	6/1	21
259	3.7	448	3.1	20	K102_0056 IE3D080K04	24	5.568	1520/273	21
330	6.6	572	6.5	15	K202_0044 IE3D080K04	32	4.364	48/11	23
360	4.6	624	3.9	14	K102_0040 IE3D080K04	24	4.000	4/1	22
P_N (50 Hz) = 0,75 kW, P_N (87 Hz) = 1,30 kW									
3.8	1.0	6.6	1.0	1793	K714_3810 IE3D080L04	117	381.0	195083/512	26
4.2	1.0	7.3	1.0	1619	K714_3440 IE3D080L04	117	344.1	44051/128	26
4.7	1.7	8.2	1.5	1434	K714_3050 IE3D080L04	117	304.8	195083/640	26
4.9	1.0	8.5	1.0	1385	K614_2940 IE3D080L04	84	294.4	3674213/12480	26
5.2	1.7	9.1	1.5	1295	K714_2750 IE3D080L04	117	275.3	44051/160	26
5.4	1.1	9.4	1.1	1251	K614_2660 IE3D080L04	84	265.9	829661/3120	26
5.8	1.9	10	1.8	1180	K714_2510 IE3D080L04	117	250.7	320943/1280	26
5.9	1.3	10	1.3	1159	K614_2460 IE3D080L04	84	246.3	1261297/5120	26
6.4	1.9	11	1.8	1066	K714_2260 IE3D080L04	117	226.5	72471/320	26
6.4	0.85	11	0.85	1061	K514_2250 IE3D080L04	63	225.4	659344/2925	26
6.5	1.4	11	1.4	1047	K614_2230 IE3D080L04	84	222.5	284809/1280	26
7.5	2.1	13	2.1	907	K714_1930 IE3D080L04	117	192.9	320943/1664	26
7.8	1.0	13	1.0	876	K514_1860 IE3D080L04	63	186.2	26071/140	26
7.8	1.7	14	1.7	868	K614_1850 IE3D080L04	84	184.6	383873/2080	26
8.3	2.1	14	2.1	820	K714_1740 IE3D080L04	117	174.2	72471/416	26
8.6	1.1	15	1.1	791	K514_1680 IE3D080L04	63	168.2	841/5	26
8.7	1.8	15	1.8	784	K614_1670 IE3D080L04	84	166.7	86681/520	26
9.5	2.5	16	2.5	714	K714_1520 IE3D080L04	117	151.7	24273/160	27
9.7	1.3	17	1.3	701	K514_1490 IE3D080L04	63	149.0	26071/175	26
9.8	2.1	17	2.1	697	K614_1480 IE3D080L04	84	148.2	4551637/30720	26
11	2.5	18	2.5	645	K714_1370 IE3D080L04	117	137.0	5481/40	27
11	1.4	19	1.4	633	K514_1350 IE3D080L04	63	134.6	3364/25	26
11	0.86	19	0.86	642	K403_1340 IE3D080L04	57	134.4	120959/900	26
11	2.3	19	2.3	630	K614_1340 IE3D080L04	84	133.8	1027789/7680	26
12	1.5	20	1.5	588	K514_1250 IE3D080L04	63	124.9	599633/4800	26
12	2.5	20	2.5	580	K614_1230 IE3D080L04	84	123.2	1261297/10240	26
13	1.7	22	1.7	531	K514_1130 IE3D080L04	63	112.8	135401/1200	26
13	2.8	22	2.7	523	K614_1110 IE3D080L04	84	111.3	284809/2560	26
13	1.1	23	1.1	513	K403_1070 IE3D080L04	57	107.4	38657/360	26
15	1.7	26	1.7	462	K513_0970 IE3D080L04	59	96.64	38657/400	26
15	2.4	26	2.4	456	K613_0950 IE3D080L04	80	95.41	293105/3072	27
15	2.0	27	2.0	443	K514_0940 IE3D080L04	63	94.15	338923/3600	26
16	0.81	28	0.81	430	K303_0900 IE3D080L04	44	90.06	16211/180	26
16	1.3	28	1.3	430	K403_0900 IE3D080L04	57	90.06	16211/180	26
17	1.7	29	1.7	417	K513_0870 IE3D080L04	59	87.29	8729/100	26
17	2.4	29	2.4	412	K613_0860 IE3D080L04	80	86.18	66185/768	27
17	2.3	29	2.3	400	K514_0850 IE3D080L04	63	85.03	76531/900	26
18	0.93	32	0.93	375	K303_0780 IE3D080L04	44	78.41	103501/1320	26
19	1.5	32	1.5	373	K403_0780 IE3D080L04	57	78.10	38657/495	26
19	2.4	32	2.4	371	K513_0780 IE3D080L04	59	77.59	26071/336	26
19	3.3	33	3.3	364	K613_0760 IE3D080L04	80	76.14	126697/1664	27
21	2.5	36	2.5	335	K513_0700 IE3D080L04	59	70.08	841/12	26
21	1.1	36	1.1	336	K402_0690 IE3D080L04	53	69.34	5547/80	26
21	3.3	36	3.3	329	K613_0690 IE3D080L04	80	68.77	28609/416	27

4.2 Selection tables 4 K helical bevel geared motors

n_2 50 Hz [rpm]	S	n_2 87 Hz [rpm]	S	M_{2N} [Nm]	Type	m [kg]	i	i_{exakt}	J_1 [kgcm ²]
P_N (50 Hz) = 0,75 kW, P_N (87 Hz) = 1,30 kW									
22	1.1	37	1.1	320	K303_0670 IE3D080L04	44	66.87	46139/690	26
21	1.7	37	1.7	322	K403_0670 IE3D080L04	57	67.30	21199/315	26
22	1.1	38	1.1	313	K303_0650 IE3D080L04	44	65.50	32422/495	26
22	1.8	38	1.8	313	K403_0650 IE3D080L04	57	65.50	32422/495	26
22	2.9	39	2.9	309	K513_0650 IE3D080L04	59	64.54	12586/195	27
25	3.2	43	3.2	279	K513_0580 IE3D080L04	59	58.30	11368/195	27
26	0.98	45	0.98	270	K302_0560 IE3D080L04	39	55.71	2451/44	26
26	1.6	45	1.6	270	K402_0560 IE3D080L04	53	55.71	2451/44	26
27	1.4	46	1.4	258	K303_0540 IE3D080L04	44	53.88	8729/162	26
27	2.1	47	2.1	257	K403_0540 IE3D080L04	57	53.69	38657/720	26
29	1.1	50	1.1	245	K402_0500 IE3D080L04	53	50.43	5547/110	26
30	1.5	51	1.5	232	K303_0490 IE3D080L04	44	48.63	184556/3795	26
30	2.4	51	2.4	234	K403_0490 IE3D080L04	57	48.94	169592/3465	26
30	3.8	52	3.8	230	K513_0480 IE3D080L04	59	48.16	2697/56	27
31	0.89	54	0.89	224	K202_0460 IE3D080L04	34	46.23	1849/40	26
31	1.5	54	1.5	224	K302_0460 IE3D080L04	39	46.23	1849/40	26
31	2.4	54	2.4	225	K402_0460 IE3D080L04	53	46.31	602/13	26
32	1.6	56	1.6	215	K303_0450 IE3D080L04	44	44.89	11223/250	26
32	2.6	56	2.6	213	K403_0450 IE3D080L04	57	44.54	1247/28	26
33	3.8	58	3.8	208	K513_0440 IE3D080L04	59	43.50	87/2	27
36	0.98	62	0.98	196	K302_0410 IE3D080L04	39	40.51	4902/121	26
36	1.6	62	1.6	196	K402_0410 IE3D080L04	53	40.51	4902/121	26
37	1.9	64	1.9	187	K303_0390 IE3D080L04	44	39.19	34916/891	26
37	2.9	64	2.9	187	K403_0390 IE3D080L04	57	39.05	38657/990	26
40	2.0	70	2.0	171	K303_0360 IE3D080L04	44	35.83	215/6	26
42	1.2	72	1.2	168	K202_0350 IE3D080L04	34	34.55	1935/56	26
42	2.1	72	2.1	168	K302_0350 IE3D080L04	39	34.73	903/26	26
43	0.95	74	0.95	163	K202_0340 IE3D080L04	34	33.62	1849/55	26
43	1.5	74	1.5	163	K302_0340 IE3D080L04	39	33.62	1849/55	26
43	2.4	74	2.4	163	K402_0340 IE3D080L04	53	33.68	4816/143	26
44	2.2	77	2.2	156	K303_0330 IE3D080L04	44	32.65	44892/1375	26
45	3.0	77	3.0	155	K403_0320 IE3D080L04	57	32.39	2494/77	26
52	0.88	–	–	136	K102_0280 IE3D080L04	27	28.05	589/21	26
52	1.5	90	1.4	136	K202_0280 IE3D080L04	34	27.95	559/20	26
52	2.6	90	2.4	135	K302_0280 IE3D080L04	39	27.88	3569/128	26
58	1.6	100	1.5	122	K202_0250 IE3D080L04	34	25.13	1935/77	26
57	2.8	99	2.6	123	K302_0250 IE3D080L04	39	25.26	3612/143	26
62	1.0	108	0.88	113	K102_0230 IE3D080L04	27	23.27	1140/49	26
62	1.8	108	1.6	112	K202_0230 IE3D080L04	34	23.18	2967/128	26
62	3.1	107	2.7	113	K302_0230 IE3D080L04	39	23.29	559/24	26
72	1.1	124	0.96	98	K102_0200 IE3D080L04	27	20.15	403/20	26
71	2.0	123	1.7	99	K202_0200 IE3D080L04	34	20.33	1118/55	26
82	1.3	143	1.1	85	K102_0175 IE3D080L04	27	17.56	2090/119	26
83	2.2	143	1.9	85	K202_0175 IE3D080L04	34	17.47	559/32	26
86	2.3	148	1.9	82	K202_0170 IE3D080L04	34	16.86	2967/176	26
86	1.3	150	1.1	81	K102_0165 IE3D080L04	27	16.71	117/7	26
102	1.4	177	1.2	68	K102_0140 IE3D080L04	27	14.11	494/35	26
104	2.6	181	2.2	67	K202_0140 IE3D080L04	34	13.85	2881/208	27
115	1.6	198	1.3	61	K102_0125 IE3D080L04	27	12.62	429/34	26
114	2.8	197	2.3	62	K202_0125 IE3D080L04	34	12.71	559/44	26
125	1.7	216	1.4	56	K102_0115 IE3D080L04	27	11.57	266/23	26
125	3.0	217	2.5	56	K202_0115 IE3D080L04	34	11.55	1247/108	27
143	1.8	247	1.5	49	K102_0100 IE3D080L04	27	10.14	507/50	26
143	3.2	248	2.7	49	K202_0100 IE3D080L04	34	10.07	2881/286	27
156	1.9	271	1.6	45	K102_0092 IE3D080L04	27	9.249	1748/189	26
157	3.4	272	2.9	45	K202_0092 IE3D080L04	34	9.190	2279/248	27
172	3.7	298	3.1	41	K202_0084 IE3D080L04	34	8.397	2494/297	27
174	2.1	301	1.7	40	K102_0083 IE3D080L04	27	8.309	1911/230	26
216	4.3	375	3.6	32	K202_0067 IE3D080L04	34	6.683	2279/341	27
217	2.4	377	2.0	32	K102_0066 IE3D080L04	27	6.644	299/45	26
241	2.6	417	2.2	29	K102_0060 IE3D080L04	27	6.000	6/1	26
260	2.7	450	2.3	27	K102_0056 IE3D080L04	27	5.568	1520/273	27
331	4.8	574	4.8	21	K202_0044 IE3D080L04	34	4.364	48/11	28
361	3.4	626	2.8	19	K102_0040 IE3D080L04	27	4.000	4/1	27

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 1,10 kW, P_N (87 Hz) = 1,91 kW									
4.7	1.1	8.2	1.0	2094	K714_3050 IE3D090S04	122	304.8	195083/640	40
5.2	1.1	9.1	1.0	1891	K714_2750 IE3D090S04	122	275.3	44051/160	40
5.7	1.3	9.9	1.2	1722	K714_2510 IE3D090S04	122	250.7	320943/1280	40
5.8	0.86	10	0.86	1692	K614_2460 IE3D090S04	89	246.3	1261297/5120	40
6.4	1.3	11	1.2	1556	K714_2260 IE3D090S04	122	226.5	72471/320	40
6.5	0.95	11	0.95	1528	K614_2230 IE3D090S04	89	222.5	284809/1280	40
7.5	1.5	13	1.5	1325	K714_1930 IE3D090S04	122	192.9	320943/1664	40
7.8	1.1	14	1.1	1268	K614_1850 IE3D090S04	89	184.6	383873/2080	40
8.3	1.5	14	1.5	1197	K714_1740 IE3D090S04	122	174.2	72471/416	40
8.6	1.3	15	1.3	1145	K614_1670 IE3D090S04	89	166.7	86681/520	40
9.5	1.7	16	1.7	1042	K714_1520 IE3D090S04	122	151.7	24273/160	41
9.7	0.88	17	0.88	1023	K514_1490 IE3D090S04	69	149.0	26071/175	40
9.7	1.4	17	1.4	1018	K614_1480 IE3D090S04	89	148.2	4551637/30720	40
11	1.7	18	1.7	941	K714_1370 IE3D090S04	122	137.0	5481/40	41
11	0.97	19	0.97	924	K514_1350 IE3D090S04	69	134.6	3364/25	40
11	1.6	19	1.6	919	K614_1340 IE3D090S04	89	133.8	1027789/7680	40
12	1.0	20	1.0	858	K514_1250 IE3D090S04	69	124.9	599633/4800	40
12	1.7	20	1.7	846	K614_1230 IE3D090S04	89	123.2	1261297/10240	40
13	1.2	22	1.2	775	K514_1130 IE3D090S04	69	112.8	135401/1200	40
13	1.9	22	1.9	764	K614_1110 IE3D090S04	89	111.3	284809/2560	40
15	1.1	26	1.1	674	K513_0970 IE3D090S04	64	96.64	38657/400	40
15	1.6	26	1.6	666	K613_0950 IE3D090S04	86	95.41	293105/3072	41
15	1.4	26	1.4	647	K514_0940 IE3D090S04	69	94.15	338923/3600	40
16	0.88	28	0.88	629	K403_0900 IE3D090S04	62	90.06	16211/180	40
16	1.1	29	1.1	609	K513_0870 IE3D090S04	64	87.29	8729/100	40
17	1.6	29	1.6	601	K613_0860 IE3D090S04	86	86.18	66185/768	41
17	1.5	29	1.5	584	K514_0850 IE3D090S04	69	85.03	76531/900	40
18	1.0	32	1.0	545	K403_0780 IE3D090S04	62	78.10	38657/495	40
19	1.7	32	1.7	541	K513_0780 IE3D090S04	64	77.59	26071/336	40
19	2.3	33	2.3	531	K613_0760 IE3D090S04	86	76.14	126697/1664	41
21	1.7	36	1.7	489	K513_0700 IE3D090S04	64	70.08	841/12	40
21	2.3	36	2.3	480	K613_0690 IE3D090S04	86	68.77	28609/416	41
21	1.2	37	1.2	470	K403_0670 IE3D090S04	62	67.30	21199/315	40
22	1.2	38	1.2	457	K403_0650 IE3D090S04	62	65.50	32422/495	40
22	2.0	39	2.0	450	K513_0650 IE3D090S04	64	64.54	12586/195	41
25	2.2	43	2.2	407	K513_0580 IE3D090S04	64	58.30	11368/195	41
26	1.1	45	1.1	394	K402_0560 IE3D090S04	58	55.71	2451/44	40
27	0.93	46	0.93	376	K303_0540 IE3D090S04	50	53.88	8729/162	40
27	1.5	46	1.5	375	K403_0540 IE3D090S04	62	53.69	38657/720	40
30	1.0	51	1.0	339	K303_0490 IE3D090S04	50	48.63	184556/3795	40
29	1.6	51	1.6	342	K403_0490 IE3D090S04	62	48.94	169592/3465	40
30	2.6	52	2.6	336	K513_0480 IE3D090S04	64	48.16	2697/56	41
31	1.1	54	1.1	327	K302_0460 IE3D090S04	45	46.23	1849/40	40
31	1.6	54	1.6	328	K402_0460 IE3D090S04	58	46.31	602/13	40
32	1.1	56	1.1	313	K303_0450 IE3D090S04	50	44.89	11223/250	40
32	1.8	56	1.8	311	K403_0450 IE3D090S04	62	44.54	1247/28	40
33	2.6	57	2.6	304	K513_0440 IE3D090S04	64	43.50	87/2	41
36	1.1	62	1.1	287	K402_0410 IE3D090S04	58	40.51	4902/121	40
37	1.3	64	1.3	273	K303_0390 IE3D090S04	50	39.19	34916/891	40
37	2.0	64	2.0	273	K403_0390 IE3D090S04	62	39.05	38657/990	40
40	1.4	70	1.4	250	K303_0360 IE3D090S04	50	35.83	215/6	40
40	2.0	70	2.0	249	K403_0360 IE3D090S04	62	35.72	13717/384	40
42	0.82	72	0.82	245	K202_0350 IE3D090S04	40	34.55	1935/56	40
41	1.4	72	1.4	246	K302_0350 IE3D090S04	45	34.73	903/26	40
41	2.2	72	2.2	246	K402_0350 IE3D090S04	58	34.76	4171/120	40
43	1.1	74	1.1	238	K302_0340 IE3D090S04	45	33.62	1849/55	40
43	1.6	74	1.6	238	K402_0340 IE3D090S04	58	33.68	4816/143	40
44	1.5	76	1.5	228	K303_0330 IE3D090S04	50	32.65	44892/1375	40
44	2.0	77	2.0	226	K403_0320 IE3D090S04	62	32.39	2494/77	40
52	1.0	89	0.95	198	K202_0280 IE3D090S04	40	27.95	559/20	40
52	1.8	89	1.7	197	K302_0280 IE3D090S04	45	27.88	3569/128	40
52	2.8	90	2.5	197	K402_0280 IE3D090S04	58	27.77	1333/48	41
57	1.1	99	1.0	178	K202_0250 IE3D090S04	40	25.13	1935/77	40
57	1.9	99	1.8	179	K302_0250 IE3D090S04	45	25.26	3612/143	40
57	2.6	99	2.6	179	K402_0250 IE3D090S04	58	25.28	4171/165	41

4.2 Selection tables 4 K helical bevel geared motors

n_2 50 Hz [rpm]	S	n_2 87 Hz [rpm]	S	M_{2N} [Nm]	Type	m [kg]	i	i_{exakt}	J_1 [kgcm ²]
P_N (50 Hz) = 1,10 kW, P_N (87 Hz) = 1,91 kW									
62	1.2	108	1.1	164	K202_0230 IE3D090S04	40	23.18	2967/128	40
62	2.1	107	1.9	165	K302_0230 IE3D090S04	45	23.29	559/24	40
71	1.4	123	1.2	144	K202_0200 IE3D090S04	40	20.33	1118/55	40
71	2.4	123	2.1	144	K302_0200 IE3D090S04	45	20.28	3569/176	40
82	0.86	–	–	124	K102_0175 IE3D090S04	32	17.56	2090/119	40
82	1.5	143	1.3	124	K202_0175 IE3D090S04	40	17.47	559/32	40
83	2.7	144	2.3	122	K302_0175 IE3D090S04	45	17.29	1591/92	41
85	1.6	148	1.3	119	K202_0170 IE3D090S04	40	16.86	2967/176	40
85	2.7	147	2.3	120	K302_0170 IE3D090S04	45	16.94	559/33	41
86	0.89	–	–	118	K102_0165 IE3D090S04	32	16.71	117/7	40
102	0.99	177	0.84	100	K102_0140 IE3D090S04	32	14.11	494/35	40
104	1.8	180	1.5	98	K202_0140 IE3D090S04	40	13.85	2881/208	41
103	3.1	179	2.6	99	K302_0140 IE3D090S04	45	13.94	1505/108	41
114	1.1	198	0.90	89	K102_0125 IE3D090S04	32	12.62	429/34	40
113	1.9	196	1.6	90	K202_0125 IE3D090S04	40	12.71	559/44	40
114	3.3	198	2.8	89	K302_0125 IE3D090S04	45	12.58	3182/253	41
125	1.1	216	0.96	82	K102_0115 IE3D090S04	32	11.57	266/23	40
125	2.0	216	1.7	82	K202_0115 IE3D090S04	40	11.55	1247/108	41
142	1.2	246	1.0	72	K102_0100 IE3D090S04	32	10.14	507/50	40
143	2.2	248	1.9	71	K202_0100 IE3D090S04	40	10.07	2881/286	41
156	1.3	270	1.1	65	K102_0092 IE3D090S04	32	9.249	1748/189	40
157	2.4	271	2.0	65	K202_0092 IE3D090S04	40	9.190	2279/248	41
171	2.5	297	2.1	59	K202_0084 IE3D090S04	40	8.397	2494/297	41
173	1.4	300	1.2	59	K102_0083 IE3D090S04	32	8.309	1911/230	40
215	2.9	373	2.5	47	K202_0067 IE3D090S04	40	6.683	2279/341	41
217	1.6	375	1.4	47	K102_0066 IE3D090S04	32	6.644	299/45	40
240	1.8	416	1.5	42	K102_0060 IE3D090S04	32	6.000	6/1	40
240	3.1	416	2.6	42	K202_0060 IE3D090S04	40	6.000	6/1	42
259	1.8	448	1.6	39	K102_0056 IE3D090S04	32	5.568	1520/273	41
330	3.3	572	3.3	31	K202_0044 IE3D090S04	40	4.364	48/11	42
360	2.3	624	1.9	28	K102_0040 IE3D090S04	32	4.000	4/1	41
P_N (50 Hz) = 1,50 kW, P_N (87 Hz) = 2,60 kW									
4.8	0.85	–	–	2811	K714_3050 IE3D090LX04	131	304.8	195083/640	58
5.3	0.86	–	–	2539	K714_2750 IE3D090LX04	131	275.3	44051/160	58
5.8	0.98	10	0.91	2312	K714_2510 IE3D090LX04	131	250.7	320943/1280	58
6.4	0.98	11	0.91	2088	K714_2260 IE3D090LX04	131	226.5	72471/320	58
7.5	1.1	13	1.1	1779	K714_1930 IE3D090LX04	131	192.9	320943/1664	58
7.9	0.85	14	0.85	1702	K614_1850 IE3D090LX04	98	184.6	383873/2080	58
8.4	1.1	14	1.1	1607	K714_1740 IE3D090LX04	131	174.2	72471/416	58
8.7	0.94	15	0.94	1537	K614_1670 IE3D090LX04	98	166.7	86681/520	58
9.6	1.3	17	1.3	1399	K714_1520 IE3D090LX04	131	151.7	24273/160	59
9.8	1.1	17	1.1	1366	K614_1480 IE3D090LX04	98	148.2	4551637/30720	58
11	1.3	18	1.3	1264	K714_1370 IE3D090LX04	131	137.0	5481/40	59
11	1.2	19	1.2	1234	K614_1340 IE3D090LX04	98	133.8	1027789/7680	58
12	1.3	20	1.3	1136	K614_1230 IE3D090LX04	98	123.2	1261297/10240	58
13	0.87	22	0.87	1041	K514_1130 IE3D090LX04	77	112.8	135401/1200	58
13	1.4	23	1.4	1026	K614_1110 IE3D090LX04	98	111.3	284809/2560	58
15	0.84	26	0.84	905	K513_0970 IE3D090LX04	73	96.64	38657/400	58
15	1.2	26	1.2	894	K613_0950 IE3D090LX04	94	95.41	293105/3072	59
15	1.0	27	1.0	868	K514_0940 IE3D090LX04	77	94.15	338923/3600	58
17	0.84	29	0.84	818	K513_0870 IE3D090LX04	73	87.29	8729/100	58
17	1.2	29	1.2	807	K613_0860 IE3D090LX04	94	86.18	66185/768	59
17	1.1	30	1.1	784	K514_0850 IE3D090LX04	77	85.03	76531/900	58
19	1.2	32	1.2	727	K513_0780 IE3D090LX04	73	77.59	26071/336	58
19	1.7	33	1.7	713	K613_0760 IE3D090LX04	94	76.14	126697/1664	59
21	1.3	36	1.3	657	K513_0700 IE3D090LX04	73	70.08	841/12	58
21	1.7	37	1.7	644	K613_0690 IE3D090LX04	94	68.77	28609/416	59
22	0.87	37	0.87	631	K403_0670 IE3D090LX04	71	67.30	21199/315	58
22	0.90	38	0.90	614	K403_0650 IE3D090LX04	71	65.50	32422/495	58
23	1.5	39	1.5	605	K513_0650 IE3D090LX04	73	64.54	12586/195	59
25	1.6	43	1.6	546	K513_0580 IE3D090LX04	73	58.30	11368/195	59
26	0.80	45	0.80	530	K402_0560 IE3D090LX04	67	55.71	2451/44	58
27	1.1	47	1.1	503	K403_0540 IE3D090LX04	71	53.69	38657/720	58
30	1.2	51	1.2	459	K403_0490 IE3D090LX04	71	48.94	169592/3465	58
30	1.9	52	1.9	451	K513_0480 IE3D090LX04	73	48.16	2697/56	59

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 1,50 kW, P_N (87 Hz) = 2,60 kW									
31	1.2	54	1.2	440	K402_0460 IE3D090LX04	67	46.31	602/13	58
32	0.83	56	0.83	421	K303_0450 IE3D090LX04	58	44.89	11223/250	58
33	1.3	57	1.3	417	K403_0450 IE3D090LX04	71	44.54	1247/28	58
33	1.9	58	1.9	408	K513_0440 IE3D090LX04	73	43.50	87/2	59
36	0.80	62	0.80	385	K402_0410 IE3D090LX04	67	40.51	4902/121	58
37	0.95	64	0.95	367	K303_0390 IE3D090LX04	58	39.19	34916/891	58
37	1.5	65	1.5	366	K403_0390 IE3D090LX04	71	39.05	38657/990	58
41	1.0	70	1.0	336	K303_0360 IE3D090LX04	58	35.83	215/6	58
41	1.5	71	1.5	335	K403_0360 IE3D090LX04	71	35.72	13717/384	58
42	1.1	73	1.1	330	K302_0350 IE3D090LX04	53	34.73	903/26	58
42	1.7	73	1.6	330	K402_0350 IE3D090LX04	67	34.76	4171/120	58
43	1.2	75	1.2	320	K402_0340 IE3D090LX04	67	33.68	4816/143	58
45	1.1	77	1.1	306	K303_0330 IE3D090LX04	58	32.65	44892/1375	58
45	1.5	78	1.5	303	K403_0320 IE3D090LX04	71	32.39	2494/77	58
52	1.3	90	1.2	265	K302_0280 IE3D090LX04	53	27.88	3569/128	58
52	2.1	91	1.9	264	K402_0280 IE3D090LX04	67	27.77	1333/48	59
58	0.84	–	–	239	K202_0250 IE3D090LX04	48	25.13	1935/77	58
58	1.4	100	1.3	240	K302_0250 IE3D090LX04	53	25.26	3612/143	58
58	2.0	100	2.0	240	K402_0250 IE3D090LX04	67	25.28	4171/165	59
63	0.91	109	0.80	220	K202_0230 IE3D090LX04	48	23.18	2967/128	58
62	1.6	108	1.4	221	K302_0230 IE3D090LX04	53	23.29	559/24	58
62	2.4	108	2.1	221	K402_0230 IE3D090LX04	67	23.29	559/24	59
72	1.0	124	0.87	193	K202_0200 IE3D090LX04	48	20.33	1118/55	58
72	1.8	124	1.5	193	K302_0200 IE3D090LX04	53	20.28	3569/176	58
72	2.3	125	2.3	192	K402_0200 IE3D090LX04	67	20.20	1333/66	59
83	1.1	144	0.97	166	K202_0175 IE3D090LX04	48	17.47	559/32	58
84	2.0	146	1.7	164	K302_0175 IE3D090LX04	53	17.29	1591/92	59
86	1.2	149	0.99	160	K202_0170 IE3D090LX04	48	16.86	2967/176	58
86	2.0	149	1.7	161	K302_0170 IE3D090LX04	53	16.94	559/33	59
105	1.3	182	1.1	132	K202_0140 IE3D090LX04	48	13.85	2881/208	59
104	2.3	181	2.0	132	K302_0140 IE3D090LX04	53	13.94	1505/108	59
115	1.4	198	1.2	121	K202_0125 IE3D090LX04	48	12.71	559/44	58
116	2.4	200	2.1	120	K302_0125 IE3D090LX04	53	12.58	3182/253	59
126	0.84	–	–	110	K102_0115 IE3D090LX04	41	11.57	266/23	58
126	1.5	218	1.3	110	K202_0115 IE3D090LX04	48	11.55	1247/108	59
125	2.5	217	2.2	110	K302_0115 IE3D090LX04	53	11.61	1161/100	59
143	0.92	–	–	96	K102_0100 IE3D090LX04	41	10.14	507/50	58
144	1.7	250	1.4	96	K202_0100 IE3D090LX04	48	10.07	2881/286	59
144	2.5	249	2.4	96	K302_0100 IE3D090LX04	53	10.14	3010/297	59
157	0.98	272	0.83	88	K102_0092 IE3D090LX04	41	9.249	1748/189	58
158	1.8	274	1.5	87	K202_0092 IE3D090LX04	48	9.190	2279/248	59
173	1.9	300	1.6	80	K202_0084 IE3D090LX04	48	8.397	2494/297	59
172	2.4	298	2.4	80	K302_0084 IE3D090LX04	53	8.444	2322/275	60
175	1.1	303	0.89	79	K102_0083 IE3D090LX04	41	8.309	1911/230	58
218	2.2	377	1.8	64	K202_0067 IE3D090LX04	48	6.683	2279/341	59
219	1.2	379	1.0	63	K102_0066 IE3D090LX04	41	6.644	299/45	58
243	1.3	420	1.1	57	K102_0060 IE3D090LX04	41	6.000	6/1	58
243	2.3	420	2.0	57	K202_0060 IE3D090LX04	48	6.000	6/1	60
261	1.4	453	1.2	53	K102_0056 IE3D090LX04	41	5.568	1520/273	59
333	2.4	577	2.4	41	K202_0044 IE3D090LX04	48	4.364	48/11	60
364	1.7	630	1.4	38	K102_0040 IE3D090LX04	41	4.000	4/1	59
P_N (50 Hz) = 2,20 kW, P_N (87 Hz) = 3,81 kW									
3.9	1.1	6.7	0.98	5099	K914_3740 IE3D100KX04	317	373.7	13775935/36864	111
4.7	0.94	8.1	0.94	4242	K814_3110 IE3D100KX04	203	310.9	2149075/6912	111
4.9	1.4	8.5	1.2	4008	K914_2940 IE3D100KX04	317	293.8	977647/3328	111
5.2	0.94	8.9	0.94	3832	K814_2810 IE3D100KX04	203	280.8	485275/1728	111
5.7	1.2	9.8	1.1	3496	K814_2560 IE3D100KX04	203	256.2	8854189/34560	111
5.9	1.6	10	1.4	3371	K914_2470 IE3D100KX04	317	247.0	3288449/13312	111
6.3	1.3	11	1.1	3157	K814_2310 IE3D100KX04	203	231.4	1999333/8640	111
7.4	0.90	13	0.90	2666	K714_1950 IE3D100KX04	145	195.4	2600745/13312	111
7.6	1.6	13	1.4	2618	K814_1920 IE3D100KX04	203	191.9	85963/448	111
7.6	1.9	13	1.7	2615	K914_1920 IE3D100KX04	317	191.7	4710481/24576	112
8.2	1.0	14	1.0	2408	K714_1760 IE3D100KX04	145	176.5	587265/3328	111
8.4	1.7	14	1.4	2365	K814_1730 IE3D100KX04	203	173.3	2773/16	111
9.3	2.0	16	1.7	2138	K814_1570 IE3D100KX04	203	156.7	601741/3840	111

4.2 Selection tables 4 K helical bevel geared motors

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 2,20 kW, P_N (87 Hz) = 3,81 kW									
9.4	1.1	16	1.1	2097	K714_1540 IE3D100KX04	145	153.7	39339/256	111
9.7	2.2	17	2.0	2033	K914_1490 IE3D100KX04	317	149.0	9154331/61440	112
10	2.0	18	1.7	1931	K814_1420 IE3D100KX04	203	141.5	135877/960	111
10	1.3	18	1.3	1894	K714_1390 IE3D100KX04	145	138.8	8883/64	111
11	1.4	20	1.4	1733	K714_1270 IE3D100KX04	145	127.0	520149/4096	111
11	2.2	20	2.0	1731	K814_1270 IE3D100KX04	203	126.9	1461371/11520	112
12	2.2	20	2.2	1716	K914_1260 IE3D100KX04	317	125.8	2221925/17664	113
13	1.5	22	1.5	1565	K714_1150 IE3D100KX04	145	114.7	117453/1024	111
13	2.2	22	2.0	1563	K814_1150 IE3D100KX04	203	114.6	329987/2880	112
15	1.4	25	1.4	1366	K713_0990 IE3D100KX04	136	98.54	100905/1024	111
15	1.8	25	1.8	1345	K714_0990 IE3D100KX04	145	98.60	1009701/10240	111
15	2.2	26	2.2	1347	K813_0970 IE3D100KX04	190	97.17	31093/320	113
15	2.2	27	2.2	1280	K914_0940 IE3D100KX04	317	93.78	4177219/44544	114
16	1.4	28	1.4	1234	K713_0890 IE3D100KX04	136	89.00	22785/256	111
16	2.0	28	2.0	1215	K714_0890 IE3D100KX04	145	89.06	227997/2560	111
17	2.2	29	2.2	1217	K813_0880 IE3D100KX04	190	87.76	7021/80	113
18	2.2	32	2.2	1093	K713_0790 IE3D100KX04	136	78.83	20181/256	112
19	1.4	33	1.4	1055	K613_0760 IE3D100KX04	108	76.14	126697/1664	111
20	2.4	35	2.4	994	K813_0720 IE3D100KX04	190	71.70	10325/144	114
20	2.2	35	2.2	987	K713_0710 IE3D100KX04	136	71.20	4557/64	112
21	1.4	37	1.4	953	K613_0690 IE3D100KX04	108	68.77	28609/416	111
22	1.0	39	1.0	895	K513_0650 IE3D100KX04	87	64.54	12586/195	111
22	2.5	39	2.5	899	K713_0650 IE3D100KX04	136	64.85	33201/512	112
23	1.6	39	1.6	883	K613_0640 IE3D100KX04	108	63.71	130479/2048	111
25	2.5	43	2.5	812	K713_0590 IE3D100KX04	136	58.57	7497/128	113
25	1.1	43	1.1	808	K513_0580 IE3D100KX04	87	58.30	11368/195	111
25	1.8	44	1.8	798	K613_0580 IE3D100KX04	108	57.55	29463/512	111
29	2.8	50	2.8	691	K713_0500 IE3D100KX04	136	49.88	166005/3328	114
30	3.2	51	3.2	679	K813_0490 IE3D100KX04	190	48.99	5487/112	119
30	1.3	52	1.3	668	K513_0480 IE3D100KX04	87	48.16	2697/56	111
30	2.2	53	2.2	662	K613_0480 IE3D100KX04	108	47.73	39711/832	112
32	2.8	56	2.8	625	K713_0450 IE3D100KX04	136	45.05	37485/832	114
33	1.5	58	1.5	603	K513_0440 IE3D100KX04	87	43.50	87/2	111
33	3.2	57	3.2	613	K813_0440 IE3D100KX04	190	44.25	177/4	119
34	2.4	58	2.3	598	K613_0430 IE3D100KX04	108	43.11	8967/208	112
38	1.7	65	1.7	534	K513_0390 IE3D100KX04	87	38.53	2697/70	111
37	3.3	64	3.3	544	K713_0390 IE3D100KX04	136	39.23	2511/64	116
38	2.7	66	2.5	531	K613_0380 IE3D100KX04	108	38.32	156953/4096	113
42	1.1	72	1.1	489	K402_0350 IE3D100KX04	81	34.76	4171/120	110
42	1.9	72	1.9	482	K513_0350 IE3D100KX04	87	34.80	174/5	112
42	3.0	73	2.7	480	K613_0350 IE3D100KX04	108	34.61	35441/1024	113
45	2.0	78	2.0	448	K513_0320 IE3D100KX04	87	32.31	20677/640	112
50	2.2	86	2.2	405	K513_0290 IE3D100KX04	87	29.18	4669/160	112
52	0.89	90	0.84	392	K302_0280 IE3D100KX04	67	27.88	3569/128	110
52	1.4	90	1.3	391	K402_0280 IE3D100KX04	81	27.77	1333/48	111
57	1.4	99	1.3	356	K402_0250 IE3D100KX04	81	25.28	4171/165	111
60	2.7	103	2.6	338	K513_0240 IE3D100KX04	87	24.35	11687/480	113
62	1.1	108	0.94	328	K302_0230 IE3D100KX04	67	23.29	559/24	110
62	1.7	108	1.4	328	K402_0230 IE3D100KX04	81	23.29	559/24	111
66	3.0	114	2.8	305	K513_0220 IE3D100KX04	87	21.99	2639/120	113
72	1.2	124	1.0	285	K302_0200 IE3D100KX04	67	20.28	3569/176	110
72	1.8	124	1.6	284	K402_0200 IE3D100KX04	81	20.20	1333/66	111
75	3.4	130	3.0	268	K513_0195 IE3D100KX04	87	19.35	27869/1440	114
76	4.1	132	4.0	263	K613_0190 IE3D100KX04	108	18.99	17019/896	118
84	1.4	145	1.2	243	K302_0175 IE3D100KX04	67	17.29	1591/92	111
83	2.0	144	1.7	245	K402_0175 IE3D100KX04	81	17.41	731/42	111
86	1.4	148	1.2	238	K302_0170 IE3D100KX04	67	16.94	559/33	111
86	2.1	148	1.8	238	K402_0170 IE3D100KX04	81	16.94	559/33	111
90	4.0	-	-	223	K513_0160 IE3D100KX04	87	16.09	26071/1620	115
100	4.1	-	-	201	K513_0145 IE3D100KX04	87	14.54	5887/405	116
105	0.90	-	-	195	K202_0140 IE3D100KX04	62	13.85	2881/208	111
104	1.6	180	1.3	196	K302_0140 IE3D100KX04	67	13.94	1505/108	111
104	2.4	181	2.0	195	K402_0140 IE3D100KX04	81	13.89	1333/96	112
114	0.96	198	0.81	179	K202_0125 IE3D100KX04	62	12.71	559/44	110
115	1.7	200	1.4	177	K302_0125 IE3D100KX04	67	12.58	3182/253	111

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 2,20 kW, P_N (87 Hz) = 3,81 kW									
115	2.5	198	2.1	178	K402_0125 IE3D100KX04	81	12.66	2924/231	112
126	1.0	218	0.86	162	K202_0115 IE3D100KX04	62	11.55	1247/108	111
125	1.8	216	1.5	163	K302_0115 IE3D100KX04	67	11.61	1161/100	111
126	2.7	218	2.3	162	K402_0115 IE3D100KX04	81	11.52	645/56	113
144	1.1	249	0.94	142	K202_0100 IE3D100KX04	62	10.07	2881/286	111
143	1.9	248	1.6	143	K302_0100 IE3D100KX04	67	10.14	3010/297	111
144	2.9	249	2.5	142	K402_0100 IE3D100KX04	81	10.10	1333/132	112
156	2.1	271	1.7	130	K302_0093 IE3D100KX04	67	9.267	1075/116	112
158	1.2	273	1.0	129	K202_0092 IE3D100KX04	62	9.190	2279/248	111
157	3.1	272	2.6	130	K402_0092 IE3D100KX04	81	9.238	2365/256	114
173	1.3	299	1.1	118	K202_0084 IE3D100KX04	62	8.397	2494/297	111
172	2.2	297	1.9	119	K302_0084 IE3D100KX04	67	8.444	2322/275	112
196	2.4	340	2.0	104	K302_0074 IE3D100KX04	67	7.391	473/64	113
204	1.4	353	1.2	100	K202_0071 IE3D100KX04	62	7.118	2107/296	111
217	1.5	376	1.2	94	K202_0067 IE3D100KX04	62	6.683	2279/341	111
215	2.6	373	2.2	95	K302_0067 IE3D100KX04	67	6.740	2150/319	112
242	1.6	419	1.3	84	K202_0060 IE3D100KX04	62	6.000	6/1	112
242	2.8	419	2.3	84	K302_0060 IE3D100KX04	67	6.000	6/1	113
270	3.0	467	2.5	76	K302_0054 IE3D100KX04	67	5.375	43/8	113
280	1.7	485	1.5	73	K202_0052 IE3D100KX04	62	5.177	2107/407	112
332	2.0	575	1.6	61	K202_0044 IE3D100KX04	62	4.364	48/11	112
332	3.4	575	2.9	61	K302_0044 IE3D100KX04	67	4.364	48/11	114
363	2.1	628	1.7	56	K202_0040 IE3D100KX04	62	4.000	4/1	112
P_N (50 Hz) = 3,00 kW, P_N (87 Hz) = 5,20 kW									
4.9	1.0	8.5	0.88	5473	K914_2940 IE3D100LX04	322	293.8	977647/3328	131
5.7	0.88	9.8	0.84	4773	K814_2560 IE3D100LX04	208	256.2	8854189/34560	131
5.9	1.2	10	1.0	4603	K914_2470 IE3D100LX04	322	247.0	3288449/13312	131
6.3	0.97	11	0.84	4311	K814_2310 IE3D100LX04	208	231.4	1999333/8640	131
7.6	1.2	13	1.1	3575	K814_1920 IE3D100LX04	208	191.9	85963/448	131
7.6	1.4	13	1.2	3571	K914_1920 IE3D100LX04	322	191.7	4710481/24576	132
8.4	1.3	14	1.1	3229	K814_1730 IE3D100LX04	208	173.3	2773/16	131
9.3	1.4	16	1.2	2920	K814_1570 IE3D100LX04	208	156.7	601741/3840	131
9.4	0.84	16	0.84	2863	K714_1540 IE3D100LX04	150	153.7	39339/256	131
9.7	1.6	17	1.5	2776	K914_1490 IE3D100LX04	322	149.0	9154331/61440	132
10	1.5	18	1.2	2637	K814_1420 IE3D100LX04	208	141.5	135877/960	131
10	0.93	18	0.93	2586	K714_1390 IE3D100LX04	150	138.8	8883/64	131
11	1.0	20	1.0	2366	K714_1270 IE3D100LX04	150	127.0	520149/4096	131
11	1.6	20	1.5	2364	K814_1270 IE3D100LX04	208	126.9	1461371/11520	132
12	1.6	20	1.6	2344	K914_1260 IE3D100LX04	322	125.8	2221925/17664	133
13	1.1	22	1.1	2137	K714_1150 IE3D100LX04	150	114.7	117453/1024	131
13	1.6	22	1.5	2135	K814_1150 IE3D100LX04	208	114.6	329987/2880	132
15	0.99	25	0.99	1865	K713_0990 IE3D100LX04	141	98.54	100905/1024	131
15	1.3	25	1.3	1837	K714_0990 IE3D100LX04	150	98.60	1009701/10240	131
15	1.6	26	1.6	1839	K813_0970 IE3D100LX04	195	97.17	31093/320	133
15	1.6	27	1.6	1747	K914_0940 IE3D100LX04	322	93.78	4177219/44544	134
16	0.99	28	0.99	1685	K713_0890 IE3D100LX04	141	89.00	22785/256	131
16	1.4	28	1.4	1659	K714_0890 IE3D100LX04	150	89.06	227997/2560	131
17	1.6	29	1.6	1661	K813_0880 IE3D100LX04	195	87.76	7021/80	133
18	1.6	32	1.6	1492	K713_0790 IE3D100LX04	141	78.83	20181/256	132
18	1.8	32	1.8	1503	K813_0790 IE3D100LX04	195	79.38	45725/576	134
19	1.0	33	1.0	1441	K613_0760 IE3D100LX04	113	76.14	126697/1664	131
20	1.8	35	1.8	1357	K813_0720 IE3D100LX04	195	71.70	10325/144	134
20	1.6	35	1.6	1348	K713_0710 IE3D100LX04	141	71.20	4557/64	132
21	1.0	37	1.0	1302	K613_0690 IE3D100LX04	113	68.77	28609/416	131
22	1.8	39	1.8	1227	K713_0650 IE3D100LX04	141	64.85	33201/512	132
23	1.2	39	1.2	1206	K613_0640 IE3D100LX04	113	63.71	130479/2048	131
25	1.8	43	1.8	1109	K713_0590 IE3D100LX04	141	58.57	7497/128	133
25	0.82	43	0.82	1103	K513_0580 IE3D100LX04	92	58.30	11368/195	131
25	1.3	44	1.3	1089	K613_0580 IE3D100LX04	113	57.55	29463/512	131
29	2.1	50	2.1	944	K713_0500 IE3D100LX04	141	49.88	166005/3328	134
30	2.3	51	2.3	927	K813_0490 IE3D100LX04	195	48.99	5487/112	139
30	0.99	52	0.99	912	K513_0480 IE3D100LX04	92	48.16	2697/56	131
30	1.6	53	1.6	903	K613_0480 IE3D100LX04	113	47.73	39711/832	132
32	2.1	56	2.1	853	K713_0450 IE3D100LX04	141	45.05	37485/832	134
33	1.1	58	1.1	823	K513_0440 IE3D100LX04	92	43.50	87/2	131

4.2 Selection tables 4 K helical bevel geared motors

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 3,00 kW, P_N (87 Hz) = 5,20 kW									
33	2.3	57	2.3	838	K813_0440 IE3D100LX04	195	44.25	177/4	139
34	1.8	58	1.7	816	K613_0430 IE3D100LX04	113	43.11	8967/208	132
38	1.2	65	1.2	729	K513_0390 IE3D100LX04	92	38.53	2697/70	131
37	2.4	64	2.4	743	K713_0390 IE3D100LX04	141	39.23	2511/64	136
38	2.0	66	1.9	725	K613_0380 IE3D100LX04	113	38.32	156953/4096	133
42	0.82	–	–	668	K402_0350 IE3D100LX04	86	34.76	4171/120	130
42	1.4	72	1.4	659	K513_0350 IE3D100LX04	92	34.80	174/5	132
42	2.2	73	2.0	655	K613_0350 IE3D100LX04	113	34.61	35441/1024	133
45	1.5	78	1.5	612	K513_0320 IE3D100LX04	92	32.31	20677/640	132
46	2.4	79	2.1	603	K613_0320 IE3D100LX04	113	31.86	130479/4096	134
50	1.6	86	1.6	552	K513_0290 IE3D100LX04	92	29.18	4669/160	132
50	2.7	87	2.2	545	K613_0290 IE3D100LX04	113	28.77	29463/1024	134
52	1.0	90	0.92	533	K402_0280 IE3D100LX04	86	27.77	1333/48	131
57	1.0	99	0.98	486	K402_0250 IE3D100LX04	86	25.28	4171/165	131
60	2.0	103	1.9	461	K513_0240 IE3D100LX04	92	24.35	11687/480	133
62	1.2	108	1.0	447	K402_0230 IE3D100LX04	86	23.29	559/24	131
66	2.2	114	2.0	416	K513_0220 IE3D100LX04	92	21.99	2639/120	133
72	0.90	–	–	389	K302_0200 IE3D100LX04	72	20.28	3569/176	130
72	1.4	124	1.1	388	K402_0200 IE3D100LX04	86	20.20	1333/66	131
75	2.5	130	2.2	366	K513_0195 IE3D100LX04	92	19.35	27869/1440	134
76	3.0	132	3.0	360	K613_0190 IE3D100LX04	113	18.99	17019/896	138
84	1.0	145	0.84	332	K302_0175 IE3D100LX04	72	17.29	1591/92	131
83	1.5	144	1.3	334	K402_0175 IE3D100LX04	86	17.41	731/42	131
83	2.7	144	2.4	331	K513_0175 IE3D100LX04	92	17.48	6293/360	134
86	1.0	148	0.86	325	K302_0170 IE3D100LX04	72	16.94	559/33	131
86	1.5	148	1.3	325	K402_0170 IE3D100LX04	86	16.94	559/33	131
85	3.0	146	3.0	325	K613_0170 IE3D100LX04	113	17.16	549/32	138
90	3.0	–	–	305	K513_0160 IE3D100LX04	92	16.09	26071/1620	135
100	3.0	–	–	275	K513_0145 IE3D100LX04	92	14.54	5887/405	136
104	1.2	180	0.97	268	K302_0140 IE3D100LX04	72	13.94	1505/108	131
104	1.7	181	1.5	267	K402_0140 IE3D100LX04	86	13.89	1333/96	132
115	1.2	200	1.0	242	K302_0125 IE3D100LX04	72	12.58	3182/253	131
115	1.8	198	1.6	243	K402_0125 IE3D100LX04	86	12.66	2924/231	132
125	1.3	216	1.1	223	K302_0115 IE3D100LX04	72	11.61	1161/100	131
126	2.0	218	1.7	221	K402_0115 IE3D100LX04	86	11.52	645/56	133
144	0.82	–	–	193	K202_0100 IE3D100LX04	67	10.07	2881/286	131
143	1.4	248	1.2	195	K302_0100 IE3D100LX04	72	10.14	3010/297	131
144	2.1	249	1.8	194	K402_0100 IE3D100LX04	86	10.10	1333/132	132
156	1.5	271	1.3	178	K302_0093 IE3D100LX04	72	9.267	1075/116	132
158	0.87	–	–	177	K202_0092 IE3D100LX04	67	9.190	2279/248	131
157	2.3	272	1.9	177	K402_0092 IE3D100LX04	86	9.238	2365/256	134
173	0.92	–	–	161	K202_0084 IE3D100LX04	67	8.397	2494/297	131
172	1.6	297	1.4	162	K302_0084 IE3D100LX04	72	8.444	2322/275	132
173	2.4	300	2.1	161	K402_0084 IE3D100LX04	86	8.377	645/77	133
196	1.8	340	1.5	142	K302_0074 IE3D100LX04	72	7.391	473/64	133
204	1.0	353	0.87	137	K202_0071 IE3D100LX04	67	7.118	2107/296	131
217	1.1	376	0.91	128	K202_0067 IE3D100LX04	67	6.683	2279/341	131
215	1.9	373	1.6	129	K302_0067 IE3D100LX04	72	6.740	2150/319	132
216	2.8	374	2.4	129	K402_0067 IE3D100LX04	86	6.719	215/32	134
242	1.2	419	0.98	115	K202_0060 IE3D100LX04	67	6.000	6/1	132
242	2.0	419	1.7	115	K302_0060 IE3D100LX04	72	6.000	6/1	133
270	2.2	467	1.8	103	K302_0054 IE3D100LX04	72	5.375	43/8	133
280	1.3	485	1.1	99	K202_0052 IE3D100LX04	67	5.177	2107/407	132
332	1.4	575	1.2	84	K202_0044 IE3D100LX04	67	4.364	48/11	132
332	2.5	575	2.1	84	K302_0044 IE3D100LX04	72	4.364	48/11	134
363	1.5	628	1.3	77	K202_0040 IE3D100LX04	67	4.000	4/1	132
363	2.7	628	2.2	77	K302_0040 IE3D100LX04	72	4.000	4/1	135
P_N (50 Hz) = 4,00 kW, P_N (87 Hz) = 6,93 kW									
5.9	0.90	–	–	6067	K914_2470 IE3D112M04	328	247.0	3288449/13312	171
7.6	0.89	13	0.80	4713	K814_1920 IE3D112M04	214	191.9	85963/448	171
7.6	1.1	13	0.93	4707	K914_1920 IE3D112M04	328	191.7	4710481/24576	172
8.5	0.95	15	0.80	4257	K814_1730 IE3D112M04	214	173.3	2773/16	171
9.3	1.1	16	0.93	3849	K814_1570 IE3D112M04	214	156.7	601741/3840	171
9.8	1.2	17	1.1	3659	K914_1490 IE3D112M04	328	149.0	9154331/61440	172
10	1.1	18	0.93	3476	K814_1420 IE3D112M04	214	141.5	135877/960	171

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 4,00 kW, P_N (87 Hz) = 6,93 kW									
12	1.2	20	1.1	3116	K814_1270 IE3D112M04	214	126.9	1461371/11520	172
12	1.2	20	1.2	3089	K914_1260 IE3D112M04	328	125.8	2221925/17664	173
13	0.85	22	0.85	2817	K714_1150 IE3D112M04	156	114.7	117453/1024	171
13	1.2	22	1.1	2814	K814_1150 IE3D112M04	214	114.6	329987/2880	172
15	0.99	26	0.99	2422	K714_0990 IE3D112M04	156	98.60	1009701/10240	171
15	1.2	26	1.2	2424	K813_0970 IE3D112M04	201	97.17	31093/320	173
16	1.2	27	1.2	2303	K914_0940 IE3D112M04	328	93.78	4177219/44544	174
16	1.1	28	1.1	2187	K714_0890 IE3D112M04	156	89.06	227997/2560	171
17	1.2	29	1.2	2190	K813_0880 IE3D112M04	201	87.76	7021/80	173
19	1.2	32	1.2	1967	K713_0790 IE3D112M04	147	78.83	20181/256	172
18	1.3	32	1.3	1981	K813_0790 IE3D112M04	201	79.38	45725/576	174
20	1.3	35	1.3	1789	K813_0720 IE3D112M04	201	71.70	10325/144	174
21	1.2	36	1.2	1777	K713_0710 IE3D112M04	147	71.20	4557/64	172
23	1.4	39	1.4	1618	K713_0650 IE3D112M04	147	64.85	33201/512	172
23	0.91	40	0.91	1590	K613_0640 IE3D112M04	119	63.71	130479/2048	171
25	1.4	43	1.4	1461	K713_0590 IE3D112M04	147	58.57	7497/128	173
25	1.0	44	1.0	1436	K613_0580 IE3D112M04	119	57.55	29463/512	171
29	1.6	51	1.6	1245	K713_0500 IE3D112M04	147	49.88	166005/3328	174
30	1.8	52	1.8	1222	K813_0490 IE3D112M04	201	48.99	5487/112	179
31	1.2	53	1.2	1191	K613_0480 IE3D112M04	119	47.73	39711/832	172
33	1.6	56	1.6	1124	K713_0450 IE3D112M04	147	45.05	37485/832	174
34	0.83	58	0.83	1085	K513_0440 IE3D112M04	98	43.50	87/2	171
33	1.8	57	1.8	1104	K813_0440 IE3D112M04	201	44.25	177/4	179
34	1.3	59	1.3	1076	K613_0430 IE3D112M04	119	43.11	8967/208	172
38	0.94	66	0.94	961	K513_0390 IE3D112M04	98	38.53	2697/70	171
37	1.8	65	1.8	979	K713_0390 IE3D112M04	147	39.23	2511/64	176
38	1.5	66	1.4	956	K613_0380 IE3D112M04	119	38.32	156953/4096	173
42	1.0	73	1.0	868	K513_0350 IE3D112M04	98	34.80	174/5	172
42	1.7	73	1.5	864	K613_0350 IE3D112M04	119	34.61	35441/1024	173
41	1.8	72	1.8	884	K713_0350 IE3D112M04	147	35.44	567/16	176
45	1.1	79	1.1	806	K513_0320 IE3D112M04	98	32.31	20677/640	172
46	1.8	80	1.6	795	K613_0320 IE3D112M04	119	31.86	130479/4096	174
50	1.2	87	1.2	728	K513_0290 IE3D112M04	98	29.18	4669/160	172
51	2.0	88	1.7	718	K613_0290 IE3D112M04	119	28.77	29463/1024	174
60	1.5	104	1.4	608	K513_0240 IE3D112M04	98	24.35	11687/480	173
63	0.93	–	–	590	K402_0230 IE3D112M04	92	23.29	559/24	171
67	1.6	115	1.5	549	K513_0220 IE3D112M04	98	21.99	2639/120	173
73	1.0	126	0.87	511	K402_0200 IE3D112M04	92	20.20	1333/66	171
76	1.9	131	1.7	483	K513_0195 IE3D112M04	98	19.35	27869/1440	174
77	2.3	134	2.2	474	K613_0190 IE3D112M04	119	18.99	17019/896	178
84	1.1	146	0.96	441	K402_0175 IE3D112M04	92	17.41	731/42	171
84	2.1	145	1.8	436	K513_0175 IE3D112M04	98	17.48	6293/360	174
86	1.2	150	0.97	429	K402_0170 IE3D112M04	92	16.94	559/33	171
85	2.3	148	2.3	428	K613_0170 IE3D112M04	119	17.16	549/32	178
91	2.2	–	–	402	K513_0160 IE3D112M04	98	16.09	26071/1620	175
101	2.3	–	–	363	K513_0145 IE3D112M04	98	14.54	5887/405	176
105	0.88	–	–	353	K302_0140 IE3D112M04	78	13.94	1505/108	171
106	1.3	183	1.1	352	K402_0140 IE3D112M04	92	13.89	1333/96	172
116	0.94	–	–	318	K302_0125 IE3D112M04	78	12.58	3182/253	171
116	1.4	200	1.2	320	K402_0125 IE3D112M04	92	12.66	2924/231	172
126	0.99	219	0.83	294	K302_0115 IE3D112M04	78	11.61	1161/100	171
127	1.5	220	1.3	292	K402_0115 IE3D112M04	92	11.52	645/56	173
145	1.1	250	0.91	257	K302_0100 IE3D112M04	78	10.14	3010/297	171
145	1.6	251	1.4	256	K402_0100 IE3D112M04	92	10.10	1333/132	172
158	1.1	274	0.97	235	K302_0093 IE3D112M04	78	9.267	1075/116	172
159	1.7	275	1.5	234	K402_0092 IE3D112M04	92	9.238	2365/256	174
173	1.2	301	1.0	214	K302_0084 IE3D112M04	78	8.444	2322/275	172
175	1.8	303	1.6	212	K402_0084 IE3D112M04	92	8.377	645/77	173
198	1.3	343	1.1	187	K302_0074 IE3D112M04	78	7.391	473/64	173
219	0.82	–	–	169	K202_0067 IE3D112M04	73	6.683	2279/341	171
217	1.4	376	1.2	171	K302_0067 IE3D112M04	78	6.740	2150/319	172
218	2.1	378	1.8	170	K402_0067 IE3D112M04	92	6.719	215/32	174
244	0.88	–	–	152	K202_0060 IE3D112M04	73	6.000	6/1	172
244	1.5	423	1.3	152	K302_0060 IE3D112M04	78	6.000	6/1	173
273	1.7	472	1.4	136	K302_0054 IE3D112M04	78	5.375	43/8	173

4.2 Selection tables 4 K helical bevel geared motors

n_2 50 Hz [rpm]	S	n_2 87 Hz [rpm]	S	M_{2N} [Nm]	Type	m [kg]	i	i_{exakt}	J_1 [kgcm ²]
P_N (50 Hz) = 4,00 kW, P_N (87 Hz) = 6,93 kW									
283	0.97	490	0.82	131	K202_0052 IE3D112M04	73	5.177	2107/407	172
336	1.1	581	0.91	110	K202_0044 IE3D112M04	73	4.364	48/11	172
336	1.9	581	1.6	110	K302_0044 IE3D112M04	78	4.364	48/11	174
366	1.1	634	0.97	101	K202_0040 IE3D112M04	73	4.000	4/1	172
366	2.0	634	1.7	101	K302_0040 IE3D112M04	78	4.000	4/1	175
P_N (50 Hz) = 5,50 kW, P_N (87 Hz) = 9,53 kW									
5.0	1.1	–	–	9836	K1014_2900 IE3D132SX04	571	290.4	392553/1352	353
6.0	0.85	10	0.85	8241	K914_2430 IE3D132SX04	362	243.3	5667327/23296	353
6.2	1.3	–	–	8043	K1014_2370 IE3D132SX04	571	237.4	49383/208	354
7.8	1.1	13	1.1	6394	K914_1890 IE3D132SX04	362	188.8	2706021/14336	353
9.5	0.80	16	0.80	5228	K814_1540 IE3D132SX04	248	154.3	49383/320	352
9.8	1.9	–	–	5044	K1014_1490 IE3D132SX04	571	148.9	30969/208	356
10	1.4	17	1.4	4971	K914_1470 IE3D132SX04	362	146.7	5258871/35840	354
11	0.89	18	0.89	4722	K814_1390 IE3D132SX04	248	139.4	11151/80	352
12	0.99	20	0.99	4232	K814_1250 IE3D132SX04	248	124.9	279837/2240	353
12	1.7	20	1.6	4196	K914_1240 IE3D132SX04	362	123.9	1276425/10304	354
13	1.1	22	1.1	3823	K814_1130 IE3D132SX04	248	112.8	9027/80	353
15	1.3	26	1.3	3334	K814_0980 IE3D132SX04	248	98.41	181071/1840	353
15	1.6	27	1.6	3284	K913_0950 IE3D132SX04	350	95.41	293105/3072	356
16	2.2	27	1.9	3129	K914_0920 IE3D132SX04	362	92.35	2399679/25984	356
16	1.4	29	1.4	3011	K814_0890 IE3D132SX04	248	88.89	40887/460	353
18	1.5	32	1.5	2732	K813_0790 IE3D132SX04	235	79.38	45725/576	354
20	2.6	34	2.6	2581	K913_0750 IE3D132SX04	350	75.00	62403/832	360
20	1.7	34	1.7	2507	K814_0740 IE3D132SX04	248	73.99	1201653/16240	354
20	1.5	35	1.5	2468	K813_0720 IE3D132SX04	235	71.70	10325/144	354
22	1.9	38	1.9	2264	K814_0670 IE3D132SX04	248	66.83	38763/580	354
23	1.1	39	1.1	2232	K713_0650 IE3D132SX04	181	64.85	33201/512	352
22	1.9	39	1.9	2251	K813_0650 IE3D132SX04	235	65.41	188387/2880	355
23	2.6	40	2.6	2171	K913_0630 IE3D132SX04	350	63.07	209901/3328	363
25	1.2	43	1.2	2016	K713_0590 IE3D132SX04	181	58.57	7497/128	353
25	2.1	43	2.1	2033	K813_0590 IE3D132SX04	235	59.08	42539/720	356
29	1.4	51	1.4	1717	K713_0500 IE3D132SX04	181	49.88	166005/3328	354
30	2.5	52	2.4	1686	K813_0490 IE3D132SX04	235	48.99	5487/112	359
33	1.5	56	1.5	1551	K713_0450 IE3D132SX04	181	45.05	37485/832	354
33	2.8	57	2.6	1523	K813_0440 IE3D132SX04	235	44.25	177/4	359
37	3.1	63	2.8	1377	K813_0400 IE3D132SX04	235	40.01	12803/320	362
37	1.8	65	1.6	1350	K713_0390 IE3D132SX04	181	39.23	2511/64	356
38	1.1	66	1.0	1319	K613_0380 IE3D132SX04	153	38.32	156953/4096	353
39	3.5	67	3.5	1309	K913_0380 IE3D132SX04	350	38.04	194773/5120	380
41	3.1	70	3.0	1244	K813_0360 IE3D132SX04	235	36.14	2891/80	363
42	1.2	73	1.1	1191	K613_0350 IE3D132SX04	153	34.61	35441/1024	353
41	2.0	72	1.8	1220	K713_0350 IE3D132SX04	181	35.44	567/16	356
45	0.81	79	0.81	1112	K513_0320 IE3D132SX04	132	32.31	20677/640	352
46	1.3	80	1.2	1096	K613_0320 IE3D132SX04	153	31.86	130479/4096	354
45	2.2	78	1.9	1116	K713_0320 IE3D132SX04	181	32.42	33201/1024	358
50	0.90	87	0.90	1004	K513_0290 IE3D132SX04	132	29.18	4669/160	352
51	1.5	88	1.2	990	K613_0290 IE3D132SX04	153	28.77	29463/1024	354
50	2.4	87	2.0	1008	K713_0290 IE3D132SX04	181	29.29	7497/256	358
57	4.0	–	–	878	K813_0260 IE3D132SX04	235	25.51	140833/5520	375
58	2.6	–	–	866	K713_0250 IE3D132SX04	181	25.18	64449/2560	362
60	1.1	104	1.0	838	K513_0240 IE3D132SX04	132	24.35	11687/480	353
61	1.6	106	1.4	826	K613_0240 IE3D132SX04	153	24.01	24583/1024	356
61	4.4	–	–	824	K913_0240 IE3D132SX04	350	23.94	88877/3712	411
64	2.8	–	–	783	K713_0230 IE3D132SX04	181	22.74	14553/640	362
67	1.2	115	1.1	757	K513_0220 IE3D132SX04	132	21.99	2639/120	353
68	1.8	117	1.5	746	K613_0220 IE3D132SX04	153	21.68	5551/256	356
72	3.0	–	–	696	K713_0200 IE3D132SX04	181	20.23	119133/5888	366
76	1.4	131	1.2	666	K513_0195 IE3D132SX04	132	19.35	27869/1440	354
77	1.9	134	1.6	654	K613_0190 IE3D132SX04	153	18.99	17019/896	358
76	4.4	–	–	660	K813_0190 IE3D132SX04	235	19.18	133517/6960	388
80	3.2	–	–	629	K713_0185 IE3D132SX04	181	18.28	26901/1472	367
84	0.82	–	–	608	K402_0175 IE3D132SX04	126	17.41	731/42	351
84	1.5	145	1.3	602	K513_0175 IE3D132SX04	132	17.48	6293/360	354
85	4.4	–	–	596	K813_0175 IE3D132SX04	235	17.33	30149/1740	390
86	0.84	–	–	592	K402_0170 IE3D132SX04	126	16.94	559/33	351

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 5,50 kW, P_N (87 Hz) = 9,53 kW									
85	2.1	148	1.7	590	K613_0170 IE3D132SX04	153	17.16	549/32	358
89	3.5	–	–	564	K713_0165 IE3D132SX04	181	16.39	6293/384	371
91	1.6	–	–	554	K513_0160 IE3D132SX04	132	16.09	26071/1620	355
92	2.2	–	–	546	K613_0160 IE3D132SX04	153	15.87	54839/3456	360
99	3.7	–	–	509	K713_0150 IE3D132SX04	181	14.80	1421/96	372
101	1.7	–	–	500	K513_0145 IE3D132SX04	132	14.54	5887/405	356
102	2.3	–	–	493	K613_0145 IE3D132SX04	153	14.33	12383/864	361
106	0.96	183	0.81	485	K402_0140 IE3D132SX04	126	13.89	1333/96	352
114	1.9	–	–	441	K513_0130 IE3D132SX04	132	12.81	1537/120	357
112	4.1	–	–	449	K713_0130 IE3D132SX04	181	13.04	3339/256	379
116	1.0	200	0.86	442	K402_0125 IE3D132SX04	126	12.66	2924/231	352
116	2.5	–	–	435	K613_0125 IE3D132SX04	153	12.63	3233/256	364
124	4.3	–	–	405	K713_0120 IE3D132SX04	181	11.78	23373/1984	381
127	1.1	220	0.91	402	K402_0115 IE3D132SX04	126	11.52	645/56	353
127	2.0	–	–	398	K513_0115 IE3D132SX04	132	11.57	10759/930	358
145	1.2	251	1.0	353	K402_0100 IE3D132SX04	126	10.10	1333/132	352
144	2.2	–	–	349	K513_0100 IE3D132SX04	132	10.15	203/20	360
159	1.3	275	1.1	323	K402_0092 IE3D132SX04	126	9.238	2365/256	354
160	2.4	–	–	316	K513_0092 IE3D132SX04	132	9.168	1421/155	361
175	1.3	303	1.1	293	K402_0084 IE3D132SX04	126	8.377	645/77	353
180	2.6	–	–	280	K513_0081 IE3D132SX04	132	8.134	17081/2100	364
196	1.4	340	1.2	260	K402_0075 IE3D132SX04	126	7.456	1849/248	355
199	2.7	–	–	253	K513_0073 IE3D132SX04	132	7.347	551/75	366
218	1.5	378	1.3	235	K402_0067 IE3D132SX04	126	6.719	215/32	354
244	1.7	423	1.4	210	K402_0060 IE3D132SX04	126	6.000	6/1	357
270	1.8	468	1.5	189	K402_0054 IE3D132SX04	126	5.422	1849/341	356
336	2.1	581	1.7	152	K402_0044 IE3D132SX04	126	4.364	48/11	358
366	2.2	634	1.8	140	K402_0040 IE3D132SX04	126	4.000	4/1	360
P_N (50 Hz) = 7,50 kW, P_N (87 Hz) = 12,99 kW									
5.1	0.80	–	–	13388	K1014_2900 IE3D132MX04	569	290.4	392553/1352	353
6.2	0.95	–	–	10947	K1014_2370 IE3D132MX04	569	237.4	49383/208	354
7.8	0.80	13	0.80	8703	K914_1890 IE3D132MX04	360	188.8	2706021/14336	353
9.9	1.4	–	–	6865	K1014_1490 IE3D132MX04	569	148.9	30969/208	356
10	1.0	17	1.0	6766	K914_1470 IE3D132MX04	360	146.7	5258871/35840	354
12	1.2	21	1.1	5712	K914_1240 IE3D132MX04	360	123.9	1276425/10304	354
13	0.81	23	0.81	5203	K814_1130 IE3D132MX04	246	112.8	9027/80	353
15	0.93	26	0.93	4537	K814_0980 IE3D132MX04	246	98.41	181071/1840	353
15	1.2	27	1.2	4469	K913_0950 IE3D132MX04	348	95.41	293105/3072	356
16	1.6	28	1.4	4258	K914_0920 IE3D132MX04	360	92.35	2399679/25984	356
17	1.0	29	1.0	4098	K814_0890 IE3D132MX04	246	88.89	40887/460	353
19	1.1	32	1.1	3719	K813_0790 IE3D132MX04	233	79.38	45725/576	354
20	1.9	34	1.9	3513	K913_0750 IE3D132MX04	348	75.00	62403/832	360
20	1.2	34	1.2	3412	K814_0740 IE3D132MX04	246	73.99	1201653/16240	354
21	1.1	36	1.1	3359	K813_0720 IE3D132MX04	233	71.70	10325/144	354
22	1.4	38	1.4	3082	K814_0670 IE3D132MX04	246	66.83	38763/580	354
22	1.4	39	1.4	3064	K813_0650 IE3D132MX04	233	65.41	188387/2880	355
23	1.9	40	1.9	2954	K913_0630 IE3D132MX04	348	63.07	209901/3328	363
25	0.88	43	0.88	2744	K713_0590 IE3D132MX04	179	58.57	7497/128	353
25	1.5	43	1.5	2768	K813_0590 IE3D132MX04	233	59.08	42539/720	356
29	1.0	51	1.0	2337	K713_0500 IE3D132MX04	179	49.88	166005/3328	354
30	1.8	52	1.8	2295	K813_0490 IE3D132MX04	233	48.99	5487/112	359
30	2.2	52	2.2	2292	K913_0490 IE3D132MX04	348	48.94	100223/2048	370
33	1.1	57	1.1	2111	K713_0450 IE3D132MX04	179	45.05	37485/832	354
33	2.0	58	1.9	2073	K813_0440 IE3D132MX04	233	44.25	177/4	359
37	2.2	64	2.1	1874	K813_0400 IE3D132MX04	233	40.01	12803/320	362
37	1.3	65	1.2	1838	K713_0390 IE3D132MX04	179	39.23	2511/64	356
38	0.81	–	–	1795	K613_0380 IE3D132MX04	151	38.32	156953/4096	353
39	2.6	67	2.6	1782	K913_0380 IE3D132MX04	348	38.04	194773/5120	380
41	2.3	70	2.2	1693	K813_0360 IE3D132MX04	233	36.14	2891/80	363
42	0.89	74	0.80	1621	K613_0350 IE3D132MX04	151	34.61	35441/1024	353
41	1.4	72	1.3	1660	K713_0350 IE3D132MX04	179	35.44	567/16	356
46	0.97	80	0.85	1492	K613_0320 IE3D132MX04	151	31.86	130479/4096	354
45	1.6	79	1.4	1519	K713_0320 IE3D132MX04	179	32.42	33201/1024	358
45	2.7	79	2.4	1517	K813_0320 IE3D132MX04	233	32.39	31093/960	367
51	1.1	88	0.91	1348	K613_0290 IE3D132MX04	151	28.77	29463/1024	354

4.2 Selection tables 4 K helical bevel geared motors

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 7,50 kW, P_N (87 Hz) = 12,99 kW									
50	1.7	87	1.5	1372	K713_0290 IE3D132MX04	179	29.29	7497/256	358
50	2.7	87	2.5	1370	K813_0290 IE3D132MX04	233	29.25	7021/240	368
58	2.9	–	–	1195	K813_0260 IE3D132MX04	233	25.51	140833/5520	375
58	1.9	–	–	1179	K713_0250 IE3D132MX04	179	25.18	64449/2560	362
61	1.2	106	1.0	1125	K613_0240 IE3D132MX04	151	24.01	24583/1024	356
61	3.2	–	–	1122	K913_0240 IE3D132MX04	348	23.94	88877/3712	411
65	2.1	–	–	1065	K713_0230 IE3D132MX04	179	22.74	14553/640	362
67	0.87	116	0.82	1030	K513_0220 IE3D132MX04	130	21.99	2639/120	353
68	1.3	117	1.1	1016	K613_0220 IE3D132MX04	151	21.68	5551/256	356
73	2.2	–	–	948	K713_0200 IE3D132MX04	179	20.23	119133/5888	366
76	0.99	132	0.89	907	K513_0195 IE3D132MX04	130	19.35	27869/1440	354
77	1.4	134	1.2	890	K613_0190 IE3D132MX04	151	18.99	17019/896	358
77	3.3	–	–	899	K813_0190 IE3D132MX04	233	19.18	133517/6960	388
80	2.4	–	–	856	K713_0185 IE3D132MX04	179	18.28	26901/1472	367
84	1.1	146	0.96	819	K513_0175 IE3D132MX04	130	17.48	6293/360	354
85	3.3	–	–	812	K813_0175 IE3D132MX04	233	17.33	30149/1740	390
86	1.5	148	1.3	804	K613_0170 IE3D132MX04	151	17.16	549/32	358
90	2.6	–	–	768	K713_0165 IE3D132MX04	179	16.39	6293/384	371
91	1.2	–	–	754	K513_0160 IE3D132MX04	130	16.09	26071/1620	355
93	1.6	–	–	743	K613_0160 IE3D132MX04	151	15.87	54839/3456	360
99	2.7	–	–	693	K713_0150 IE3D132MX04	179	14.80	1421/96	372
101	1.3	–	–	681	K513_0145 IE3D132MX04	130	14.54	5887/405	356
103	1.7	–	–	671	K613_0145 IE3D132MX04	151	14.33	12383/864	361
115	1.4	–	–	600	K513_0130 IE3D132MX04	130	12.81	1537/120	357
113	3.0	–	–	611	K713_0130 IE3D132MX04	179	13.04	3339/256	379
116	1.9	–	–	592	K613_0125 IE3D132MX04	151	12.63	3233/256	364
125	3.2	–	–	552	K713_0120 IE3D132MX04	179	11.78	23373/1984	381
127	1.5	–	–	542	K513_0115 IE3D132MX04	130	11.57	10759/930	358
129	2.0	–	–	534	K613_0115 IE3D132MX04	151	11.41	22631/1984	365
146	0.87	–	–	480	K402_0100 IE3D132MX04	124	10.10	1333/132	352
145	1.6	–	–	475	K513_0100 IE3D132MX04	130	10.15	203/20	360
159	0.92	–	–	439	K402_0092 IE3D132MX04	124	9.238	2365/256	354
160	1.7	–	–	429	K513_0092 IE3D132MX04	130	9.168	1421/155	361
175	0.98	304	0.83	398	K402_0084 IE3D132MX04	124	8.377	645/77	353
181	1.9	–	–	381	K513_0081 IE3D132MX04	130	8.134	17081/2100	364
181	2.5	–	–	380	K613_0081 IE3D132MX04	151	8.107	85095/10496	377
197	1.1	341	0.90	354	K402_0075 IE3D132MX04	124	7.456	1849/248	355
200	2.0	–	–	344	K513_0073 IE3D132MX04	130	7.347	551/75	366
219	1.1	379	0.96	319	K402_0067 IE3D132MX04	124	6.719	215/32	354
245	1.2	424	1.0	285	K402_0060 IE3D132MX04	124	6.000	6/1	357
271	1.3	470	1.1	258	K402_0054 IE3D132MX04	124	5.422	1849/341	356
337	1.5	583	1.3	207	K402_0044 IE3D132MX04	124	4.364	48/11	358
368	1.6	637	1.4	190	K402_0040 IE3D132MX04	124	4.000	4/1	360
P_N (50 Hz) = 11,00 kW, P_N (87 Hz) = 19,05 kW									
7.7	0.93	–	–	12902	K1014_1900 IE3D160MX04	586	190.4	514941/2704	436
9.7	1.2	–	–	10260	K1014_1510 IE3D160MX04	586	151.4	409479/2704	437
12	1.2	–	–	8382	K1014_1240 IE3D160MX04	586	123.7	7359555/59488	439
15	0.82	27	0.82	6567	K913_0950 IE3D160MX04	365	95.41	293105/3072	436
16	1.1	–	–	6493	K1013_0940 IE3D160MX04	557	94.33	235445/2496	444
16	1.2	–	–	6324	K1014_0930 IE3D160MX04	586	93.34	252399/2704	442
20	1.3	34	1.3	5163	K913_0750 IE3D160MX04	365	75.00	62403/832	440
22	0.93	39	0.93	4502	K813_0650 IE3D160MX04	250	65.41	188387/2880	435
23	1.3	40	1.3	4341	K913_0630 IE3D160MX04	365	63.07	209901/3328	443
25	1.0	43	1.0	4067	K813_0590 IE3D160MX04	250	59.08	42539/720	436
30	1.2	52	1.2	3372	K813_0490 IE3D160MX04	250	48.99	5487/112	439
30	1.5	52	1.5	3368	K913_0490 IE3D160MX04	365	48.94	100223/2048	450
33	1.4	57	1.3	3046	K813_0440 IE3D160MX04	250	44.25	177/4	439
37	1.5	63	1.4	2754	K813_0400 IE3D160MX04	250	40.01	12803/320	442
37	0.89	65	0.82	2701	K713_0390 IE3D160MX04	196	39.23	2511/64	436
39	1.8	67	1.8	2619	K913_0380 IE3D160MX04	365	38.04	194773/5120	460
41	1.6	70	1.5	2487	K813_0360 IE3D160MX04	250	36.14	2891/80	443
41	0.98	72	0.88	2439	K713_0350 IE3D160MX04	196	35.44	567/16	436
45	1.1	78	0.93	2232	K713_0320 IE3D160MX04	196	32.42	33201/1024	438
45	1.9	78	1.6	2229	K813_0320 IE3D160MX04	250	32.39	31093/960	447
46	1.9	79	1.9	2211	K913_0320 IE3D160MX04	365	32.12	47275/1472	469

n_2	S	n_2	S	M_{2N}	Type	m	i	i_{exakt}	J_1
50 Hz		87 Hz							
[rpm]		[rpm]		[Nm]		[kg]			[kgcm ²]
P_N (50 Hz) = 11,00 kW, P_N (87 Hz) = 19,05 kW									
50	1.2	87	1.0	2016	K713_0290 IE3D160MX04	196	29.29	7497/256	438
50	1.9	87	1.7	2014	K813_0290 IE3D160MX04	250	29.25	7021/240	448
57	2.0	–	–	1756	K813_0260 IE3D160MX04	250	25.51	140833/5520	455
58	1.3	–	–	1733	K713_0250 IE3D160MX04	196	25.18	64449/2560	442
61	0.82	–	–	1652	K613_0240 IE3D160MX04	168	24.01	24583/1024	436
61	2.2	–	–	1648	K913_0240 IE3D160MX04	365	23.94	88877/3712	491
64	1.4	–	–	1565	K713_0230 IE3D160MX04	196	22.74	14553/640	442
64	2.0	–	–	1586	K813_0230 IE3D160MX04	250	23.04	31801/1380	456
68	0.88	–	–	1493	K613_0220 IE3D160MX04	168	21.68	5551/256	436
72	1.5	–	–	1393	K713_0200 IE3D160MX04	196	20.23	119133/5888	446
77	0.96	134	0.81	1307	K613_0190 IE3D160MX04	168	18.99	17019/896	438
76	2.2	–	–	1320	K813_0190 IE3D160MX04	250	19.18	133517/6960	468
80	1.6	–	–	1258	K713_0185 IE3D160MX04	196	18.28	26901/1472	447
85	2.2	–	–	1193	K813_0175 IE3D160MX04	250	17.33	30149/1740	470
85	1.0	148	0.87	1181	K613_0170 IE3D160MX04	168	17.16	549/32	438
89	1.7	–	–	1128	K713_0165 IE3D160MX04	196	16.39	6293/384	451
92	1.1	–	–	1092	K613_0160 IE3D160MX04	168	15.87	54839/3456	440
99	1.9	–	–	1019	K713_0150 IE3D160MX04	196	14.80	1421/96	452
102	1.2	–	–	987	K613_0145 IE3D160MX04	168	14.33	12383/864	441
112	2.0	–	–	898	K713_0130 IE3D160MX04	196	13.04	3339/256	459
116	1.3	–	–	869	K613_0125 IE3D160MX04	168	12.63	3233/256	444
124	2.2	–	–	811	K713_0120 IE3D160MX04	196	11.78	23373/1984	461
128	1.4	–	–	785	K613_0115 IE3D160MX04	168	11.41	22631/1984	445
181	1.7	–	–	558	K613_0081 IE3D160MX04	168	8.107	85095/10496	457
200	1.8	–	–	504	K613_0073 IE3D160MX04	168	7.323	19215/2624	459
P_N (50 Hz) = 15,00 kW, P_N (87 Hz) = 25,98 kW									
9.7	0.87	–	–	13823	K1014_1510 IE3D160LX04	646	151.4	409479/2704	1157
12	0.93	–	–	11292	K1014_1240 IE3D160LX04	646	123.7	7359555/59488	1159
16	0.84	–	–	8747	K1013_0940 IE3D160LX04	617	94.33	235445/2496	1164
16	0.93	–	–	8520	K1014_0930 IE3D160LX04	646	93.34	252399/2704	1162
20	0.98	34	0.98	6955	K913_0750 IE3D160LX04	425	75.00	62403/832	1160
23	0.98	41	0.98	5849	K913_0630 IE3D160LX04	425	63.07	209901/3328	1163
30	0.92	52	0.91	4543	K813_0490 IE3D160LX04	310	48.99	5487/112	1159
30	1.1	52	1.1	4538	K913_0490 IE3D160LX04	425	48.94	100223/2048	1170
33	1.0	58	0.97	4103	K813_0440 IE3D160LX04	310	44.25	177/4	1159
37	1.1	64	1.0	3710	K813_0400 IE3D160LX04	310	40.01	12803/320	1162
39	1.3	67	1.3	3528	K913_0380 IE3D160LX04	425	38.04	194773/5120	1180
41	1.2	71	1.1	3351	K813_0360 IE3D160LX04	310	36.14	2891/80	1163
46	1.4	79	1.2	3003	K813_0320 IE3D160LX04	310	32.39	31093/960	1167
46	1.4	80	1.4	2978	K913_0320 IE3D160LX04	425	32.12	47275/1472	1189
50	0.88	–	–	2716	K713_0290 IE3D160LX04	256	29.29	7497/256	1158
50	1.4	87	1.3	2713	K813_0290 IE3D160LX04	310	29.25	7021/240	1168
58	1.5	–	–	2366	K813_0260 IE3D160LX04	310	25.51	140833/5520	1175
59	0.97	–	–	2335	K713_0250 IE3D160LX04	256	25.18	64449/2560	1162
62	1.6	–	–	2220	K913_0240 IE3D160LX04	425	23.94	88877/3712	1211
65	1.0	–	–	2109	K713_0230 IE3D160LX04	256	22.74	14553/640	1162
64	1.5	–	–	2137	K813_0230 IE3D160LX04	310	23.04	31801/1380	1176
73	1.1	–	–	1876	K713_0200 IE3D160LX04	256	20.23	119133/5888	1166
77	1.6	–	–	1779	K813_0190 IE3D160LX04	310	19.18	133517/6960	1188
81	1.2	–	–	1695	K713_0185 IE3D160LX04	256	18.28	26901/1472	1167
85	1.6	–	–	1607	K813_0175 IE3D160LX04	310	17.33	30149/1740	1190
90	1.3	–	–	1520	K713_0165 IE3D160LX04	256	16.39	6293/384	1171
93	0.81	–	–	1471	K613_0160 IE3D160LX04	228	15.87	54839/3456	1160
100	1.4	–	–	1373	K713_0150 IE3D160LX04	256	14.80	1421/96	1172
103	0.86	–	–	1329	K613_0145 IE3D160LX04	228	14.33	12383/864	1161
113	1.5	–	–	1210	K713_0130 IE3D160LX04	256	13.04	3339/256	1179
117	0.94	–	–	1171	K613_0125 IE3D160LX04	228	12.63	3233/256	1164
125	1.6	–	–	1092	K713_0120 IE3D160LX04	256	11.78	23373/1984	1181
129	1.0	–	–	1058	K613_0115 IE3D160LX04	228	11.41	22631/1984	1165
182	1.3	–	–	752	K613_0081 IE3D160LX04	228	8.107	85095/10496	1177
201	1.4	–	–	679	K613_0073 IE3D160LX04	228	7.323	19215/2624	1179
P_N (50 Hz) = 18,50 kW, P_N (87 Hz) = 32,04 kW									
12	0.86	–	–	13970	K1014_1240 IE3D180MX04	641	123.7	7359555/59488	1159
16	1.0	–	–	10540	K1014_0930 IE3D180MX04	641	93.34	252399/2704	1162
20	1.3	–	–	8636	K1013_0750 IE3D180MX04	612	75.28	101773/1352	1172

4.2 Selection tables 4 K helical bevel geared motors

n_2 50 Hz [rpm]	S	n_2 87 Hz [rpm]	S	M_{2N} [Nm]	Type	m [kg]	i	i_{exakt}	J_1 [kgcm ²]
P_N (50 Hz) = 18,50 kW, P_N (87 Hz) = 32,04 kW									
23	0.97	41	0.97	7236	K913_0630 IE3D180MX04	420	63.07	209901/3328	1163
24	1.7	–	–	7061	K1013_0620 IE3D180MX04	612	61.55	12803/208	1181
30	1.2	52	1.2	5614	K913_0490 IE3D180MX04	420	48.94	100223/2048	1170
37	0.92	64	0.84	4590	K813_0400 IE3D180MX04	305	40.01	12803/320	1162
38	2.4	–	–	4428	K1013_0390 IE3D180MX04	612	38.60	8029/208	1216
39	1.6	67	1.6	4364	K913_0380 IE3D180MX04	420	38.04	194773/5120	1180
41	1.0	71	0.90	4146	K813_0360 IE3D180MX04	305	36.14	2891/80	1163
46	1.1	79	0.97	3716	K813_0320 IE3D180MX04	305	32.39	31093/960	1167
46	1.9	80	1.8	3684	K913_0320 IE3D180MX04	420	32.12	47275/1472	1189
50	1.2	87	1.0	3356	K813_0290 IE3D180MX04	305	29.25	7021/240	1168
58	1.3	–	–	2927	K813_0260 IE3D180MX04	305	25.51	140833/5520	1175
62	2.5	–	–	2747	K913_0240 IE3D180MX04	420	23.94	88877/3712	1211
65	0.84	–	–	2609	K713_0230 IE3D180MX04	251	22.74	14553/640	1162
64	1.4	–	–	2644	K813_0230 IE3D180MX04	305	23.04	31801/1380	1176
73	0.91	–	–	2321	K713_0200 IE3D180MX04	251	20.23	119133/5888	1166
77	1.6	–	–	2201	K813_0190 IE3D180MX04	305	19.18	133517/6960	1188
77	2.5	–	–	2187	K913_0190 IE3D180MX04	420	19.06	305/16	1235
81	0.97	–	–	2097	K713_0185 IE3D180MX04	251	18.28	26901/1472	1167
85	1.7	–	–	1988	K813_0175 IE3D180MX04	305	17.33	30149/1740	1190
90	1.0	–	–	1880	K713_0165 IE3D180MX04	251	16.39	6293/384	1171
90	1.8	–	–	1885	K813_0165 IE3D180MX04	305	16.43	42067/2560	1196
100	1.1	–	–	1698	K713_0150 IE3D180MX04	251	14.80	1421/96	1172
99	1.9	–	–	1703	K813_0150 IE3D180MX04	305	14.84	9499/640	1200
113	1.2	–	–	1496	K713_0130 IE3D180MX04	251	13.04	3339/256	1179
118	2.5	–	–	1437	K913_0125 IE3D180MX04	420	12.53	73749/5888	1308
125	1.3	–	–	1352	K713_0120 IE3D180MX04	251	11.78	23373/1984	1181
143	2.5	–	–	1179	K813_0105 IE3D180MX04	305	10.28	53041/5160	1242
145	1.4	–	–	1167	K713_0100 IE3D180MX04	251	10.17	651/64	1192
159	2.5	–	–	1065	K813_0093 IE3D180MX04	305	9.284	11977/1290	1251
161	1.5	–	–	1054	K713_0092 IE3D180MX04	251	9.188	147/16	1194
176	1.6	–	–	961	K713_0084 IE3D180MX04	251	8.373	87885/10496	1205
179	2.5	–	–	946	K813_0082 IE3D180MX04	305	8.243	96937/11760	1279
182	1.0	–	–	930	K613_0081 IE3D180MX04	223	8.107	85095/10496	1177
195	1.7	–	–	868	K713_0076 IE3D180MX04	251	7.563	19845/2624	1209
198	2.5	–	–	854	K813_0074 IE3D180MX04	305	7.445	3127/420	1292
201	1.1	–	–	840	K613_0073 IE3D180MX04	223	7.323	19215/2624	1179
P_N (50 Hz) = 22,00 kW, P_N (87 Hz) = 38,11 kW									
16	0.87	–	–	12473	K1014_0930 IE3D180LX04	687	93.34	252399/2704	1692
20	1.1	–	–	10219	K1013_0750 IE3D180LX04	658	75.28	101773/1352	1702
23	0.82	41	0.82	8562	K913_0630 IE3D180LX04	466	63.07	209901/3328	1693
24	1.4	–	–	8356	K1013_0620 IE3D180LX04	658	61.55	12803/208	1711
30	1.1	52	1.1	6643	K913_0490 IE3D180LX04	466	48.94	100223/2048	1700
38	2.0	–	–	5240	K1013_0390 IE3D180LX04	658	38.60	8029/208	1746
39	1.4	67	1.3	5164	K913_0380 IE3D180LX04	466	38.04	194773/5120	1710
41	0.86	–	–	4906	K813_0360 IE3D180LX04	351	36.14	2891/80	1693
46	0.96	79	0.82	4397	K813_0320 IE3D180LX04	351	32.39	31093/960	1697
46	1.6	80	1.5	4360	K913_0320 IE3D180LX04	466	32.12	47275/1472	1719
50	1.0	87	0.88	3971	K813_0290 IE3D180LX04	351	29.25	7021/240	1698
58	1.1	–	–	3463	K813_0260 IE3D180LX04	351	25.51	140833/5520	1705
62	2.1	–	–	3250	K913_0240 IE3D180LX04	466	23.94	88877/3712	1741
64	1.2	–	–	3128	K813_0230 IE3D180LX04	351	23.04	31801/1380	1706
77	1.4	–	–	2604	K813_0190 IE3D180LX04	351	19.18	133517/6960	1718
77	2.1	–	–	2588	K913_0190 IE3D180LX04	466	19.06	305/16	1765
81	0.82	–	–	2481	K713_0185 IE3D180LX04	297	18.28	26901/1472	1697
85	1.5	–	–	2352	K813_0175 IE3D180LX04	351	17.33	30149/1740	1720
90	0.88	–	–	2225	K713_0165 IE3D180LX04	297	16.39	6293/384	1701
90	1.5	–	–	2231	K813_0165 IE3D180LX04	351	16.43	42067/2560	1726
100	0.94	–	–	2009	K713_0150 IE3D180LX04	297	14.80	1421/96	1702
99	1.6	–	–	2015	K813_0150 IE3D180LX04	351	14.84	9499/640	1730
113	1.0	–	–	1771	K713_0130 IE3D180LX04	297	13.04	3339/256	1709
118	2.1	–	–	1700	K913_0125 IE3D180LX04	466	12.53	73749/5888	1838
125	1.1	–	–	1599	K713_0120 IE3D180LX04	297	11.78	23373/1984	1711
143	2.1	–	–	1395	K813_0105 IE3D180LX04	351	10.28	53041/5160	1772
145	1.2	–	–	1381	K713_0100 IE3D180LX04	297	10.17	651/64	1722
159	2.1	–	–	1260	K813_0093 IE3D180LX04	351	9.284	11977/1290	1781

n_2 50 Hz [rpm]	S	n_2 87 Hz [rpm]	S	M_{2N} [Nm]	Type	m [kg]	i	i_{exakt}	J_1 [kgcm ²]
P_N (50 Hz) = 22,00 kW, P_N (87 Hz) = 38,11 kW									
161	1.3	–	–	1247	K713_0092 IE3D180LX04	297	9.188	147/16	1724
176	1.4	–	–	1137	K713_0084 IE3D180LX04	297	8.373	87885/10496	1735
179	2.1	–	–	1119	K813_0082 IE3D180LX04	351	8.243	96937/11760	1809
182	0.86	–	–	1101	K613_0081 IE3D180LX04	269	8.107	85095/10496	1707
195	1.5	–	–	1027	K713_0076 IE3D180LX04	297	7.563	19845/2624	1739
198	2.1	–	–	1011	K813_0074 IE3D180LX04	351	7.445	3127/420	1822
201	0.92	–	–	994	K613_0073 IE3D180LX04	269	7.323	19215/2624	1709
P_N (50 Hz) = 30,00 kW, P_N (87 Hz) = 51,96 kW									
24	1.1	–	–	11416	K1013_0620 IE3D200LX04	756	61.55	12803/208	3161
30	1.3	–	–	9003	K1013_0490 IE3D200LX04	756	48.54	171647/3536	3176
38	1.7	–	–	7159	K1013_0390 IE3D200LX04	756	38.60	8029/208	3196
47	2.1	–	–	5849	K1013_0320 IE3D200LX04	756	31.54	144305/4576	3222
62	2.7	–	–	4413	K1013_0240 IE3D200LX04	756	23.79	4949/208	3270
78	1.8	–	–	3536	K913_0190 IE3D200LX04	564	19.06	305/16	3215
93	3.3	–	–	2944	K1013_0160 IE3D200LX04	756	15.88	37975/2392	3382
118	2.4	–	–	2323	K913_0125 IE3D200LX04	564	12.53	73749/5888	3288
187	3.3	–	–	1471	K913_0079 IE3D200LX04	564	7.934	54839/6912	3439

4.3 Dimensional drawings

In this chapter you can find the dimensions of the geared motors.

There is a dimensional drawing for every possible shaft/housing design, each with the tables for gear unit dimensions, motor dimensions and geared motor dimensions.

Dimensions can exceed the specifications of ISO 2768-mK due to casting tolerances or accumulation of individual tolerances.

We reserve the right to make dimensional changes due to ongoing technical development.

You can download 3D models of our standard drives at <https://configurator.stoeber.de/en-US/>.

Tolerances

Axis height in accordance with DIN 747	Tolerance
Up to 50 mm	-0.4 mm
Up to 250 mm	-0.5 mm
Up to 630 mm	-0.6 mm

Solid shaft	Tolerance
Shaft \varnothing fit \leq 50 mm	DIN 748-1, ISO k6
Shaft \varnothing fit $>$ 50 mm	DIN 748-1, ISO m6
Feather keys	DIN 6885-1, high form A

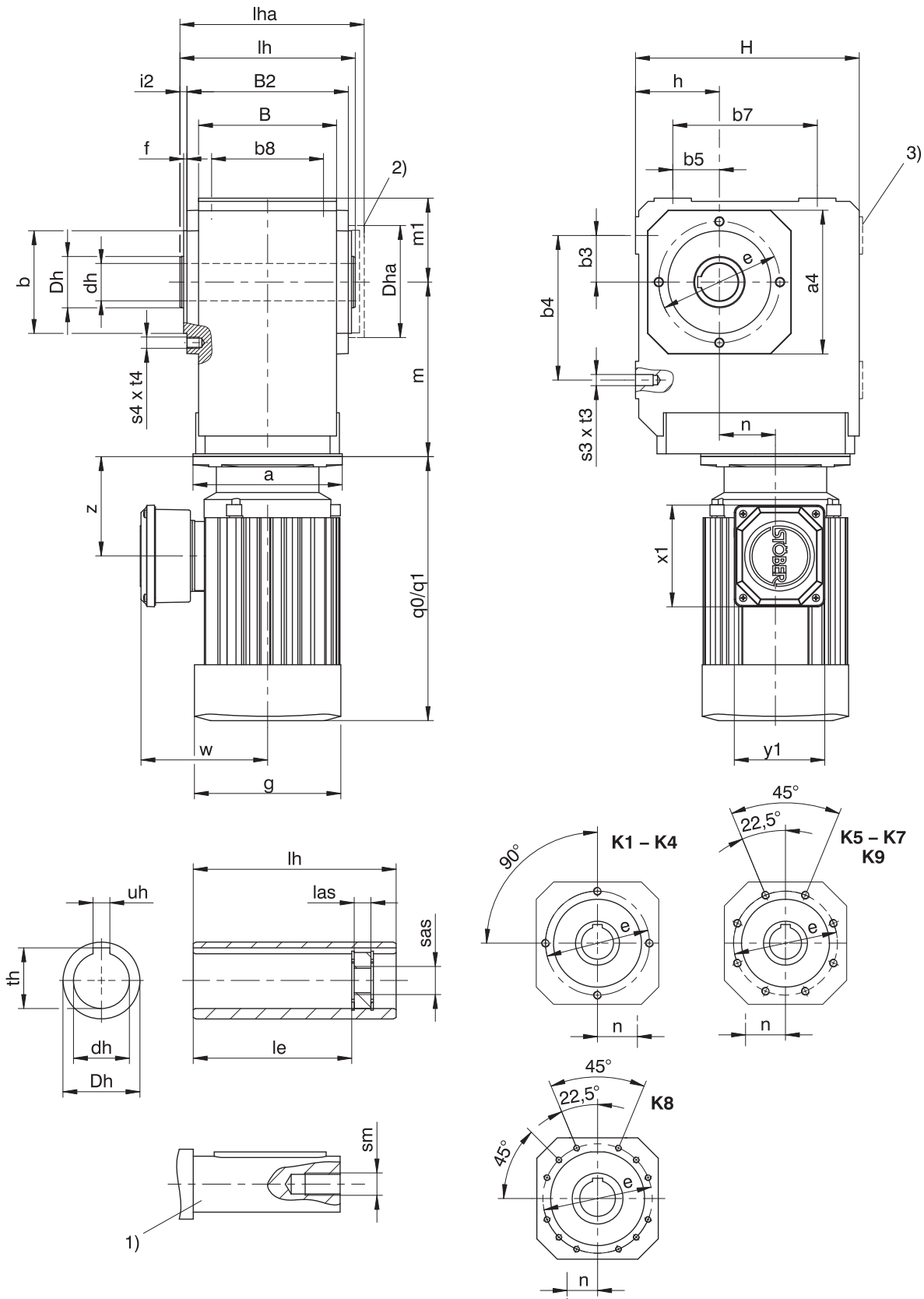
Hollow shaft	Tolerance
Hollow shaft hole fit	ISO H7
Feather keys	DIN 6885-1, high form K1 \varnothing 30: DIN 6885-3, low form

Flange	Pilot tolerance
Up to 300 mm	ISO j6
Starting at 350 mm	ISO h6

Centering holes in solid shafts in accordance with DIN 332-2, DR shape

Thread size	M4	M5	M6	M8	M10	M12	M16	M20	M24
Thread depth [mm]	10	12.5	16	19	22	28	36	42	50

4.3.1 A shaft design (hollow shaft), G housing design (pitch circle diameter)



q_0 Applies to motors without brake.

q_1 Applies to motors with brake.

1) The length of the machine shaft must be at least $2.2 \times \varnothing dh$ and the length of the feather key must be at least $2 \times \varnothing dh$.

2) Cover (optional)

3) Only for K1 (other sizes on request)

Dimensions of gear units

Type	□a4	∅b	b3	b4	b5	b7	b8	B	B2	∅dh	∅Dh	Dha	∅e	f	h	H	i2	le	lh	las	lha	m1	s3	s4	sm	sas	t3	t4	th	uh
K1	105	75 _{j6}	30	90	30	90	70	90	106	20 ^{H7}	40	□105	90	3.0	60	160	7.0	98.0	120	12	127.0	60	M8	M8	M6	M8	13	13	22.8	6 ^{JS9}
K1	105	75 _{j6}	30	90	30	90	70	90	106	25 ^{H7}	40	□105	90	3.0	60	160	7.0	98.0	120	12	127.0	60	M8	M8	M10	M12	13	13	28.3	8 ^{JS9}
K1	105	75 _{j6}	30	90	30	90	70	90	106	30 ^{H7}	40	□105	90	3.0	60	160	7.0	93.5	120	12	127.0	60	M8	M8	M10	M12	13	13	32.0	8 ^{JS9}
K2	116	82 _{j6}	35	115	35	115	90	115	134	30 ^{H7}	45	□116	100	3.0	65	190	7.0	121.5	148	12	156.0	65	M10	M8	M10	M12	16	13	33.3	8 ^{JS9}
K3	132	95 _{j6}	40	130	40	130	105	130	146	35 ^{H7}	50	□132	115	3.0	75	213	7.0	125.0	160	12	168.0	75	M10	M8	M12	M16	16	13	38.3	10 ^{JS9}
K4	152	110 _{j6}	50	155	50	155	120	148	173	40 ^{H7}	55	□152	130	3.5	90	240	7.5	157.0	188	12	197.5	90	M12	M10	M16	M20	19	16	43.3	12 ^{JS9}
K5	145	110 _{j6}	40	140	100	140	125	160	185	50 ^{H7}	65	□145	130	3.5	160	260	7.5	164.0	200	12	209.5	100	M16	M10	M16	M20	26	16	53.8	14 ^{JS9}
K6	180	140 _{j6}	50	160	110	160	130	168	200	50 ^{H7}	70	∅183	165	3.5	190	310	7.5	179.0	215	12	224.5	120	M16	M10	M16	M20	26	16	53.8	14 ^{JS9}
K7	195	155 _{j6}	55	180	125	180	145	190	226	60 ^{H7}	85	∅205	185	3.5	212	342	8.0	214.0	242	12	252.0	125	M20	M12	M20	M24	33	19	64.4	18 ^{JS9}
K8	226	185 _{j6}	75	240	165	240	185	235	282	70 ^{H7}	100	∅184	215	4.0	265	410	9.0	263.0	300	20	311.0	145	M24	M12	M20	M24	38	19	74.9	20 ^{JS9}
K9	280	230 _{j6}	95	280	185	280	225	285	330	90 ^{H7}	120	∅230	265	5.0	315	495	10.0	302.0	350	26	361.0	180	M30	M16	M24	M30	48	26	95.4	25 ^{JS9}

Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5
IE3D160MX04	313	526	641	199	166.5	193.5	138.0
IE3D160LX04	313	549	627	242	166.5	193.5	138.0
IE3D180MX04	313	549	677	242	166.5	193.5	178.0
IE3D180LX04	351	601	748	260	166.5	193.5	178.0
IE3D200LX04	390	729	878	298	207.0	209.0	242.0

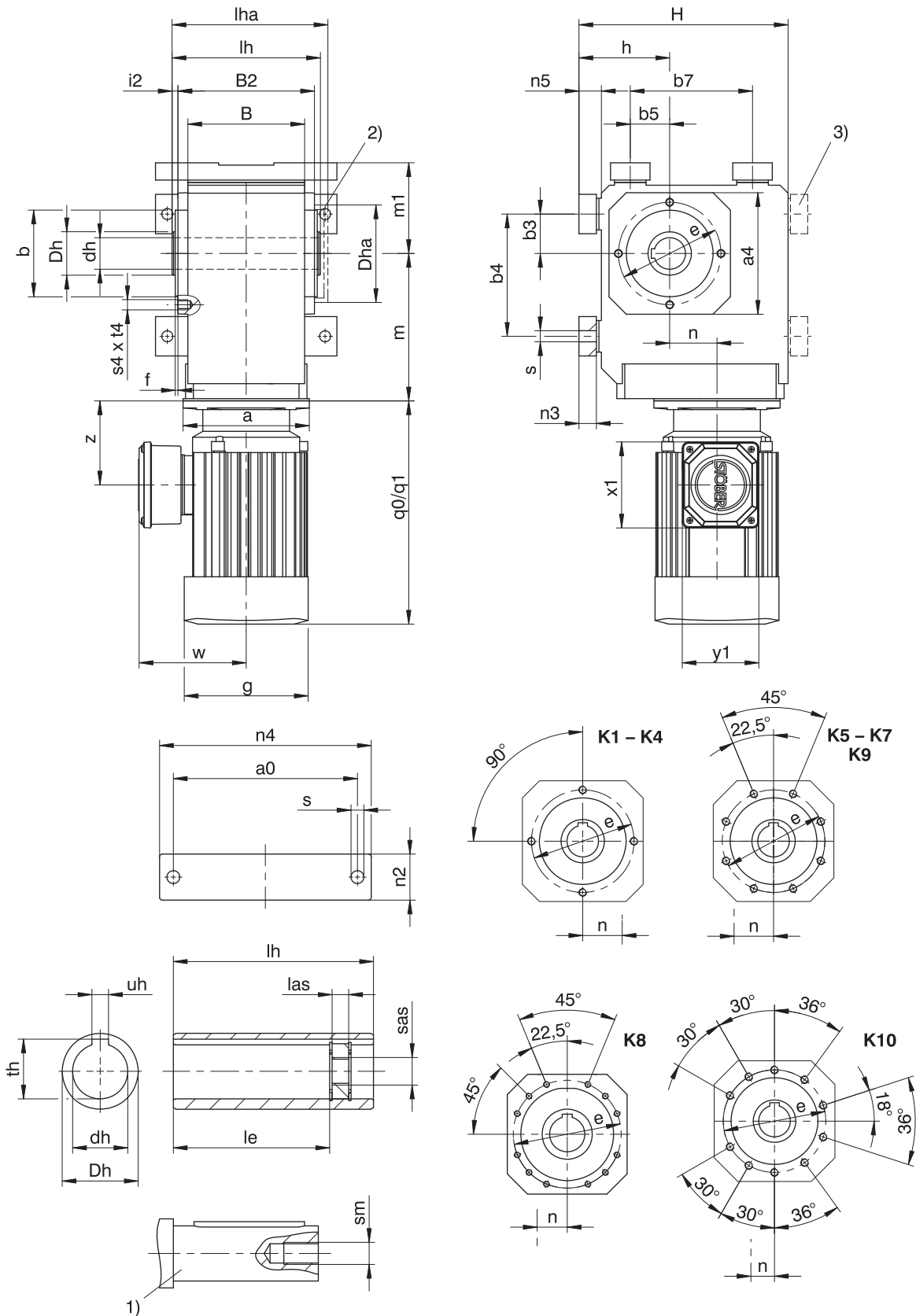
The dimensions a, m and n can be found on the next page.

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K102	∅140	124	36.0	∅140	124	36.0	∅160	128	36.0	∅160	128	36.0	-	-	-
K202	∅140	143	46.0	∅140	143	46.0	∅160	147	46.0	∅160	147	46.0	∅200	149	46.0
K203	∅140	180	46.0	∅140	180	46.0	-	-	-	-	-	-	-	-	-
K302	∅140	163	52.5	∅140	163	52.5	∅160	167	52.5	∅160	167	52.5	∅200	169	52.5
K303	∅140	200	52.5	∅140	200	52.5	∅160	210	16.0	∅160	210	16.0	-	-	-
K402	-	-	-	-	-	-	∅160	187	60.0	∅160	187	60.0	∅200	189	60.0
K403	-	-	-	∅140	220	60.0	∅160	230	23.0	∅160	230	23.0	-	-	-
K513	-	-	-	-	-	-	∅160	172	15.0	∅160	172	15.0	∅200	174	15.0
K514	-	-	-	-	-	-	∅160	215	15.0	∅160	215	15.0	-	-	-
K613	-	-	-	-	-	-	∅160	191	18.0	∅160	191	18.0	∅200	193	18.0
K614	-	-	-	-	-	-	∅160	234	18.0	∅160	234	18.0	-	-	-
K713	-	-	-	-	-	-	-	-	-	-	-	-	∅200	221	20.0
K714	-	-	-	-	-	-	∅160	263	20.0	∅160	263	20.0	∅200	283	20.0
K813	-	-	-	-	-	-	-	-	-	-	-	-	∅200	247	24.0
K814	-	-	-	-	-	-	-	-	-	-	-	-	∅200	308	24.0
K914	-	-	-	-	-	-	-	-	-	-	-	-	∅200	353	25.0

Type	IE3D112			IE3D132			IE3D160			IE3D180			IE3D200		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K202	∅200	149	46.0	-	-	-	-	-	-	-	-	-	-	-	-
K302	∅200	169	52.5	-	-	-	-	-	-	-	-	-	-	-	-
K402	∅200	189	60.0	∅250	192	60.0	-	-	-	-	-	-	-	-	-
K513	∅200	174	15.0	∅250	177	15.0	-	-	-	-	-	-	-	-	-
K613	∅200	193	18.0	∅250	196	18.0	∅300	210	18.0	∅300	210	18.0	-	-	-
K713	∅200	221	20.0	∅250	224	20.0	∅300	237	20.0	∅300	237	20.0	-	-	-
K714	∅200	283	20.0	-	-	-	-	-	-	-	-	-	-	-	-
K813	∅200	247	24.0	∅250	249	24.0	∅300	262	24.0	∅300	262	24.0	-	-	-
K814	∅200	308	24.0	∅250	320	5.0	-	-	-	-	-	-	-	-	-
K913	-	-	-	∅250	294	25.0	∅300	307	25.0	∅300	307	25.0	∅350	330	25.0
K914	∅200	353	25.0	∅250	365	25.0	-	-	-	-	-	-	-	-	-

4.3.2 A shaft design (hollow shaft), NG housing design (base + pitch circle diameter)



$q0$ Applies to motors without brake.

$q1$ Applies to motors with brake.

1) The length of the machine shaft must be at least $2.2 \times \varnothing d_h$ and the length of the feather key must be at least $2 \times \varnothing d_h$.

2) Cover (optional)

3) Only for K1 (other sizes on request)

Dimensions of gear units

Type	a0	□a4	∅b	b3	b4	b5	b7	B	B2	∅dh	∅Dh	Dha	∅e	f	h	H
K1	115	105	75 ₆	30	90	30	90	90	106	20 ^{H7}	40	□105	90	3.0	75	175
K1	115	105	75 ₆	30	90	30	90	90	106	25 ^{H7}	40	□105	90	3.0	75	175
K1	115	105	75 ₆	30	90	30	90	90	106	30 ^{H7}	40	□105	90	3.0	75	175
K2	155	116	82 ₆	35	115	35	115	115	134	30 ^{H7}	45	□116	100	3.0	88	213
K3	170	132	95 ₆	40	130	40	130	130	146	35 ^{H7}	50	□132	115	3.0	98	236
K4	200	152	110 ₆	50	155	50	155	148	173	40 ^{H7}	55	□152	130	3.5	115	265
K5	200	145	110 ₆	40	140	100	140	160	185	50 ^{H7}	65	□145	130	3.5	190	290
K6	210	180	140 ₆	50	160	110	160	168	200	50 ^{H7}	70	∅183	165	3.5	220	340
K7	241	195	155 ₆	55	180	125	180	190	226	60 ^{H7}	85	∅205	185	3.5	250	380
K8	300	226	185 ₆	75	240	165	240	235	282	70 ^{H7}	100	∅184	215	4.0	310	455
K9	360	280	230 ₆	95	280	185	280	285	330	90 ^{H7}	120	∅230	265	5.0	365	545
K10	330	340	250 ₆	115	350	265	420	400	356	100 ^{H7}	130	∅200	300	20.0	420	636

Type	i2	le	lh	las	lha	m1	n2	n3	n4	n5	∅s	s4	sm	sas	t4	th	uh
K1	7.0	98.0	120	12	127.0	75	30	13	140	15	9.0	M8	M10	M12	13	28.3	8 ^{JS9}
K1	7.0	98.0	120	12	127.0	75	30	13	140	15	9.0	M8	M6	M8	13	22.8	6 ^{JS9}
K1	7.0	93.5	120	12	127.0	75	30	13	140	15	9.0	M8	M10	M12	13	32.0	8 ^{JS9}
K2	7.0	121.5	148	12	156.0	88	40	20	185	23	11.0	M8	M10	M12	13	33.3	8 ^{JS9}
K3	7.0	125.0	160	12	168.0	98	45	20	200	23	11.0	M8	M12	M16	13	38.3	10 ^{JS9}
K4	7.5	157.0	188	12	197.5	115	50	22	230	25	14.0	M10	M16	M20	16	43.3	12 ^{JS9}
K5	7.5	164.0	200	12	209.5	130	60	27	240	30	18.0	M10	M16	M20	16	53.8	14 ^{JS9}
K6	7.5	179.0	215	12	224.5	150	65	27	250	30	18.5	M10	M16	M20	16	53.8	14 ^{JS9}
K7	8.0	214.0	242	12	252.0	163	70	35	290	38	23.0	M12	M20	M24	19	64.4	18 ^{JS9}
K8	9.0	263.0	300	20	311.0	190	85	41	360	45	27.0	M12	M20	M24	19	74.9	20 ^{JS9}
K9	10.0	302.0	350	26	361.0	230	95	46	430	50	31.0	M16	M24	M30	26	95.4	25 ^{JS9}
K10	27.0	361.0	410	26	441.0	270	120	–	400	45	39.0	M20	M24	M30	33	106.4	28 ^{JS9}

Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5
IE3D160MX04	313	526	641	199	166.5	193.5	138.0
IE3D160LX04	313	549	627	242	166.5	193.5	138.0
IE3D180MX04	313	549	677	242	166.5	193.5	178.0
IE3D180LX04	351	601	748	260	166.5	193.5	178.0
IE3D200LX04	390	729	878	298	207.0	209.0	242.0

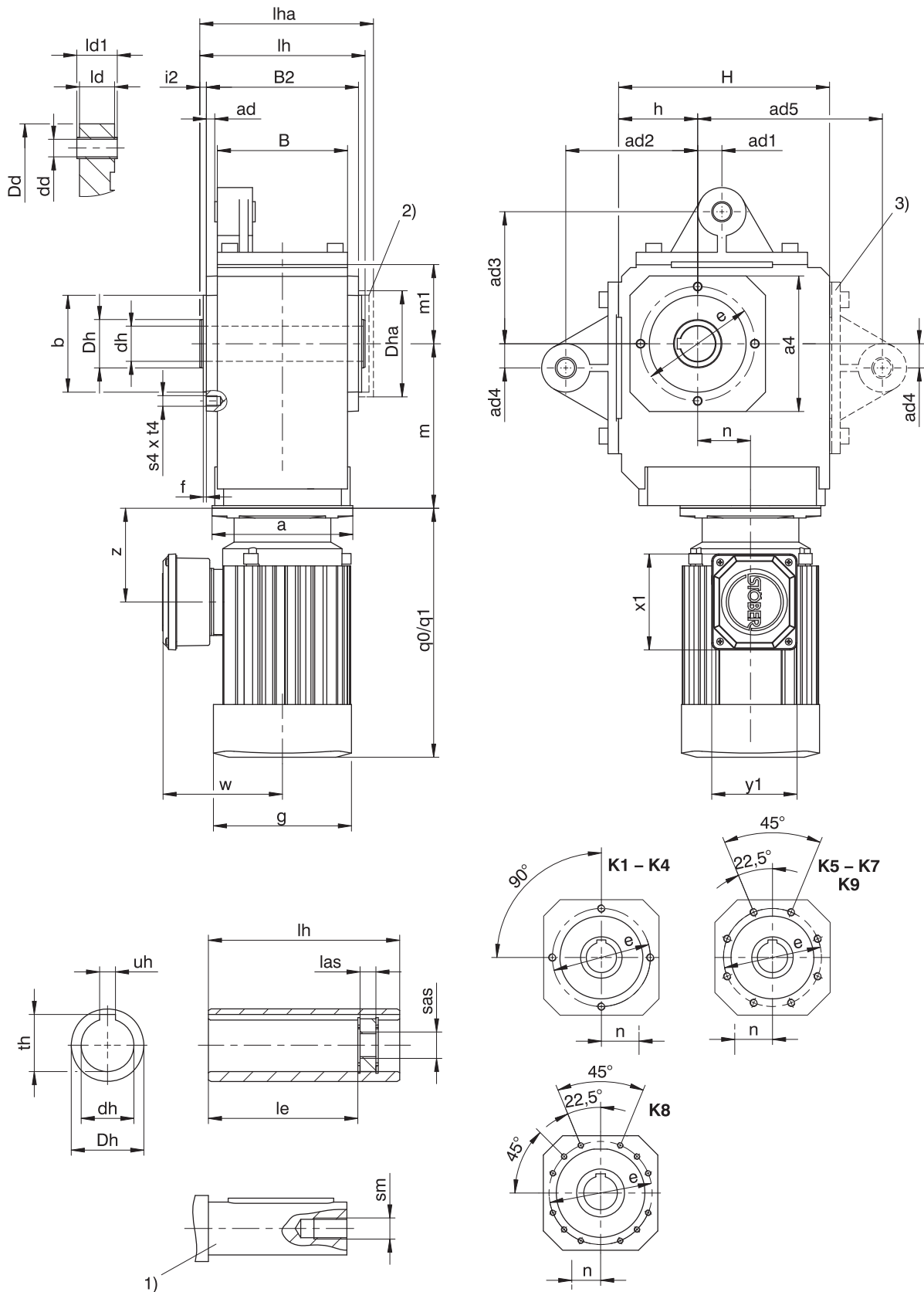
The dimensions a, m and n can be found on the next page.

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K102	∅140	124	36.0	∅140	124	36.0	∅160	128	36.0	∅160	128	36.0	-	-	-
K202	∅140	143	46.0	∅140	143	46.0	∅160	147	46.0	∅160	147	46.0	∅200	149	46.0
K203	∅140	180	46.0	∅140	180	46.0	-	-	-	-	-	-	-	-	-
K302	∅140	163	52.5	∅140	163	52.5	∅160	167	52.5	∅160	167	52.5	∅200	169	52.5
K303	∅140	200	52.5	∅140	200	52.5	∅160	210	16.0	∅160	210	16.0	-	-	-
K402	-	-	-	-	-	-	∅160	187	60.0	∅160	187	60.0	∅200	189	60.0
K403	-	-	-	∅140	220	60.0	∅160	230	23.0	∅160	230	23.0	-	-	-
K513	-	-	-	-	-	-	∅160	172	15.0	∅160	172	15.0	∅200	174	15.0
K514	-	-	-	-	-	-	∅160	215	15.0	∅160	215	15.0	-	-	-
K613	-	-	-	-	-	-	∅160	191	18.0	∅160	191	18.0	∅200	193	18.0
K614	-	-	-	-	-	-	∅160	234	18.0	∅160	234	18.0	-	-	-
K713	-	-	-	-	-	-	-	-	-	-	-	-	∅200	221	20.0
K714	-	-	-	-	-	-	∅160	263	20.0	∅160	263	20.0	∅200	283	20.0
K813	-	-	-	-	-	-	-	-	-	-	-	-	∅200	247	24.0
K814	-	-	-	-	-	-	-	-	-	-	-	-	∅200	308	24.0
K914	-	-	-	-	-	-	-	-	-	-	-	-	∅200	353	25.0

Type	IE3D112			IE3D132			IE3D160			IE3D180			IE3D200		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K202	∅200	149	46.0	-	-	-	-	-	-	-	-	-	-	-	-
K302	∅200	169	52.5	-	-	-	-	-	-	-	-	-	-	-	-
K402	∅200	189	60.0	∅250	192	60.0	-	-	-	-	-	-	-	-	-
K513	∅200	174	15.0	∅250	177	15.0	-	-	-	-	-	-	-	-	-
K613	∅200	193	18.0	∅250	196	18.0	∅300	210	18.0	∅300	210	18.0	-	-	-
K713	∅200	221	20.0	∅250	224	20.0	∅300	237	20.0	∅300	237	20.0	-	-	-
K714	∅200	283	20.0	-	-	-	-	-	-	-	-	-	-	-	-
K813	∅200	247	24.0	∅250	249	24.0	∅300	262	24.0	∅300	262	24.0	-	-	-
K814	∅200	308	24.0	∅250	320	5.0	-	-	-	-	-	-	-	-	-
K913	-	-	-	∅250	294	25.0	∅300	307	25.0	∅300	307	25.0	∅350	330	25.0
K914	∅200	353	25.0	∅250	365	25.0	-	-	-	-	-	-	-	-	-
K1013	-	-	-	-	-	-	∅300	392	28.0	∅300	392	28.0	∅350	415	28.0
K1014	-	-	-	∅250	450	28.0	∅300	475	28.0	∅300	475	28.0	-	-	-

4.3.3 A shaft design (hollow shaft), GD housing design (pitch circle diameter + torque arm bracket)



q0 Applies to motors without brake.

q1 Applies to motors with brake.

1) The length of the machine shaft must be at least $2.2 \times \varnothing dh$ and the length of the feather key must be at least $2 \times \varnothing dh$.

2) Cover (optional)

3) Only for K1 (other sizes on request)

- If you brace the gear units without the torque arm brackets provided by the manufacturer for this purpose, the dimensions for ad_2 and ad_3 must meet the specified value.

Dimensions of gear units

Type	□a4	ad	ad1	ad2	ad3	ad4	ad5	Øb	B	B2	Ødd	Ødh	ØDd	ØDh	Dha	Øe	f
K1	105	6.0	15.0	90	90	15.0	130	75 _{j6}	90	106	12 ^{H9}	20 ^{H7}	43	40	□105	90	3.0
K1	105	6.0	15.0	90	90	15.0	130	75 _{j6}	90	106	12 ^{H9}	25 ^{H7}	43	40	□105	90	3.0
K1	105	6.0	15.0	90	90	15.0	130	75 _{j6}	90	106	12 ^{H9}	30 ^{H7}	43	40	□105	90	3.0
K2	116	6.5	22.5	100	100	22.5	–	82 _{j6}	115	134	16 ^{H9}	30 ^{H7}	45	45	□116	100	3.0
K3	132	5.0	25.0	120	120	25.0	–	95 _{j6}	130	146	16 ^{H9}	35 ^{H7}	45	50	□132	115	3.0
K4	152	9.5	27.5	150	150	27.5	–	110 _{j6}	148	173	20 ^{H9}	40 ^{H7}	55	55	□152	130	3.5
K5	145	9.5	30.0	250	190	30.0	–	110 _{j6}	160	185	20 ^{H9}	50 ^{H7}	58	65	□145	130	3.5
K6	180	13.0	30.0	250	180	30.0	–	140 _{j6}	168	200	20 ^{H9}	50 ^{H7}	58	70	Ø183	165	3.5
K7	195	15.0	35.0	300	213	35.0	–	155 _{j6}	190	226	20 ^{H9}	60 ^{H7}	68	85	Ø205	185	3.5
K8	226	17.0	45.0	350	230	45.0	–	185 _{j6}	235	282	24 ^{H9}	70 ^{H7}	72	100	Ø184	215	4.0
K9	280	16.0	45.0	450	315	45.0	–	230 _{j6}	285	330	24 ^{H9}	90 ^{H7}	75	120	Ø230	265	5.0

Dimensions of gear units

Type	h	H	i2	ld	ld1	le	lh	las	lha	m1	s4	sm	sas	t4	th	uh
K1	60	160	7.0	24	28	98.0	120	12	127.0	60	M8	M6	M8	13	22.8	6 ^{JS9}
K1	60	160	7.0	24	28	98.0	120	12	127.0	60	M8	M10	M12	13	28.3	8 ^{JS9}
K1	60	160	7.0	24	28	93.5	120	12	127.0	60	M8	M10	M12	13	32.0	8 ^{JS9}
K2	65	190	7.0	32	38	121.5	148	12	156.0	65	M8	M10	M12	13	33.3	8 ^{JS9}
K3	75	213	7.0	32	38	125.0	160	12	168.0	75	M8	M12	M16	13	38.3	10 ^{JS9}
K4	90	240	7.5	40	46	157.0	188	12	197.5	90	M10	M16	M20	16	43.3	12 ^{JS9}
K5	160	260	7.5	40	46	164.0	200	12	209.5	100	M10	M16	M20	16	53.8	14 ^{JS9}
K6	190	310	7.5	40	46	179.0	215	12	224.5	120	M10	M16	M20	16	53.8	14 ^{JS9}
K7	212	342	8.0	64	70	214.0	242	12	252.0	125	M12	M20	M24	19	64.4	18 ^{JS9}
K8	265	410	9.0	102	115	263.0	300	20	311.0	145	M12	M20	M24	19	74.9	20 ^{JS9}
K9	315	495	10.0	102	115	302.0	350	26	361.0	180	M16	M24	M30	26	95.4	25 ^{JS9}

Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5
IE3D160MX04	313	526	641	199	166.5	193.5	138.0
IE3D160LX04	313	549	627	242	166.5	193.5	138.0
IE3D180MX04	313	549	677	242	166.5	193.5	178.0
IE3D180LX04	351	601	748	260	166.5	193.5	178.0
IE3D200LX04	390	729	878	298	207.0	209.0	242.0

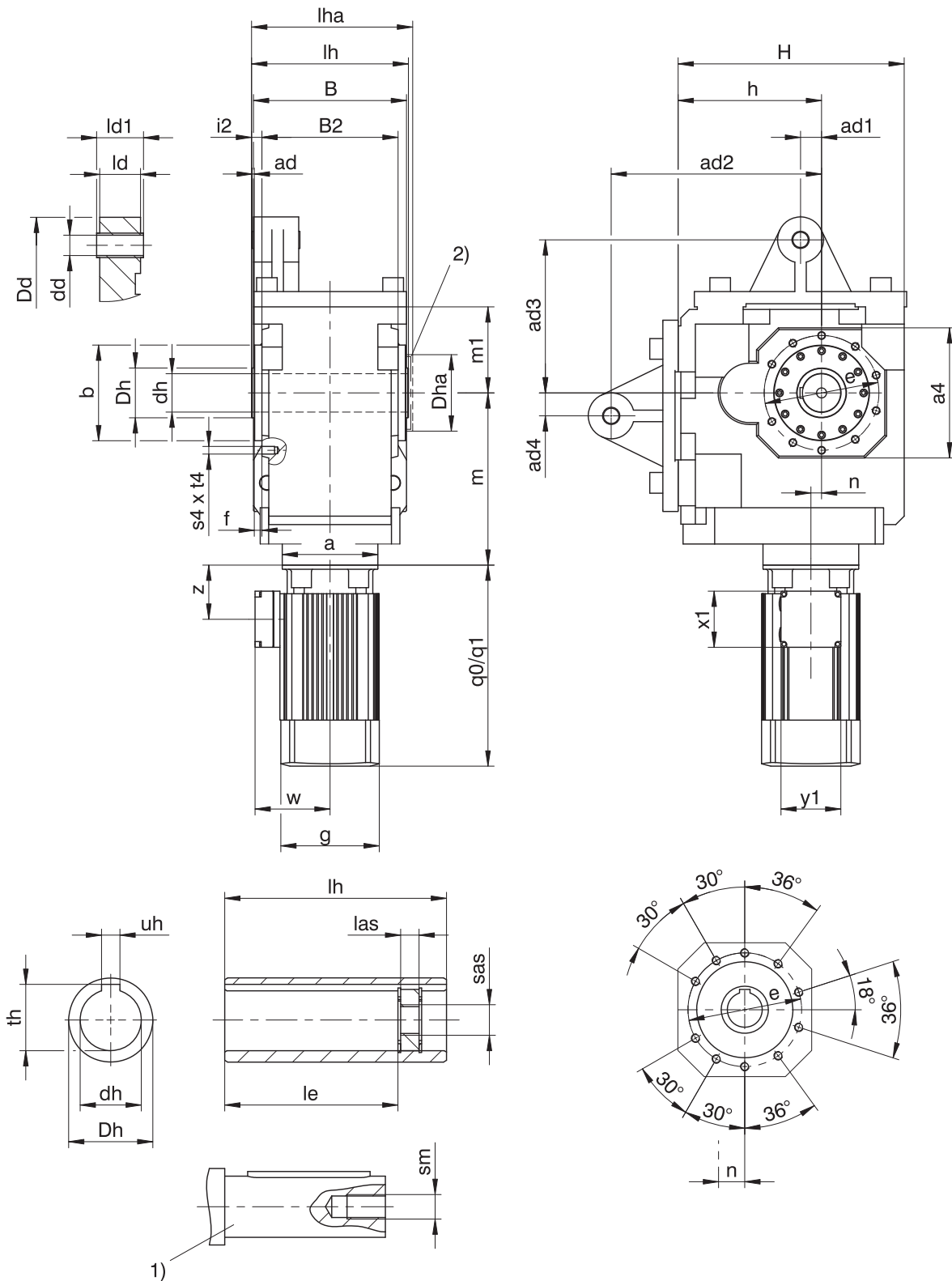
The dimensions a, m and n can be found on the next page.

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K102	∅140	124	36.0	∅140	124	36.0	∅160	128	36.0	∅160	128	36.0	-	-	-
K202	∅140	143	46.0	∅140	143	46.0	∅160	147	46.0	∅160	147	46.0	∅200	149	46.0
K203	∅140	180	46.0	∅140	180	46.0	-	-	-	-	-	-	-	-	-
K302	∅140	163	52.5	∅140	163	52.5	∅160	167	52.5	∅160	167	52.5	∅200	169	52.5
K303	∅140	200	52.5	∅140	200	52.5	∅160	210	16.0	∅160	210	16.0	-	-	-
K402	-	-	-	-	-	-	∅160	187	60.0	∅160	187	60.0	∅200	189	60.0
K403	-	-	-	∅140	220	60.0	∅160	230	23.0	∅160	230	23.0	-	-	-
K513	-	-	-	-	-	-	∅160	172	15.0	∅160	172	15.0	∅200	174	15.0
K514	-	-	-	-	-	-	∅160	215	15.0	∅160	215	15.0	-	-	-
K613	-	-	-	-	-	-	∅160	191	18.0	∅160	191	18.0	∅200	193	18.0
K614	-	-	-	-	-	-	∅160	234	18.0	∅160	234	18.0	-	-	-
K713	-	-	-	-	-	-	-	-	-	-	-	-	∅200	221	20.0
K714	-	-	-	-	-	-	∅160	263	20.0	∅160	263	20.0	∅200	283	20.0
K813	-	-	-	-	-	-	-	-	-	-	-	-	∅200	247	24.0
K814	-	-	-	-	-	-	-	-	-	-	-	-	∅200	308	24.0
K914	-	-	-	-	-	-	-	-	-	-	-	-	∅200	353	25.0

Type	IE3D112			IE3D132			IE3D160			IE3D180			IE3D200		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K202	∅200	149	46.0	-	-	-	-	-	-	-	-	-	-	-	-
K302	∅200	169	52.5	-	-	-	-	-	-	-	-	-	-	-	-
K402	∅200	189	60.0	∅250	192	60.0	-	-	-	-	-	-	-	-	-
K513	∅200	174	15.0	∅250	177	15.0	-	-	-	-	-	-	-	-	-
K613	∅200	193	18.0	∅250	196	18.0	∅300	210	18.0	∅300	210	18.0	-	-	-
K713	∅200	221	20.0	∅250	224	20.0	∅300	237	20.0	∅300	237	20.0	-	-	-
K714	∅200	283	20.0	-	-	-	-	-	-	-	-	-	-	-	-
K813	∅200	247	24.0	∅250	249	24.0	∅300	262	24.0	∅300	262	24.0	-	-	-
K814	∅200	308	24.0	∅250	320	5.0	-	-	-	-	-	-	-	-	-
K913	-	-	-	∅250	294	25.0	∅300	307	25.0	∅300	307	25.0	∅350	330	25.0
K914	∅200	353	25.0	∅250	365	25.0	-	-	-	-	-	-	-	-	-

4.3.4 A shaft design (hollow shaft), NGD housing design (foot + pitch circle diameter + torque arm bracket)



q_0 Applies to motors without brake.

q_1 Applies to motors with brake.

1) The length of the machine shaft must be at least 2.2 x $\varnothing dh$ and the length of the feather key must be at least 2 x $\varnothing dh$.

2) Cover (optional)

- If you brace the gear units without the torque arm brackets provided by the manufacturer for this purpose, the dimensions for ad_2 and ad_3 must meet the specified value.

Dimensions of gear units

Type	□a4	ad	ad1	ad2	ad3	ad4	Øb	B	B2	Ødd	Ødh	ØDd	ØDh	Dha	Øe	f
K10	340	5	60	550	400	55	250 _{h6}	400	356	40 ^{H9}	100 ^{H7}	120	130	Ø200	300	20

Dimensions of gear units

Type	h	H	i2	ld	ld1	le	lh	las	lha	m1	s4	sm	sas	t4	th	uh
K10	375	591	27	118	124	361	410	26	441	225	M20	M24	M30	33	106.4	28 ^{JS9}

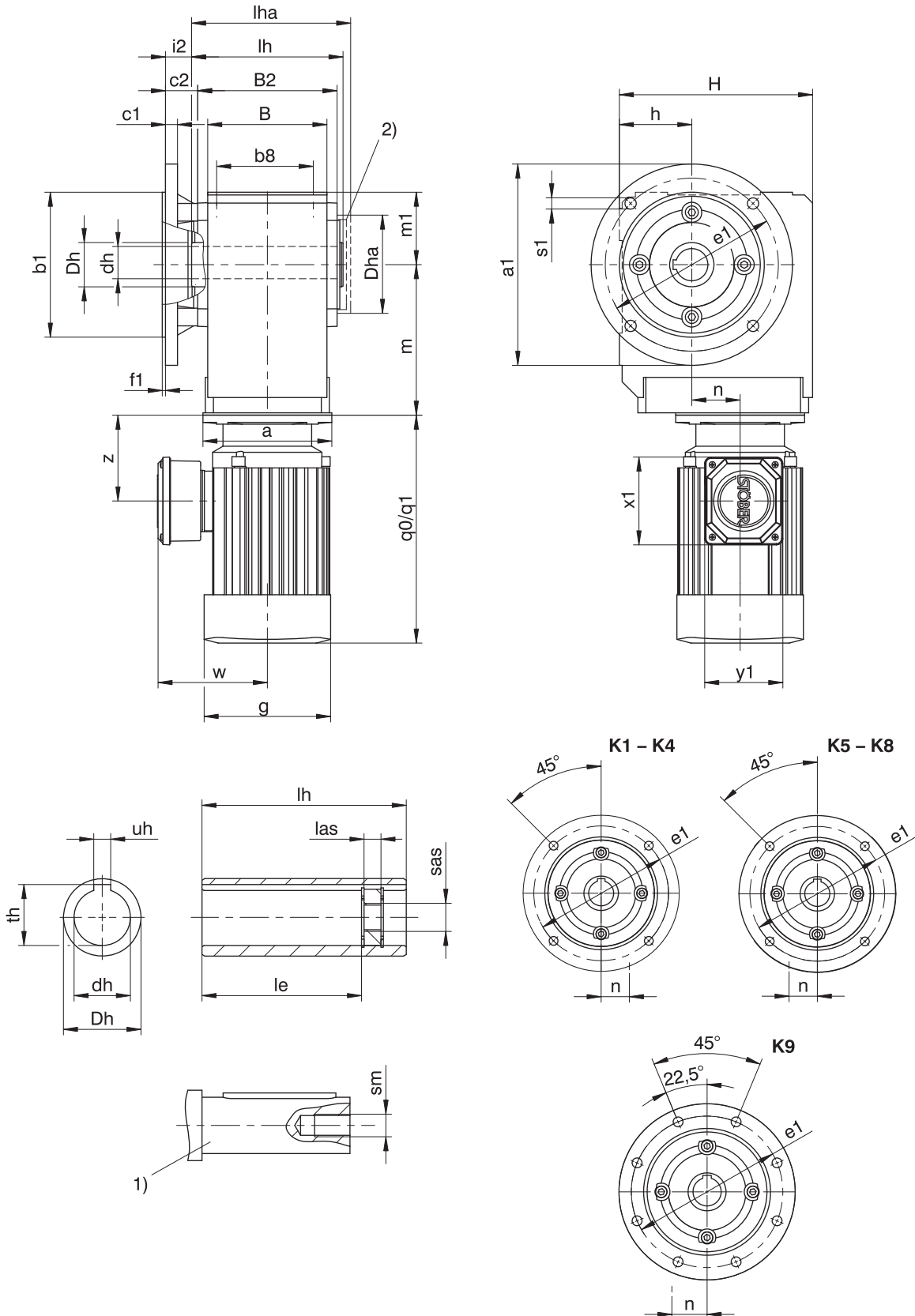
Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5
IE3D160MX04	313	526	641	199	166.5	193.5	138.0
IE3D160LX04	313	549	627	242	166.5	193.5	138.0
IE3D180MX04	313	549	677	242	166.5	193.5	178.0
IE3D180LX04	351	601	748	260	166.5	193.5	178.0
IE3D200LX04	390	729	878	298	207.0	209.0	242.0

Dimensions of geared motors

Type	IE3D132			IE3D160			IE3D180			IE3D200		
	a	m	n	a	m	n	a	m	n	a	m	n
K1013	–	–	–	Ø300	392	28.0	Ø300	392	28.0	Ø350	415	28.0
K1014	Ø250	450	28.0	Ø300	475	28.0	Ø300	475	28.0	–	–	–

4.3.5 A shaft design (hollow shaft), F housing design (round flange)



q_0 Applies to motors without brake.

q_1 Applies to motors with brake.

1) The length of the machine shaft must be at least $2.2 \times \varnothing d_h$ and the length of the feather key must be at least $2 \times \varnothing d_h$.

2) Cover (optional)

Dimensions of gear units

Type	Øa1	Øb1	b8	B	B2	c1	c2	Ødh	ØDh	Dha	Øe1	f1	h	H	i2	le	lh	las	lha	m1	Øs1	sm	sas	th	uh
K1	160	110 _{js}	70	90	106	10	32.0	20 ^{H7}	40	□105	130	3.5	60	160	25.0	98.0	120	12	127.0	60	9	M6	M8	22.8	6 ^{JS9}
K1	160	110 _{js}	70	90	106	10	32.0	25 ^{H7}	40	□105	130	3.5	60	160	25.0	98.0	120	12	127.0	60	9	M10	M12	28.3	8 ^{JS9}
K1	160	110 _{js}	70	90	106	10	32.0	30 ^{H7}	40	□105	130	3.5	60	160	25.0	93.5	120	12	127.0	60	9	M10	M12	32.0	8 ^{JS9}
K2	200	130 _{js}	90	115	134	12	32.0	30 ^{H7}	45	□116	165	3.5	65	190	25.0	121.5	148	12	156.0	65	11	M10	M12	33.3	8 ^{JS9}
K3	200	130 _{js}	105	130	146	14	38.0	35 ^{H7}	50	□132	165	3.5	75	213	31.0	125.0	160	12	168.0	75	11	M12	M16	38.3	10 ^{JS9}
K4	250	180 _{js}	120	148	173	15	40.0	40 ^{H7}	55	□152	215	4.0	90	240	32.5	157.0	188	12	197.5	90	14	M16	M20	43.3	12 ^{JS9}
K5	250	180 _{js}	125	160	185	15	39.5	50 ^{H7}	65	□145	215	4.0	160	260	32.0	164.0	200	12	209.5	100	14	M16	M20	53.8	14 ^{JS9}
K6	300	230 _{js}	130	168	200	17	36.0	50 ^{H7}	70	Ø183	265	4.0	190	310	28.5	179.0	215	12	224.5	120	14	M16	M20	53.8	14 ^{JS9}
K7	350	250 _{h6}	145	190	226	18	44.0	60 ^{H7}	85	Ø205	300	5.0	212	342	36.0	214.0	242	12	252.0	125	18	M20	M24	64.4	18 ^{JS9}
K8	400	300 _{h6}	185	235	282	20	45.0	70 ^{H7}	100	Ø184	350	5.0	265	410	36.0	263.0	300	20	311.0	145	18	M20	M24	74.9	20 ^{JS9}
K9	450	350 _{h6}	225	285	330	23	50.0	90 ^{H7}	120	Ø230	400	5.0	315	495	40.0	302.0	350	26	361.0	180	18	M24	M30	95.4	25 ^{JS9}

Dimensions of additional round flanges

Type	Øa1	Øb1	c1	Øe1	f1	Øs1
K1	140	95 _{js}	10	115	3.0	9
K2	160	110 _{js}	12	130	3.5	9
K3	160	110 _{js}	14	130	3.5	9
K3	250	180 _{js}	14	215	4.0	14
K8	350	250 _{h6}	18	300	5.0	18
K8	450	350 _{h6}	20	400	5.0	18

Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5
IE3D160MX04	313	526	641	199	166.5	193.5	138.0
IE3D160LX04	313	549	627	242	166.5	193.5	138.0
IE3D180MX04	313	549	677	242	166.5	193.5	178.0
IE3D180LX04	351	601	748	260	166.5	193.5	178.0
IE3D200LX04	390	729	878	298	207.0	209.0	242.0

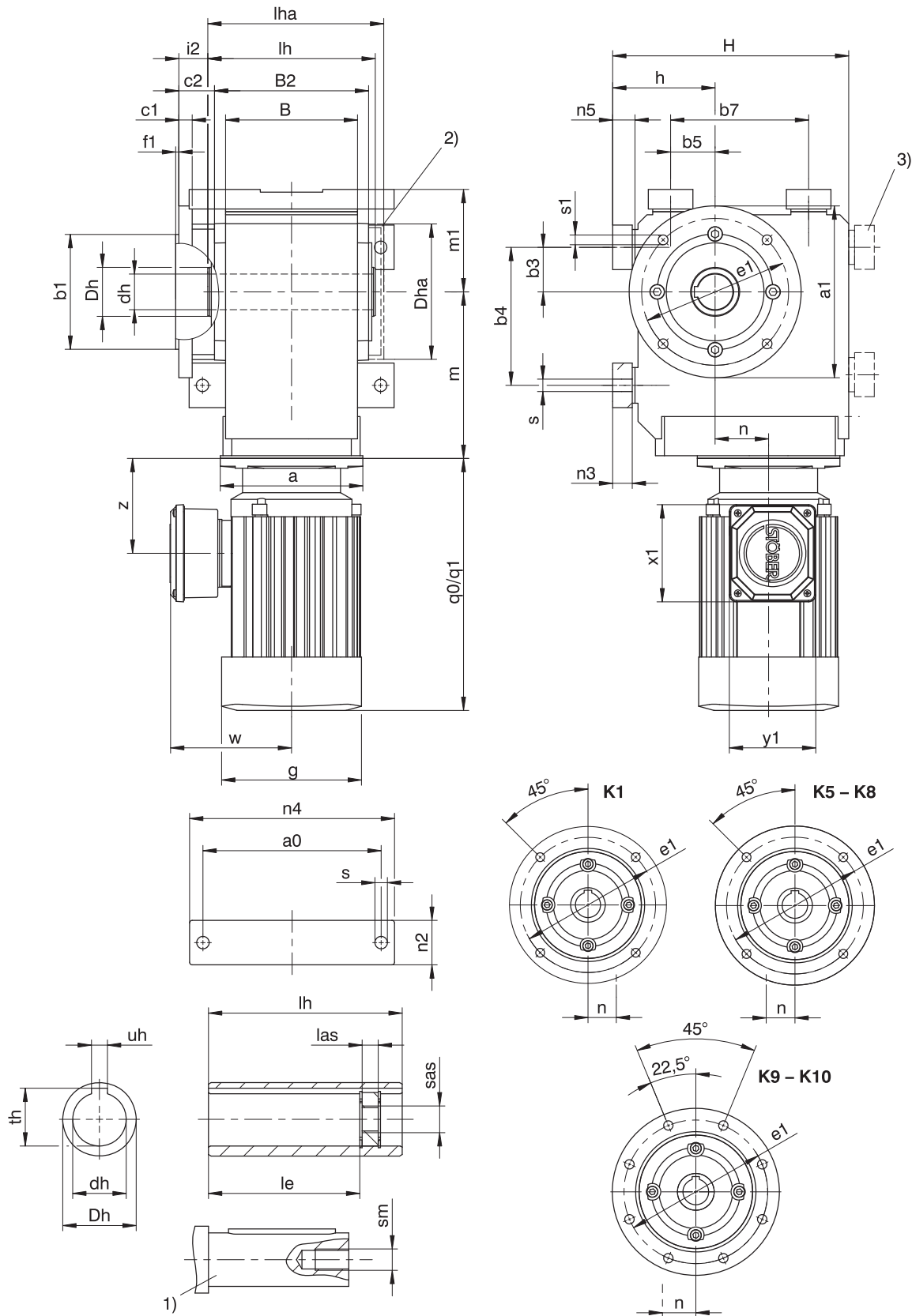
The dimensions a, m and n can be found on the next page.

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K102	∅140	124	36.0	∅140	124	36.0	∅160	128	36.0	∅160	128	36.0	-	-	-
K202	∅140	143	46.0	∅140	143	46.0	∅160	147	46.0	∅160	147	46.0	∅200	149	46.0
K203	∅140	180	46.0	∅140	180	46.0	-	-	-	-	-	-	-	-	-
K302	∅140	163	52.5	∅140	163	52.5	∅160	167	52.5	∅160	167	52.5	∅200	169	52.5
K303	∅140	200	52.5	∅140	200	52.5	∅160	210	16.0	∅160	210	16.0	-	-	-
K402	-	-	-	-	-	-	∅160	187	60.0	∅160	187	60.0	∅200	189	60.0
K403	-	-	-	∅140	220	60.0	∅160	230	23.0	∅160	230	23.0	-	-	-
K513	-	-	-	-	-	-	∅160	172	15.0	∅160	172	15.0	∅200	174	15.0
K514	-	-	-	-	-	-	∅160	215	15.0	∅160	215	15.0	-	-	-
K613	-	-	-	-	-	-	∅160	191	18.0	∅160	191	18.0	∅200	193	18.0
K614	-	-	-	-	-	-	∅160	234	18.0	∅160	234	18.0	-	-	-
K713	-	-	-	-	-	-	-	-	-	-	-	-	∅200	221	20.0
K714	-	-	-	-	-	-	∅160	263	20.0	∅160	263	20.0	∅200	283	20.0
K813	-	-	-	-	-	-	-	-	-	-	-	-	∅200	247	24.0
K814	-	-	-	-	-	-	-	-	-	-	-	-	∅200	308	24.0
K914	-	-	-	-	-	-	-	-	-	-	-	-	∅200	353	25.0

Type	IE3D112			IE3D132			IE3D160			IE3D180			IE3D200		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K202	∅200	149	46.0	-	-	-	-	-	-	-	-	-	-	-	-
K302	∅200	169	52.5	-	-	-	-	-	-	-	-	-	-	-	-
K402	∅200	189	60.0	∅250	192	60.0	-	-	-	-	-	-	-	-	-
K513	∅200	174	15.0	∅250	177	15.0	-	-	-	-	-	-	-	-	-
K613	∅200	193	18.0	∅250	196	18.0	∅300	210	18.0	∅300	210	18.0	-	-	-
K713	∅200	221	20.0	∅250	224	20.0	∅300	237	20.0	∅300	237	20.0	-	-	-
K714	∅200	283	20.0	-	-	-	-	-	-	-	-	-	-	-	-
K813	∅200	247	24.0	∅250	249	24.0	∅300	262	24.0	∅300	262	24.0	-	-	-
K814	∅200	308	24.0	∅250	320	5.0	-	-	-	-	-	-	-	-	-
K913	-	-	-	∅250	294	25.0	∅300	307	25.0	∅300	307	25.0	∅350	330	25.0
K914	∅200	353	25.0	∅250	365	25.0	-	-	-	-	-	-	-	-	-

4.3.6 A shaft design (hollow shaft), NF housing design (base + round flange)



q0 Applies to motors without brake.

q1 Applies to motors with brake.

1) The length of the machine shaft must be at least 2.2 x $\varnothing d_h$ and the length of the feather key must be at least 2 x $\varnothing d_h$.

2) Cover (optional)

3) Only for K1 (other sizes on request)

Dimensions of gear units

Type	a0	Øa1	Øb1	b3	b4	b5	b7	B	B2	c1	c2	Ødh	ØDh	Dha	Øe1	f1	h
K1	115	160	110 _⊖	30	90	30	90	90	106	10	32.0	20 ^{H7}	40	□105	130	3.5	75
K1	115	160	110 _⊖	30	90	30	90	90	106	10	32.0	25 ^{H7}	40	□105	130	3.5	75
K1	115	160	110 _⊖	30	90	30	90	90	106	10	32.0	30 ^{H7}	40	□105	130	3.5	75
K5	200	250	180 _⊖	40	140	100	140	160	185	15	39.5	50 ^{H7}	65	□145	215	4.0	190
K6	210	300	230 _⊖	50	160	110	160	168	200	17	36.0	50 ^{H7}	70	Ø183	265	4.0	220
K7	241	350	250 _{h6}	55	180	125	180	190	226	18	44.0	60 ^{H7}	85	Ø205	300	5.0	250
K8	300	400	300 _{h6}	75	240	165	240	235	282	20	45.0	70 ^{H7}	100	Ø184	350	5.0	310
K9	360	450	350 _{h6}	95	280	185	280	285	330	23	50.0	90 ^{H7}	120	Ø230	400	5.0	365
K10	330	550	450 _{h6}	115	350	265	420	400	356	25	78.0	100 ^{H7}	130	Ø200	500	5.0	420

Dimensions of gear units

Type	H	i2	las	le	lh	lha	m1	n2	n3	n4	n5	Øs	Øs1	sm	sas	th	uh
K1	175	25.0	12	98.0	120	127.0	75	30	13	140	15	9.0	9	M10	M12	28.3	8 ^{JS9}
K1	175	25.0	12	98.0	120	127.0	75	30	13	140	15	9.0	9	M6	M8	22.8	6 ^{JS9}
K1	175	25.0	12	93.5	120	127.0	75	30	13	140	15	9.0	9	M10	M12	32.0	8 ^{JS9}
K5	290	32.0	12	164.0	200	209.5	130	60	27	240	30	18.0	14	M16	M20	53.8	14 ^{JS9}
K6	340	28.5	12	179.0	215	224.5	150	65	27	250	30	18.5	14	M16	M20	53.8	14 ^{JS9}
K7	380	36.0	12	214.0	242	252.0	163	70	35	290	38	23.0	18	M20	M24	64.4	18 ^{JS9}
K8	455	36.0	20	263.0	300	311.0	190	85	41	360	45	27.0	18	M20	M24	74.9	20 ^{JS9}
K9	545	40.0	26	302.0	350	361.0	230	95	46	430	50	31.0	18	M24	M30	95.4	25 ^{JS9}
K10	636	51.0	26	361.0	410	441.0	270	120	–	400	45	39.0	18	M24	M30	106.4	28 ^{JS9}

Dimensions of additional round flanges

Type	Øa1	Øb1	c1	Øe1	f1	Øs1
K1	140	95 _⊖	10	115	3	9
K8	350	250 _{h6}	18	300	5	18
K8	450	350 _{h6}	20	400	5	18

All other dimensions can be found on the next page.

Dimensions of motors

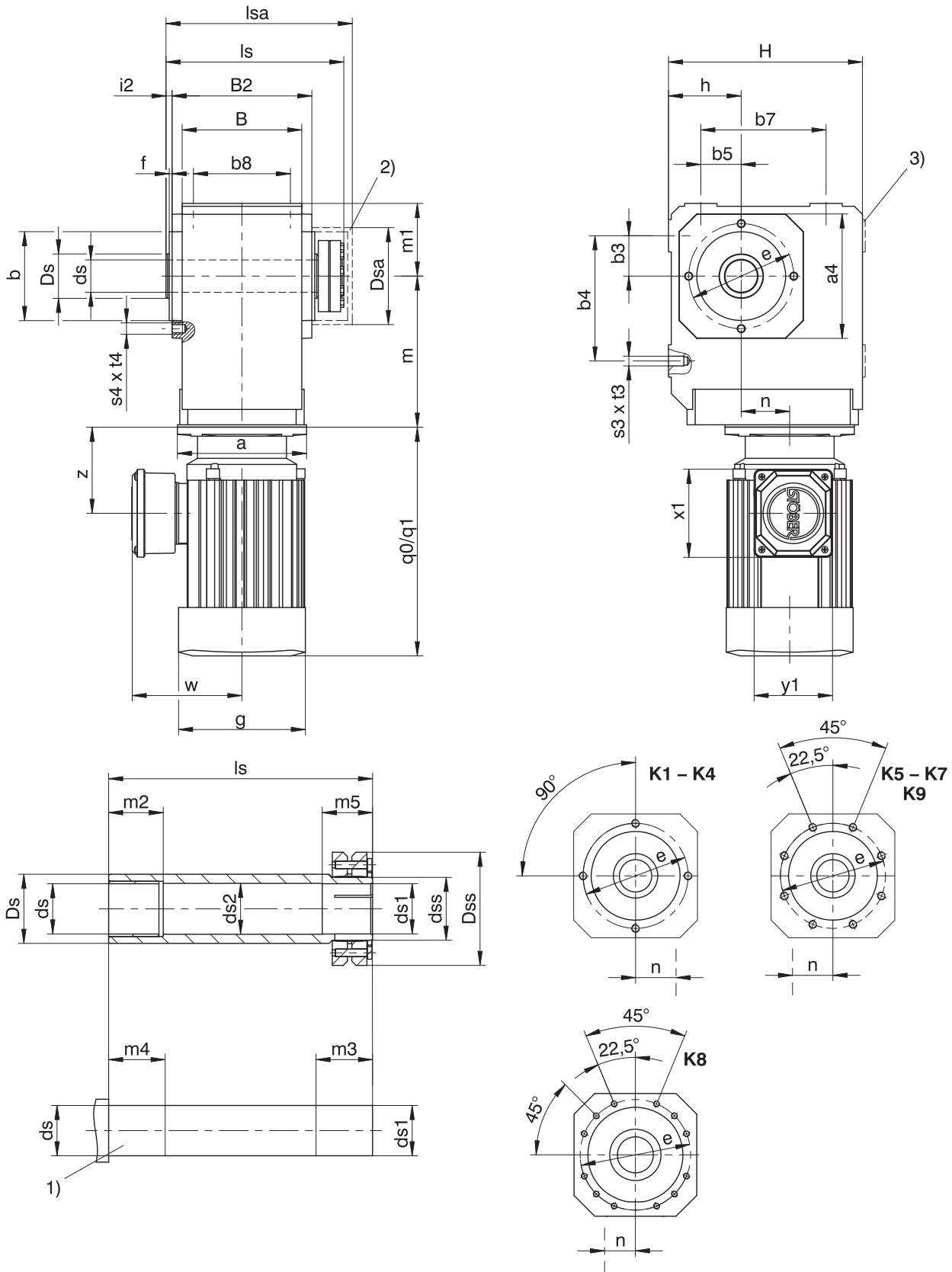
Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5
IE3D160MX04	313	526	641	199	166.5	193.5	138.0
IE3D160LX04	313	549	627	242	166.5	193.5	138.0
IE3D180MX04	313	549	677	242	166.5	193.5	178.0
IE3D180LX04	351	601	748	260	166.5	193.5	178.0
IE3D200LX04	390	729	878	298	207.0	209.0	242.0

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K102	∅140	124	36.0	∅140	124	36.0	∅160	128	36.0	∅160	128	36.0	-	-	-
K513	-	-	-	-	-	-	∅160	172	15.0	∅160	172	15.0	∅200	174	15.0
K514	-	-	-	-	-	-	∅160	215	15.0	∅160	215	15.0	-	-	-
K613	-	-	-	-	-	-	∅160	191	18.0	∅160	191	18.0	∅200	193	18.0
K614	-	-	-	-	-	-	∅160	234	18.0	∅160	234	18.0	-	-	-
K713	-	-	-	-	-	-	-	-	-	-	-	-	∅200	221	20.0
K714	-	-	-	-	-	-	∅160	263	20.0	∅160	263	20.0	∅200	283	20.0
K813	-	-	-	-	-	-	-	-	-	-	-	-	∅200	247	24.0
K814	-	-	-	-	-	-	-	-	-	-	-	-	∅200	308	24.0
K914	-	-	-	-	-	-	-	-	-	-	-	-	∅200	353	25.0

Type	IE3D112			IE3D132			IE3D160			IE3D180			IE3D200		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K513	∅200	174	15.0	∅250	177	15.0	-	-	-	-	-	-	-	-	-
K613	∅200	193	18.0	∅250	196	18.0	∅300	210	18.0	∅300	210	18.0	-	-	-
K713	∅200	221	20.0	∅250	224	20.0	∅300	237	20.0	∅300	237	20.0	-	-	-
K714	∅200	283	20.0	-	-	-	-	-	-	-	-	-	-	-	-
K813	∅200	247	24.0	∅250	249	24.0	∅300	262	24.0	∅300	262	24.0	-	-	-
K814	∅200	308	24.0	∅250	320	5.0	-	-	-	-	-	-	-	-	-
K913	-	-	-	∅250	294	25.0	∅300	307	25.0	∅300	307	25.0	∅350	330	25.0
K914	∅200	353	25.0	∅250	365	25.0	-	-	-	-	-	-	-	-	-
K1013	-	-	-	-	-	-	∅300	392	28.0	∅300	392	28.0	∅350	415	28.0
K1014	-	-	-	∅250	450	28.0	∅300	475	28.0	∅300	475	28.0	-	-	-

4.3.7 S shaft design (hollow shaft with shrink disk), G housing design (pitch circle diameter)



q_0 Applies to motors without brake.

q_1 Applies to motors with brake.

1) Machine shaft: The dimension l must meet or exceed the specified value.

2) Cover (optional)

3) Only for K1 (other sizes on request)

Dimensions of gear units

Type	a4	b	b3	b4	b5	b7	b8	B	B2	Øds	Øds1	Øds2	Ødss	ØDs	ØDsa	ØDss	Øe	f	h	H	i2	ls	lsa	m1	m2	m3	m4	m5	s3	s4	t3	t4
K1	105	75 _{f6}	30	90	30	90	70	90	106	25 _{h9}	25 _{h9} ^{H7}	25.5	30	40	80	60	90	3.0	60	160	7.0	149	163	60	20	34	25	29	M8	M8	13	13
K2	116	82 _{f6}	35	115	35	115	90	115	134	30 _{h9}	30 _{h9} ^{H7}	30.5	36	45	88	72	100	3.0	65	190	7.0	178	193	65	25	39	30	34	M10	M8	16	13
K3	132	95 _{f6}	40	130	40	130	105	130	146	35 _{h9}	35 _{h9} ^{H7}	35.5	44	50	101	80	115	3.0	75	213	7.0	190	206	75	30	39	35	34	M10	M8	16	13
K4	152	110 _{f6}	50	155	50	155	120	148	173	40 _{h9}	40 _{h9} ^{H7}	40.5	50	55	114	88	130	3.5	90	240	7.5	220	243	90	40	39	45	34	M12	M10	19	16
K5	145	110 _{f6}	40	140	100	140	125	160	185	50 _{h9}	50 _{h9} ^{H7}	50.5	62	65	116	106	130	3.5	160	260	7.5	237	254	100	40	44	45	39	M16	M10	26	16
K6	180	140 _{f6}	50	160	110	160	130	168	200	50 _{h9}	50 _{h9} ^{H7}	50.5	62	70	128	106	165	3.5	190	310	7.5	254	276	120	40	45	45	40	M16	M10	26	16
K7	195	155 _{h6}	55	180	125	180	145	190	226	60 _{h6}	60 _{h6} ^{H7}	62.0	75	85	161.5	138	185	3.5	212	342	8.0	278	314	125	40	45	45	40	M20	M12	33	19
K8	226	185 _{h6}	75	240	165	240	185	235	282	70 _{h6}	70 _{h6} ^{H7}	72.0	90	100	193	155	215	4.0	265	410	9.0	352	378	145	50	60	60	50	M24	M12	38	19
K9	280	230 _{h6}	95	280	185	280	225	285	330	90 _{h6}	90 _{h6} ^{H7}	92.0	120	120	244	200	265	5.0	315	495	10.0	418	428	180	60	70	70	60	M30	M16	48	26

Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5
IE3D160MX04	313	526	641	199	166.5	193.5	138.0
IE3D160LX04	313	549	627	242	166.5	193.5	138.0
IE3D180MX04	313	549	677	242	166.5	193.5	178.0
IE3D180LX04	351	601	748	260	166.5	193.5	178.0
IE3D200LX04	390	729	878	298	207.0	209.0	242.0

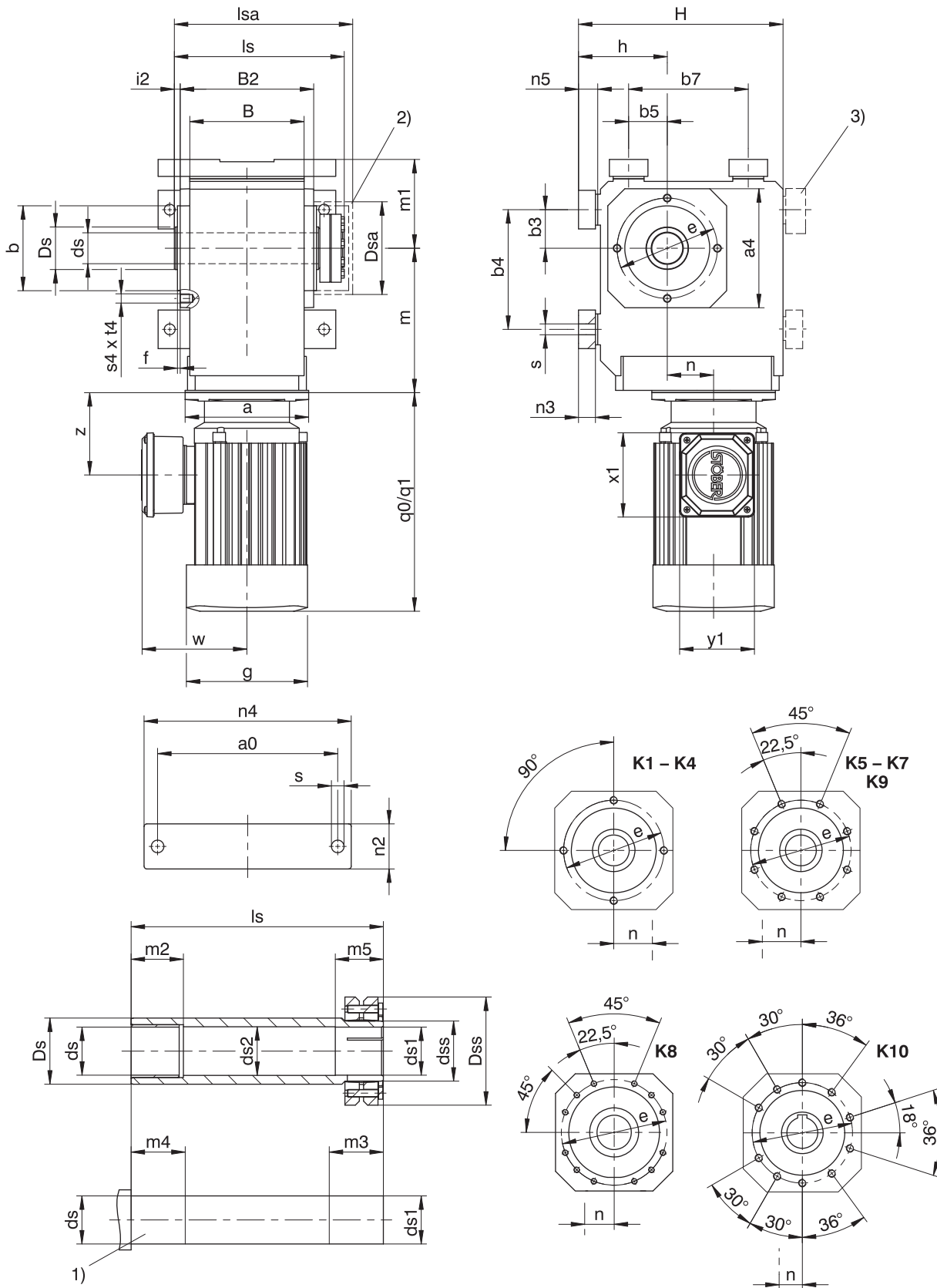
The dimensions a, m and n can be found on the next page.

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K102	∅140	124	36.0	∅140	124	36.0	∅160	128	36.0	∅160	128	36.0	-	-	-
K202	∅140	143	46.0	∅140	143	46.0	∅160	147	46.0	∅160	147	46.0	∅200	149	46.0
K203	∅140	180	46.0	∅140	180	46.0	-	-	-	-	-	-	-	-	-
K302	∅140	163	52.5	∅140	163	52.5	∅160	167	52.5	∅160	167	52.5	∅200	169	52.5
K303	∅140	200	52.5	∅140	200	52.5	∅160	210	16.0	∅160	210	16.0	-	-	-
K402	-	-	-	-	-	-	∅160	187	60.0	∅160	187	60.0	∅200	189	60.0
K403	-	-	-	∅140	220	60.0	∅160	230	23.0	∅160	230	23.0	-	-	-
K513	-	-	-	-	-	-	∅160	172	15.0	∅160	172	15.0	∅200	174	15.0
K514	-	-	-	-	-	-	∅160	215	15.0	∅160	215	15.0	-	-	-
K613	-	-	-	-	-	-	∅160	191	18.0	∅160	191	18.0	∅200	193	18.0
K614	-	-	-	-	-	-	∅160	234	18.0	∅160	234	18.0	-	-	-
K713	-	-	-	-	-	-	-	-	-	-	-	-	∅200	221	20.0
K714	-	-	-	-	-	-	∅160	263	20.0	∅160	263	20.0	∅200	283	20.0
K813	-	-	-	-	-	-	-	-	-	-	-	-	∅200	247	24.0
K814	-	-	-	-	-	-	-	-	-	-	-	-	∅200	308	24.0
K914	-	-	-	-	-	-	-	-	-	-	-	-	∅200	353	25.0

Type	IE3D112			IE3D132			IE3D160			IE3D180			IE3D200		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K202	∅200	149	46.0	-	-	-	-	-	-	-	-	-	-	-	-
K302	∅200	169	52.5	-	-	-	-	-	-	-	-	-	-	-	-
K402	∅200	189	60.0	∅250	192	60.0	-	-	-	-	-	-	-	-	-
K513	∅200	174	15.0	∅250	177	15.0	-	-	-	-	-	-	-	-	-
K613	∅200	193	18.0	∅250	196	18.0	∅300	210	18.0	∅300	210	18.0	-	-	-
K713	∅200	221	20.0	∅250	224	20.0	∅300	237	20.0	∅300	237	20.0	-	-	-
K714	∅200	283	20.0	-	-	-	-	-	-	-	-	-	-	-	-
K813	∅200	247	24.0	∅250	249	24.0	∅300	262	24.0	∅300	262	24.0	-	-	-
K814	∅200	308	24.0	∅250	320	5.0	-	-	-	-	-	-	-	-	-
K913	-	-	-	∅250	294	25.0	∅300	307	25.0	∅300	307	25.0	∅350	330	25.0
K914	∅200	353	25.0	∅250	365	25.0	-	-	-	-	-	-	-	-	-

4.3.8 S shaft design (hollow shaft with shrink disk), NG housing design (base + pitch circle diameter)



q_0 Applies to motors without brake.

q_1 Applies to motors with brake.

1) Machine shaft: The dimension l_s must meet or exceed the specified value.

2) Cover (optional)

3) Only for K1 (other sizes on request)

Dimensions of gear units

Type	a0	a4	Øb	b3	b4	b5	b7	B	B2	Øds	Øds1	Øds2	Ødss	ØDs	ØDsa
K1	115	105	75 _{j6}	30	90	30	90	90	106	25 _{h9}	25 _{h9} ^{H7}	25.5	30	40	80
K2	155	116	82 _{j6}	35	115	35	115	115	134	30 _{h9}	30 _{h9} ^{H7}	30.5	36	45	88
K3	170	132	95 _{j6}	40	130	40	130	130	146	35 _{h9}	35 _{h9} ^{H7}	35.5	44	50	101
K4	200	152	110 _{j6}	50	155	50	155	148	173	40 _{h9}	40 _{h9} ^{H7}	40.5	50	55	114
K5	200	145	110 _{j6}	40	140	100	140	160	185	50 _{h9}	50 _{h9} ^{H7}	50.5	62	65	116
K6	210	180	140 _{j6}	50	160	110	160	168	200	50 _{h9}	50 _{h9} ^{H7}	50.5	62	70	128
K7	241	195	155 _{j6}	55	180	125	180	190	226	60 _{h6}	60 _{h6} ^{H7}	62.0	75	85	161.5
K8	300	226	185 _{j6}	75	240	165	240	235	282	70 _{h6}	70 _{h6} ^{H7}	72.0	90	100	193
K9	360	280	230 _{j6}	95	280	185	280	285	330	90 _{h6}	90 _{h6} ^{H7}	92.0	120	120	244
K10	330	340	250 _{h6}	115	350	265	420	400	356	100 _{h6}	100 _{h6} ^{H7}	102.0	130	130	274

Dimensions of gear units

Type	ØDss	Øe	f	h	H	i2	ls	lsa	m1	m2	m3	m4	m5	n2	n3	n4	n5	Øs	s4	t4
K1	60	90	3.0	75	175	7.0	149	163	75	20	34	25	29	30	13	140	15	9.0	M8	13
K2	72	100	3.0	88	213	7.0	178	193	88	25	39	30	34	40	20	185	23	11.0	M8	13
K3	80	115	3.0	98	236	7.0	190	206	98	30	39	35	34	45	20	200	23	11.0	M8	13
K4	88	130	3.5	115	265	7.5	220	243	115	40	39	45	34	50	22	230	25	14.0	M10	16
K5	106	130	3.5	190	290	7.5	237	254	130	40	44	45	39	60	27	240	30	18.0	M10	16
K6	106	165	3.5	220	340	7.5	254	276	150	40	45	45	40	65	27	250	30	18.5	M10	16
K7	138	185	3.5	250	380	8.0	278	314	163	40	45	45	40	70	35	290	38	23.0	M12	19
K8	155	215	4.0	310	455	9.0	352	378	190	50	60	60	50	85	41	360	45	27.0	M12	19
K9	200	265	5.0	365	545	10.0	418	428	230	60	70	70	60	95	46	430	50	31.0	M16	26
K10	215	300	20.0	420	636	27.0	483	497	270	60	80	70	70	120	–	400	45	39.0	M20	33

Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5
IE3D160MX04	313	526	641	199	166.5	193.5	138.0
IE3D160LX04	313	549	627	242	166.5	193.5	138.0
IE3D180MX04	313	549	677	242	166.5	193.5	178.0
IE3D180LX04	351	601	748	260	166.5	193.5	178.0
IE3D200LX04	390	729	878	298	207.0	209.0	242.0

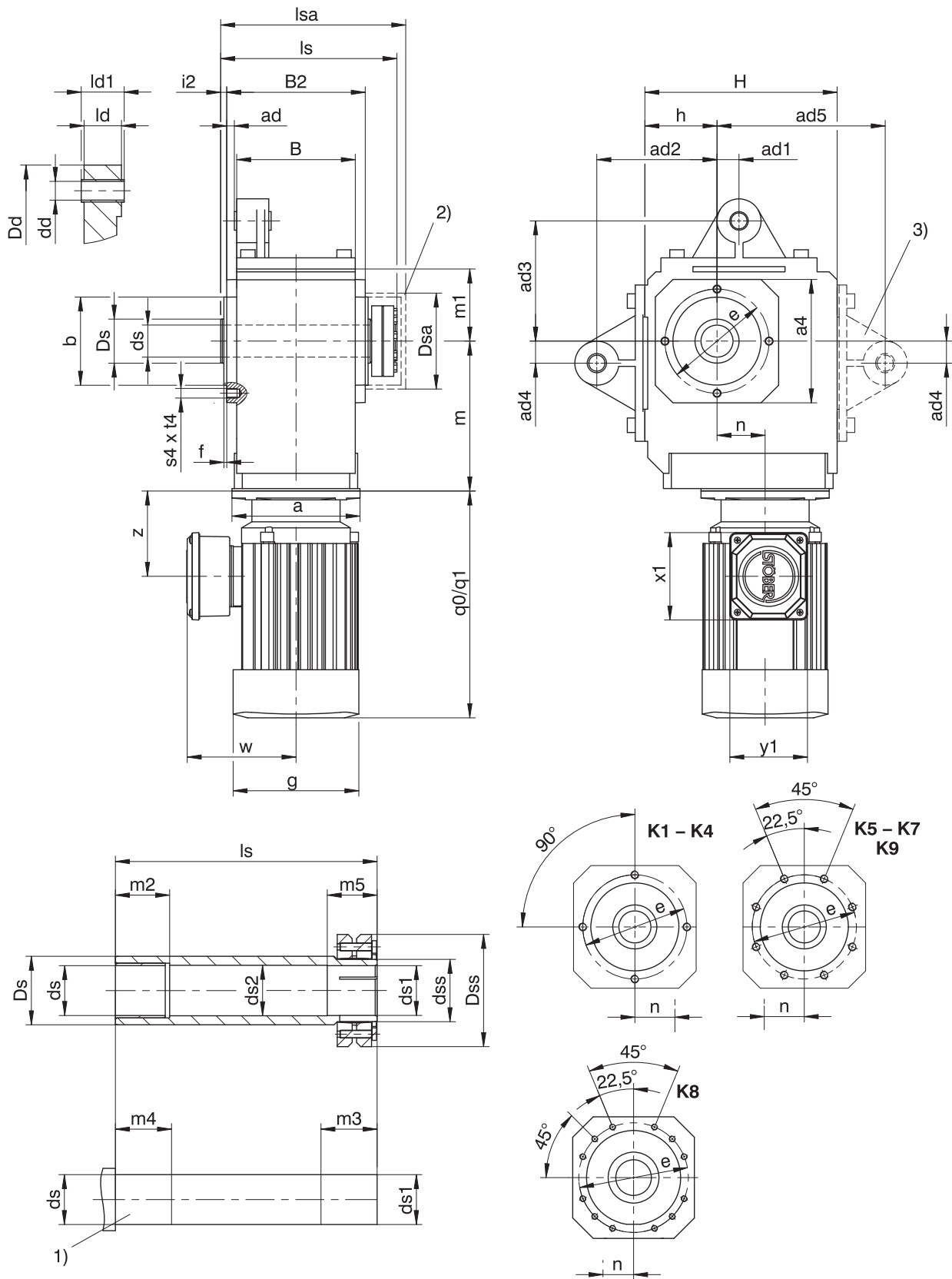
The dimensions a, m and n can be found on the next page.

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K102	∅140	124	36.0	∅140	124	36.0	∅160	128	36.0	∅160	128	36.0	-	-	-
K202	∅140	143	46.0	∅140	143	46.0	∅160	147	46.0	∅160	147	46.0	∅200	149	46.0
K203	∅140	180	46.0	∅140	180	46.0	-	-	-	-	-	-	-	-	-
K302	∅140	163	52.5	∅140	163	52.5	∅160	167	52.5	∅160	167	52.5	∅200	169	52.5
K303	∅140	200	52.5	∅140	200	52.5	∅160	210	16.0	∅160	210	16.0	-	-	-
K402	-	-	-	-	-	-	∅160	187	60.0	∅160	187	60.0	∅200	189	60.0
K403	-	-	-	∅140	220	60.0	∅160	230	23.0	∅160	230	23.0	-	-	-
K513	-	-	-	-	-	-	∅160	172	15.0	∅160	172	15.0	∅200	174	15.0
K514	-	-	-	-	-	-	∅160	215	15.0	∅160	215	15.0	-	-	-
K613	-	-	-	-	-	-	∅160	191	18.0	∅160	191	18.0	∅200	193	18.0
K614	-	-	-	-	-	-	∅160	234	18.0	∅160	234	18.0	-	-	-
K713	-	-	-	-	-	-	-	-	-	-	-	-	∅200	221	20.0
K714	-	-	-	-	-	-	∅160	263	20.0	∅160	263	20.0	∅200	283	20.0
K813	-	-	-	-	-	-	-	-	-	-	-	-	∅200	247	24.0
K814	-	-	-	-	-	-	-	-	-	-	-	-	∅200	308	24.0
K914	-	-	-	-	-	-	-	-	-	-	-	-	∅200	353	25.0

Type	IE3D112			IE3D132			IE3D160			IE3D180			IE3D200		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K202	∅200	149	46.0	-	-	-	-	-	-	-	-	-	-	-	-
K302	∅200	169	52.5	-	-	-	-	-	-	-	-	-	-	-	-
K402	∅200	189	60.0	∅250	192	60.0	-	-	-	-	-	-	-	-	-
K513	∅200	174	15.0	∅250	177	15.0	-	-	-	-	-	-	-	-	-
K613	∅200	193	18.0	∅250	196	18.0	∅300	210	18.0	∅300	210	18.0	-	-	-
K713	∅200	221	20.0	∅250	224	20.0	∅300	237	20.0	∅300	237	20.0	-	-	-
K714	∅200	283	20.0	-	-	-	-	-	-	-	-	-	-	-	-
K813	∅200	247	24.0	∅250	249	24.0	∅300	262	24.0	∅300	262	24.0	-	-	-
K814	∅200	308	24.0	∅250	320	5.0	-	-	-	-	-	-	-	-	-
K913	-	-	-	∅250	294	25.0	∅300	307	25.0	∅300	307	25.0	∅350	330	25.0
K914	∅200	353	25.0	∅250	365	25.0	-	-	-	-	-	-	-	-	-
K1013	-	-	-	-	-	-	∅300	392	28.0	∅300	392	28.0	∅350	415	28.0
K1014	-	-	-	∅250	450	28.0	∅300	475	28.0	∅300	475	28.0	-	-	-

4.3.9 S shaft design (hollow shaft with shrink disk), GD housing design (pitch circle diameter + torque arm bracket)



- q0 Applies to motors without brake.
- q1 Applies to motors with brake.
- 1) Machine shaft: The dimension l_s must meet or exceed the specified value.
- 2) Cover (optional)
- 3) Only for K1 (other sizes on request)
- If you brace the gear units without the torque arm brackets provided by the manufacturer for this purpose, the dimensions for ad_2 and ad_3 must meet the specified value.

Dimensions of gear units

Type	□a4	ad	ad1	ad2	ad3	ad4	ad5	Øb	B	B2	Ødd	Øds	Øds1	Øds2	Ødss	ØDd	ØDs	ØDsa
K1	105	6.0	15.0	90	90	15.0	130	75 _{j6}	90	106	12 ^{H9}	25 _{h9}	25 _{h9} ^{H7}	25.5	30	43	40	80
K2	116	6.5	22.5	100	100	22.5	–	82 _{j6}	115	134	16 ^{H9}	30 _{h9}	30 _{h9} ^{H7}	30.5	36	45	45	88
K3	132	5.0	25.0	120	120	25.0	–	95 _{j6}	130	146	16 ^{H9}	35 _{h9}	35 _{h9} ^{H7}	35.5	44	45	50	101
K4	152	9.5	27.5	150	150	27.5	–	110 _{j6}	148	173	20 ^{H9}	40 _{h9}	40 _{h9} ^{H7}	40.5	50	55	55	114
K5	145	9.5	30.0	250	190	30.0	–	110 _{j6}	160	185	20 ^{H9}	50 _{h9}	50 _{h9} ^{H7}	50.5	62	58	65	116
K6	180	13.0	30.0	250	180	30.0	–	140 _{j6}	168	200	20 ^{H9}	50 _{h9}	50 _{h9} ^{H7}	50.5	62	58	70	128
K7	195	15.0	35.0	300	213	35.0	–	155 _{h6}	190	226	20 ^{H9}	60 _{h6}	60 _{h6} ^{H7}	62.0	75	68	85	161.5
K8	226	17.0	45.0	350	230	45.0	–	185 _{h6}	235	282	24 ^{H9}	70 _{h6}	70 _{h6} ^{H7}	72.0	90	72	100	193
K9	280	16.0	45.0	450	315	45.0	–	230 _{h6}	285	330	24 ^{H9}	90 _{h6}	90 _{h6} ^{H7}	92.0	120	75	120	244

Dimensions of gear units

Type	ØDss	Øe	f	h	H	i2	ld	ld1	ls	lsa	m1	m2	m3	m4	m5	s4	t4
K1	60	90	3.0	60	160	7.0	24	28	149	163	60	20	34	25	29	M8	13
K2	72	100	3.0	65	190	7.0	32	38	178	193	65	25	39	30	34	M8	13
K3	80	115	3.0	75	213	7.0	32	38	190	206	75	30	39	35	34	M8	13
K4	88	130	3.5	90	240	7.5	40	46	220	243	90	40	39	45	34	M10	16
K5	106	130	3.5	160	260	7.5	40	46	237	254	100	40	44	45	39	M10	16
K6	106	165	3.5	190	310	7.5	40	46	254	276	120	40	45	45	40	M10	16
K7	138	185	3.5	212	342	8.0	64	70	278	314	125	40	45	45	40	M12	19
K8	155	215	4.0	265	410	9.0	102	115	352	378	145	50	60	60	50	M12	19
K9	200	265	5.0	315	495	10.0	102	115	418	428	180	60	70	70	60	M16	26

Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5
IE3D160MX04	313	526	641	199	166.5	193.5	138.0
IE3D160LX04	313	549	627	242	166.5	193.5	138.0
IE3D180MX04	313	549	677	242	166.5	193.5	178.0
IE3D180LX04	351	601	748	260	166.5	193.5	178.0
IE3D200LX04	390	729	878	298	207.0	209.0	242.0

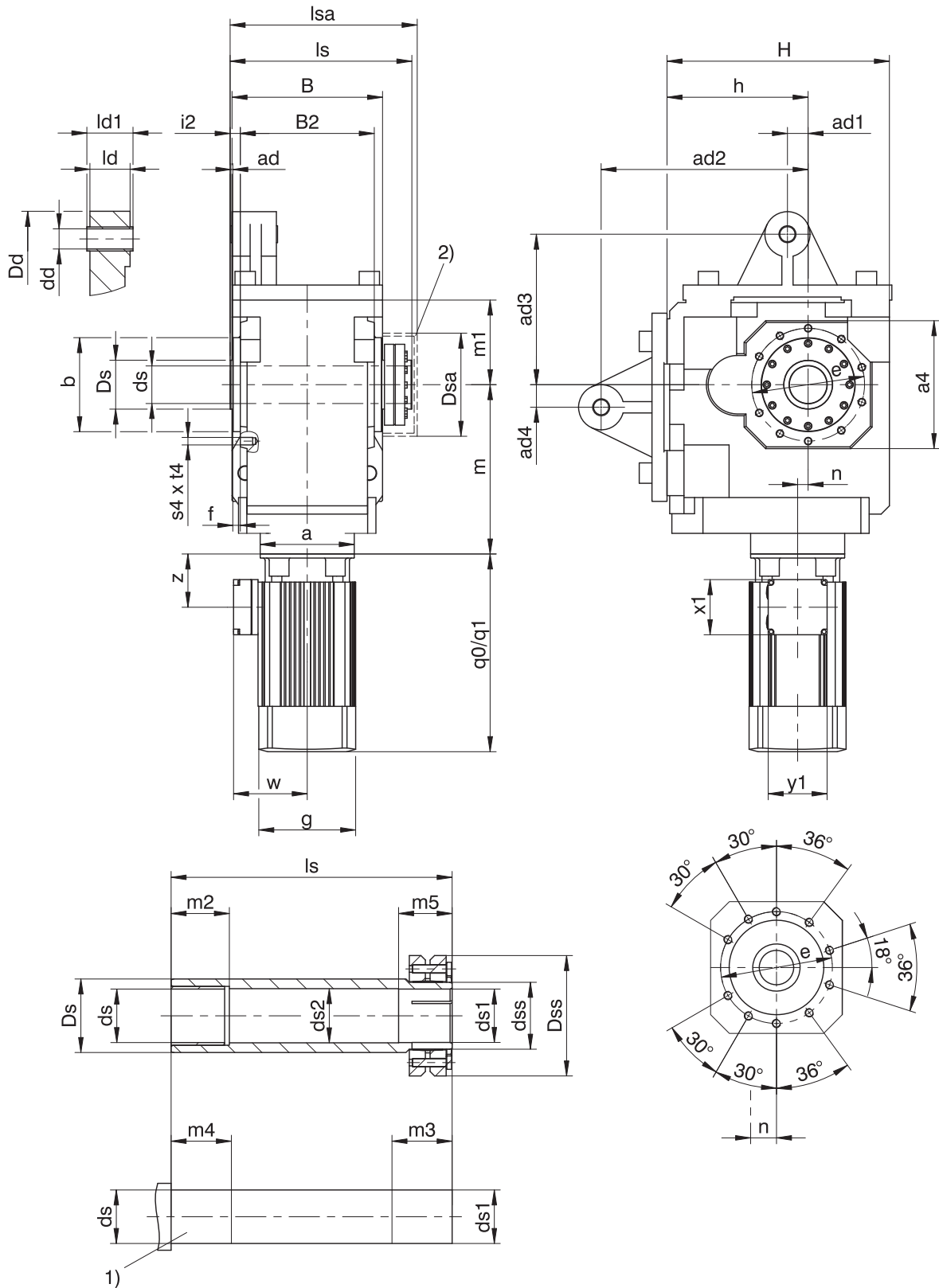
The dimensions a, m and n can be found on the next page.

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K102	∅140	124	36.0	∅140	124	36.0	∅160	128	36.0	∅160	128	36.0	-	-	-
K202	∅140	143	46.0	∅140	143	46.0	∅160	147	46.0	∅160	147	46.0	∅200	149	46.0
K203	∅140	180	46.0	∅140	180	46.0	-	-	-	-	-	-	-	-	-
K302	∅140	163	52.5	∅140	163	52.5	∅160	167	52.5	∅160	167	52.5	∅200	169	52.5
K303	∅140	200	52.5	∅140	200	52.5	∅160	210	16.0	∅160	210	16.0	-	-	-
K402	-	-	-	-	-	-	∅160	187	60.0	∅160	187	60.0	∅200	189	60.0
K403	-	-	-	∅140	220	60.0	∅160	230	23.0	∅160	230	23.0	-	-	-
K513	-	-	-	-	-	-	∅160	172	15.0	∅160	172	15.0	∅200	174	15.0
K514	-	-	-	-	-	-	∅160	215	15.0	∅160	215	15.0	-	-	-
K613	-	-	-	-	-	-	∅160	191	18.0	∅160	191	18.0	∅200	193	18.0
K614	-	-	-	-	-	-	∅160	234	18.0	∅160	234	18.0	-	-	-
K713	-	-	-	-	-	-	-	-	-	-	-	-	∅200	221	20.0
K714	-	-	-	-	-	-	∅160	263	20.0	∅160	263	20.0	∅200	283	20.0
K813	-	-	-	-	-	-	-	-	-	-	-	-	∅200	247	24.0
K814	-	-	-	-	-	-	-	-	-	-	-	-	∅200	308	24.0
K914	-	-	-	-	-	-	-	-	-	-	-	-	∅200	353	25.0

Type	IE3D112			IE3D132			IE3D160			IE3D180			IE3D200		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K202	∅200	149	46.0	-	-	-	-	-	-	-	-	-	-	-	-
K302	∅200	169	52.5	-	-	-	-	-	-	-	-	-	-	-	-
K402	∅200	189	60.0	∅250	192	60.0	-	-	-	-	-	-	-	-	-
K513	∅200	174	15.0	∅250	177	15.0	-	-	-	-	-	-	-	-	-
K613	∅200	193	18.0	∅250	196	18.0	∅300	210	18.0	∅300	210	18.0	-	-	-
K713	∅200	221	20.0	∅250	224	20.0	∅300	237	20.0	∅300	237	20.0	-	-	-
K714	∅200	283	20.0	-	-	-	-	-	-	-	-	-	-	-	-
K813	∅200	247	24.0	∅250	249	24.0	∅300	262	24.0	∅300	262	24.0	-	-	-
K814	∅200	308	24.0	∅250	320	5.0	-	-	-	-	-	-	-	-	-
K913	-	-	-	∅250	294	25.0	∅300	307	25.0	∅300	307	25.0	∅350	330	25.0
K914	∅200	353	25.0	∅250	365	25.0	-	-	-	-	-	-	-	-	-

4.3.10 S shaft design (hollow shaft with shrink disk), NGD housing design (foot + pitch circle diameter + torque arm bracket)



- q0 Applies to motors without brake.
- q1 Applies to motors with brake.
- 1) Machine shaft: The dimension ls must meet or exceed the specified value.
- 2) Cover (optional)
- If you brace the gear units without the torque arm brackets provided by the manufacturer for this purpose, the dimensions for ad2 and ad3 must meet the specified value.

Dimensions of gear units

Type	□a4	ad	ad1	ad2	ad3	ad4	∅b	B	B2	∅dd	∅ds	∅ds1	∅ds2	∅dss	∅Dd	∅Ds	∅Dsa
K10	340	5	55	550	400	60	250 _{h6}	400	356	40 ^{H9}	100 _{h6}	100 _{h6} ^{H7}	102	130	120	130	274

Dimensions of gear units

Type	∅Dss	∅e	f	h	H	i2	ld	ld1	ls	lsa	m1	m2	m3	m4	m5	s4	t4
K10	215	300	20	375	591	27	118	124	483	497	225	60	80	70	70	M20	33

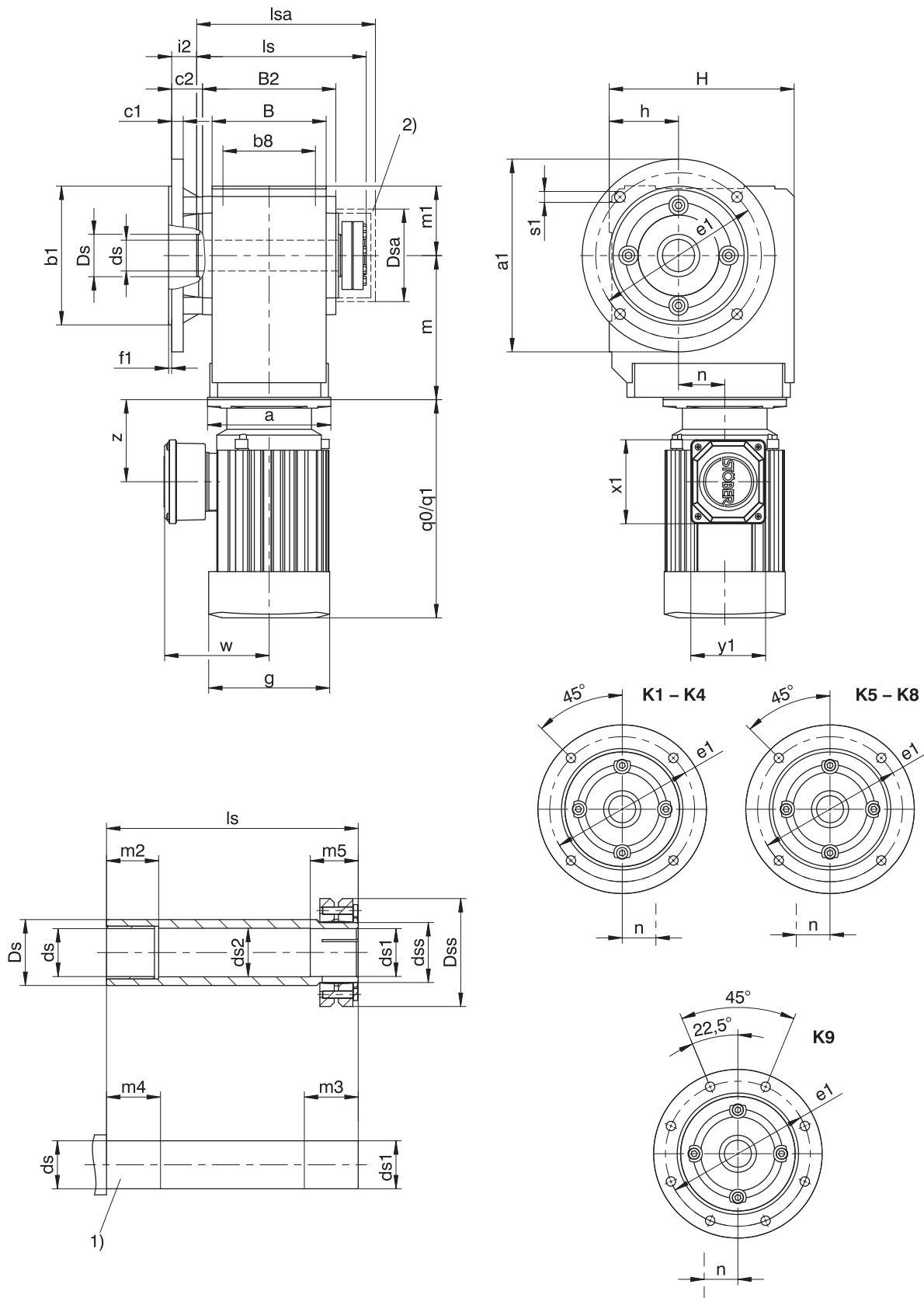
Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5
IE3D160MX04	313	526	641	199	166.5	193.5	138.0
IE3D160LX04	313	549	627	242	166.5	193.5	138.0
IE3D180MX04	313	549	677	242	166.5	193.5	178.0
IE3D180LX04	351	601	748	260	166.5	193.5	178.0
IE3D200LX04	390	729	878	298	207.0	209.0	242.0

Dimensions of geared motors

Type	IE3D132			IE3D160			IE3D180			IE3D200		
	a	m	n	a	m	n	a	m	n	a	m	n
K1013	–	–	–	∅300	392	28.0	∅300	392	28.0	∅350	415	28.0
K1014	∅250	450	28.0	∅300	475	28.0	∅300	475	28.0	–	–	–

4.3.11 S shaft design (hollow shaft with shrink disk), F housing design (round flange)



q_0 Applies to motors without brake.

q_1 Applies to motors with brake.

1) Machine shaft: The dimension l_s must meet or exceed the specified value.

2) Cover (optional)

Dimensions of gear units

Type	Øa1	Øb1	b8	B	B2	c1	c2	Øds	Øds1	Øds2	Ødss	ØDs	ØDsa	ØDss	Øe1	f1	h	H	i2	ls	lsa	m1	m2	m3	m4	m5	Øs1
K1	160	110 _β	70	90	106	10	32.0	25 _{h9}	25 _{h9} ^{H7}	25.5	30	40	80	60	130	3.5	60	160	25.0	149	163	60	20	34	25	29	9
K2	200	130 _β	90	115	134	12	32.0	30 _{h9}	30 _{h9} ^{H7}	30.5	36	45	88	72	165	3.5	65	190	25.0	178	193	65	25	39	30	34	11
K3	200	130 _β	105	130	146	14	38.0	35 _{h9}	35 _{h9} ^{H7}	35.5	44	50	101	80	165	3.5	75	213	31.0	190	206	75	30	39	35	34	11
K4	250	180 _β	120	148	173	15	40.0	40 _{h9}	40 _{h9} ^{H7}	40.5	50	55	114	88	215	4.0	90	240	32.5	220	243	90	40	39	45	34	14
K5	250	180 _β	125	160	185	15	39.5	50 _{h9}	50 _{h9} ^{H7}	50.5	62	65	116	106	215	4.0	160	260	32.0	237	254	100	40	44	45	39	14
K6	300	230 _β	130	168	200	17	36.0	50 _{h9}	50 _{h9} ^{H7}	50.5	62	70	128	106	265	4.0	190	310	28.5	254	276	120	40	45	45	40	14
K7	350	250 _{h6}	145	190	226	18	44.0	60 _{h6}	60 _{h6} ^{H7}	62.0	75	85	161.5	138	300	5.0	212	342	36.0	278	314	125	40	45	45	40	18
K8	400	300 _{h6}	185	235	282	20	45.0	70 _{h6}	70 _{h6} ^{H7}	72.0	90	100	193	155	350	5.0	265	410	36.0	352	378	145	50	60	60	50	18
K9	450	350 _{h6}	225	285	330	23	50.0	90 _{h6}	90 _{h6} ^{H7}	92.0	120	120	244	200	400	5.0	315	495	40.0	418	428	180	60	70	70	60	18

Dimensions of additional round flanges

Type	Øa1	Øb1	c1	Øe1	f1	Øs1
K1	140	95 _β	10	115	3.0	9
K2	160	110 _β	12	130	3.5	9
K3	160	110 _β	14	130	3.5	9
K3	250	180 _β	14	215	4.0	14
K8	350	250 _{h6}	18	300	5.0	18
K8	450	350 _{h6}	20	400	5.0	18

Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5
IE3D160MX04	313	526	641	199	166.5	193.5	138.0
IE3D160LX04	313	549	627	242	166.5	193.5	138.0
IE3D180MX04	313	549	677	242	166.5	193.5	178.0
IE3D180LX04	351	601	748	260	166.5	193.5	178.0
IE3D200LX04	390	729	878	298	207.0	209.0	242.0

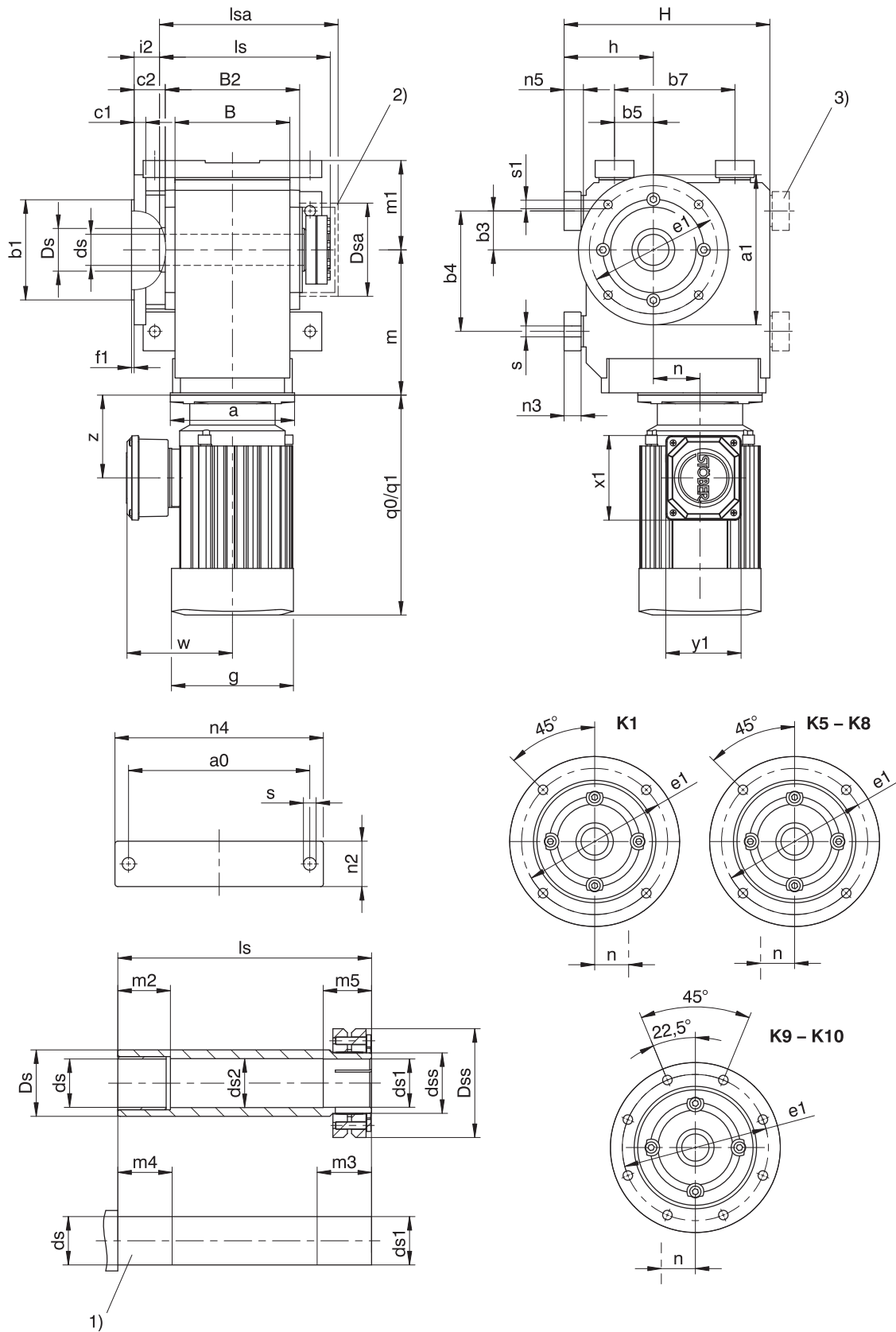
The dimensions a, m and n can be found on the next page.

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K102	∅140	124	36.0	∅140	124	36.0	∅160	128	36.0	∅160	128	36.0	-	-	-
K202	∅140	143	46.0	∅140	143	46.0	∅160	147	46.0	∅160	147	46.0	∅200	149	46.0
K203	∅140	180	46.0	∅140	180	46.0	-	-	-	-	-	-	-	-	-
K302	∅140	163	52.5	∅140	163	52.5	∅160	167	52.5	∅160	167	52.5	∅200	169	52.5
K303	∅140	200	52.5	∅140	200	52.5	∅160	210	16.0	∅160	210	16.0	-	-	-
K402	-	-	-	-	-	-	∅160	187	60.0	∅160	187	60.0	∅200	189	60.0
K403	-	-	-	∅140	220	60.0	∅160	230	23.0	∅160	230	23.0	-	-	-
K513	-	-	-	-	-	-	∅160	172	15.0	∅160	172	15.0	∅200	174	15.0
K514	-	-	-	-	-	-	∅160	215	15.0	∅160	215	15.0	-	-	-
K613	-	-	-	-	-	-	∅160	191	18.0	∅160	191	18.0	∅200	193	18.0
K614	-	-	-	-	-	-	∅160	234	18.0	∅160	234	18.0	-	-	-
K713	-	-	-	-	-	-	-	-	-	-	-	-	∅200	221	20.0
K714	-	-	-	-	-	-	∅160	263	20.0	∅160	263	20.0	∅200	283	20.0
K813	-	-	-	-	-	-	-	-	-	-	-	-	∅200	247	24.0
K814	-	-	-	-	-	-	-	-	-	-	-	-	∅200	308	24.0
K914	-	-	-	-	-	-	-	-	-	-	-	-	∅200	353	25.0

Type	IE3D112			IE3D132			IE3D160			IE3D180			IE3D200		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K202	∅200	149	46.0	-	-	-	-	-	-	-	-	-	-	-	-
K302	∅200	169	52.5	-	-	-	-	-	-	-	-	-	-	-	-
K402	∅200	189	60.0	∅250	192	60.0	-	-	-	-	-	-	-	-	-
K513	∅200	174	15.0	∅250	177	15.0	-	-	-	-	-	-	-	-	-
K613	∅200	193	18.0	∅250	196	18.0	∅300	210	18.0	∅300	210	18.0	-	-	-
K713	∅200	221	20.0	∅250	224	20.0	∅300	237	20.0	∅300	237	20.0	-	-	-
K714	∅200	283	20.0	-	-	-	-	-	-	-	-	-	-	-	-
K813	∅200	247	24.0	∅250	249	24.0	∅300	262	24.0	∅300	262	24.0	-	-	-
K814	∅200	308	24.0	∅250	320	5.0	-	-	-	-	-	-	-	-	-
K913	-	-	-	∅250	294	25.0	∅300	307	25.0	∅300	307	25.0	∅350	330	25.0
K914	∅200	353	25.0	∅250	365	25.0	-	-	-	-	-	-	-	-	-

4.3.12 S shaft design (hollow shaft with shrink disk), NF housing design (base + round flange)



- | | | | |
|-------|---|-------|-------------------------------|
| q_0 | Applies to motors without brake. | q_1 | Applies to motors with brake. |
| 1) | Machine shaft: The dimension l_s must meet or exceed the specified value. | 2) | Cover (optional) |
| 3) | Only for K1 (other sizes on request) | | |

Dimensions of gear units

Type	a0	Øa1	Øb1	b3	b4	b5	b7	B	B2	c1	c2	Øds	Øds1	Øds2	Ødss	ØDs	ØDsa	ØDss
K1	115	160	110 _{f6}	30	90	30	90	90	106	10	32.0	25 _{h9}	25 _{h9} ^{H7}	25.5	30	40	80.0	60
K5	200	250	180 _{f6}	40	140	100	140	160	185	15	39.5	50 _{h9}	50 _{h9} ^{H7}	50.5	62	65	116.0	106
K6	210	300	230 _{f6}	50	160	110	160	168	200	17	36.0	50 _{h9}	50 _{h9} ^{H7}	50.5	62	70	128.0	106
K7	241	350	250 _{h6}	55	180	125	180	190	226	18	44.0	60 _{h6}	60 _{h6} ^{H7}	62.0	75	85	161.5	138
K8	300	400	300 _{h6}	75	240	165	240	235	282	20	45.0	70 _{h6}	70 _{h6} ^{H7}	72.0	90	100	193.0	155
K9	360	450	350 _{h6}	95	280	185	280	285	330	23	50.0	90 _{h6}	90 _{h6} ^{H7}	92.0	120	120	244.0	200
K10	330	550	450 _{h6}	115	350	265	420	400	356	25	78.0	100 _{h6}	100 _{h6} ^{H7}	102.0	130	130	274.0	215

Dimensions of gear units

Type	Øe1	f1	h	H	i2	ls	lsa	m1	m2	m3	m4	m5	n2	n3	n4	n5	Øs	Øs1
K1	130	3.5	75	175	25.0	149	163	75	20	34	25	29	30	13	140	15	9.0	9
K5	215	4.0	190	290	32.0	237	254	130	40	44	45	39	60	27	240	30	18.0	14
K6	265	4.0	220	340	28.5	254	276	150	40	45	45	40	65	27	250	30	18.5	14
K7	300	5.0	250	380	36.0	278	314	163	40	45	45	40	70	35	290	38	23.0	18
K8	350	5.0	310	455	36.0	352	378	190	50	60	60	50	85	41	360	45	27.0	18
K9	400	5.0	365	545	40.0	418	428	230	60	70	70	60	95	46	430	50	31.0	18
K10	500	5.0	420	636	51.0	483	497	270	60	80	70	70	120	–	400	45	39.0	18

Dimensions of additional round flanges

Type	Øa1	Øb1	c1	Øe1	f1	Øs1
K1	140	95 _{f6}	10	115	3	9
K8	350	250 _{h6}	18	300	5	18
K8	450	350 _{h6}	20	400	5	18

Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5
IE3D160MX04	313	526	641	199	166.5	193.5	138.0
IE3D160LX04	313	549	627	242	166.5	193.5	138.0
IE3D180MX04	313	549	677	242	166.5	193.5	178.0
IE3D180LX04	351	601	748	260	166.5	193.5	178.0
IE3D200LX04	390	729	878	298	207.0	209.0	242.0

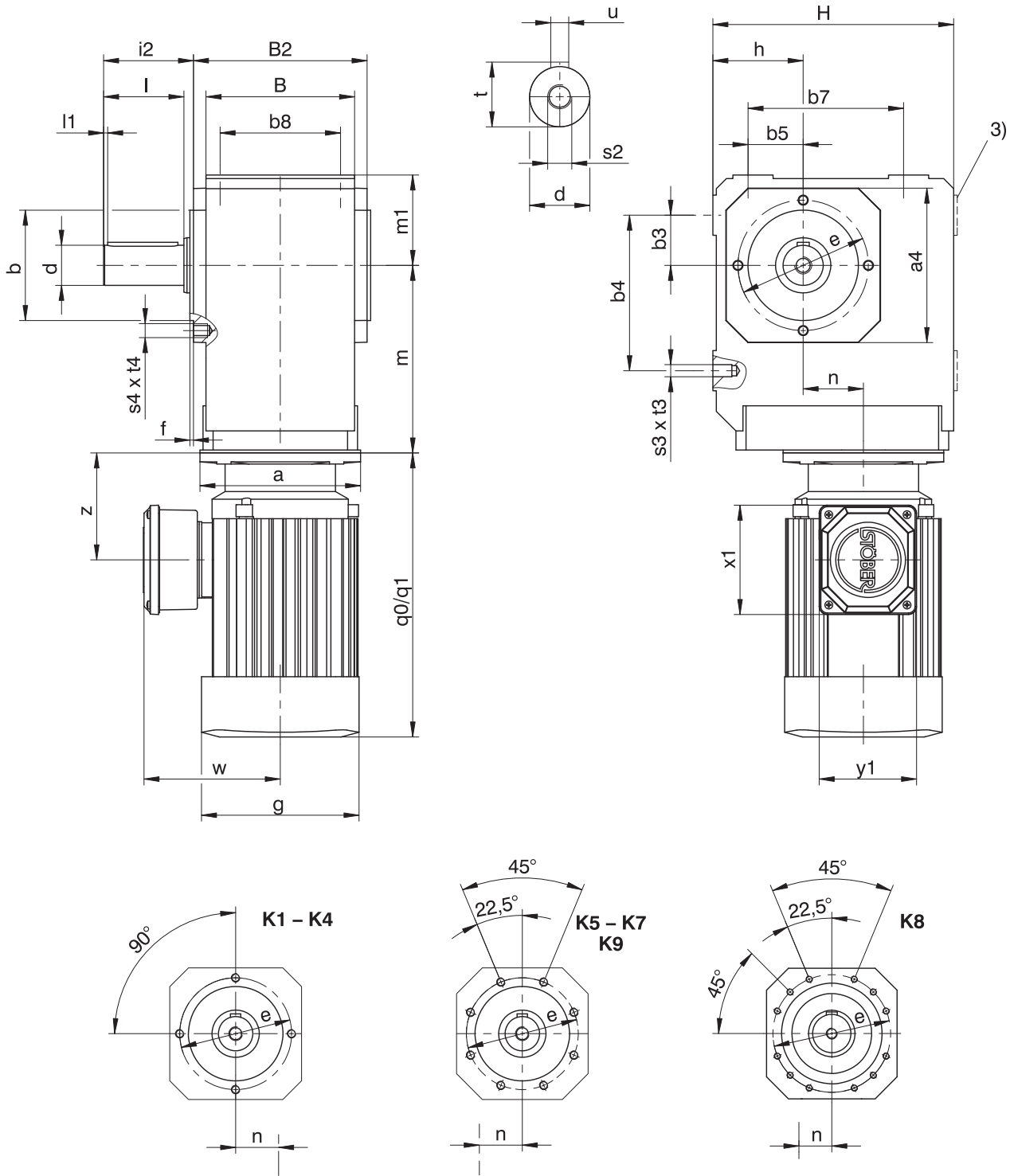
The dimensions a, m and n can be found on the next page.

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K102	∅140	124	36.0	∅140	124	36.0	∅160	128	36.0	∅160	128	36.0	-	-	-
K513	-	-	-	-	-	-	∅160	172	15.0	∅160	172	15.0	∅200	174	15.0
K514	-	-	-	-	-	-	∅160	215	15.0	∅160	215	15.0	-	-	-
K613	-	-	-	-	-	-	∅160	191	18.0	∅160	191	18.0	∅200	193	18.0
K614	-	-	-	-	-	-	∅160	234	18.0	∅160	234	18.0	-	-	-
K713	-	-	-	-	-	-	-	-	-	-	-	-	∅200	221	20.0
K714	-	-	-	-	-	-	∅160	263	20.0	∅160	263	20.0	∅200	283	20.0
K813	-	-	-	-	-	-	-	-	-	-	-	-	∅200	247	24.0
K814	-	-	-	-	-	-	-	-	-	-	-	-	∅200	308	24.0
K914	-	-	-	-	-	-	-	-	-	-	-	-	∅200	353	25.0

Type	IE3D112			IE3D132			IE3D160			IE3D180			IE3D200		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K513	∅200	174	15.0	∅250	177	15.0	-	-	-	-	-	-	-	-	-
K613	∅200	193	18.0	∅250	196	18.0	∅300	210	18.0	∅300	210	18.0	-	-	-
K713	∅200	221	20.0	∅250	224	20.0	∅300	237	20.0	∅300	237	20.0	-	-	-
K714	∅200	283	20.0	-	-	-	-	-	-	-	-	-	-	-	-
K813	∅200	247	24.0	∅250	249	24.0	∅300	262	24.0	∅300	262	24.0	-	-	-
K814	∅200	308	24.0	∅250	320	5.0	-	-	-	-	-	-	-	-	-
K913	-	-	-	∅250	294	25.0	∅300	307	25.0	∅300	307	25.0	∅350	330	25.0
K914	∅200	353	25.0	∅250	365	25.0	-	-	-	-	-	-	-	-	-
K1013	-	-	-	-	-	-	∅300	392	28.0	∅300	392	28.0	∅350	415	28.0
K1014	-	-	-	∅250	450	28.0	∅300	475	28.0	∅300	475	28.0	-	-	-

4.3.13 A shaft design (solid shaft), G housing design (pitch circle diameter)



q0 Applies to motors without brake.

3) Only for K1 (other sizes on request)

- K1 - K9: Solid shaft on both sides available.

q1 Applies to motors with brake.

- K1 - K4: solid shaft without feather key available, on request starting at K5.

Dimensions of gear units

Type	□a4	∅b	b3	b4	b5	b7	b8	B	B2	∅d	∅e	f	h	H	i2	l	l1	m1	s2	s3	s4	t	t3	t4	u
K1	105	75 _g	30	90	30	90	70	90	106	25 _{k6}	90	3.0	60	160	62.0	50	4	60	M10	M8	M8	28.0	13	13	A8×7×40
K2	116	82 _g	35	115	35	115	90	115	134	30 _{k6}	100	3.0	65	190	68.0	60	4	65	M10	M10	M8	33.0	16	13	A8×7×50
K3	132	95 _g	40	130	40	130	105	130	146	30 _{k6}	115	3.0	75	213	69.0	60	4	75	M10	M10	M8	33.0	16	13	A8×7×50
K4	152	110 _g	50	155	50	155	120	148	173	40 _{k6}	130	3.5	90	240	89.5	80	4	90	M16	M12	M10	43.0	19	16	A12×8×70
K5	145	110 _g	40	140	100	140	125	160	185	45 _{k6}	130	3.5	160	260	129.5	90	4	100	M16	M16	M10	48.5	26	16	A14×9×80
K6	180	140 _g	50	160	110	160	130	168	200	50 _{k6}	165	3.5	190	310	136.0	100	4	120	M16	M16	M10	53.5	26	16	A14×9×90
K7	195	155 _g	55	180	125	180	145	190	226	60 _{m6}	185	3.5	212	342	164.0	120	4	125	M20	M20	M12	64.0	33	19	A18×11×110
K8	226	185 _g	75	240	165	240	185	235	282	70 _{m6}	215	4.0	265	410	185.0	140	5	145	M20	M24	M12	74.5	38	19	A20×12×125
K9	280	230 _g	95	280	185	280	225	285	330	90 _{m6}	265	5.0	315	495	220.0	170	8	180	M24	M30	M16	95.0	48	26	A25×14×140

Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5
IE3D160MX04	313	526	641	199	166.5	193.5	138.0
IE3D160LX04	313	549	627	242	166.5	193.5	138.0
IE3D180MX04	313	549	677	242	166.5	193.5	178.0
IE3D180LX04	351	601	748	260	166.5	193.5	178.0
IE3D200LX04	390	729	878	298	207.0	209.0	242.0

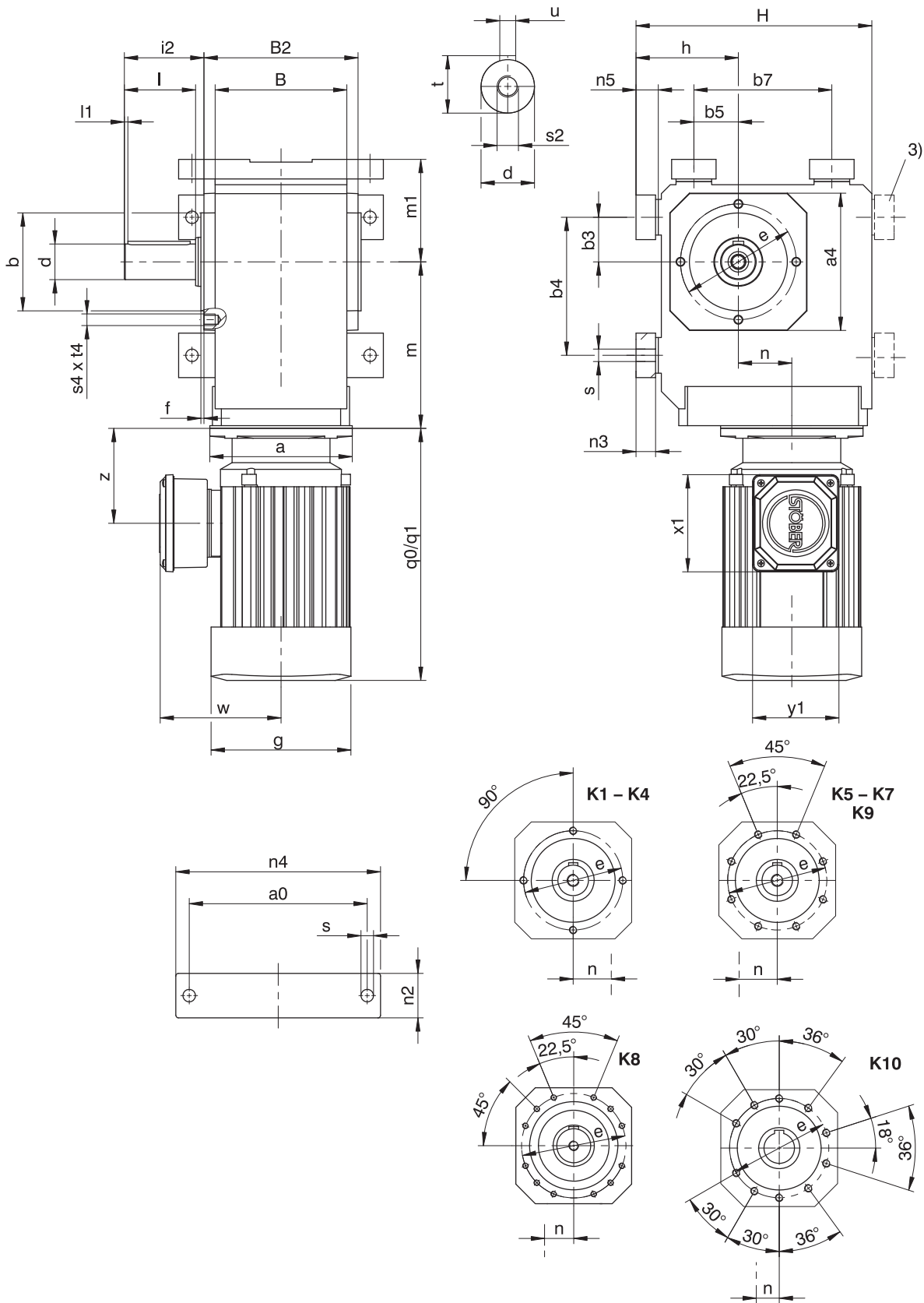
The dimensions a, m and n can be found on the next page.

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K102	∅140	124	36.0	∅140	124	36.0	∅160	128	36.0	∅160	128	36.0	-	-	-
K202	∅140	143	46.0	∅140	143	46.0	∅160	147	46.0	∅160	147	46.0	∅200	149	46.0
K203	∅140	180	46.0	∅140	180	46.0	-	-	-	-	-	-	-	-	-
K302	∅140	163	52.5	∅140	163	52.5	∅160	167	52.5	∅160	167	52.5	∅200	169	52.5
K303	∅140	200	52.5	∅140	200	52.5	∅160	210	16.0	∅160	210	16.0	-	-	-
K402	-	-	-	-	-	-	∅160	187	60.0	∅160	187	60.0	∅200	189	60.0
K403	-	-	-	∅140	220	60.0	∅160	230	23.0	∅160	230	23.0	-	-	-
K513	-	-	-	-	-	-	∅160	172	15.0	∅160	172	15.0	∅200	174	15.0
K514	-	-	-	-	-	-	∅160	215	15.0	∅160	215	15.0	-	-	-
K613	-	-	-	-	-	-	∅160	191	18.0	∅160	191	18.0	∅200	193	18.0
K614	-	-	-	-	-	-	∅160	234	18.0	∅160	234	18.0	-	-	-
K713	-	-	-	-	-	-	-	-	-	-	-	-	∅200	221	20.0
K714	-	-	-	-	-	-	∅160	263	20.0	∅160	263	20.0	∅200	283	20.0
K813	-	-	-	-	-	-	-	-	-	-	-	-	∅200	247	24.0
K814	-	-	-	-	-	-	-	-	-	-	-	-	∅200	308	24.0
K914	-	-	-	-	-	-	-	-	-	-	-	-	∅200	353	25.0

Type	IE3D112			IE3D132			IE3D160			IE3D180			IE3D200		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K202	∅200	149	46.0	-	-	-	-	-	-	-	-	-	-	-	-
K302	∅200	169	52.5	-	-	-	-	-	-	-	-	-	-	-	-
K402	∅200	189	60.0	∅250	192	60.0	-	-	-	-	-	-	-	-	-
K513	∅200	174	15.0	∅250	177	15.0	-	-	-	-	-	-	-	-	-
K613	∅200	193	18.0	∅250	196	18.0	∅300	210	18.0	∅300	210	18.0	-	-	-
K713	∅200	221	20.0	∅250	224	20.0	∅300	237	20.0	∅300	237	20.0	-	-	-
K714	∅200	283	20.0	-	-	-	-	-	-	-	-	-	-	-	-
K813	∅200	247	24.0	∅250	249	24.0	∅300	262	24.0	∅300	262	24.0	-	-	-
K814	∅200	308	24.0	∅250	320	5.0	-	-	-	-	-	-	-	-	-
K913	-	-	-	∅250	294	25.0	∅300	307	25.0	∅300	307	25.0	∅350	330	25.0
K914	∅200	353	25.0	∅250	365	25.0	-	-	-	-	-	-	-	-	-

4.3.14 V shaft design (solid shaft), NG housing design (base + pitch circle diameter)



q0 Applies to motors without brake.

3) Only for K1 (other sizes on request)

- K1 – K9: Solid shaft on both sides available.

q1 Applies to motors with brake.

- K1 – K4: solid shaft without feather key available, on request starting at K5.

Dimensions of gear units

Type	a0	a4	Øb	b3	b4	b5	b7	B	B2	Ød	Øe	f	h	H	i2	l	l1	m1	n2	n3	n4	n5	Øs	s2	s4	t	t4	u
K1	115	105	75 _{j6}	30	90	30	90	90	106	25 _{k6}	90	3.0	75	175	62.0	50	4	75	30	13	140	15	9.0	M10	M8	28.0	13	A8×7×40
K2	155	116	82 _{j6}	35	115	35	115	115	134	30 _{k6}	100	3.0	88	213	68.0	60	4	88	40	20	185	23	11.0	M10	M8	33.0	13	A8×7×50
K3	170	132	95 _{j6}	40	130	40	130	130	146	30 _{k6}	115	3.0	98	236	69.0	60	4	98	45	20	200	23	11.0	M10	M8	33.0	13	A8×7×50
K4	200	152	110 _{j6}	50	155	50	155	148	173	40 _{k6}	130	3.5	115	265	89.5	80	4	115	50	22	230	25	14.0	M16	M10	43.0	16	A12×8×70
K5	200	145	110 _{j6}	40	140	100	140	160	185	45 _{k6}	130	3.5	190	290	129.5	90	4	130	60	27	240	30	18.0	M16	M10	48.5	16	A14×9×80
K6	210	180	140 _{j6}	50	160	110	160	168	200	50 _{k6}	165	3.5	220	340	136.0	100	4	150	65	27	250	30	18.5	M16	M10	53.5	16	A14×9×90
K7	241	195	155 _{j6}	55	180	125	180	190	226	60 _{m6}	185	3.5	250	380	164.0	120	4	163	70	35	290	38	23.0	M20	M12	64.0	19	A18×11×110
K8	300	226	185 _{j6}	75	240	165	240	235	282	70 _{m6}	215	4.0	310	455	185.0	140	5	190	85	41	360	45	27.0	M20	M12	74.5	19	A20×12×125
K9	360	280	230 _{j6}	95	280	185	280	285	330	90 _{m6}	265	5.0	365	545	220.0	170	8	230	95	46	430	50	31.0	M24	M16	95.0	26	A25×14×140
K10	330	340	250 _{m6}	115	350	265	420	400	356	110 _{m6}	300	20.0	420	636	240.0	210	15	270	120	–	400	45	39.0	M24	M20	116.0	33	A28×16×180

Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5
IE3D160MX04	313	526	641	199	166.5	193.5	138.0
IE3D160LX04	313	549	627	242	166.5	193.5	138.0
IE3D180MX04	313	549	677	242	166.5	193.5	178.0
IE3D180LX04	351	601	748	260	166.5	193.5	178.0
IE3D200LX04	390	729	878	298	207.0	209.0	242.0

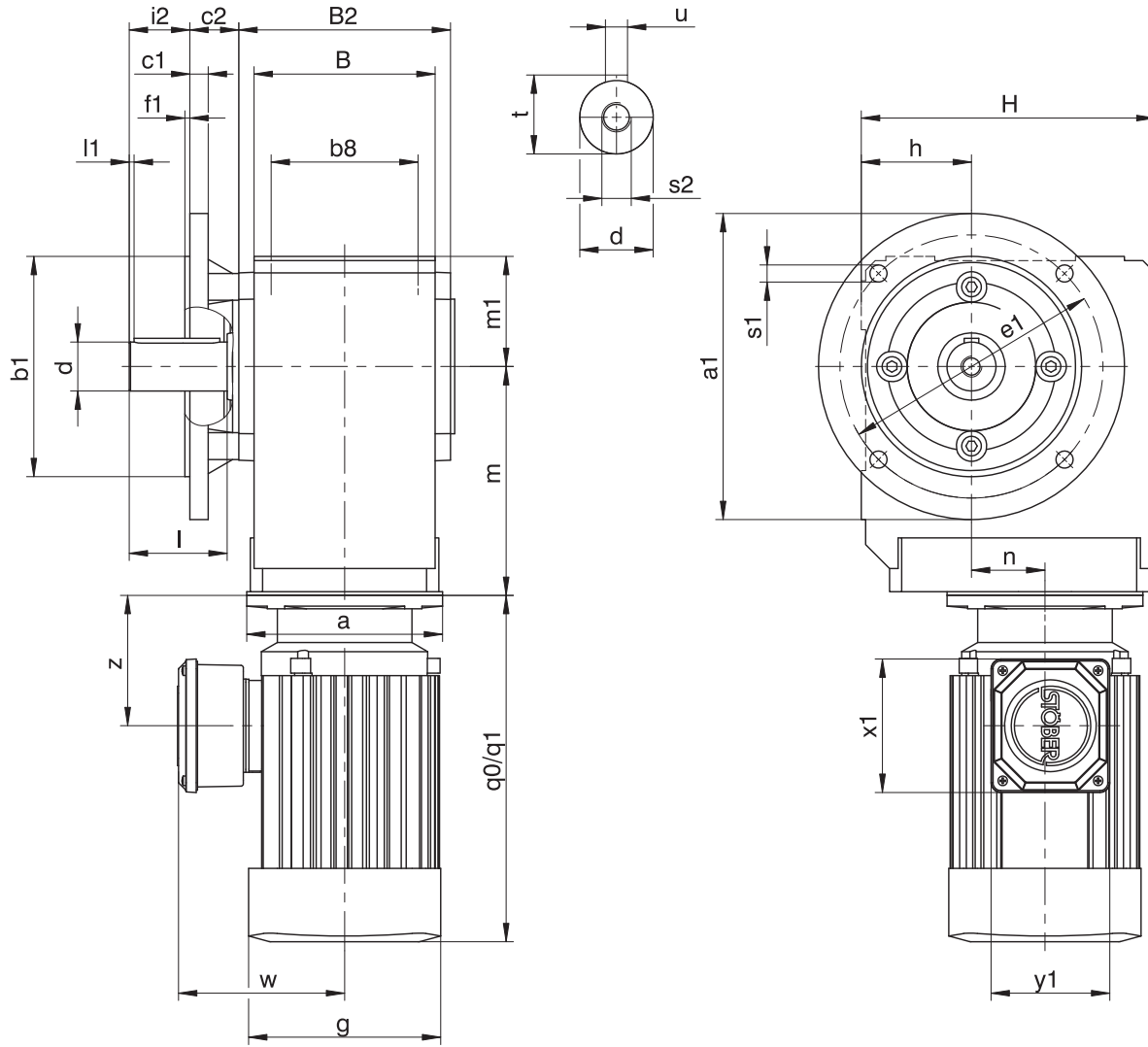
The dimensions a, m and n can be found on the next page.

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K102	∅140	124	36.0	∅140	124	36.0	∅160	128	36.0	∅160	128	36.0	-	-	-
K202	∅140	143	46.0	∅140	143	46.0	∅160	147	46.0	∅160	147	46.0	∅200	149	46.0
K203	∅140	180	46.0	∅140	180	46.0	-	-	-	-	-	-	-	-	-
K302	∅140	163	52.5	∅140	163	52.5	∅160	167	52.5	∅160	167	52.5	∅200	169	52.5
K303	∅140	200	52.5	∅140	200	52.5	∅160	210	16.0	∅160	210	16.0	-	-	-
K402	-	-	-	-	-	-	∅160	187	60.0	∅160	187	60.0	∅200	189	60.0
K403	-	-	-	∅140	220	60.0	∅160	230	23.0	∅160	230	23.0	-	-	-
K513	-	-	-	-	-	-	∅160	172	15.0	∅160	172	15.0	∅200	174	15.0
K514	-	-	-	-	-	-	∅160	215	15.0	∅160	215	15.0	-	-	-
K613	-	-	-	-	-	-	∅160	191	18.0	∅160	191	18.0	∅200	193	18.0
K614	-	-	-	-	-	-	∅160	234	18.0	∅160	234	18.0	-	-	-
K713	-	-	-	-	-	-	-	-	-	-	-	-	∅200	221	20.0
K714	-	-	-	-	-	-	∅160	263	20.0	∅160	263	20.0	∅200	283	20.0
K813	-	-	-	-	-	-	-	-	-	-	-	-	∅200	247	24.0
K814	-	-	-	-	-	-	-	-	-	-	-	-	∅200	308	24.0
K914	-	-	-	-	-	-	-	-	-	-	-	-	∅200	353	25.0

Type	IE3D112			IE3D132			IE3D160			IE3D180			IE3D200		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K202	∅200	149	46.0	-	-	-	-	-	-	-	-	-	-	-	-
K302	∅200	169	52.5	-	-	-	-	-	-	-	-	-	-	-	-
K402	∅200	189	60.0	∅250	192	60.0	-	-	-	-	-	-	-	-	-
K513	∅200	174	15.0	∅250	177	15.0	-	-	-	-	-	-	-	-	-
K613	∅200	193	18.0	∅250	196	18.0	∅300	210	18.0	∅300	210	18.0	-	-	-
K713	∅200	221	20.0	∅250	224	20.0	∅300	237	20.0	∅300	237	20.0	-	-	-
K714	∅200	283	20.0	-	-	-	-	-	-	-	-	-	-	-	-
K813	∅200	247	24.0	∅250	249	24.0	∅300	262	24.0	∅300	262	24.0	-	-	-
K814	∅200	308	24.0	∅250	320	5.0	-	-	-	-	-	-	-	-	-
K913	-	-	-	∅250	294	25.0	∅300	307	25.0	∅300	307	25.0	∅350	330	25.0
K914	∅200	353	25.0	∅250	365	25.0	-	-	-	-	-	-	-	-	-
K1013	-	-	-	-	-	-	∅300	392	28.0	∅300	392	28.0	∅350	415	28.0
K1014	-	-	-	∅250	450	28.0	∅300	475	28.0	∅300	475	28.0	-	-	-

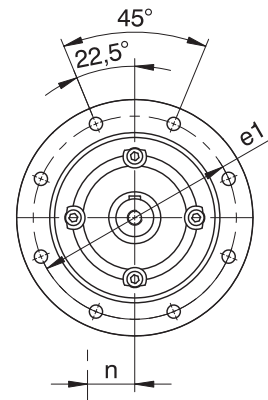
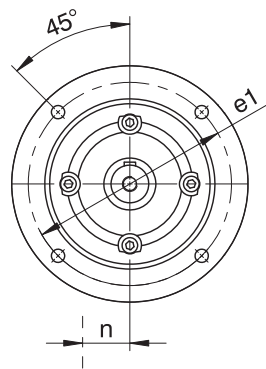
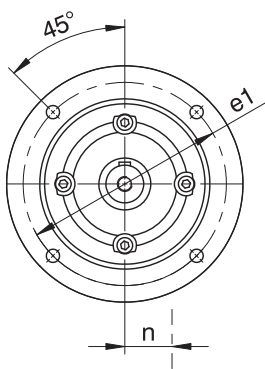
4.3.15 V shaft design (solid shaft), F housing design (round flange)



K1 – K4

K5 – K8

K9



$q0$ Applies to motors without brake.

$q1$ Applies to motors with brake.

- K1 – K4: solid shaft without feather key available, on request starting at K5.

- K1 – K9: Solid shaft on both sides available.

Dimensions of gear units

Type	Øa1	Øb1	b8	B	B2	c1	c2	Ød	Øe1	f1	h	H	i2	l	l1	m1	Øs1	s2	t	u
K1	160	110 _{js}	70	90	106	10	32.0	25 _{h6}	130	3.5	60	160	30.0	50	4	60	9	M10	28.0	A8×7×40
K2	200	130 _{js}	90	115	134	12	32.0	30 _{h6}	165	3.5	65	190	36.0	60	4	65	11	M10	33.0	A8×7×50
K3	200	130 _{js}	105	130	146	14	38.0	30 _{h6}	165	3.5	75	213	31.0	60	4	75	11	M10	33.0	A8×7×50
K4	250	180 _{js}	120	148	173	15	40.0	40 _{h6}	215	4.0	90	240	49.5	80	4	90	14	M16	43.0	A12×8×70
K5	250	180 _{js}	125	160	185	15	39.5	45 _{h6}	215	4.0	160	260	90.0	90	4	100	14	M16	48.5	A14×9×80
K6	300	230 _{js}	130	168	200	17	36.0	50 _{h6}	265	4.0	190	310	100.0	100	4	120	14	M16	53.5	A14×9×90
K7	350	250 _{h6}	145	190	226	18	44.0	60 _{h6}	300	5.0	212	342	120.0	120	4	125	18	M20	64.0	A18×11×110
K8	400	300 _{h6}	185	235	282	20	45.0	70 _{h6}	350	5.0	265	410	140.0	140	5	145	18	M20	74.5	A20×12×125
K9	450	350 _{h6}	225	285	330	23	50.0	90 _{h6}	400	5.0	315	495	170.0	170	8	180	18	M24	95.0	A25×14×140

Dimensions of additional round flanges

Type	Øa1	Øb1	c1	Øe1	f1	Øs1
K1	140	95 _{js}	10	115	3.0	9
K2	160	110 _{js}	12	130	3.5	9
K3	160	110 _{js}	14	130	3.5	9
K3	250	180 _{js}	14	215	4.0	14
K8	350	250 _{h6}	18	300	5.0	18
K8	450	350 _{h6}	20	400	5.0	18

Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5
IE3D160MX04	313	526	641	199	166.5	193.5	138.0
IE3D160LX04	313	549	627	242	166.5	193.5	138.0
IE3D180MX04	313	549	677	242	166.5	193.5	178.0
IE3D180LX04	351	601	748	260	166.5	193.5	178.0
IE3D200LX04	390	729	878	298	207.0	209.0	242.0

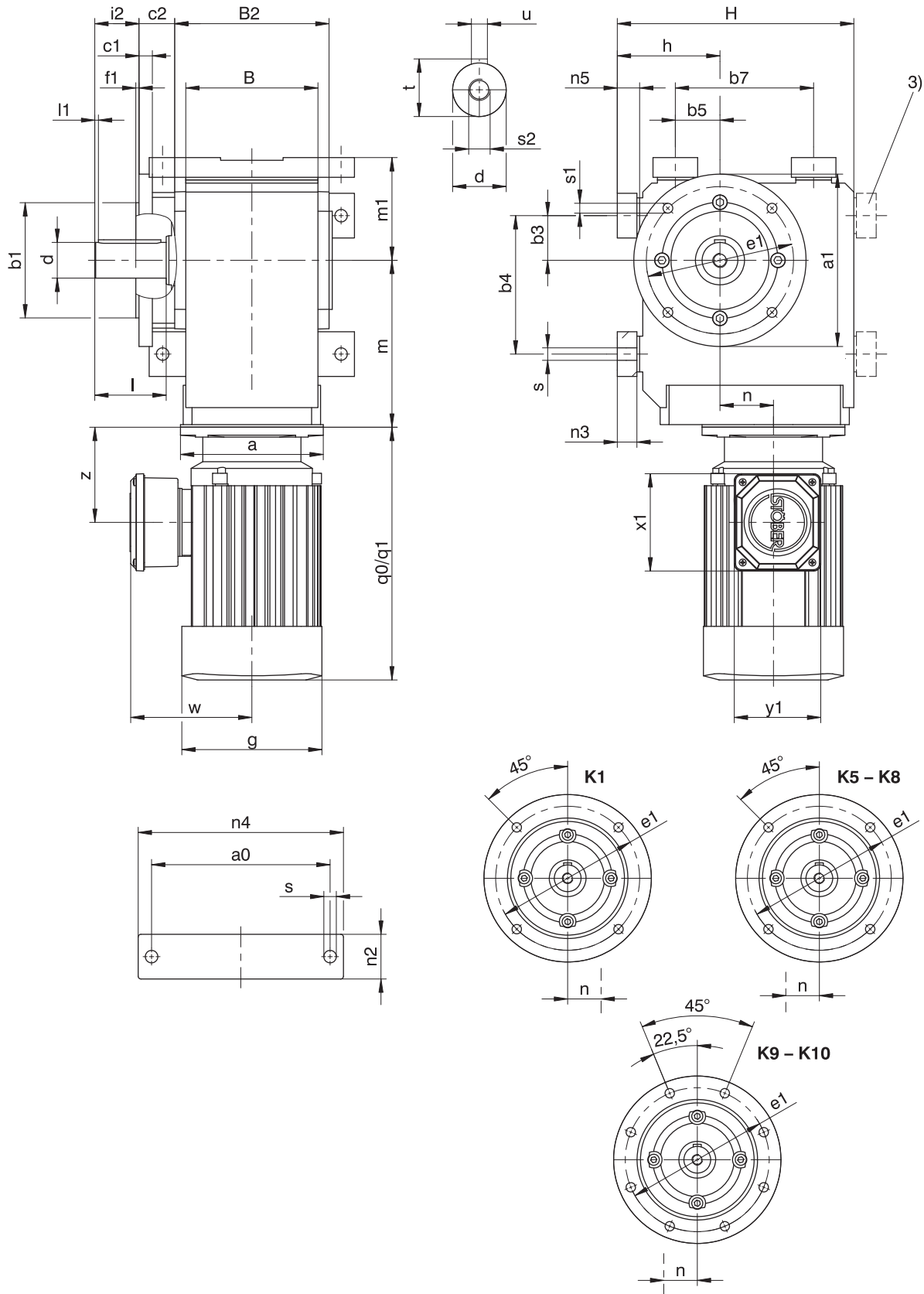
The dimensions a, m and n can be found on the next page.

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K102	∅140	124	36.0	∅140	124	36.0	∅160	128	36.0	∅160	128	36.0	-	-	-
K202	∅140	143	46.0	∅140	143	46.0	∅160	147	46.0	∅160	147	46.0	∅200	149	46.0
K203	∅140	180	46.0	∅140	180	46.0	-	-	-	-	-	-	-	-	-
K302	∅140	163	52.5	∅140	163	52.5	∅160	167	52.5	∅160	167	52.5	∅200	169	52.5
K303	∅140	200	52.5	∅140	200	52.5	∅160	210	16.0	∅160	210	16.0	-	-	-
K402	-	-	-	-	-	-	∅160	187	60.0	∅160	187	60.0	∅200	189	60.0
K403	-	-	-	∅140	220	60.0	∅160	230	23.0	∅160	230	23.0	-	-	-
K513	-	-	-	-	-	-	∅160	172	15.0	∅160	172	15.0	∅200	174	15.0
K514	-	-	-	-	-	-	∅160	215	15.0	∅160	215	15.0	-	-	-
K613	-	-	-	-	-	-	∅160	191	18.0	∅160	191	18.0	∅200	193	18.0
K614	-	-	-	-	-	-	∅160	234	18.0	∅160	234	18.0	-	-	-
K713	-	-	-	-	-	-	-	-	-	-	-	-	∅200	221	20.0
K714	-	-	-	-	-	-	∅160	263	20.0	∅160	263	20.0	∅200	283	20.0
K813	-	-	-	-	-	-	-	-	-	-	-	-	∅200	247	24.0
K814	-	-	-	-	-	-	-	-	-	-	-	-	∅200	308	24.0
K914	-	-	-	-	-	-	-	-	-	-	-	-	∅200	353	25.0

Type	IE3D112			IE3D132			IE3D160			IE3D180			IE3D200		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K202	∅200	149	46.0	-	-	-	-	-	-	-	-	-	-	-	-
K302	∅200	169	52.5	-	-	-	-	-	-	-	-	-	-	-	-
K402	∅200	189	60.0	∅250	192	60.0	-	-	-	-	-	-	-	-	-
K513	∅200	174	15.0	∅250	177	15.0	-	-	-	-	-	-	-	-	-
K613	∅200	193	18.0	∅250	196	18.0	∅300	210	18.0	∅300	210	18.0	-	-	-
K713	∅200	221	20.0	∅250	224	20.0	∅300	237	20.0	∅300	237	20.0	-	-	-
K714	∅200	283	20.0	-	-	-	-	-	-	-	-	-	-	-	-
K813	∅200	247	24.0	∅250	249	24.0	∅300	262	24.0	∅300	262	24.0	-	-	-
K814	∅200	308	24.0	∅250	320	5.0	-	-	-	-	-	-	-	-	-
K913	-	-	-	∅250	294	25.0	∅300	307	25.0	∅300	307	25.0	∅350	330	25.0
K914	∅200	353	25.0	∅250	365	25.0	-	-	-	-	-	-	-	-	-

4.3.16 V shaft design (solid shaft), NF housing design (base + round flange)



q0 Applies to motors without brake.

3) Only for K1 (other sizes on request)

- K1 - K10: Solid shaft on both sides available.

q1 Applies to motors with brake.

- K1 - K4: solid shaft without feather key available, on request starting at K5.

Dimensions of gear units

Type	a0	Øa1	Øb1	b3	b4	b5	b7	B	B2	c1	c2	Ød	Øe1	f1	h	H	i2	l	l1	m1	n2	n3	n4	n5	Øs	Øs1	s2	t	u
K1	115	160	110 _g	30	90	30	90	90	106	10	32.0	25 _{kg}	130	3.5	75	175	30.0	50	4	75	30	13	140	15	9.0	9	M10	28.0	A8×7×40
K5	200	250	180 _g	40	140	100	140	160	185	15	39.5	45 _{kg}	215	4.0	190	290	90.0	90	4	130	60	27	240	30	18.0	14	M16	48.5	A14×9×80
K6	210	300	230 _g	50	160	110	160	168	200	17	36.0	50 _{kg}	265	4.0	220	340	100.0	100	4	150	65	27	250	30	18.5	14	M16	53.5	A14×9×90
K7	241	350	250 _{hg}	55	180	125	180	190	226	18	44.0	60 _{mg}	300	5.0	250	380	120.0	120	4	163	70	35	290	38	23.0	18	M20	64.0	A18×11×110
K8	300	400	300 _{hg}	75	240	165	240	235	282	20	45.0	70 _{mg}	350	5.0	310	455	140.0	140	5	190	85	41	360	45	27.0	18	M20	74.5	A20×12×125
K9	360	450	350 _{hg}	95	280	185	280	285	330	23	50.0	90 _{mg}	400	5.0	365	545	170.0	170	8	230	95	46	430	50	31.0	18	M24	95.0	A25×14×140
K10	330	550	450 _{hg}	115	350	265	420	400	356	25	78.0	110 _{mg}	500	5.0	420	636	210.0	210	15	270	120	-	400	45	39.0	18	M24	116.0	A28×16×180

Dimensions of additional round flanges

Type	Øa1	Øb1	c1	Øe1	f1	Øs1
K1	140	95 _g	10	115	3	9
K8	350	250 _{hg}	18	300	5	18
K8	450	350 _{hg}	20	400	5	18

Dimensions of motors

Type	g	q0	q1	w	x1	y1	z
IE3D063K04	124	208	261	121	109.0	97.0	94.0
IE3D063M04	124	208	261	121	109.0	97.0	94.0
IE3D071K04	139	238	295	128	109.0	97.0	97.0
IE3D071L04	139	238	295	128	109.0	97.0	97.0
IE3D080K04	157	261	329	137	109.0	97.0	107.0
IE3D080L04	157	283	351	137	109.0	97.0	107.0
IE3D090S04	177	310	380	146	120.0	109.0	114.0
IE3D090LX04	177	365	435	146	120.0	109.0	114.0
IE3D100KX04	196	404	491	155	120.0	109.0	120.0
IE3D100LX04	196	444	531	155	120.0	109.0	120.0
IE3D112M04	217	424	521	178	146.5	156.5	134.0
IE3D132SX04	258	476	591	199	146.5	156.5	141.5
IE3D132MX04	258	476	591	199	146.5	156.5	141.5
IE3D160MX04	313	526	641	199	166.5	193.5	138.0
IE3D160LX04	313	549	627	242	166.5	193.5	138.0
IE3D180MX04	313	549	677	242	166.5	193.5	178.0
IE3D180LX04	351	601	748	260	166.5	193.5	178.0
IE3D200LX04	390	729	878	298	207.0	209.0	242.0

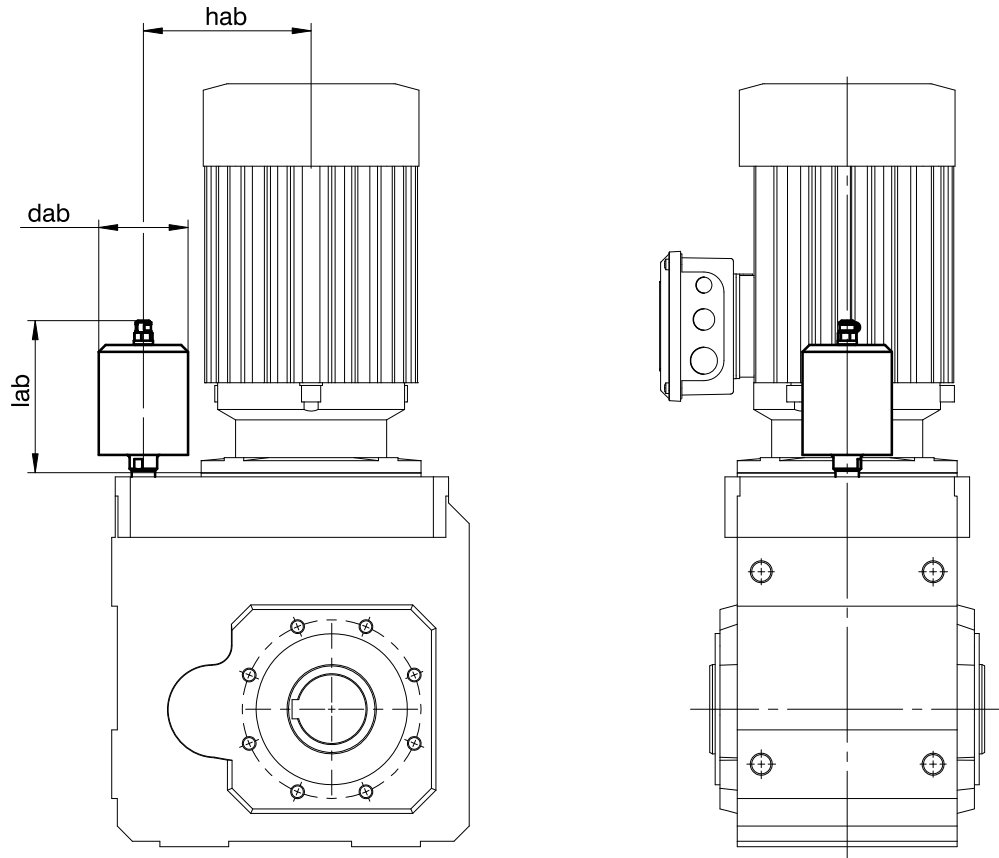
The dimensions a, m and n can be found on the next page.

Dimensions of geared motors

Type	IE3D063			IE3D071			IE3D080			IE3D090			IE3D100		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K102	∅140	124	36.0	∅140	124	36.0	∅160	128	36.0	∅160	128	36.0	-	-	-
K513	-	-	-	-	-	-	∅160	172	15.0	∅160	172	15.0	∅200	174	15.0
K514	-	-	-	-	-	-	∅160	215	15.0	∅160	215	15.0	-	-	-
K613	-	-	-	-	-	-	∅160	191	18.0	∅160	191	18.0	∅200	193	18.0
K614	-	-	-	-	-	-	∅160	234	18.0	∅160	234	18.0	-	-	-
K713	-	-	-	-	-	-	-	-	-	-	-	-	∅200	221	20.0
K714	-	-	-	-	-	-	∅160	263	20.0	∅160	263	20.0	∅200	283	20.0
K813	-	-	-	-	-	-	-	-	-	-	-	-	∅200	247	24.0
K814	-	-	-	-	-	-	-	-	-	-	-	-	∅200	308	24.0
K914	-	-	-	-	-	-	-	-	-	-	-	-	∅200	353	25.0

Type	IE3D112			IE3D132			IE3D160			IE3D180			IE3D200		
	a	m	n	a	m	n	a	m	n	a	m	n	a	m	n
K513	∅200	174	15.0	∅250	177	15.0	-	-	-	-	-	-	-	-	-
K613	∅200	193	18.0	∅250	196	18.0	∅300	210	18.0	∅300	210	18.0	-	-	-
K713	∅200	221	20.0	∅250	224	20.0	∅300	237	20.0	∅300	237	20.0	-	-	-
K714	∅200	283	20.0	-	-	-	-	-	-	-	-	-	-	-	-
K813	∅200	247	24.0	∅250	249	24.0	∅300	262	24.0	∅300	262	24.0	-	-	-
K814	∅200	308	24.0	∅250	320	5.0	-	-	-	-	-	-	-	-	-
K913	-	-	-	∅250	294	25.0	∅300	307	25.0	∅300	307	25.0	∅350	330	25.0
K914	∅200	353	25.0	∅250	365	25.0	-	-	-	-	-	-	-	-	-
K1013	-	-	-	-	-	-	∅300	392	28.0	∅300	392	28.0	∅350	415	28.0
K1014	-	-	-	∅250	450	28.0	∅300	475	28.0	∅300	475	28.0	-	-	-

4.3.17 Oil expansion tank



Dimensions

Type	IE3D080			IE3D090			IE3D100			IE3D112			IE3D132			IE3D160			IE3D180			IE3D200				
	dab	hab	lab	dab	hab	lab	dab	hab	lab	dab	hab	lab	dab	hab	lab	dab	hab	lab	dab	hab	lab	dab	hab	lab		
K513	65	122.0	113.5	65	122.0	113.5	65	130.0	165.0	65	130.0	165.0	65	167.0	165.0	-	-	-	-	-	-	-	-	-	-	
K613	65	148.5	116.5	65	148.5	116.5	65	148.5	116.5	65	148.5	116.5	65	198.5	165.0	65	194.5	191.0	65	194.5	191.0	-	-	-	-	
K713	-	-	-	-	-	-	65	170.0	114.5	65	170.0	114.5	65	170.0	115.5	65	214.0	191.5	65	214.0	191.5	-	-	-	-	
K813	-	-	-	-	-	-	73	205.0	129.5	73	205.0	129.5	73	205.0	129.5	73	205.0	129.5	73	205.0	129.5	-	-	-	-	
K913	-	-	-	-	-	-	-	-	-	-	-	-	73	255.0	129.5	73	255.0	129.5	73	255.0	129.5	73	255.0	129.5	73	255.0
K1013	-	-	-	-	-	-	-	-	-	-	-	-	-	-	73	305.0	126.0	73	305.0	126.0	73	305.0	112.0	-	-	

More information can be found in Chapter [▶ 4.6.3](#)

4.4 Type designation

This chapter shows you an explanation of the type designation with the associated options.

Additional ordering information not included in the type designation can be found at the end of the chapter.

Example code

K	4	0	2	A	G	0560	IE3D080L04
---	---	---	---	---	---	------	------------

Explanation

Code	Designation	Design
K	Type	Helical bevel gear unit
4	Size	4 (example)
0	Generation	Generation 0
1		Generation 1
2	Stages	Two-stage
3		Three-stage
4		Four-stage
A	Shaft	Hollow shaft with keyway
S		Hollow shaft with shrink ring
V		Solid shaft
G	Housing	Pitch circle diameter
F		Round flange
NG		Foot + pitch circle diameter
NF		Foot + round flange
GD		Pitch circle diameter + torque arm bracket
NGD		Foot + pitch circle diameter + torque arm bracket
0560	Transmission ratio (i x 10 rounded)	i = 55.71 (example)
IE3D080	Motor	IE3D asynchronous motor
L04		

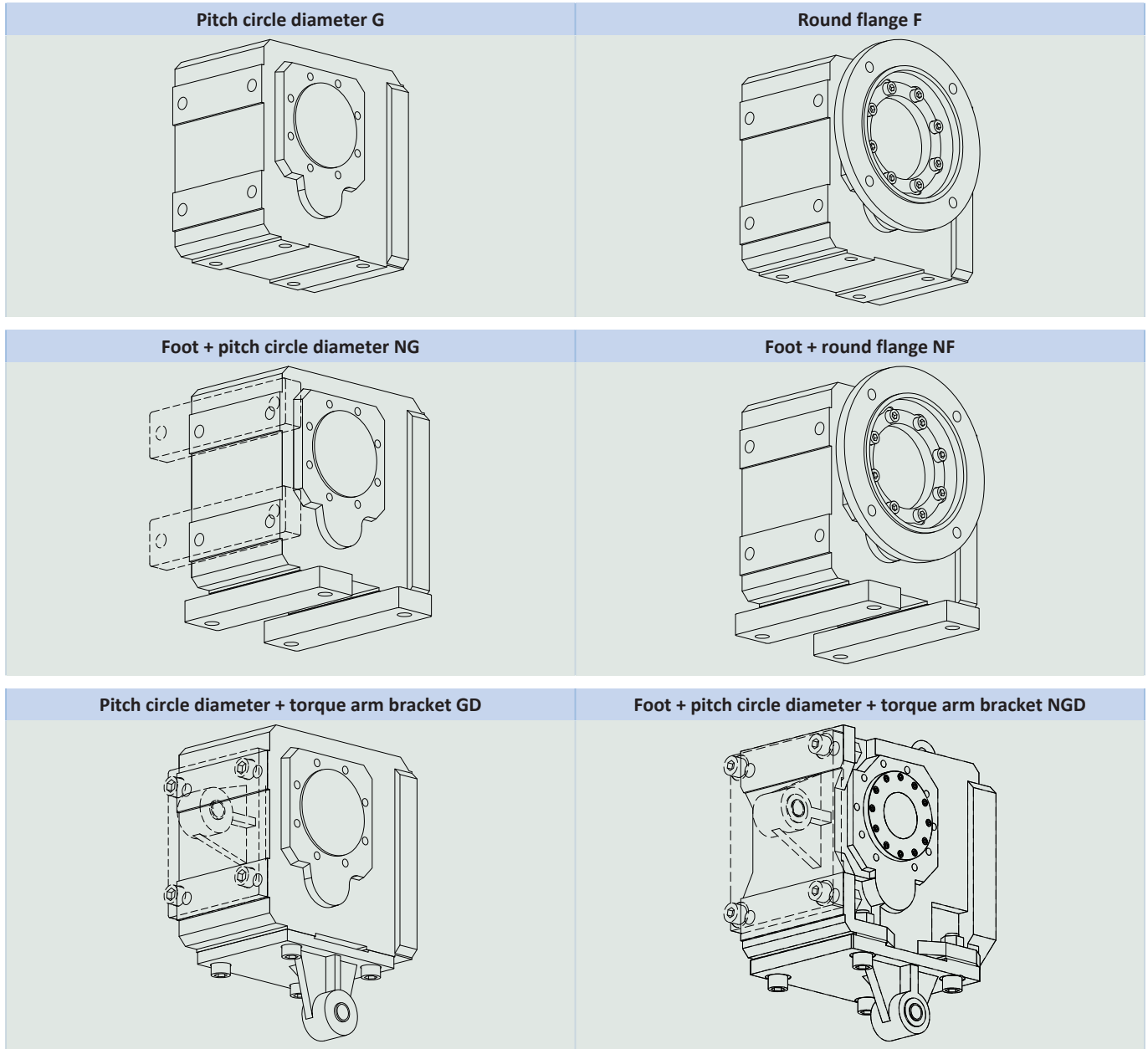
To complete the type designation, also specify the following in your order:

- A detailed type designation of the motor, see the chapter [▶ 5.4](#)
- The mounting position, see the chapter [▶ 4.5.4](#)
- Attachment of solid shaft: gear unit side 3 or 4; solid shaft on both sides
- Attachment of hollow shaft with keyway: insertion side 3 or 4
- Attachment of hollow shaft with shrink ring: shrink ring on gear unit side 3 or 4
- Attachment of foot plates: gear unit side 1 or 5
- Attachment of flange: gear unit side 3 or 4
- Pitch circle diameter: gear unit side 3 or 4
- Attachment of torque arm bracket: torque arm bracket on gear unit side 1 or 5, eye on gear unit side 3 or 4
- The position of the terminal box, see the chapter [▶ 4.5.6](#)
- Oil expansion tank (recommended for gear units in mounting position EL5), see the chapter [▶ 4.6.3](#)
- Standard or reinforced output bearing

An explanation of the gear unit sides can be found in the chapter [▶ 4.5.4](#).

4.5 Product description

4.5.1 Housing design



	G	F	NG	NF	GD	NGD
K1	✓	✓	✓	✓	✓	-
K2	✓	✓	✓	-	✓	-
K3	✓	✓	✓	-	✓	-
K4	✓	✓	✓	-	✓	-
K5	✓	✓	✓	✓	✓	-
K6	✓	✓	✓	✓	✓	-
K7	✓	✓	✓	✓	✓	-
K8	✓	✓	✓	✓	✓	-
K9	✓	✓	✓	✓	✓	-
K10	-	-	✓	✓	-	✓

4.5.2 Combinatorial shaft/housing design

Shaft design	Housing design						
	Code	G	F	NG	NF	GD	NGD
Hollow shaft with keyway	A	AG	AF	ANG	ANF	AGD	ANGD
Hollow shaft with shrink ring	S	SG	SF	SNG	SNF	SGD	SNGD
Solid shaft ¹⁾	V	VG	VF	VNG	VNF	–	–

¹⁾ Gear units in sizes K1 – K10 come with a solid shaft with feather key as standard. Gear units in sizes K1 – K4 can be ordered with the option of a solid shaft without feather key. Only upon request starting at size K5.

4.5.3 Installation conditions

Hollow shaft

The hollow shaft hole tolerance is ISO H7. The tolerance of the machine shaft must be ISO k6.

Take care to align the machine shaft with the gear unit hollow shaft when attaching the gear unit.

Maximum deviation ≤ 0.03 mm.

For simpler assembly and disassembly of the machine shaft, the hollow shafts are equipped with a spiral groove (as a grease deposit).

A hardened, threaded keeper plate is included in the scope of delivery. You also have the option to order the hollow shaft without a keeper plate.

Hollow shaft with shrink ring

The tolerance of the hollow shaft hole is ISO H7.

The machine shaft must be executed as follows:

Gear unit type	Tolerance
K1 to K6	ISO h9
K7 to K10	ISO h6

Select a material for the machine shaft with a permitted surface pressure of $p \geq 325$ N/mm².

Possible materials:

- C45E +QT
- 42CrMo4

Fastening the gear units on the machine side using the pitch circle diameter

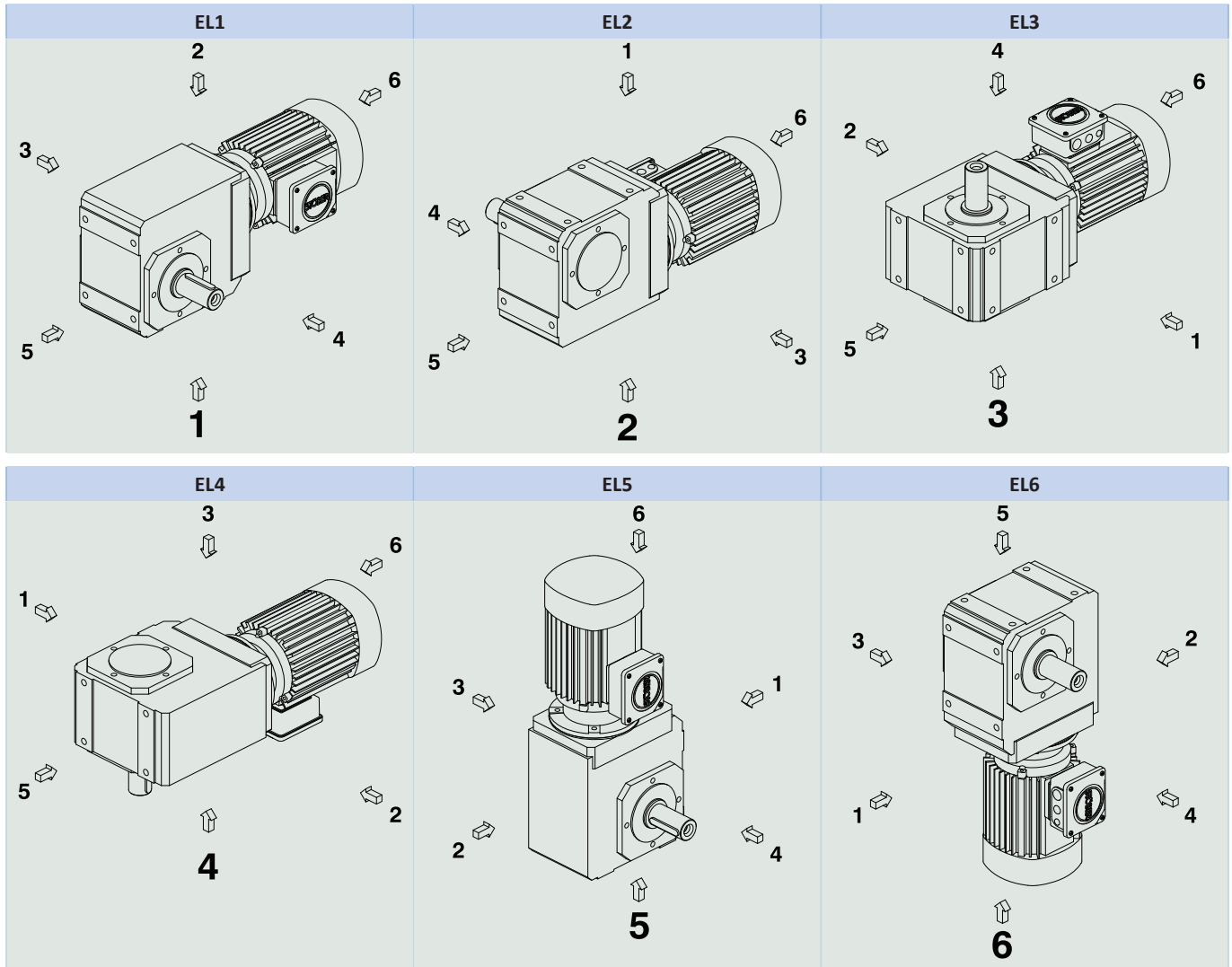
The specified torques and forces only apply when gear units are fastened on the machine side using screws of strength class 10.9. In addition, the gear housings must be adjusted at the pilot. The machine-side fit must be H7.

4.5.4 Mounting positions

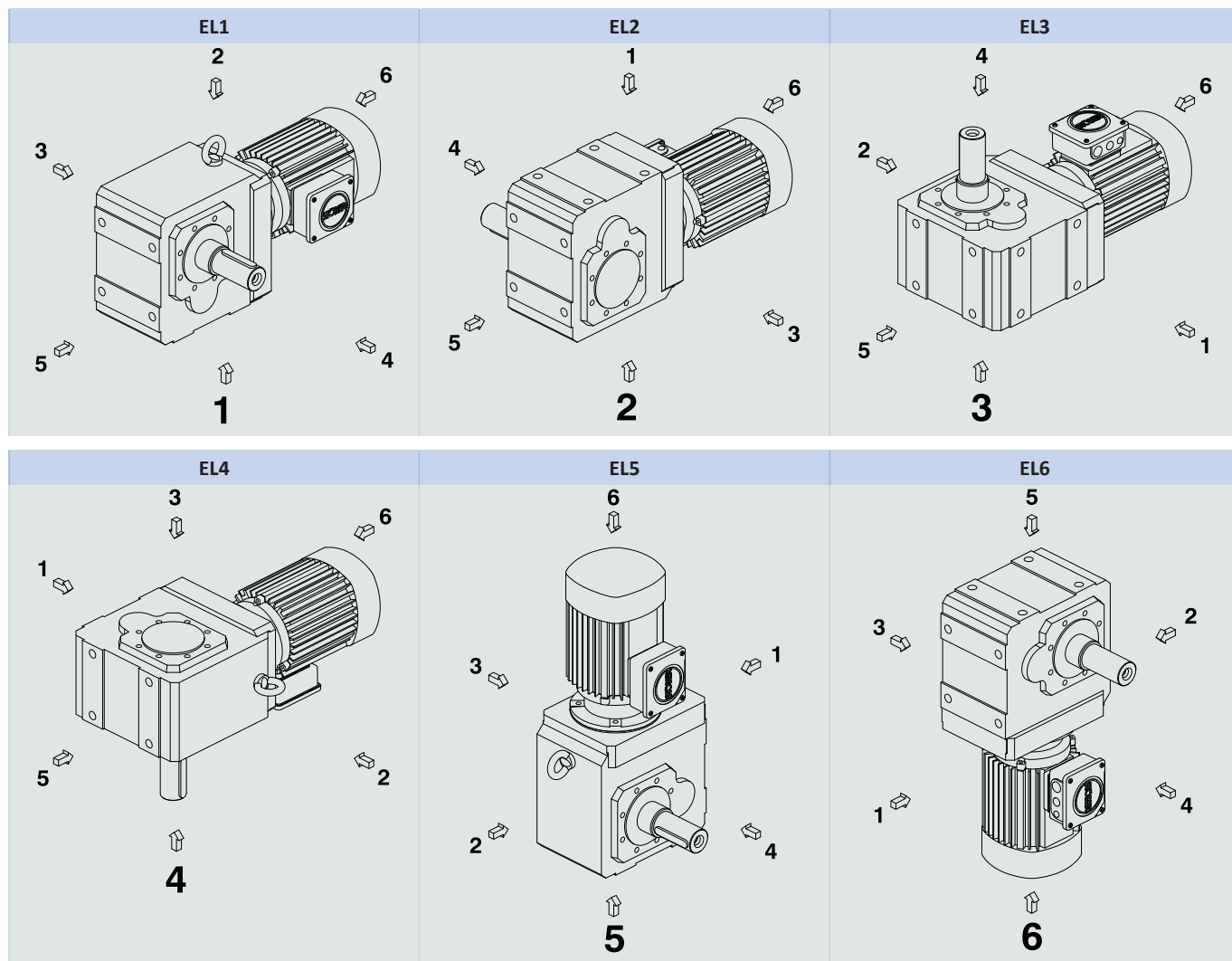
The following table shows the standard mounting positions.

The numbers identify the gear unit sides. The mounting position is defined by the gear side facing downwards.

Mounting positions for gear unit sizes K1 – K4



Mounting positions for gear unit sizes K5 – K10



Since the lubricant filling volume of the gear unit depends on the mounting position, the mounting position must be specified when ordering.

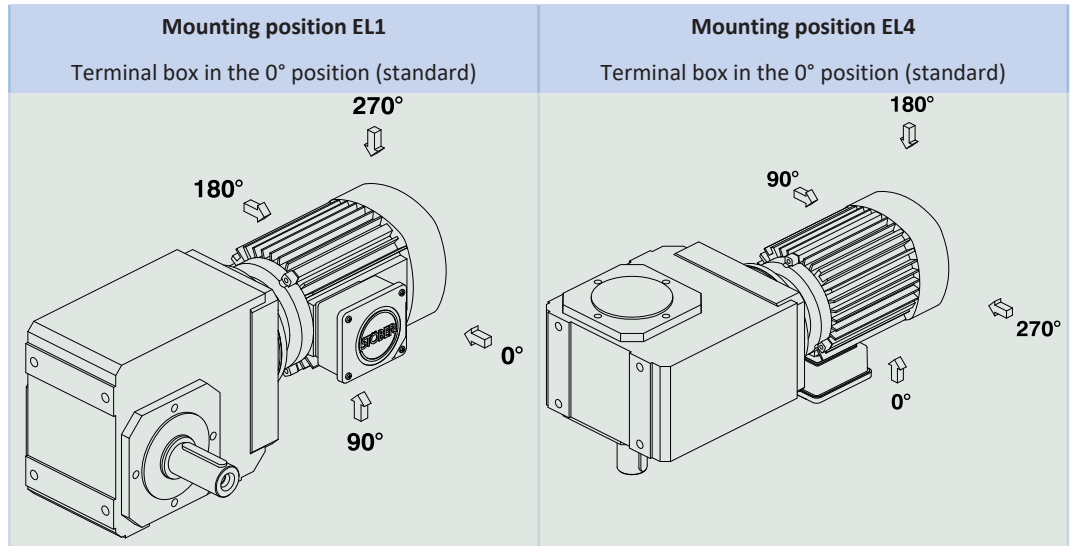
4.5.5 Lubricants

STOBER fills the gear units with the amount and type of lubricant specified on the nameplate. The filling volume and the structure of the gear units depend on the mounting position.

Only install the gear units in the intended mounting position! Reposition the gear units only after consulting STOBER. Otherwise, STOBER assumes no liability for the gear units.

You will receive lubricants for use in the food industry upon request.

4.5.6 Position of the terminal box



Indicate variations for your geared motor in the order.

Note that the terminal box position rotates along with the geared motor if the geared motor rotates to another mounting position.

4.5.7 Other product features

Feature	Value
Max. permitted gear unit temperature (on the surface of the gear unit)	≤ 80 °C
Paint	RAL 7001 Silver gray Optional selection of various RAL colors.
(ATEX) Directive 2014/34/EU	You can get asynchronous motors for use in potentially explosive atmospheres on request.
Efficiency:	
η_{get} two-stage	97%
η_{get} three-stage	96%
η_{get} four-stage	94%
Protection class	IP56

4.5.8 Losses due to splashing

Increased losses due to splashing can occur in individual cases under certain operating conditions. These can lead to oil leakage or unacceptably high operating temperatures.

Please coordinate with STOBBER to determine a suitable course of action if:

- The surrounding temperature is under -10 °C or over $+40\text{ °C}$
- The gear unit type meets the following conditions:

Type	Mounting position	n_{1N} [rpm]	ED	i
K5, K6	EL5, EL6	> 2500	> 60%, > 20 min	< 18
K7, K8	EL5, EL6	> 2000	> 60%, > 20 min	< 15
K9, K10	EL5, EL6	> 1750	> 60%, > 20 min	< 15

4.5.9 Maintenance

The instructions for maintenance can be found in the operating manual, ID 443027_en, at <http://www.stoeber.de/en/downloads/>. Enter the ID of the documentation in the Search... field.

Ventilation

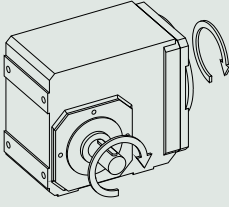
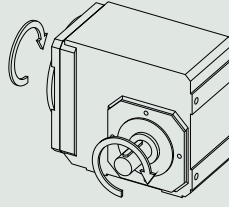
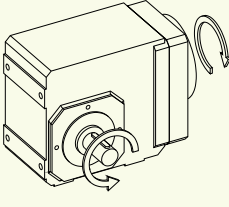
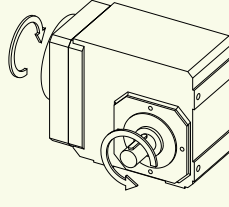
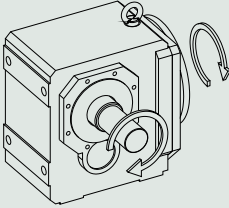
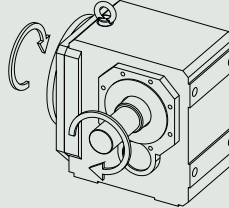
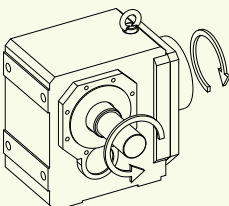
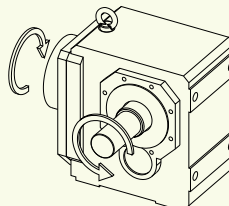
Air release valves are fitted as a standard feature and independently of installation position for gear unit sizes K5 to K10.

For the position and dimensions of the air release valve, refer to the 3D model.

Download the 3D model at <https://configurator.stoeber.de/en-US/>.

4.5.10 Direction of rotation

Solid shaft (V), solid shaft on both sides (V), hollow shaft with keyway (A)

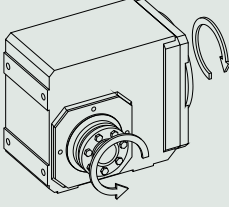
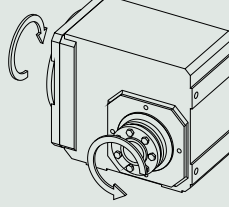
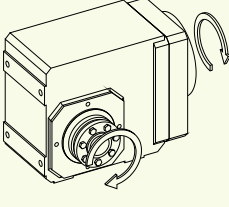
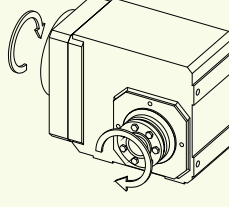
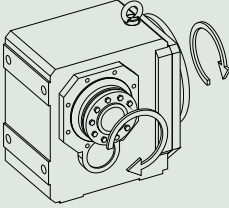
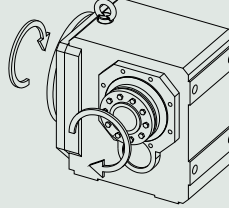
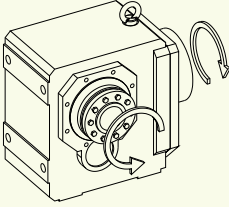
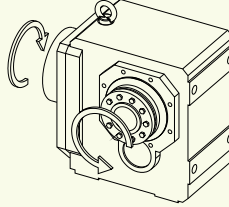
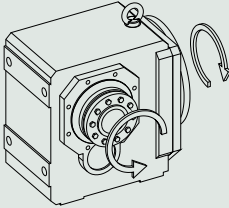
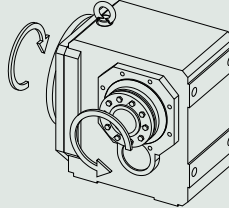
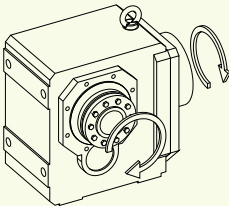
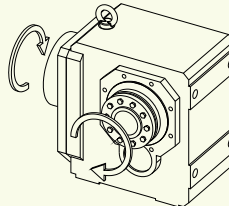
Type	Output side 4	Output side 3
K102 – K402		
K203 – K403		
K513 – K1013		
K514 – K1014		

The specified directions of rotation also apply to gear units with hollow shaft (A) if the entry side of the machine shaft corresponds to the side of the solid shaft that is shown.

The direction of rotation for the shaft design of a solid shaft on both sides corresponds to the direction of rotation for output side 4.

The pictures show mounting position EL1.

Hollow shaft with shrink ring (S)

Type	Shrink ring side 4	Shrink ring side 3
K102 – K402		
K203 – K403		
K513 – K813		
K514 – K814		
K913 – K1013		
K914 – K1014		

The pictures show mounting position EL1.

4.6 Project configuration

Project your drives using the information in this chapter. In doing so, observe the limit conditions in this chapter to ensure a safe design.

An explanation of the formula symbols can be found in Chapter [▶ 13.1](#)

Determine the following for your application:

- The actual torque M_{2N^*}
- The actual speed n_{2^*}
- The operating mode operating factor fB_{op}
- The runtime operating factor fB_t
- The motor operating factor fB_{mot}
- The duty cycle ED in %

$$ED = \frac{t_{op}}{T} \cdot 100\%$$

For the S4 and S8 operating mode:

- The mass moment of inertia J_{2^*}

$$J_{1^*} = \frac{J_{2^*}}{i^2}$$

Calculate the motor rating necessary for your application:

$$P_{N^*} = \frac{M_{2N^*} \cdot n_{2^*} \cdot fB_{mot}}{9550}$$

Using the determined values and the calculated motor rating, select a suitable drive from the selection table.


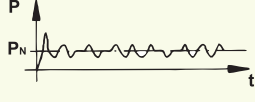

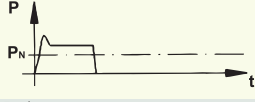
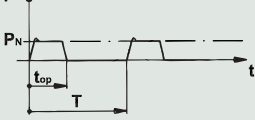
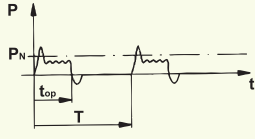
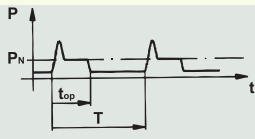
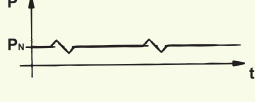
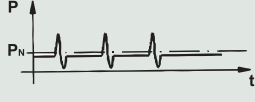
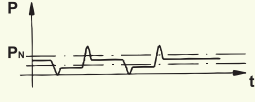
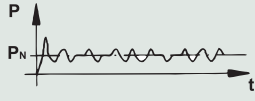
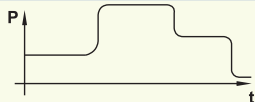
Then check the following conditions:

$$M_{2N^*} \cdot fB_{op} \cdot fB_t < M_{2N} \cdot S$$

$$P_{N^*} < P_N$$

Operating factors

Run time	fB_t
Daily runtime ≤ 8 h	1.00
Daily runtime ≤ 16 h	1.15
Daily runtime ≤ 24 h	1.20

Operating mode	Characteristic output curve	ED	fB _{op}	fB _{mot}
S1 Continuous operation with soft start <ul style="list-style-type: none"> Start time up to 30 s 		100 %	1.00	1.00
S1 Continuous operation with normal start <ul style="list-style-type: none"> Asynchronous motors with direct switch-on or dynamic loading Start time up to 30 s 		100 %	1.25	1.00
S1 Continuous operation with high-load start <ul style="list-style-type: none"> Start time up to 30 s 		100 %	1.25	1.25
S2 brief operation <ul style="list-style-type: none"> Operating time t_{op} ≤ 3 minutes 		≤ 30 %	0.75	0.75
S3 Periodic cyclic operation <ul style="list-style-type: none"> Cycle time T ≤ 10 minutes Cyclic operation with braking motor Low additional flywheel weights J_{1*} < 0,5 · J₁ 		≤ 25 %	0.70	0.70
		≤ 40 %	1.00	1.00
		≤ 60 %	1.25	1.25
S4 Periodic cyclic operation with the effect of the start-up process <ul style="list-style-type: none"> Cycle time T ≤ 10 minutes Cyclic operation with braking motor Larger additional flywheel weights 		40 %	J _{1*} ≤ J ₁ : 1.40 J _{1*} ~ 3 · J ₁ : 1.60	1.40
S6 Uninterrupted periodic operation 	100 %	1.25	1.00	
S6 Uninterrupted periodic operation with short-term loading <ul style="list-style-type: none"> Low speeds Low additional flywheel weights J_{1*} < 0,5 · J₁ 		100 %	1.40	1.00
S6 Uninterrupted periodic operation with impact loading <ul style="list-style-type: none"> High speeds Large additional flywheel weights 		100 %	1.60	1.25
S8 Uninterrupted periodic operation <ul style="list-style-type: none"> With load changes With speed changes 		100 %	J _{1*} ≤ J ₁ : 1.40 J _{1*} ~ 3 · J ₁ : 1.60	J _{1*} ≤ J ₁ : 1.25 J _{1*} ~ 3 · J ₁ : 1.40
S9 Non-periodic operation <ul style="list-style-type: none"> With load changes With speed changes 		100 %	J _{1*} ≤ J ₁ : 1.40 J _{1*} ~ 3 · J ₁ : 1.60	J _{1*} ≤ J ₁ : 1.25 J _{1*} ~ 3 · J ₁ : 1.40
S10 Operation with individual constant loads 	100 %	1.00	1.00	

Tab. 1: Operating factors for operating modes S1 to S10

4.6.1 Permitted shaft loads for the output shaft

The values specified in the tables apply to the permitted shaft loads:

- For shaft dimensions in accordance with the catalog
- For output speeds $n_{2m^*} \leq 20$ rpm ($F_{2axN} = F_{2ax20}$; $F_{2radN} = F_{2rad20}$; $M_{2kN} = M_{2k20}$)
- Only if radial forces on the gear unit are stabilized by its pilots for the pitch circle diameter and flange housing design

4.6.1.1 V shaft design

Permitted shaft loads for V shaft design (solid shaft)

Type	z_2 [mm]	F_{2ax20} [N]	F_{2rad20} [N]	$F_{2rad,acc}$ [N]	M_{2k20} [Nm]	$M_{2k,acc}$ [Nm]
K1	40.0	1900	5000	5000	325	325
K2	42.0	2100	6000	6000	430	430
K3	45.0	2400	7000	7000	525	525
K4	52.0	3500	11200	11200	1050	1050
K5	72.0	3500	13450	13450	1580	1580
K6	72.0	4000	16000	16000	1960	1960
K7	85.0	5500	22000	22000	3200	3200
K8	60.0	7250	29000	29000	3800	3800
K9	87.0	16500	65000	65000	11200	11200
K10	84.0	25000	80000	80000	15200	15200

Reduced values apply in the case of a V shaft design (solid shaft) in conjunction with an NF housing design (foot + round flange):

Type	z_2 [mm]	F_{2ax20} [N]	F_{2rad20} [N]	$F_{2rad,acc}$ [N]	M_{2k20} [Nm]	$M_{2k,acc}$ [Nm]
K10	132.0	25000	64000	64000	15200	15200

For the V solid shaft design on both sides, the values for F_{2rad20} and M_{2k20} must be multiplied by a factor of 0.7.

For other output speeds, download diagrams at <https://configurator.stoeber.de/en-US/>.

The following applies to output speeds $n_{2m^*} > 20$ rpm:

$$F_{2axN} = \frac{F_{2ax20}}{\sqrt[3]{\frac{n_{2m^*}}{20 \text{ rpm}}}}$$

$$F_{2radN} = \frac{F_{2rad20}}{\sqrt[3]{\frac{n_{2m^*}}{20 \text{ rpm}}}}$$

$$M_{2kN} = \frac{M_{2k20}}{\sqrt[3]{\frac{n_{2m^*}}{20 \text{ rpm}}}}$$

The values for F_{2ax20} , F_{2rad20} and M_{2k20} can be found in the table "Permitted shaft loads" in this chapter.

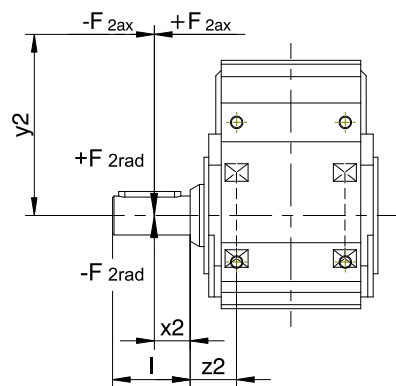


Fig. 1: Force application points for solid shaft

The specified values for F_{2rad20} and $F_{2rad,acc}$ refer to an application of force at the center of the output shaft: $x_2 = l/2$.

Shaft dimensions can be found in the "Dimensional drawings" chapter.

The following applies to other force application points:

$$M_{2k,acc^*} = \frac{2 \cdot F_{2ax^*} \cdot y_2 + F_{2rad,acc^*} \cdot (x_2 + z_2)}{1000}$$

For applications with multiple axial and/or radial forces, you must add the forces as vectors.

In the event of EMERGENCY OFF operation (max. 1000 load changes), you can multiply the permitted forces and torques for F_{2ax20} , F_{2rad20} and M_{2k20} by a factor of two.

Also note the calculation for equivalent values:

$$M_{2k,eq^*} = \sqrt[3]{\frac{|n_{2m,1^*}| \cdot t_{1^*} \cdot |M_{2k,acc,1^*}|^3 + \dots + |n_{2m,n^*}| \cdot t_{n^*} \cdot |M_{2k,acc,n^*}|^3}{|n_{2m,1^*}| \cdot t_{1^*} + \dots + |n_{2m,n^*}| \cdot t_{n^*}}}$$

$$F_{2rad,eq^*} = \sqrt[3]{\frac{|n_{2m,1^*}| \cdot t_{1^*} \cdot |F_{2rad,acc,1^*}|^3 + \dots + |n_{2m,n^*}| \cdot t_{n^*} \cdot |F_{2rad,acc,n^*}|^3}{|n_{2m,1^*}| \cdot t_{1^*} + \dots + |n_{2m,n^*}| \cdot t_{n^*}}}$$

4.6.1.2 A and S shaft design

Permitted shaft loads for A shaft design (hollow shaft with keyway)

Type	z_2 [mm]	F_{2ax20} [N]	F_{2rad20} [N]	$F_{2rad,acc}$ [N]	M_{2k20} [Nm]	$M_{2k,acc}$ [Nm]
K1	40.0	1900	5000	5000	240	240
K2	42.0	2100	6000	6000	310	310
K3	45.0	2400	7000	7000	380	380
K4	52.0	3500	11200	11200	740	740
K5	39.0	2500	13450	13450	1000	1000
K6	42.0	3000	16000	16000	1300	1300
K7	45.0	4100	22000	22000	2100	2100
K8	50.0	5300	29000	29000	2600	2600
K9	56.0	7000	65000	65000	3600	3600
K10	56.0	9000	80000	80000	5000	5000

Permitted shaft loads for S shaft design (hollow shaft with shrink ring)

Type	z_2 [mm]	F_{2ax20} [N]	F_{2rad20} [N]	$F_{2rad,acc}$ [N]	M_{2k20} [Nm]	$M_{2k,acc}$ [Nm]
K1	40.0	1900	5000	5000	240	240
K2	42.0	2100	6000	6000	310	310
K3	45.0	2400	7000	7000	380	380
K4	52.0	3500	11200	11200	740	740
K5	39.0	2500	13450	13450	1000	1000
K6	42.0	3000	16000	16000	1300	1300
K7	45.0	4100	22000	22000	2100	2100
K8	50.0	5300	29000	29000	2600	2600
K9	56.0	7000	65000	65000	3600	3600
K10	56.0	9000	80000	80000	5000	5000

For other output speeds, download diagrams at <https://configurator.stoeber.de/en-US/>.

The following applies to output speeds $n_{2m^*} > 20$ rpm:

$$F_{2axN} = \frac{F_{2ax20}}{\sqrt[3]{\frac{n_{2m^*}}{20 \text{ rpm}}}}$$

$$F_{2radN} = \frac{F_{2rad20}}{\sqrt[3]{\frac{n_{2m^*}}{20 \text{ rpm}}}}$$

$$M_{2kN} = \frac{M_{2k20}}{\sqrt[3]{\frac{n_{2m^*}}{20 \text{ rpm}}}}$$

The values for F_{2ax20} , F_{2rad20} and M_{2k20} can be found in the table "Permitted shaft loads" in this chapter.

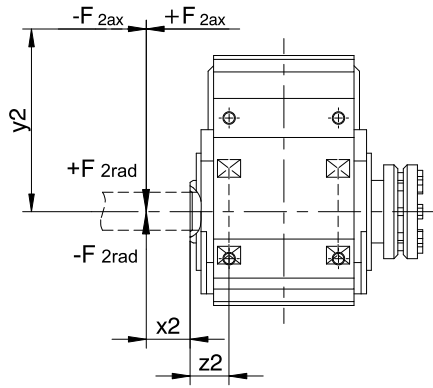


Fig. 2: Force application points for hollow shaft

You can determine the permitted radial forces from the permitted tilting torque M_{2kN} and $M_{2k,acc}$. The actual radial forces may not exceed the permitted radial forces. The permitted radial forces pertain to the shaft end ($x_2 = 0$).

$$M_{2k,acc} = \frac{2 \cdot F_{2ax} \cdot y_2 + F_{2rad,acc} \cdot (x_2 + z_2)}{1000}$$

For applications with multiple axial and/or radial forces, you must add the forces as vectors.

In the event of EMERGENCY OFF operation (max. 1000 load changes), you can multiply the permitted forces and torques for F_{2ax20} , F_{2rad20} and M_{2k20} by a factor of two.

Also note the calculation for equivalent values:

$$M_{2k,eq} = \sqrt[3]{\frac{|n_{2m,1}| \cdot t_1 \cdot |M_{2k,acc,1}|^3 + \dots + |n_{2m,n}| \cdot t_n \cdot |M_{2k,acc,n}|^3}{|n_{2m,1}| \cdot t_1 + \dots + |n_{2m,n}| \cdot t_n}}$$

$$F_{2rad,eq} = \sqrt[3]{\frac{|n_{2m,1}| \cdot t_1 \cdot |F_{2rad,acc,1}|^3 + \dots + |n_{2m,n}| \cdot t_n \cdot |F_{2rad,acc,n}|^3}{|n_{2m,1}| \cdot t_1 + \dots + |n_{2m,n}| \cdot t_n}}$$

4.6.2 Radial shaft seal rings

Leak-proofness

Our gear units are equipped with high-quality radial shaft seal rings and checked for leaks. However, a leak cannot be fully ruled out over the length of use of a gear unit. If you use a gear unit with goods incompatible with the lubricant, you must take measures to prevent direct contact with the gear unit lubricant in case of a leak.

4.6.3 Oil expansion tank

The gear units have a higher fill level in mounting position EL5. The oil expansion tank prevents oil from escaping out of the gear unit.

Notes

- We recommend using an oil expansion tank in mounting position EL5 (additional cost) for fast running gear units with an input speed $n_1 > 1750$ rpm and gear ratios $i < 20$.
- It is not possible to use an oil expansion tank if the plug connector is at 90°!
- The oil expansion tank can only be used with certain sizes; see the chapter [\[▶ 4.3.17\]](#)

4.7 Additional documentation

Additional documentation related to the product can be found at

<http://www.stoeber.de/en/downloads/>

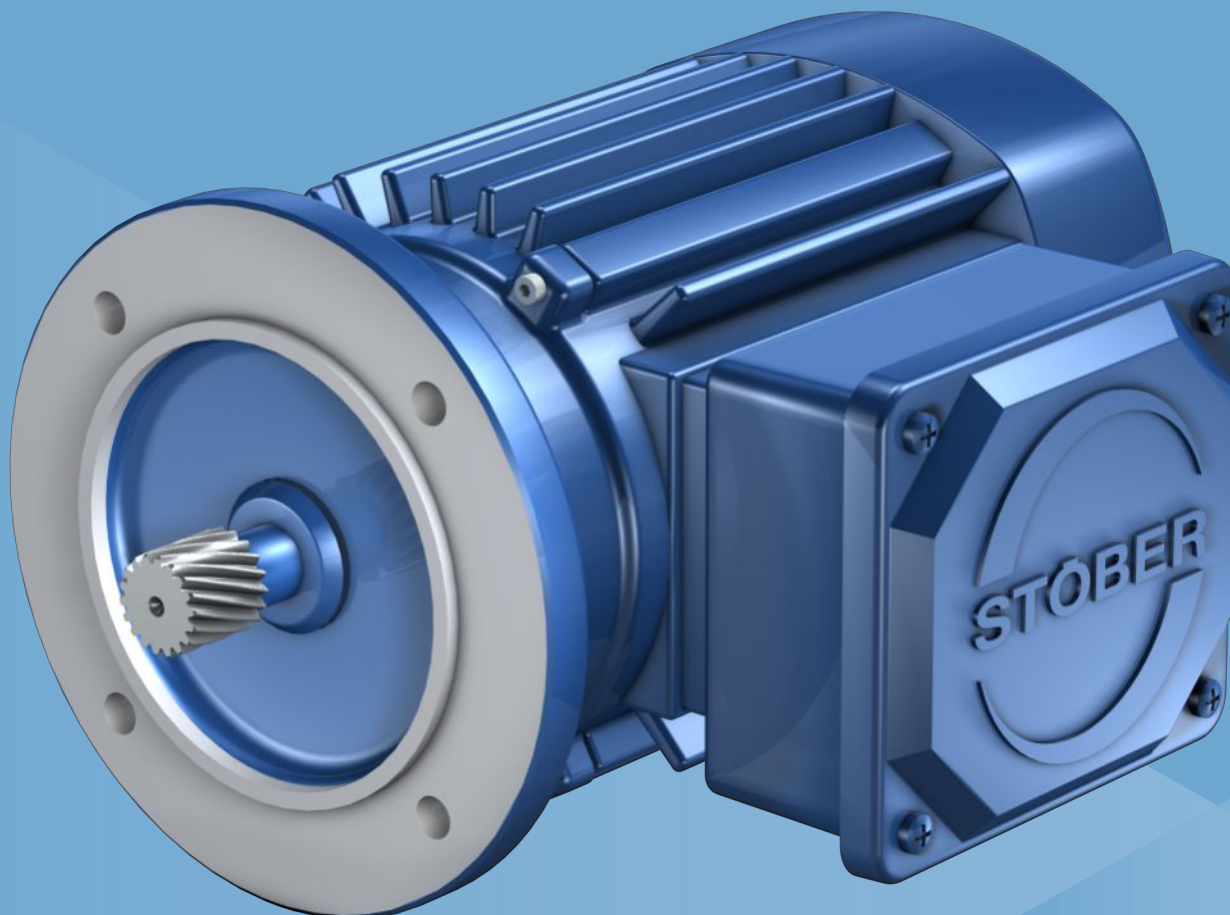
Enter the ID of the documentation in the Search field.

Documentation	ID
Operating manual for C/F/K/S gear units and gear motors	443027_en

5 Asynchronous motors

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5 Asynchronous motors

5.1 Overview

Asynchronous motors

Features

- Self-ventilation or forced ventilation (optional) ✓
- Spring-loaded brake (optional) ✓
- Incremental encoder (optional) or SSI absolute encoder (optional) ✓
- Elimination of referencing with multi-turn absolute encoders (optional) ✓
- Terminal box ✓
- Energy efficiency class IE3 in accordance with EN 60034-30-1 ✓

Technical data (400 V ± 10%, 50 Hz)

n_2	1400 – 1480 rpm
P_N	0.12 – 30 kW
M_N	0.82 – 194 Nm
I_N	0.35 – 54 A

5.2 Selection tables

The technical data specified in the following selection table applies to:

- Installation altitudes up to 1000 m above sea level
- Surrounding temperatures from -20 °C to 40 °C
- 230 / 400 V AC nominal voltage
- 50 Hz nominal frequency
- 4 poles

For technical data for other motor designs, go to <https://configurator.stoeber.de/en-US/>.

An explanation of the formula symbols can be found in the chapter [\[▶ 13.1\]](#).

Observe the legal requirements in the chapter [\[▶ 5.6.1\]](#).

The type designation for the motors in this product catalog and on the nameplate of the motor are different. The allocation is shown in the following table.

Type on nameplate	Type in catalog
IE3-W41R 63 K4	IE3D063K04
IE3-W41R 63 G4	IE3D063M04
IE3-W41R 71 K4	IE3D071K04
IE3-W41R 71 G4	IE3D071L04
IE3-W41R 80 K4	IE3D080K04
IE3-W41R 80 G4	IE3D080L04
IE3-W41R 90 SY4	IE3D090S04
IE3-W41R 90 LX4	IE3D090LX04
IE3-W41R 100 L4	IE3D100KX04
IE3-W41R 100 LU4	IE3D100LX04
IE3-W41R 112 MW4	IE3D112M04
IE3-W42R 132 S4	IE3D132SX04
IE3-W43R 132 M4	IE3D132MX04
IE3-W43R 160 M4	IE3D160MX04
IE3-W41R 160 L4	IE3D160LX04
IE3-W43R 180 M4	IE3D180MX04
IE3-W43R 180 L4	IE3D180LX04
IE3-W43R 200 L4	IE3D200LX04

The technical data for the motors can be found in the following selection table.

Type	Y/ Δ	η			$\cos\phi_N$	P_N [kW]	n_N [rpm]	I_N [A]	M_N [Nm]	I_{1mot}/I_N	M_{1mot}/M_N	M_k/M_N	J [kgcm ²]	m [kg]
		[%]	[%]	[%]										
		100%	75%	50%										
IE3D063K04	Y	64.80	63.40	58.70	0.71	0.12	1400	0.35	0.82	3.8	2.0	2.3	4.00	6.30
IE3D063M04	Y	69.90	69.50	64.30	0.67	0.18	1415	0.55	1.21	4.4	2.8	2.9	5.00	7.10
IE3D071K04	Y	73.50	73.10	69.60	0.71	0.25	1430	0.66	1.67	5.6	2.5	2.9	8.70	9.90
IE3D071L04	Y	77.30	78.20	73.10	0.69	0.37	1430	0.98	2.50	6.2	2.8	3.2	10.7	11.0
IE3D080K04	Y	80.80	80.10	76.70	0.77	0.55	1440	1.27	3.65	6.6	3.0	3.6	20.7	14.5
IE3D080L04	Y	82.50	82.30	79.60	0.77	0.75	1445	1.70	5.00	7.0	3.1	3.7	26.0	17.0
IE3D090S04	Y	84.10	82.60	79.70	0.76	1.10	1440	2.50	7.30	6.7	2.8	3.7	40.0	22.5
IE3D090LX04	Y	85.30	85.80	82.90	0.75	1.50	1455	3.40	9.80	9.5	4.5	4.9	58.0	31.0
IE3D100KX04	Y	86.70	87.00	85.10	0.81	2.20	1450	4.55	14.5	8.2	2.9	3.8	110	45.0
IE3D100LX04	Y	87.70	88.80	87.70	0.77	3.00	1450	6.35	19.8	7.7	3.0	4.0	130	50.0
IE3D112M04	Δ	88.60	88.90	87.40	0.82	4.00	1465	7.90	26.1	9.4	3.0	4.5	170	56.0
IE3D132SX04	Δ	90.20	91.00	90.60	0.87	5.50	1465	10.0	36.0	7.1	2.1	3.3	350	90.0
IE3D132MX04	Δ	90.50	90.50	89.20	0.75	7.50	1470	16.0	49.0	7.6	3.0	3.9	350	88.0
IE3D160MX04	Δ	91.40	91.90	91.50	0.82	11.00	1465	21.0	72.0	7.0	2.3	3.4	430	105
IE3D160LX04	Δ	92.20	92.40	91.60	0.85	15.00	1475	27.5	97.0	8.7	3.1	3.5	1150	165
IE3D180MX04	Δ	92.60	92.70	91.90	0.84	18.50	1475	34.5	120	7.8	2.9	3.3	1150	160
IE3D180LX04	Δ	93.00	93.30	92.70	0.83	22.00	1475	41.0	142	6.9	2.0	3.0	1680	206
IE3D200LX04	Δ	93.60	94.00	93.70	0.86	30.00	1480	54.0	194	6.4	1.8	2.5	3130	304

2-pole motors are available on request.

5.3 Dimensional drawings

In the following dimensional drawings, motors are shown with an output flange for direct attachment to STOBBER gear units. Note that other dimensions may apply to motors with an IEC output flange, cURus test symbol or EISA 2007 certification in some cases. You can find corresponding dimensional drawings at <https://configurator.stoeber.de/en-US/>.

For IE3D080 – IE3D112 motors, the center of the terminal box is not at the center line of the motor axis.

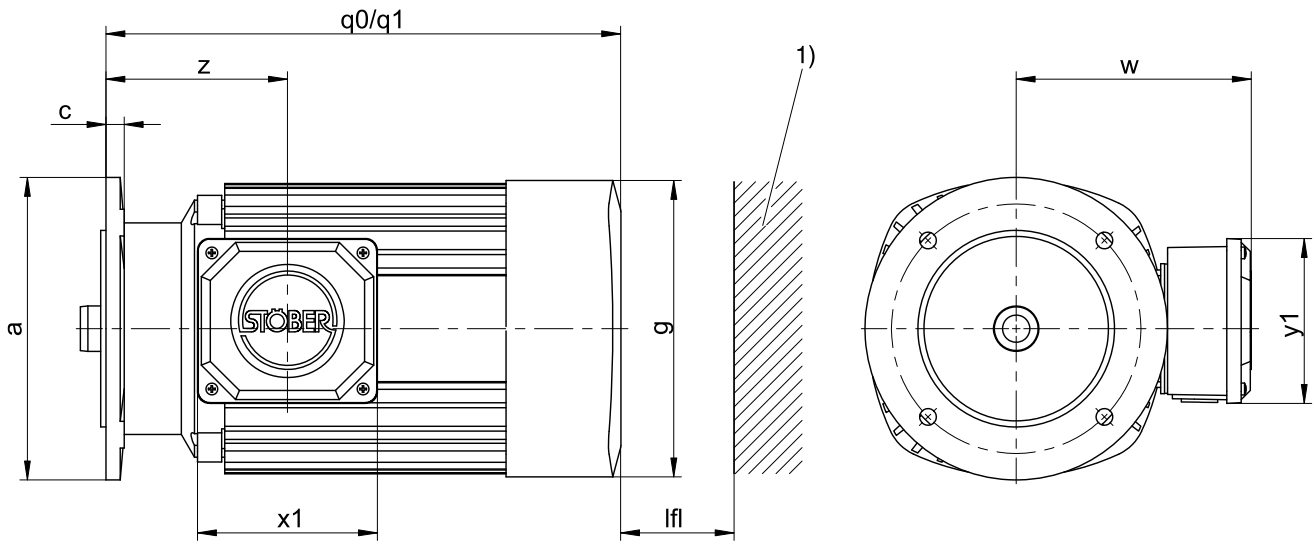
Dimensions can exceed the specifications of ISO 2768-mK due to casting tolerances or accumulation of individual tolerances.

We reserve the right to make dimensional changes due to ongoing technical development.

You can download 3D models of our standard drives at <https://configurator.stoeber.de/en-US/>.

5.3.1 Motors with self-ventilation

In the following dimensional drawings, motors are shown with an output flange for direct attachment to STÖBER gear units. Note that other dimensions may apply to motors with an IEC output flange, cURus test symbol or EISA 2007 certification in some cases. You can find corresponding dimensional drawings at <https://configurator.stoeber.de/en-US/>.



q_0 Applies to motors without brake

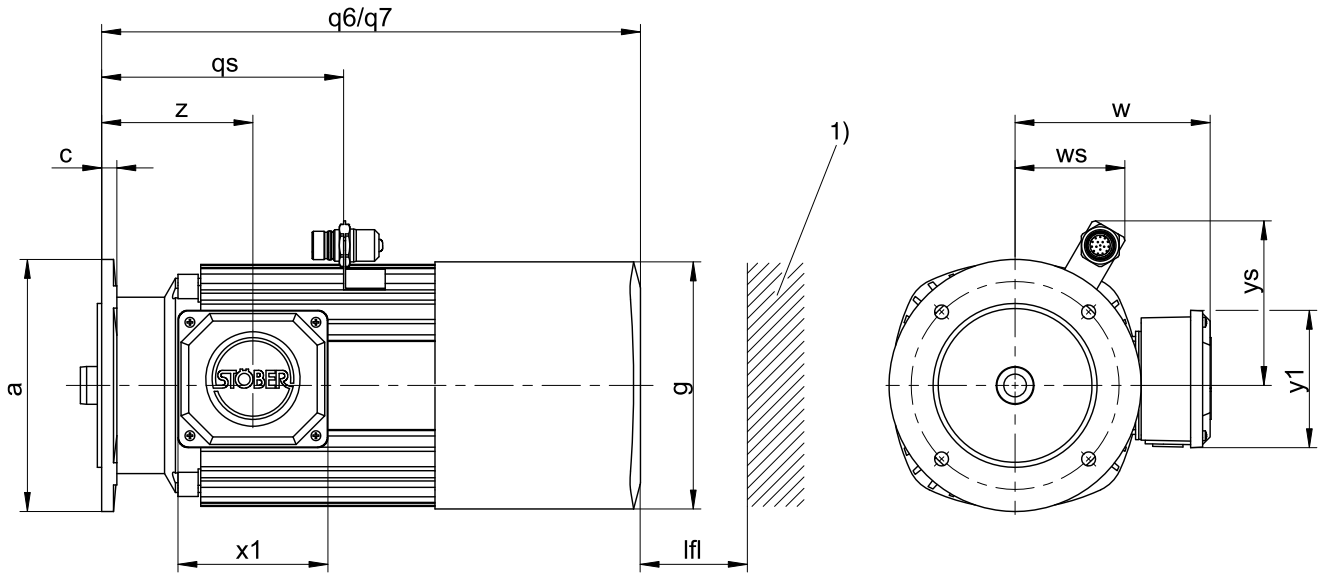
q_1 Applies to motors with brake

1) Machine wall

Type	pz	Øa	c	g	lfl	q0	q1	w	x1	y1	z
IE3D063K04	4	140	11	124	14	208	261	121	109	97	94
IE3D063M04	4	140	11	124	14	208	261	121	109	97	94
IE3D071K04	4	140	11	139	14	238	295	128	109	97	97
IE3D071L04	4	140	11	139	14	238	295	128	109	97	97
IE3D080K04	4	160	10	157	16	261	329	137	109	97	107
IE3D080L04	4	160	11	157	16	283	351	137	109	97	107
IE3D090S04	4	160	11	177	18	310	380	146	120	109	114
IE3D090LX04	4	160	11	177	18	365	435	146	120	109	114
IE3D100KX04	4	200	12	196	20	404	491	155	120	109	120
IE3D100LX04	4	200	12	196	20	444	531	155	120	109	120
IE3D112M04	4	200	12	217	35	424	521	178	147	157	134
IE3D132SX04	4	250	11	258	35	476	591	199	147	157	142
IE3D132MX04	4	250	11	258	35	476	591	199	147	157	142
IE3D160MX04	4	300	12	313	35	526	641	199	167	194	138
IE3D160LX04	4	300	12	313	35	549	627	242	167	194	138
IE3D180MX04	4	300	16	313	35	549	677	242	167	194	178
IE3D180LX04	4	300	16	351	35	601	748	260	167	194	178
IE3D200LX04	4	350	20	390	35	729	878	298	207	209	242

5.3.2 Motors with self-ventilation and encoder

In the following dimensional drawings, motors are shown with an output flange for direct attachment to STÖBER gear units. Note that other dimensions may apply to motors with an IEC output flange, cURus test symbol or EISA 2007 certification in some cases. You can find corresponding dimensional drawings at <https://configurator.stoebler.de/en-US/>.



q6 Applies to motors without brake

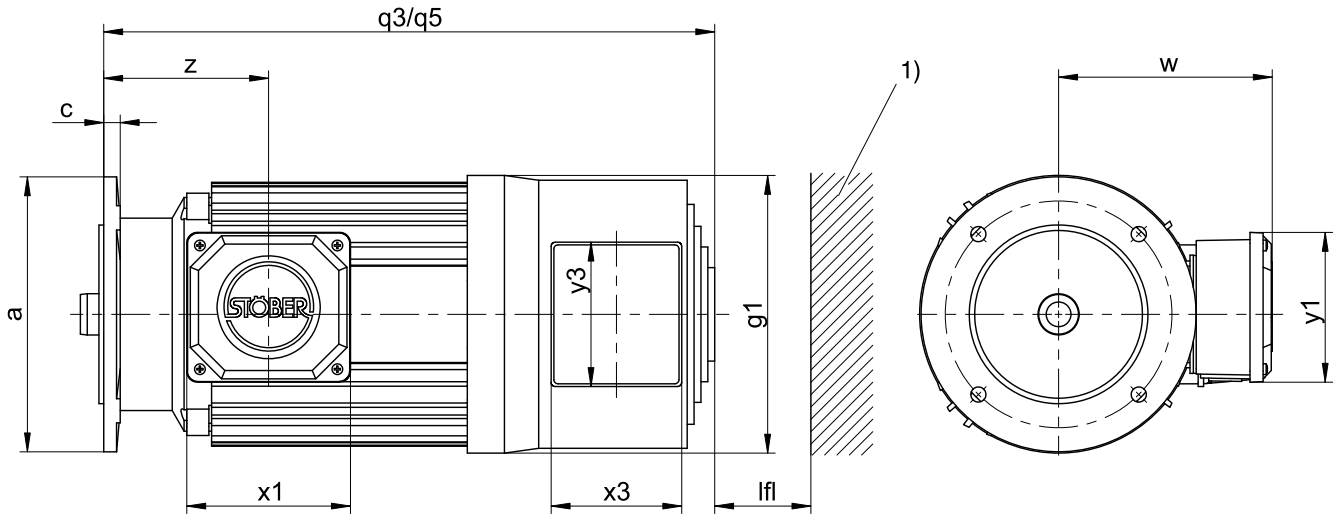
q7 Applies to motors with brake

1) Machine wall

Type	pz	Øa	c	g	lfl	q6	q7	qs	w	ws	x1	y1	ys	z
IE3D063K04	4	140	11	124	14	261	316	123	121	63	109	97	90	94
IE3D063M04	4	140	11	124	14	261	316	123	121	63	109	97	90	94
IE3D071K04	4	140	11	139	14	295	353	126	128	67	109	97	97	97
IE3D071L04	4	140	11	139	14	295	353	126	128	67	109	97	97	97
IE3D080K04	4	160	10	157	16	329	386	172	137	77	109	97	113	107
IE3D080L04	4	160	11	157	16	351	408	172	137	77	109	97	113	107
IE3D090S04	4	160	11	177	18	380	437	186	146	82	120	109	121	114
IE3D090LX04	4	160	11	177	18	435	492	186	146	82	120	109	121	114
IE3D100KX04	4	200	12	196	20	491	543	192	155	87	120	109	131	120
IE3D100LX04	4	200	12	196	20	531	583	192	155	87	120	109	131	120
IE3D112M04	4	200	12	217	35	521	569	102	178	92	147	157	131	134
IE3D132SX04	4	250	11	258	35	591	706	213	199	102	147	157	145	142
IE3D132MX04	4	250	11	258	35	591	716	213	199	102	147	157	145	142
IE3D160MX04	4	300	12	313	35	641	756	213	199	102	167	194	145	138
IE3D160LX04	4	300	12	313	35	627	804	285	242	123	167	194	166	138
IE3D180MX04	4	300	16	313	35	677	804	285	242	123	167	194	166	178
IE3D180LX04	4	300	16	351	35	748	895	326	260	136	167	194	179	178
IE3D200LX04	4	350	20	390	35	878	1026	361	298	155	207	209	198	242

5.3.3 Motors with forced ventilation

In the following dimensional drawings, motors are shown with an output flange for direct attachment to STÖBER gear units. Note that other dimensions may apply to motors with an IEC output flange, cURus test symbol or EISA 2007 certification in some cases. You can find corresponding dimensional drawings at <https://configurator.stoerber.de/en-US/>.



q3 Applies to motors without brake

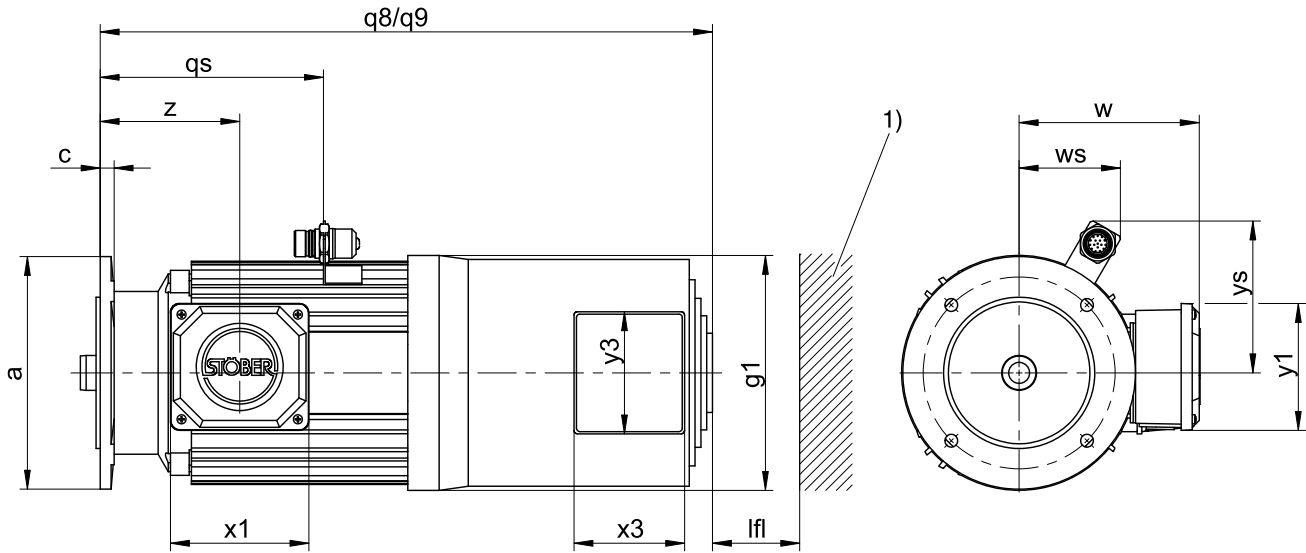
q5 Applies to motors with brake

1) Machine wall

Type	pz	Øa	c	g1	lfl	q3	q5	w	x1	x3	y1	y3	z
IE3D063K04	4	140	11	115	14	311	350	121	109	105	97	105	94
IE3D063M04	4	140	11	115	14	311	350	121	109	105	97	105	94
IE3D071K04	4	140	11	131	14	343	388	128	109	105	97	105	97
IE3D071L04	4	140	11	131	14	343	388	128	109	105	97	105	97
IE3D080K04	4	160	10	146	16	362	421	137	109	105	97	105	107
IE3D080L04	4	160	11	162	16	384	443	137	109	95	97	105	107
IE3D090S04	4	160	11	182	18	416	467	146	120	95	109	105	114
IE3D090LX04	4	160	11	182	18	471	522	146	120	95	109	105	114
IE3D100KX04	4	200	12	200	20	508	590	155	120	95	109	105	120
IE3D100LX04	4	200	12	200	20	548	630	155	120	95	109	105	120
IE3D112M04	4	200	12	234	35	559	609	178	147	95	157	105	134
IE3D132SX04	4	250	11	258	35	615	715	199	147	95	157	105	142
IE3D132MX04	4	250	11	258	35	615	715	199	147	95	157	105	142
IE3D160MX04	4	300	12	313	35	665	765	199	167	95	194	105	138
IE3D160LX04	4	300	12	313	35	722	835	242	167	95	194	105	138
IE3D180MX04	4	300	16	338	35	722	835	242	167	95	194	105	178
IE3D180LX04	4	300	16	338	35	774	909	260	167	95	194	105	178
IE3D200LX04	4	350	20	424	35	923	1108	298	207	95	209	105	242

5.3.4 Motors with forced ventilation and encoder

In the following dimensional drawings, motors are shown with an output flange for direct attachment to STÖBER gear units. Note that other dimensions may apply to motors with an IEC output flange, cURus test symbol or EISA 2007 certification in some cases. You can find corresponding dimensional drawings at <https://configurator.stoerber.de/en-US/>.



q8 Applies to motors without brake

q9 Applies to motors with brake

1) Machine wall

Type	pz	Øa	c	g1	lfl	q8	q9	qs	w	ws	x1	x3	y1	y3	ys	z
IE3D063K04	4	140	11	115	14	350	400	123	121	63	109	105	97	105	90	94
IE3D063M04	4	140	11	115	14	350	400	123	121	63	109	105	97	105	90	94
IE3D071K04	4	140	11	131	14	388	423	126	128	67	109	105	97	105	97	97
IE3D071L04	4	140	11	131	14	388	423	126	128	67	109	105	97	105	97	97
IE3D080K04	4	160	10	146	16	421	451	172	137	77	109	105	97	105	113	107
IE3D080L04	4	160	11	162	16	443	473	172	137	77	109	95	97	105	113	107
IE3D090S04	4	160	11	182	18	467	517	186	146	82	120	95	109	105	121	114
IE3D090LX04	4	160	11	182	18	522	572	186	146	82	120	95	109	105	121	114
IE3D100KX04	4	200	12	200	20	590	618	192	155	87	120	95	109	105	131	120
IE3D100LX04	4	200	12	200	20	630	658	192	155	87	120	95	109	105	131	120
IE3D112M04	4	200	12	234	35	609	634	102	178	92	147	95	157	105	131	134
IE3D132SX04	4	250	11	258	35	715	815	213	199	102	147	95	157	105	145	142
IE3D132MX04	4	250	11	258	35	715	815	213	199	102	147	95	157	105	145	142
IE3D160MX04	4	300	12	313	35	765	865	213	199	102	167	95	194	105	145	138
IE3D160LX04	4	300	12	313	35	835	935	285	242	123	167	95	194	105	166	138
IE3D180MX04	4	300	16	338	35	835	935	285	242	123	167	95	194	105	166	178
IE3D180LX04	4	300	16	338	35	909	1009	326	260	136	167	95	194	105	179	178
IE3D200LX04	4	350	20	424	35	1108	1216	361	298	155	207	95	209	105	198	242

5.4 Type designation

IE3	D	080	K	04
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Explanation

Code	Designation	Design
IE3	Energy efficiency class in accordance with EN 60034-30-1	IE3
D	Type	Asynchronous motor
080	Size	80 (example)
K/KX	Length	Short
L/LX		Long
M/MX		Medium
S/SX		Small
02	Number of poles	2
04		4

The type designation on the motor nameplate differs from the type designation in the product catalog. The allocation can be found in the Selection Tables chapter.

To complete the type designation, also specify the following in your order:

- With IEC output flange or for direct attachment to STOBBER gear units?
- With spring-loaded brake? (see the chapter [\[▶ 5.5.7\]](#))?
- With cURus test symbol option?
- With EISA 2007 certification option?
- With forced ventilation option (see the chapter [\[▶ 5.5.6.1\]](#))?
- With forced ventilation and encoder option (see the chapter Encoders)?
- Side for cable entry (see the chapter [\[▶ 5.5.8.1\]](#))

5.5 Product description

5.5.1 General features

Feature	Description
Design	IM B5, IM V1, IM V3 in accordance with EN 60034-7
Protection class	IP54
Thermal class	155 (F) in accordance with EN 60034-1 (155 °C, heating $\Delta\theta = 100$ K)
Cooling	IC 411 self-ventilation IC 416 forced ventilation (option)
Paint	RAL 7001 Silver gray Optional selection of various RAL colors.
Bearing	Rolling bearing with lifetime lubrication
Vibration intensity	A in accordance with EN 60034-14
Noise level	Limit values in accordance with EN 60034-9

5.5.2 Electrical features

General electrical features of the asynchronous motors are described in this chapter. Details can be found in the "Selection tables" chapter.

IE3D063 – IE3D100

	50 Hz	60 Hz
Nominal voltage	Delta connection: AC 230 V Star connection: AC 400 V	Delta connection: AC 265 V Star connection: AC 460 V
Voltage range	Delta connection: AC 220 – 240 V Star connection: AC 380 – 420 V	Delta connection: AC 220 – 275 V Star connection: AC 380 – 480 V

IE3D112 – IE3D200 motors

	50 Hz	60 Hz
Nominal voltage	Delta connection: AC 400 V	Delta connection: AC 460 V
Voltage range	Delta connection: AC 380 – 420 V	Delta connection: AC 380 – 480 V

5.5.3 Ambient conditions

Standard ambient conditions for transport, storage and operation of the motor are described in this chapter.

Feature	Description
Surrounding temperature for transport/storage	–30 °C to +85 °C
Surrounding temperature for operation	–15 °C to +40 °C
Relative humidity	5% to 95%, no condensation
Installation altitude	≤ 1000 m above sea level
Shock load	≤ 50 m/s ² (5 g), 6 ms in accordance with EN 60068-2-27

Notes

- STOBBER asynchronous motors are not suitable for potentially explosive atmospheres. You can get asynchronous motors for use in potentially explosive atmospheres on request.
- Secure the connection cables close to the motor so that cable vibrations do not place impermissible loads on the screw connections, terminal boxes or plug connectors.
- Also take into consideration the shock load of the motor due to output units (such as gear units and pumps) which are coupled with the motor.

5.5.4 Encoders

Asynchronous motors with forced ventilation can optionally be equipped with an incremental or absolute encoder. Self-ventilated asynchronous motors are optionally available with an incremental encoder. The encoder connection method is described in Chapter [5.5.8](#).

5.5.4.1 Incremental encoders

Incremental encoder technical data can be found in this chapter.

Feature	Description
Sensing principle	Optical
Pulses per revolution	2048
Reference signal	Zero pulse
TTL output level	RS422
HTL output level	Push-pull
TTL operating voltage	DC 5 V ± 5%
HTL operating voltage	DC 8 – 30 V

5.5.4.2 Multi-turn absolute encoders

Multi-turn absolute encoder technical data can be found in this chapter. This encoder is used to detect several revolutions of the motor shaft, making it possible to reduce the amount of referencing.

Technical Data

Feature	Description
Type	EQN 425
Interface	SSI
Code	Gray
Position values per revolution	8192 (13 bits)
Recordable revolutions	4096 (12 bits)
Operating voltage	DC 4.75 – 30 V

5.5.5 PTC thermistor

In this chapter, you can find technical data on the PTC thermistor that can optionally be installed in STOBER asynchronous motors for implementing thermal winding protection. To prevent damage to the motor, always monitor the PTC thermistor with appropriate devices that will turn off the motor if the maximum permitted winding temperature is exceeded.

The PTC thermistor is a triple thermistor in accordance with DIN 44082 that allows the temperature of each winding phase to be monitored. The resistance values in the following table and curve refer to a single thermistor in accordance with DIN 44081. These values must be multiplied by 3 for a triple thermistor in accordance with DIN 44082.

Feature	Description
Nominal response temperature ϑ_{NAT}	145 °C ± 5 K
Resistance R -20 °C up to $\vartheta_{NAT} - 20$ K	≤ 250 Ω
Resistance R with $\vartheta_{NAT} - 5$ K	≤ 550 Ω
Resistance R with $\vartheta_{NAT} + 5$ K	≥ 1330 Ω
Resistance R with $\vartheta_{NAT} + 15$ K	≥ 4000 Ω
Operating voltage	≤ DC 7.5 V
Thermal response time	< 5 s
Thermal class	155 (F) in accordance with EN 60034-1 (155 °C, heating $\Delta\vartheta = 100$ K)

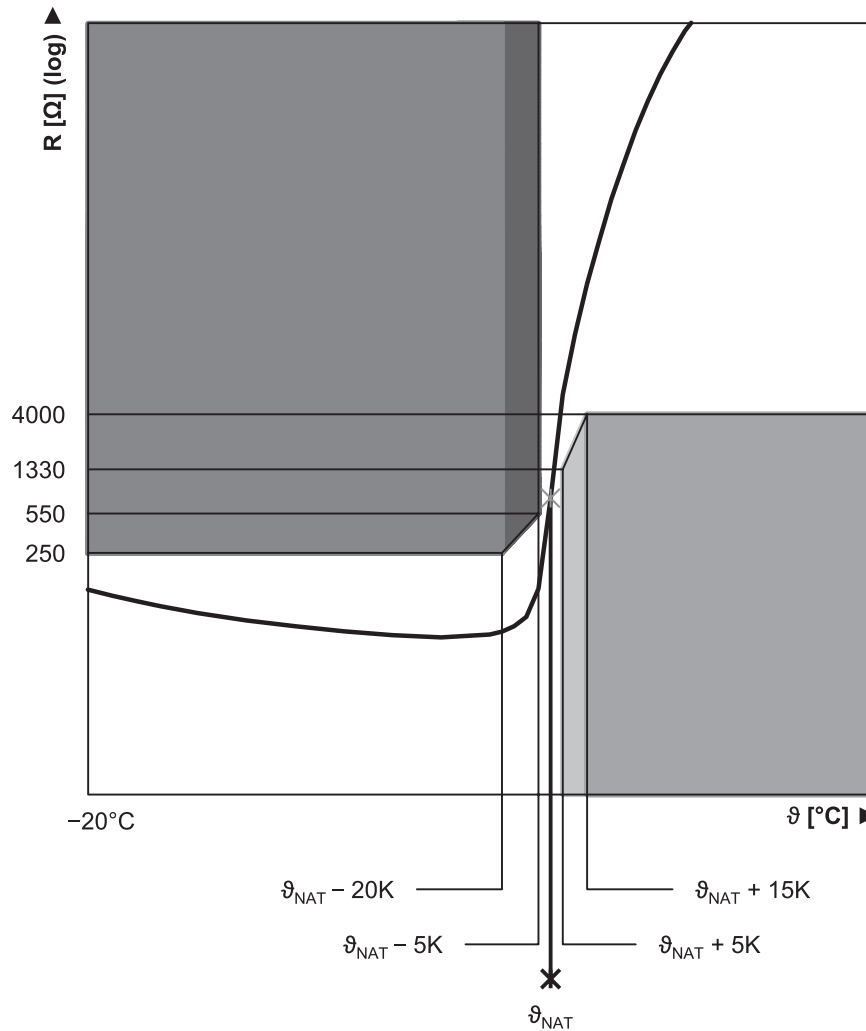


Fig. 1: PTC thermistor curve (single thermistor)

5.5.6 Cooling

STOBER asynchronous motors in the standard design are cooled using the impeller installed on the motor shaft (self-ventilation). In this process, the motor waste heat is transported away by the air aspirated by the impeller and blown over the motor cooling fins.

5.5.6.1 Forced ventilation

STOBER asynchronous motors can be equipped with an optional forced ventilation unit. This may be necessary at low speeds or for operation on a drive controller in order to ensure cooling independent of the motor speed. A forced ventilation unit can also be added later. The performance data for motors with forced ventilation can be found in Chapter [5.2](#) and the dimensional drawings in Chapter [5.3](#).

Technical data (50 Hz)

Motor	Type	$U_{N,F}$ [V]	$I_{N,F}$ [A]	$\cos\phi_F$	n_F [rpm]	q_{VF} [m ³ /h]	$L_{pA,F}$ [dBA]	C_F [μF]
IE3D063K04.IE3D063M04	FL-63	Δ_c	0.18	0.99	2710	54	47	3
IE3D063K04.IE3D063M04	FL-63	Δ 220–240 / Y 380–420	0.15/0.09	0.45	2830	54	47	–
IE3D071K04.IE3D071L04	FL-71	Δ_c	0.18	0.99	2730	78	51	3
IE3D071K04.IE3D071L04	FL-71	Δ 220–240 / Y 380–420	0.15/0.09	0.48	2820	78	51	–
IE3D080K04.IE3D080L04	FL-80	Δ_c	0.19	0.98	2650	128	54	3
IE3D080K04.IE3D080L04	FL-80	Δ 220–240 / Y 380–420	0.16/0.09	0.56	2760	128	54	–
IE3D090LX04.IE3D090S04	FL-90	Δ_c	0.29	0.89	2890	216	59	3
IE3D090LX04.IE3D090S04	FL-90	Δ 220–240 / Y 380–420	0.39/0.22	0.47	2890	216	59	–
IE3D100KX04.IE3D100LX04	FL-100	Δ_c	0.29	0.94	2820	278	60	3
IE3D100KX04.IE3D100LX04	FL-100	Δ 220–240 / Y 380–420	0.37/0.21	0.56	2830	278	60	–
IE3D112M04	FL-112	Δ_c	0.27	0.96	2750	355	62	3
IE3D112M04	FL-112	Δ 220–240 / Y 380–420	0.35/0.20	0.69	2780	355	62	–

Technical data for force-ventilated motors of size 132 or larger are available on request.

Technical data (60 Hz)

Motor	Type	$U_{N,F}$ [V]	$I_{N,F}$ [A]	$\cos\phi_F$	n_F [rpm]	q_{VF} [m ³ /h]	$L_{pA,F}$ [dBA]	C_F [μF]
IE3D063K04.IE3D063M04	FL-63	Δ_c	0.21	0.98	3020	69	52	3
IE3D063K04.IE3D063M04	FL-63	Δ 220–275 / Y 380–480	0.14/0.08	0.47	3420	69	52	–
IE3D071K04.IE3D071L04	FL-71	Δ_c	0.21	0.98	3000	99	56	3
IE3D071K04.IE3D071L04	FL-71	Δ 220–275 / Y 380–480	0.13/0.07	0.52	3370	99	56	–
IE3D080K04.IE3D080L04	FL-80	Δ_c	0.22	0.97	2600	151	58	3
IE3D080K04.IE3D080L04	FL-80	Δ 220–275 / Y 380–480	0.13/0.07	0.70	3250	151	58	–
IE3D090LX04.IE3D090S04	FL-90	Δ_c	0.23	0.99	3390	258	63	3
IE3D090LX04.IE3D090S04	FL-90	Δ 220–275 / Y 380–480	0.32/0.18	0.55	3430	258	63	–
IE3D100KX04.IE3D100LX04	FL-100	Δ_c	0.28	0.99	3240	328	65	3
IE3D100KX04.IE3D100LX04	FL-100	Δ 220–275 / Y 380–480	0.30/0.18	0.66	3390	328	65	–
IE3D112M04	FL-112	Δ_c	0.36	0.99	2800	418	66	3
IE3D112M04	FL-112	Δ 220–275 / Y 380–480	0.29/0.17	0.77	3260	418	66	–

Technical data for force-ventilated motors of size 132 or larger are available on request.

5.5.7 Brake

STOBER asynchronous motors can optionally be equipped with a spring-loaded brake that engages automatically when switching off the supply voltage and quickly brings the motor shaft to a stop. The spring-loaded brake is designed for dynamic applications with regular braking operations at high speed.

The spring-loaded brake can be released in the de-energized state using an optional manual release lever.

5.5.7.1 Power supply

DC voltage is needed to supply power to the spring-loaded brake. The DC voltage can be provided by an external DC voltage source or by rectifiers installed in the motor terminal box or control cabinet. If you use an external DC voltage source, connect a S14 K35 varistor (or comparable) in parallel to the brake coil to protect your machine from switching surges.

The brake coil is designed for 115 V DC (K38 brake type) or 127 V DC (L48 brake type) by default. Additional designs are optionally available.

Rectifiers installed in the motor terminal box can be supplied with AC voltage directly from the motor terminal board in many applications. During project configuration, ensure that the permitted input voltage U_{1rf} for the rectifier and the nominal voltage for the brake are not exceeded. The following interactions apply depending on the rectifier design:

- Half-wave rectifier: $U_{2rf} = 0.45 \times U_{1rf}$
- Bridge rectifier: $U_{2rf} = 0.9 \times U_{1rf}$
- Powerbox rectifier: $220 \text{ V AC} \leq U_{1rf} \leq 277 \text{ V AC}$

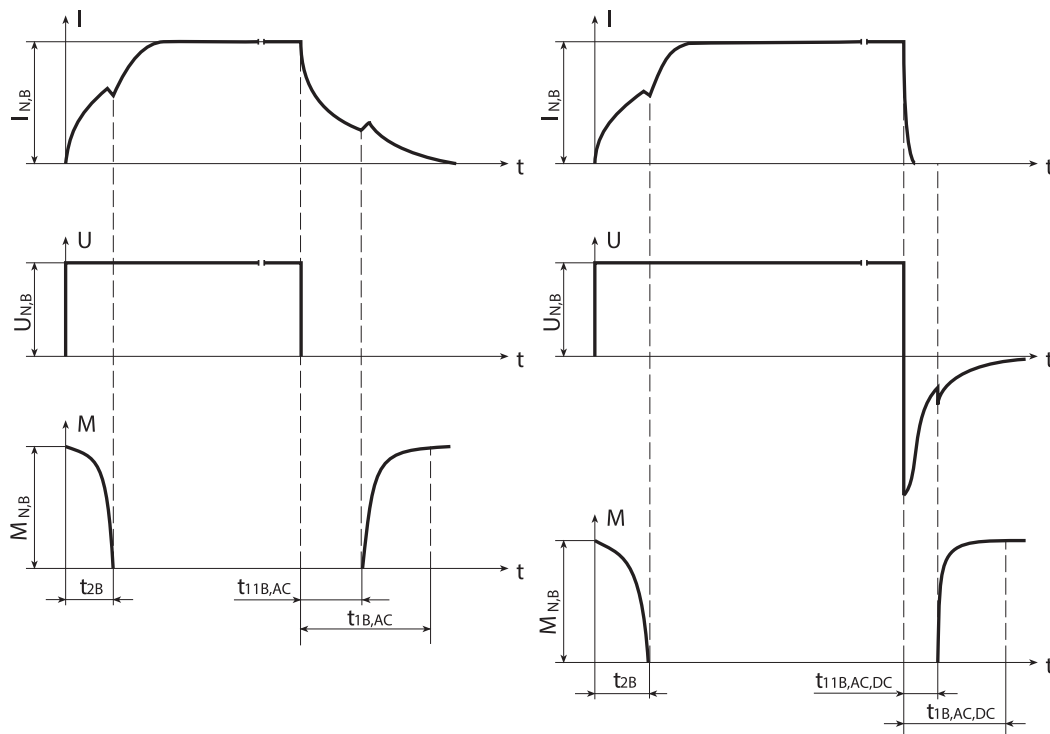
Supplying the rectifier with power from the motor terminal board is not permitted in the following applications:

- Motors operated on a frequency inverter;
- Motors with polarity reversal;
- Motors operated in star/delta starting circuit.

5.5.7.2 Connection

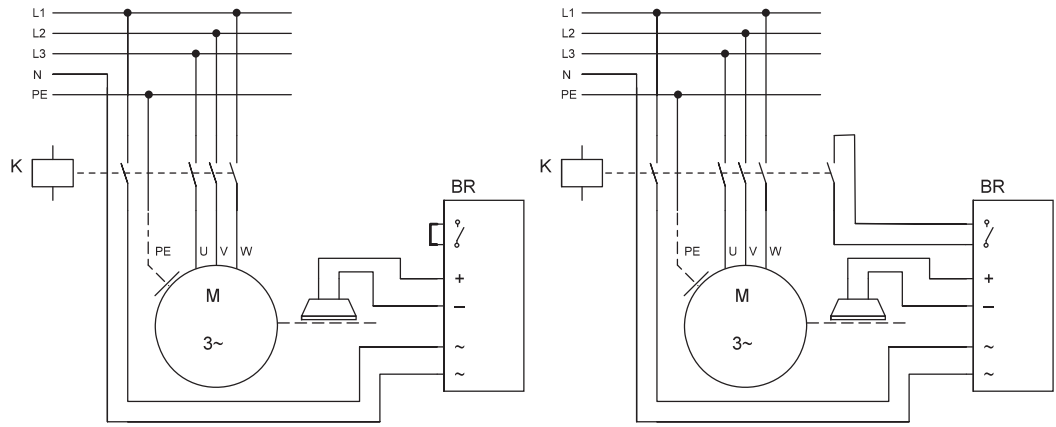
The spring-loaded brake engages once its power supply is switched off. In terms of the circuitry, the power supply can be switched off in two ways. The alternating current side of the rectifier always has to be switched. Simultaneously switching the alternating current side of the rectifier significantly reduces the linking time $t_{1,B}$ and trigger delay $t_{11,B}$ until the brake engages. The following diagrams and technical data illustrate this point.

For more information, refer to the connection plan included in the delivery of every motor.



Switching behavior of the brake during AC-side switching

Switching behavior of the brake during DC-side switching



Switching example for AC-side switching

Switching example for AC and DC-side switching

5.5.7.3 Powerbox rectifier

STOBER asynchronous motors with spring-loaded brake are equipped with a device called a Powerbox rectifier as standard. A Powerbox rectifier acts as a bridge rectifier during overexcitation and then as a half-wave rectifier afterwards. This provides the following advantages:

- Faster brake engaging;
- Longer intervals between maintenance because the maximum permitted air gap x_{Bmax} increases;
- Increase in brake life span.

The Powerbox rectifier also offers the advantage that it is possible to supply the rectifier with power from the motor terminal board in many applications for wide-range motors.

Features

Feature	Description
Installation location	IE3D63 – IE3D132 motors: Terminal box or control cabinet IE3D160 to IE3D200 motors: control cabinet
Input voltage	180 – 300 V AC \pm 0%, 50/60 Hz (applicable for a wide range of 220 – 275 V AC \pm 5%, 50/60 Hz)
Overexcitation time	350 ms \pm 10%
Conductor length	Maximum of 100 m (from Powerbox rectifier to brake coil)
Max. permitted output current at 45 °C	1.2 A continuously 2.4 A for 350 ms
Max. permitted output current at 75 °C	0.7 A continuously 1.4 A for 350 ms

The following table describes the technical data for spring-loaded brakes operated using a Powerbox rectifier.

Technical data

Motor	Type	$M_{N,B}$ [Nm]	$U_{N,B}$ [V]	U_{1rf} [V] 50-60 [Hz]	$x_{B,N}$ [mm]	x_{Bmax} [mm]	t_{2B} [ms]	$t_{11B,AC,DC}$ [ms]	$t_{11B,AC}$ [ms]	K_{Bpb}	Z_B [1/h]
IE3D063K_B.IE3D063M_B	K38-02R	2.5	115	220 – 275	0.20	0.8 – 1.02	26 – 21	9 – 11	30 – 33	3.0 – 4.1	3300
IE3D071K_B.IE3D071L_B	K38-02	5.0	115	220 – 275	0.20	0.8 – 1.02	26 – 21	9 – 11	30 – 33	3.0 – 4.1	3300
IE3D080K_B.IE3D080L_B	K38-03	10	115	220 – 275	0.20	1.36 – 1.75	31 – 26	13 – 16	78 – 85	3.9 – 5.2	2400
IE3D090LX_B.IE3D090S_B	K38-04	20	115	220 – 275	0.20	1.6 – 2.1	50 – 44	17 – 21	126 – 139	3.5 – 5.3	2400
IE3D100KX_B.IE3D100LX_B	K38-05	36	115	220 – 275	0.20	2.1 – 2.8	55 – 48	35 – 42	186 – 198	4.8 – 6.5	1500
IE3D112M_B	L48-14	60	127	220 – 275	0.30	2.5 – 3.4	89 – 76	54 – 65	359 – 390	4.6 – 6.2	300
IE3D132MX_B.IE3D132SX_B	L48-16	80	127	220 – 275	0.30	2.5 – 3.4	107 – 91	75 – 90	497 – 540	4.1 – 5.6	300
IE3D160LX_B.IE3D160MX_B	L48-18	150	127	220 – 275	0.40	2.5 – 3.4	179 – 152	91 – 110	608 – 660	4.7 – 6.3	300
IE3D180LX_B.IE3D180MX_B	L48-20	260	127	220 – 275	0.40	2.5 – 3.4	238 – 203	166 – 200	1105 – 1200	3.5 – 5.9	120
IE3D200LX_B	L48-25	400	127	220 – 275	0.50	2.5 – 3.4	286 – 244	224 – 270	1492 – 1620	4.3 – 6.0	60

Notes

Note that the performance data for the brake depends on the Powerbox rectifier input voltage U_{1rf} .

An explanation of the formula symbols can be found in the Chapter [▶ 13.1](#).

5.5.7.4 Half-wave or bridge rectifier

The DC voltage for the spring-loaded brake can also be converted from AC voltage by an optional half-wave rectifier or bridge rectifier.

Half-wave rectifiers are intended for applications lacking an AC voltage ≤ 277 V AC for the rectifier. If lower voltages are available, a bridge rectifier with better DC voltage quality should be used.

The following table describes the technical data for spring-loaded brakes operated using a half-wave or bridge rectifier.

Technical data

Motor	Type	$M_{N,B}$ [Nm]	P_{B20} [W]	$W_{B,Radj}$ [kJ]	$W_{B,R01}$ [kJ]	$x_{B,N}$ [mm]	$x_{B,max}$ [mm]	y_{Blim} [mm]	t_{2B} [ms]	$t_{11B,AC,DC}$ [ms]	$t_{11B,AC}$ [ms]	ΔJ_B [kgcm ²]	Δm_B [kg]
IE3D063K_B.IE3D063M_B	K38-02R	2.5	25	15000	7500	0.20	0.4	5.5	40	10	70	0.28	1.10
IE3D071K_B.IE3D071L_B	K38-02	5.0	25	15000	7500	0.20	0.4	5.5	40	10	70	0.28	1.10
IE3D080K_B.IE3D080L_B	K38-03	10	30	37500	12500	0.20	0.5	6.5	55	15	100	0.79	1.65
IE3D090LX_B.IE3D090S_B	K38-04	20	30	76000	19000	0.20	0.6	8.0	90	25	180	1.50	3.30
IE3D100KX_B.IE3D100LX_B	K38-05	36	48	112000	28000	0.20	0.6	10.0	110	25	220	3.85	4.95
IE3D112M_B	L48-14	60	50	215000	43000	0.30	0.8	6.0	150	65	390	6.93	5.72
IE3D132MX_B.IE3D132SX_B	L48-16	80	55	434000	62000	0.30	1.0	7.5	180	90	540	16.5	8.69
IE3D160LX_B.IE3D160MX_B	L48-18	150	85	540000	90000	0.40	1.0	8.0	300	110	660	31.9	13.2
IE3D180LX_B.IE3D180MX_B	L48-20	260	100	612000	76500	0.40	1.2	9.6	400	200	1200	80.3	21.2
IE3D200LX_B	L48-25	400	110	792000	88000	0.50	1.4	12.5	500	270	1620	220	32.0

An explanation of the formula symbols can be found in the Chapter [13.1](#).

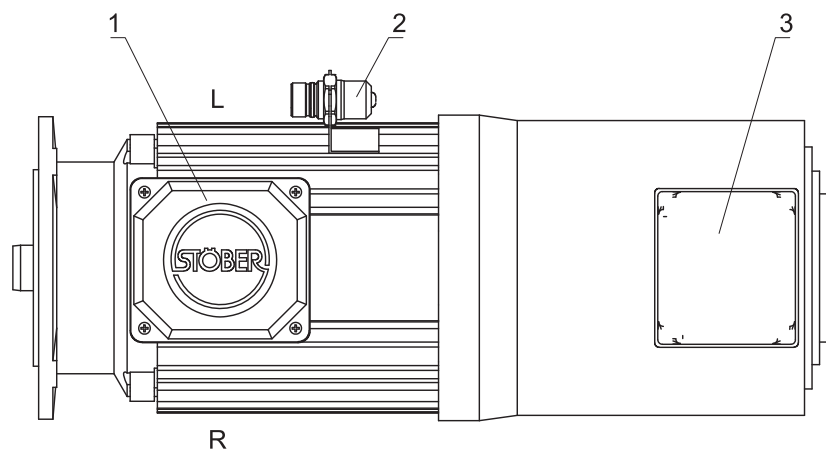
5.5.8 Connection method

5.5.8.1 Position of the connections

In the following figure, there are markings on both sides of the terminal box through which the connecting cables can be routed into the terminal box. Specify one of the two sides when placing your order. If the motor is installed in another mounting position, the position of the terminal box and optional connections changes accordingly.

You can find the position of the motor terminal box in relation to the geared motor in the corresponding chapter of this catalog.

You can find the dimensions of the terminal box in Chapter [5.3](#).



- 1 Motor terminal box
- 2 Encoder plug connector (optional)
- 3 Forced ventilation unit terminal box (optional)
- L Left side of the terminal box
- R Right side of the terminal box

5.5.8.2 Motor terminal box

The motor power connections and other connections are located in the terminal box.

In the terminal box, there are three metric tapped holes for screw connections. The tapped holes are closed with plugs. The diameter of the tapped holes depends on the size of the motor, as shown in the following table.

Size	1st bore	2nd bore	3rd bore
063	M20	M16	M12
071	M20	M16	M12
080	M20	M16	M12
090	M25	M20	M12
100	M25	M20	M12
112	M25	M20	M12
132	M32	M32	M20
160	M40	M40	M20
180	M40	M40	M20
200	M50	M50	M20

For the motor connection, use shielded cables and screw connections connected to the cable shielding in order to avoid EMC problems.


Power connection

The terminal box contains a terminal board with connections labeled in accordance with EN 60034-8. Terminal links are provided for a wye or delta connection. The terminal box contains 3 metric threaded holes for connection cable screw connections. The screw connections are not included in the scope of delivery.

The connection schema for the different connection types is shown in the following table.

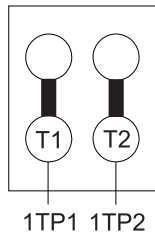
Circuit type	Connection schema
Delta connection	
Star connection	
Star/delta starting circuit	

Grounding conductor connection

For connecting the grounding conductor, the terminal box contains a grounding screw that is marked with the  symbol in accordance with IEC 60417-DB. The cross-section of the grounding conductor has to be at least as large as the cross-section of the lines in the power connection.

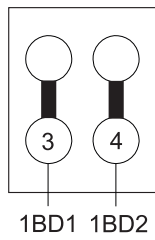
PTC thermistor connection

The terminal box contains connection terminals for the PTC thermistor for implementing thermal winding protection (optional).



Spring-loaded brake connection

The terminal box also contains connection terminals for the spring-loaded brake (optional).



5.5.8.3 Encoder connection

A plug connector with a quick lock is installed on the motor housing for the optional encoder connection. You can find the dimensions and position of the plug connector in Chapter [▶ 5.3]. You can find appropriate cables for the connection to the drive controller in Chapter [▶ 11].

In the following connection assignment, the colors of the motor-internal connecting wires are specified in accordance with IEC 60757.

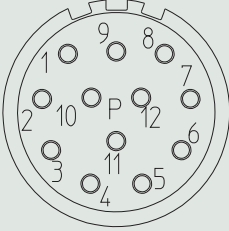
SSI digital encoder, plug connector size con.23

Connection diagram	Pin	Connection	Color
	1	Clock +	VT
	2	Up sense	WH GN
	3		
	4		
	5	Data -	PK
	6	Data +	GY
	7		
	8	Clock -	YE
	9		
	10	0 V GND	WH GN
	11		
	12	Up +	BN GN

Pin 2 is connected to pin 12 in the plug connector

HTL/TTL incremental encoder, plug connector size con.23

Color 1 of the motor-internal connecting wires applies up to motor size 80, color 2 applies starting with motor size 90.

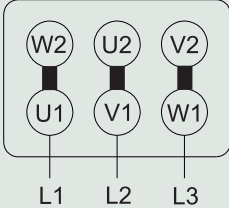
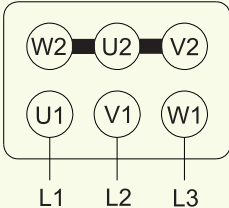
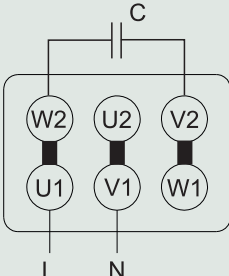
Connection diagram	Pin	Connection	Color 1	Color 2
	1	B -	PK	BK
	2	Up sense	-	YE
	3	N +	BU	PK
	4	N -	RD	WH
	5	A +	GN	GN
	6	A -	YE	BN
	7			
	8	B +	GY	GY
	9			
	10	0 V GND	WH	BU
	11	0 V GND	-	VT
	12	Up +	BN	RD

5.5.8.4 Forced ventilation unit terminal box


The power connections for the optional forced ventilation unit are located in a separate terminal box.

The terminal box contains a terminal board with connections labeled in accordance with EN 60034-8. Terminal links are provided for a wye or delta connection. The terminal box contains 3 metric threaded holes for connection cable screw connections. The screw connections are not included in the scope of delivery.

The connection types for the forced ventilation unit power supply are described in the following table.

Connection type	Connection schema
Delta connection	
Star connection	
Steinmetz connection with operating capacitor C	

The operating capacitor C for the Steinmetz connection is not included in the forced ventilation unit scope of delivery.

For connecting the grounding conductor, the terminal box contains a grounding screw that is marked with the  symbol in accordance with IEC 60417-DB. The cross-section of the grounding conductor has to be at least as large as the cross-section of the lines in the power connection.

5.6 Project configuration

5.6.1 Legal requirements

In many countries or economic regions, putting asynchronous motors on the market requires complying with certain laws. Below you can find information on a few legal requirements to be observed in conjunction with projecting STOBER asynchronous motors.

European Union

Asynchronous motors fall under the scope of the (Low Voltage) Directive 2014/35/EU and must bear the CE mark.

Asynchronous motors are also subject to (Ecodesign) Directive 2009/125/EC. The products offered in this catalog correspond to the current regulation on electric motors and speed controls (EU) 2019/1781 of 2019-10-01.

Accordingly, asynchronous motors brought onto the market on or after 2021-07-01 that have a nominal output voltage of 0.12 to 0.55 kW must meet at least energy efficiency class IE2.

Similarly, asynchronous motors brought onto the market on or after 2021-07-01 that have a nominal output voltage of 0.75 to 1000 kW must meet at least energy efficiency class IE3.

STOBER supplies motors with a nominal power of 0.12 kW – 0.55 kW in the energy efficiency class IE3 as well as motors with a nominal power of 0.75 kW – 45 kW, also in energy efficiency class IE3.

USA

Asynchronous motors brought onto the market in the United States are subject to the Energy Independence and Security Act of 2007 (EISA) under US law and must be registered with the US Department of Energy (DoE). This includes labeling the asynchronous motor's nameplate with the "ee" logo and the CC registration number.

Certificates and standards

The following certificates and standards are not required by law but are common in some countries:

- Registration with Underwriters Laboratory (UL). This includes labeling the asynchronous motor's nameplate with the CURus logo and registration number.
- Electrical design of the asynchronous motor in accordance with the NEMA-MG 1 standard in the United States.

Available combinations

STOBER Asynchronous motors are available in the following combinations in relation to the properties listed above:

Conformity/Certificate	Nominal frequency
CE	50 Hz
CE, cURus, NEMA	50/60 Hz
EISA, cURus	60 Hz (on request)

5.6.2 Operation on a drive controller

Drive controllers can adjust the speed of asynchronous motors to any value with minimal losses. In this chapter, you can find information on operating asynchronous motors above and below the nominal frequency.

Operation below the nominal frequency

Operating asynchronous motors with self-ventilation below approximately 60% of the nominal frequency requires limiting the motor current as well as the torque as a result. Otherwise the motor may overheat. This type of limiting is not necessary on motors with forced ventilation.

5.6.2.1 Operation above the nominal frequency

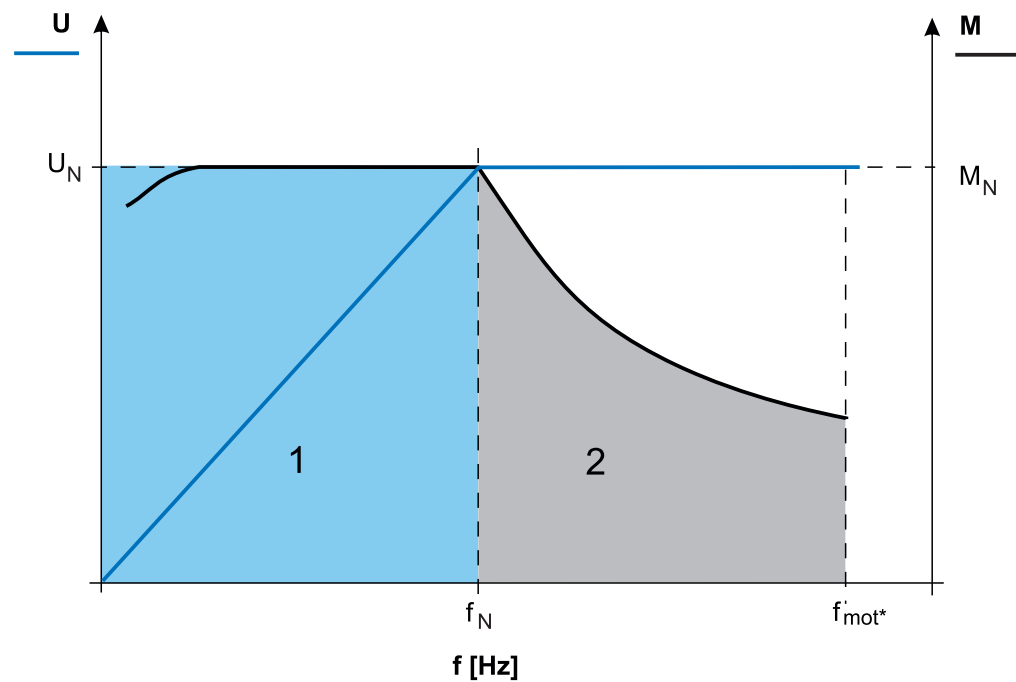
The motor can also be operated above its nominal frequency. Two basic operating modes for doing so are explained below:

- Operation in a field weakening range
- Operation per the 87 Hz curve

Operation in a field weakening range

If the motor is operated above its nominal frequency at a constant nominal voltage, operation is considered in the field weakening range. For this operating mode, the drive controller is configured to a maximum frequency that is greater than the nominal frequency (e.g. 80 Hz/400 V). Speed increases as the drive controller frequency increases; torque, in contrast, decreases proportionally because the flux in the motor drops.

You can operate the motor in the field weakening range using both a delta and a star connection.

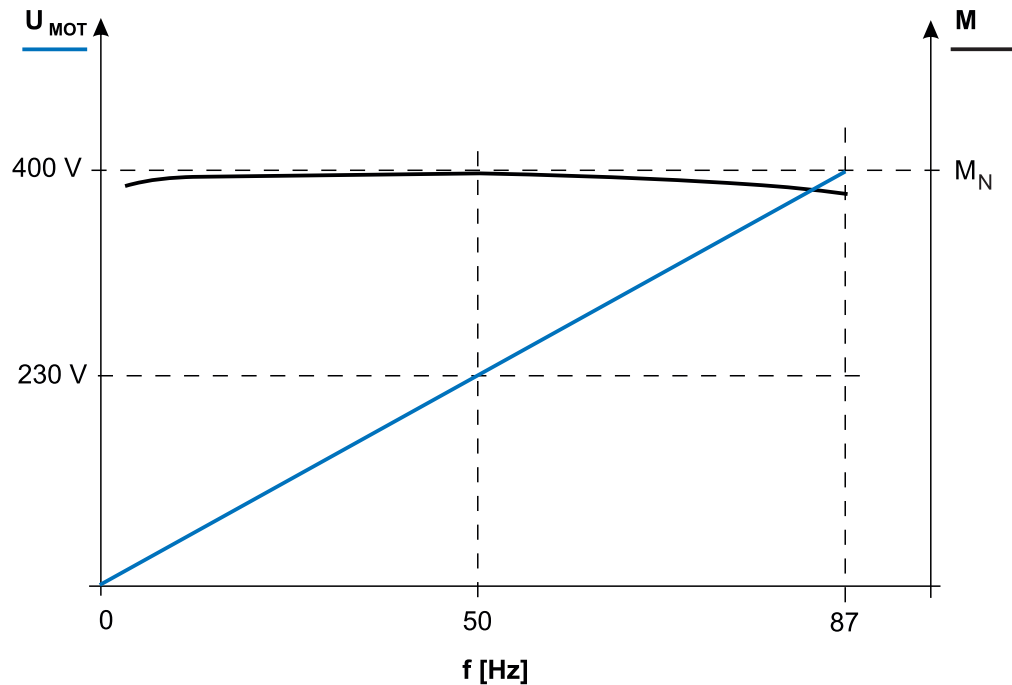


1 Constant torque range

2 Field weakening range

Operation per the 87 Hz curve

In this operating mode, the speed of the motor also increases proportionally to the motor voltage to a value above its nominal frequency. In this process, the torque remains almost constant. To this end, a 50 Hz, 230/400 V motor is connected with a delta setup, but the drive controller is configured to 87 Hz, 400 V. This can increase the speed by $\sqrt{3}$ times the nominal frequency (87 Hz) with virtually constant torque. In doing so, the motor voltage is also increased continuously so that the motor operates with constant flux instead of field weakening.



Keep the following information in mind in this context:

- The motor must be designed for operation per the 87 Hz characteristic. Keep this in mind when placing an order.
- Take the higher ($\sqrt{3}$ -times) current requirement of the motor when selecting the drive controller.
- You can find the connection schema for the delta connection in the chapter [▶ 5.5.8.2](#).

5.7 Further information

5.7.1 Directives and standards

STOBER asynchronous motors correspond to the following directives and standards:

- (Low Voltage) Directive 2014/35/EU
- (Ecodesign) Directive 2009/125/EC (if applicable)
- EN 60034-1:2010 + Cor.:2010
- EN 60204-1:2018
- EN 60038:2011

5.7.2 Marks and test symbols

STOBER asynchronous motors can be provided with the following marks and test symbols:



CE mark: The product meets the requirements of EU directives (standard).



cURus test symbol "Systems, Electrical Insulation - Component", registered with Underwriters Laboratories USA (optional).



ee logo: The asynchronous motor conforms to the Energy Independence and Security Act of 2007 (EISA) under US law and is registered with the US Department of Energy (DoE) under registration number CC301B (optional).

5.7.3 Additional documentation

Additional documentation related to the product can be found at

<http://www.stoeber.de/en/downloads/>

Enter the ID of the documentation in the Search field.

Documentation	ID
Operating manual for asynchronous motors	442577_en
Operating manual for asynchronous motor encoder	442025_en
Operating manual for brake for asynchronous motors	442015_en

6 SC6 Drive controllers

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6 Drive controllers

SC6

6.1 Overview

Our more compact version for the encoderless Lean motor

Features

- Single or double-axis controller with a nominal output current up to 19 A and 250% overload capacity
- Sensorless position control of STOBBER Lean motors
- Control of rotary synchronous servo motors, asynchronous motors and torque motors
- One Cable Solution EnDat 3
- Electronic motor nameplate via EnDat encoder interfaces
- Integrated EtherCAT or PROFINET communication
- STO safety technology using terminals or STO and SS1 using FSoE or PROFIsafe: SIL 3, PL e (Cat. 4)
- Integrated brake control
- Single-ended nominal power consumption on double-axis controllers for operation of motors with different power
- Energy supply through direct power supply
- Flexible DC link connection for multi-axis applications

6.1.1 Features

The compact stand-alone SC6 drive controller allows for sensorless control of Lean motors of the LM series. These motors provide energy efficiency at the performance level of synchronous servo motors. They also guarantee high investment protection, thanks to energy efficiency class IE5 and the corresponding higher efficiency compared to IE4 asynchronous motors. However, the SC6 can also be used in combination with asynchronous motors or synchronous servo motors with encoders (e.g. the EZ series). SC6 is available in three sizes with a nominal output current of up to 19 A: Sizes 0 and 1 as a double-axis controller, size 2 as a single-axis controller.

The optimized vector control, sensorless vector control, U/f slip-compensated and U/f controller control types are available for use with asynchronous motors.



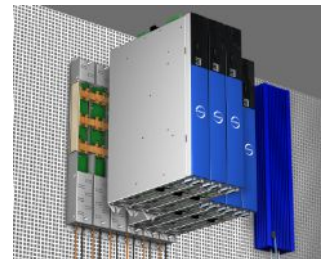
The compact SC6 for Lean motors of the LM series

As small as a paperback

You save valuable space in your control cabinet because, with a width of just 45 mm, this drive controller is the most compact solution on the market. It offers all the features that a designer requires.

Quick DC-Link

The drive controllers have the option of a DC link connection. This technology makes it possible for the regenerative production of energy from one drive to be used as motor energy by another drive. The Quick DC-Link rear structure element has been developed to set up a reliable and efficient rail connection to the DC link connection. This optionally available accessory connects the DC links of the individual drive controllers by means of copper rails that can carry a load of up to 200 A. The rails can be attached without any tools using quick fastening clamps.



Perfectly adapted combinations

SC6 drive controllers can be combined with the STOBER SI6 and SD6 series as needed. For the general energy supply, the drive controllers from the SC6, SI6 and SD6 series are connected to each other using Quick DC-Link modules.

Tailored energy usage

When using double-axis modules, the unused power reserves of one axis can be used for other axes.

Fewer clicks, less wiring

The installation of the drive controller is as easy as you could imagine. There is no difficult wiring. Even if you are connecting the drive controllers in a DC link, the patented Quick DC-Link modules allow for a simple "click" into the standard copper rails as well as the simple installation and connection of the drive controllers.

Safety functions

The safety concept of the drive controller is based on the STO (Safe Torque Off) function. The concept corresponds to SIL 3 according to DIN EN 61800-5-2 and PL e (Cat. 4) according to DIN EN ISO 13849-1. For double-axis controllers, the STO safety function has a two-channel structure that acts upon both axes. For connection to a higher-level safety circuit, different interfaces are available (terminals, FSoE or PROFIsafe).

Heavy duty

There is an extremely robust design concealed behind the elegant exterior. All components—from the stable, well-shielded sheet steel housing to the motor connectors—far exceed the set values of industry standards. The inside is also anything but small-scale: ample computer capacities, high-quality components, careful workmanship.

6.1.2 Software components**Project configuration and commissioning**

The 6th generation of DriveControlSuite project configuration and commissioning software has all the functions for the efficient use of drive controllers in single-axis and multi-axis applications. The program guides you step by step through the complete project configuration and parameterization process using wizards.

Open communication

The Ethernet-based EtherCAT and PROFINET fieldbus systems are available in the drive controller.

Applications

A drive-based application is recommended for the decentralized motion control of sophisticated machines.

The drive-based application package from STOBBER is the right choice wherever universal and flexible solutions are needed. The Drive Based application provides drive-based motion control for positioning, velocity and torque/force with the PLCopen Motion Control command set. These standard commands have been combined into operating modes for different applications and supplemented with additional functions such as motion block linking, cams and much more. For the command operating mode, all properties of the movements are specified directly by the controller. The properties of the movements in the drive are predefined in the motion block operating mode so that only a start signal is necessary to perform the movement. Linking can be used to define complete motion sequences. There is a separate operating mode available for applications controlled by velocity or torque/force such as pumps, fans or conveyor belts. This also allows for operation without a controller.

In addition, the CiA 402 and PROFIdrive applications are also available, which include both the controller-based and drive-based operating modes and application classes.

Furthermore, programming based on IEC 61131-3 with CFC can be used to create new applications or expand existing ones.

6.1.3 Application training

STOBBER offers a multi-level training program that is essentially focused on the drive controller.

G6 Basic

Training content: System overview, installation and commissioning of the drive controller. Use of option modules. Parameterization, commissioning and diagnostics using the commissioning software. Remote maintenance. Basics of controller optimization. Configuration of the drive train. Integrated software functions. Software applications. Connection to a higher-level controller. Basics of safety technology. Practical exercises on training topics.

Software used: DriveControlSuite.

G6 Customized

Training content: Special knowledge for regulating, control and safety technology. Electronic cam disk. Practical exercises on training topics.

6.2 Technical data

Technical data for the drive controller can be found in the following chapters.

6.2.1 Type designation

SC	6	A	0	6	2	Z
----	---	---	---	---	---	---

Tab. 1: Example code for type designation

Code	Designation	Design
SC	Series	
6	Generation	Generation 6
A	Version	
0 – 2	Size	
6	Power output stage	Power output stage within the size
2	Axis controller	Double-axis controller
1		Single-axis controller
Z	Safety technology	SZ6: Without safety technology
R		SR6: STO using terminals
U		SU6: STO and SS1 using PROFIsafe
Y		SY6: STO and SS1 using FSoE

Tab. 2: Meaning of the example code

6.2.2 Sizes

Type	ID No.	Size	Axis controller
SC6A062	56690	Size 0	Double-axis controller
SC6A162	56691	Size 1	Double-axis controller
SC6A261	56692	Size 2	Single-axis controller

Tab. 3: Available SC6 types and sizes



SC6 in sizes 0 to 2

Note that the basic device is delivered without terminals. Suitable terminal sets are available separately for each size.

6.2.3 General technical data

The following information applies to all device types.

Device features	
Protection class of the device	IP20
Protection class of the installation space	At least IP54
Protection class	Protection class I in accordance with EN 61140
Radio interference suppression	Integrated line filter in accordance with EN 61800-3, interference emission class C3
Overvoltage category	III in accordance with EN 61800-5-1
Marks and test symbols	CE, cULus, RoHS

Tab. 4: Device features

Transport and storage conditions	
Storage/transport temperature	-20 °C to +70 °C Maximum change: 20 K/h
Relative humidity	Maximum relative humidity 85%, non-condensing
Vibration (transport) in accordance with EN 60068-2-6	5 Hz ≤ f ≤ 9 Hz: 3.5 mm 9 Hz ≤ f ≤ 200 Hz: 10 m/s ² 200 Hz ≤ f ≤ 500 Hz: 15 m/s ²
Fall height for freefall ¹ Weight < 100 kg in accordance with EN 61800-2 (or IEC 60721-3-2, class 2M1)	0.25 m

Tab. 5: Transport and storage conditions

Operating conditions	
Surrounding temperature during operation	0 °C to 45 °C with nominal data 45 °C to 55 °C with derating -2.5% / K
Relative humidity	Maximum relative humidity 85%, non-condensing
Installation altitude	0 m to 1000 m above sea level without restrictions 1000 m to 2000 m above sea level with -1.5%/100 m derating
Pollution degree	Pollution degree 2 in accordance with EN 50178
Ventilation	Installed fan
Vibration (operation) in accordance with EN 60068-2-6	5 Hz ≤ f ≤ 9 Hz: 0.35 mm 9 Hz ≤ f ≤ 200 Hz: 1 m/s ²

Tab. 6: Operating conditions

Discharge times	
Self-discharge of DC link	15 min

Tab. 7: Discharge times of the DC link circuit

6.2.4 Electrical data

The electrical data of the available SC6 sizes as well as the properties of the brake chopper can be found in the following sections.

Information

For the time span between energizing two devices, note that:

- Direct, repeat activation of the supply voltage is possible for cyclical power-on/power-off operation.
- A time span of > 15 minutes must be observed between two energizing processes during continuous, cyclical power-on/power-off operation with increased charging capacity.

Information

The STO safety function is available for safe stopping as an alternative to continuous, cyclical power-on/power-off operation.

An explanation of the formula symbols used can be found in the chapter [\[13.1\]](#).

6.2.4.1 Control unit

Electrical data	All types
U_{1CU}	24 V _{DC} +20%/–15%
I_{1maxCU}	0.5 A

Tab. 8: Control unit electrical data

6.2.4.2 Power unit: Size 0

Electrical data	SC6A062
U_{1PU}	$3 \times 400 V_{AC}$, +32% / -50%, 50/60 Hz; $3 \times 480 V_{AC}$, +10% / -58%, 50/60 Hz
f_{2PU}	0 – 700 Hz
U_{2PU}	0 – max. U_{1PU}
$U_{2PU,ZK}$	$\sqrt{2} \times U_{1PU}$
C_{PU}	270 μ F
$C_{N,PU}$	1400 μ F
C_{maxPU}	1880 μ F

Tab. 9: SC6 electrical data, size 0

The charging capacity depends on the time between two energizing processes:

Information

For the maximum charging capacity C_{maxPU} , a time span of ≥ 15 min must be maintained between two energizing processes.

Nominal currents up to +45 °C (in the control cabinet)

Electrical data	SC6A062
$f_{PWM,PU}$	4 kHz
$I_{1N,PU}$	10 A
$I_{2N,PU}$	2×4.5 A
I_{2maxPU}	210% for 2 s; 150% for 30 s

Tab. 10: SC6 electrical data, size 0, for 4 kHz clock frequency

Electrical data	SC6A062
$f_{PWM,PU}$	8 kHz
$I_{1N,PU}$	8.9 A
$I_{2N,PU}$	2×4 A
I_{2maxPU}	250% for 2 s; 200% for 5 s

Tab. 11: SC6 electrical data, size 0, for 8 kHz clock frequency

Electrical data	SC6A062
U_{onCH}	780 – 800 V_{DC}
U_{offCH}	740 – 760 V_{DC}
R_{2minRB}	100 Ω
P_{maxRB}	6.4 kW
P_{effRB}	2.9 kW

Tab. 12: Brake chopper electrical data, size 0

6.2.4.3 Power unit: Size 1

Electrical data	SC6A162
U_{1PU}	$3 \times 400 V_{AC}$, +32% / -50%, 50/60 Hz; $3 \times 480 V_{AC}$, +10% / -58%, 50/60 Hz
f_{2PU}	0 – 700 Hz
U_{2PU}	0 – max. U_{1PU}
$U_{2PU,ZK}$	$\sqrt{2} \times U_{1PU}$
C_{PU}	940 μ F
$C_{N,PU}$	1400 μ F
C_{maxPU}	1880 μ F

Tab. 13: SC6 electrical data, size 1

The charging capacity depends on the time between two energizing processes:

Information

For the maximum charging capacity C_{maxPU} , a time span of ≥ 15 min must be maintained between two energizing processes.

Nominal currents up to +45 °C (in the control cabinet)

Electrical data	SC6A162
$f_{PWM,PU}$	4 kHz
$I_{1N,PU}$	23.2 A
$I_{2N,PU}$	2×10 A
I_{2maxPU}	210% for 2 s; 150% for 30 s

Tab. 14: SC6 electrical data, size 1, for 4 kHz clock frequency

Electrical data	SC6A162
$f_{PWM,PU}$	8 kHz
$I_{1N,PU}$	20.9 A
$I_{2N,PU}$	2×9 A
I_{2maxPU}	250% for 2 s; 200% for 5 s

Tab. 15: SC6 electrical data, size 1, for 8 kHz clock frequency

Electrical data	SC6A162
U_{onCH}	$780 - 800 V_{DC}$
U_{offCH}	$740 - 760 V_{DC}$
R_{2minRB}	47 Ω
P_{maxRB}	13.6 kW
P_{effRB}	6.2 kW

Tab. 16: Brake chopper electrical data, size 1

6.2.4.4 Power unit: Size 2

Electrical data	SC6A261
U_{1PU}	$3 \times 400 V_{AC}$, +32% / -50%, 50/60 Hz; $3 \times 480 V_{AC}$, +10% / -58%, 50/60 Hz
f_{2PU}	0 – 700 Hz
U_{2PU}	0 – max. U_{1PU}
$U_{2PU,ZK}$	$\sqrt{2} \times U_{1PU}$
C_{PU}	940 μF
$C_{N,PU}$	1400 μF
C_{maxPU}	1880 μF

Tab. 17: SC6 electrical data, size 2

The charging capacity depends on the time between two energizing processes:

Information

For the maximum charging capacity C_{maxPU} , a time span of ≥ 15 min must be maintained between two energizing processes.

Nominal currents up to +45 °C (in the control cabinet)

Electrical data	SC6A261
$f_{PWM,PU}$	4 kHz
$I_{1N,PU}$	22.6 A
$I_{2N,PU}$	19 A
I_{2maxPU}	210% for 2 s; 150% for 30 s

Tab. 18: SC6 electrical data, size 2, for 4 kHz clock frequency

Electrical data	SC6A261
$f_{PWM,PU}$	8 kHz
$I_{1N,PU}$	17.9 A
$I_{2N,PU}$	15 A
I_{2maxPU}	250% for 2 s; 200% for 5 s

Tab. 19: SC6 electrical data, size 2, for 8 kHz clock frequency

Electrical data	SC6A261
U_{onCH}	780 – 800 V_{DC}
U_{offCH}	740 – 760 V_{DC}
R_{2minRB}	47 Ω
P_{maxRB}	13.6 kW
P_{effRB}	6.2 kW

Tab. 20: Brake chopper electrical data, size 2

6.2.4.5 DC link connection

The charging capacity of the drive controllers can be increased by a DC link connection only if the power grid supply is connected to all drive controllers simultaneously.

6.2.4.6 Single-ended nominal power consumption on double-axis controllers

Operating two motors on one double-axis controller makes it possible to operate one of the motors with a continuous current above the nominal current of the drive controller if the continuous current of the second connected motor is lower than the nominal current of the drive controller. This enables economical combinations of double-axis controllers and motors.

The nominal output current for axis B can be determined using the following formula if the output current for axis A is known:

Example 1

$$I_{2PU(B)} = I_{2N,PU} - (I_{2PU(A)} - I_{2N,PU}) \times \frac{3}{5} \quad \text{where} \quad 0 \leq I_{2PU(A)} \leq I_{2N,PU}$$

Example 2

$$I_{2PU(B)} = I_{2N,PU} - (I_{2PU(A)} - I_{2N,PU}) \times \frac{5}{3} \quad \text{where} \quad I_{2N,PU} \leq I_{2PU(A)} \leq 1,6 \times I_{2N,PU}$$

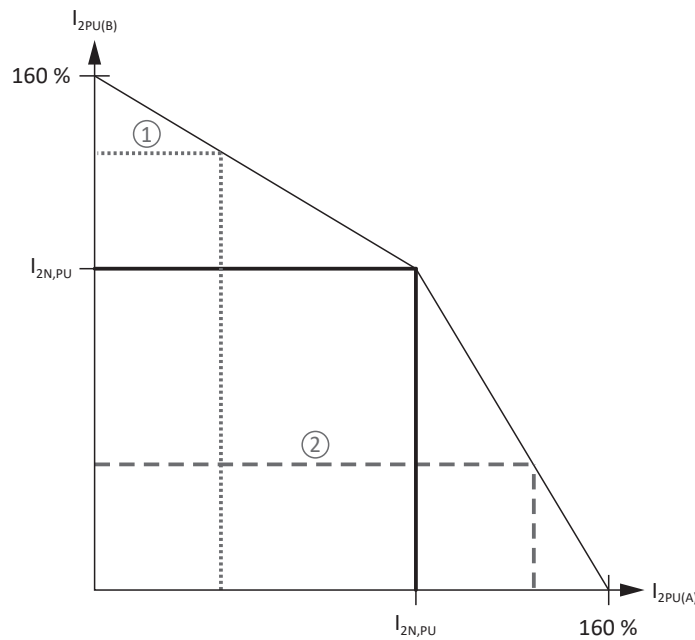


Fig. 1: Asymmetric load on double-axis controllers

Information

Note that the available maximum currents I_{2maxPU} of the axis controllers are also relative to the nominal output current $I_{2N,PU}$ for single-ended nominal power consumption.

6.2.4.7 Power loss data in accordance with EN 61800-9-2

Type	Nominal current $I_{2N,PU}$	Apparent power	Absolute losses $P_{V,CU}^2$	Operating points ³								IE class ⁴	Comparison ⁵
				(0/25)	(0/50)	(0/100)	(50/25)	(50/50)	(50/100)	(90/50)	(90/100)		
				Relative losses									
	[A]	[kVA]	[W]	[%]									
SC6A062	4.5	6.2	Max. 10	1.34	1.49	1.86	1.40	1.63	2.19	1.84	2.77	IE2	
SC6A162	10	13.9	Max. 10	0.76	0.92	1.43	0.81	1.04	1.75	1.22	2.29	IE2	
SC6A261	19	13.2	10	0.77	0.95	1.56	0.82	1.08	1.89	1.25	2.43	IE2	
				Absolute losses									
	[A]	[kVA]	[W]	P_V [W]									[%]
SC6A062	4.5	6.2	Max. 10	83.2	92.5	115.2	86.7	100.8	135.8	113.9	171.7	IE2	36.0
SC6A162	10	13.9	Max. 10	105.5	128.3	198.8	113.1	145.1	243.5	170.1	318.7	IE2	40.8
SC6A261	19	13.2	Max. 10	101.2	125.8	206.1	108.5	142.0	249.5	165.6	320.4	IE2	41.0

Tab. 21: Power loss data of the SC6 drive controller in accordance with EN 61800-9-2

General conditions

The specified losses apply to a drive controller. They apply to both axes together in the case of double-axis controllers.

The loss data applies to drive controllers without any accessories.

The power loss calculation is based on a three-phase supply voltage with 400 V_{AC}/50 Hz.

The calculated data includes a supplement of 10% in accordance with EN 61800-9-2.

The power loss specifications refer to a clock frequency of 4 kHz.

The absolute losses for a power unit that is switched off refer to the 24 V_{DC} power supply of the control electronics.

6.2.4.8 Power loss data of accessories

If you intend to order the drive controller with accessory parts, losses increase as follows.

Type	Absolute losses P_V [W]
SR6 safety module	1
SY6 or SU6 safety module	2

Tab. 22: Absolute losses of the accessories

Information

Note the absolute power loss of the encoder (usually < 3 W) and of the brake when designing as well.

Loss specifications for other optional accessories can be found in the technical data of the respective accessory part.

² Absolute losses for a power unit that is switched off

³ Operating points for relative motor stator frequency in % and relative torque current in %

⁴ IE class in accordance with EN 61800-9-2

⁵ Comparison of the losses for the reference related to IE2 in the nominal point (90, 100)

6.2.5 Cycle times

Possible cycle times can be found in the following table.

Type	Cycle times	Relevant parameters
Application	250 μ s, 500 μ s, 1 ms, 2 ms, 4 ms, 8 ms	Adjustable in A150
EtherCAT fieldbus, cyclical communication	250 μ s, 500 μ s, 1 ms, 2 ms, 4 ms, 8 ms	Adjustable in A150
PROFINET RT fieldbus, cyclical communication	1 ms, 2 ms, 4 ms, 8 ms	Adjustable in A150
PROFINET IRT fieldbus, cyclical communication	1 ms, 2 ms, 4 ms	Adjustable in A150
Motion core (movement calculation)	250 μ s	—
Control cascade	62.5 μ s, 125 μ s	Depending on B24

Tab. 23: Cycle times

6.2.6 Derating

When dimensioning the drive controller, observe the derating of the nominal output current as a function of the clock frequency, surrounding temperature and installation altitude. There is no restriction for a surrounding temperature from 0 °C to 45 °C and an installation altitude of 0 m to 1000 m. The details given below apply to values outside these ranges.

6.2.6.1 Effect of the clock frequency

Changing the clock frequency f_{PWM} affects the amount of noise produced by the drive, among other things. However, increasing the clock frequency results in increased losses. During project configuration, define the highest clock frequency and use it to determine the nominal output current $I_{2N,PU}$ for dimensioning the drive controller.

Type	$I_{2N,PU}$ 4 kHz [A]	$I_{2N,PU}$ 8 kHz [A]	$I_{2N,PU}$ 16 kHz [A]
SC6A062	2 × 4.5	2 × 4	2 × 3
SC6A162	2 × 10	2 × 9	2 × 5
SC6A261	19	15	8

Tab. 24: Nominal output current $I_{2N,PU}$ dependent on the clock frequency

6.2.6.2 Effect of the surrounding temperature

Derating as a function of the surrounding temperature is determined as follows:

- 0 °C to 45 °C: No restrictions ($D_T = 100\%$)
- 45 °C to 55 °C: Derating $-2.5\%/K$

Example

The drive controller needs to be operated at 50 °C.

The derating factor D_T is calculated as follows

$$D_T = 100\% - 5 \times 2.5\% = 87.5\%$$

6.2.6.3 Effect of the installation altitude

Derating as a function of the installation altitude is determined as follows:

- 0 m to 1000 m: No restriction ($D_{IA} = 100\%$)
- 1000 m to 2000 m: Derating $-1.5\%/100$ m

Example

The drive controller needs to be installed at an altitude of 1500 m above sea level.

The derating factor D_{IA} is calculated as follows:

$$D_{IA} = 100\% - 5 \times 1.5\% = 92.5\%$$

6.2.6.4 Calculating the derating

Follow these steps for the calculation:

1. Determine the highest clock frequency (f_{PWM}) that will be used during operation and use it to determine the nominal current $I_{2N,PU}$.
2. Determine the derating factors for installation altitude and surrounding temperature.
3. Calculate the reduced nominal current $I_{2N,PU(red)}$ in accordance with the following formula:

$$I_{2N,PU(red)} = I_{2N,PU} \times D_T \times D_{IA}$$

Example

A drive controller of type SC6A062 needs to be operated at a clock frequency of 8 kHz at an altitude of 1500 m above sea level and a surrounding temperature of 50 °C.

The nominal current of the SC6A062 at 8 kHz is 4 A per axis. The derating factor D_T is calculated as follows:

$$D_T = 100\% - 5 \times 2.5\% = 87.5\%$$

The derating factor D_{IA} is calculated as follows:

$$D_{IA} = 100\% - 5 \times 1.5\% = 92.5\%$$

The output current of importance for the project configuration is:

$$I_{2N,PU(red)} = 4 \text{ A} \times 0.875 \times 0.925 = 3.24 \text{ A}$$

6.2.7 Dimensions

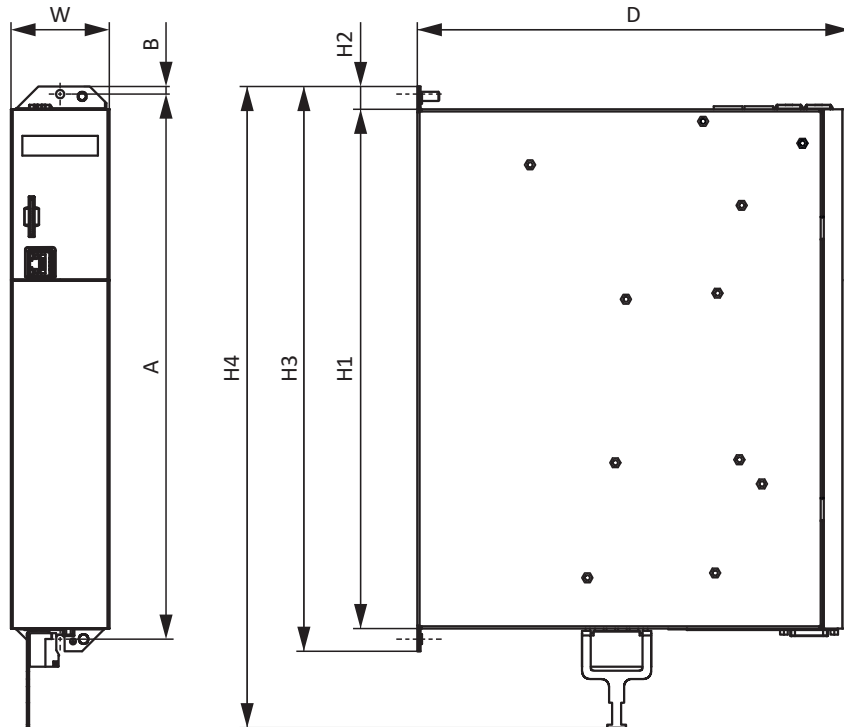


Fig. 2: SC6 dimensional drawing

Dimension			Size 0	Size 1	Size 2
Drive controller	Width	W	45	65	
	Depth	D	265	286	
	Body height	H1	343		
	Fastening clip height	H2	15		
	Height incl. fastening clips	H3	373		
	Total height incl. shield connection	H4	423		
	Fastening holes (M5)	Vertical distance	A	360+2	
Vertical distance to the upper edge		B	5		

Tab. 25: SC6 dimensions [mm]

6.2.8 Weight

Type	Weight without packaging [g]	Weight with packaging [g]
SC6A062	3600	5200
SC6A162	5300	6700
SC6A261	5200	6400

Tab. 26: SC6 weight [g]

6.2.9 Minimum clearances

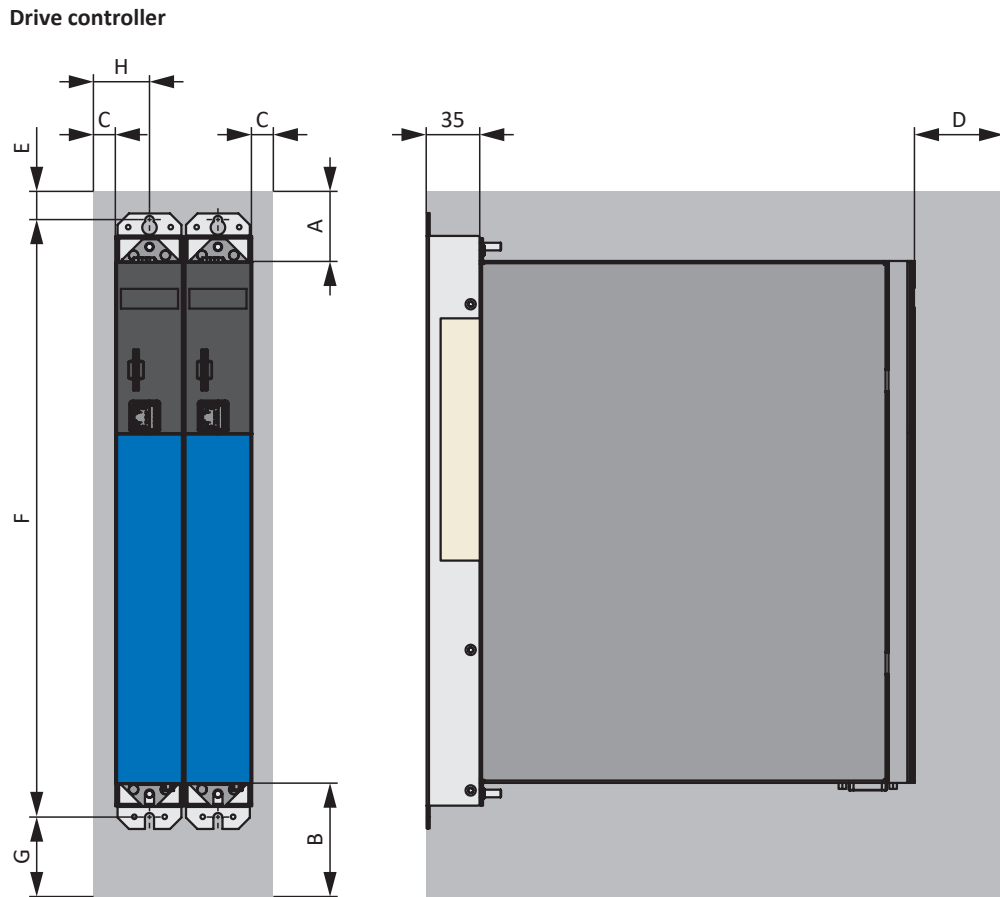


Fig. 3: Minimum clearances

The specified dimensions relate to the outer edges of the drive controller.

Minimum clearance	A (above)	B (below)	C (on the side)	D (in front)
All sizes	100	200	5	50 ⁶

Tab. 27: Minimum clearances [mm]

Dimension	E	F	G	H
SC6A062	73.5	393+2	approx. 174.5	27.5
SC6A162	73.5	393+2	approx. 174.5	37.5
SC6A261				

Tab. 28: Dimensions [mm]

Chokes and filters

Avoid installation below drive controllers or supply modules. For installation in a control cabinet, a distance of approximately 100 mm to other neighboring components is recommended. This distance ensures proper heat dissipation for chokes and filters.

Braking resistors

Avoid installation below drive controllers or supply modules. In order for heated air to flow out unimpeded, a minimum clearance of approximately 200 mm must be maintained in relation to neighboring components or walls and approximately 300 mm must be maintained to components above or ceilings.

6.3 Drive controller/motor combinations

Parameterization of a STÖBER drive controller is remarkably easy, especially in combination with four-pole STÖBER asynchronous motors. The motor is fully typed by inputting just the motor size (e.g. 90L) and its wiring (star or delta). A delta connection (measurement point 230 V, 50 Hz) is available for motors up to 3 kW (size 100). By increasing the voltage at higher frequencies, the full torque can be drawn through the motor up to 87 Hz. It usually makes sense to take this expanded speed adjustment range into account when selecting the gear unit. You can find more detailed information in the chapter [\[▶ 5.6\]](#).

An explanation of the formula symbols used can be found in the chapter [\[▶ 13.1\]](#).

									SC6A062	SC6A162	SC6A261
									$I_{2N,PU}$ [A] ($f_{PWM,PU} = 4$ kHz)		
	f_T [Hz]	pz	Con- nection	P_N [kW]	n_N [rpm]	M_N [Nm]	M_k/M_N	I_N [A]	4.5	10	19
Δ 230 V / Y 400 V motor winding									$I_{2N,PU} / I_N$		
IE3D080L04	50	4	Y	0.75	1445	5.0	3.7	1.7	2.6		
IE3D080L04	87	4	Δ	1.3	2503	5.0	3.7	2.94	1.5		
IE3D090S04	50	4	Y	1.1	1440	7.3	3.7	2.5	1.8		
IE3D090S04	87	4	Δ	1.91	2494	7.3	3.7	4.33	1.0		
IE3D090LX04	50	4	Y	1.5	1455	9.8	4.9	3.4	1.3		
IE3D090LX04	87	4	Δ	2.6	2503	9.8	4.9	5.89		1.7	
IE3D100KX04	50	4	Y	2.2	1450	14.5	3.8	4.55		2.2	
IE3D100KX04	87	4	Δ	3.81	2511	14.5	3.8	7.88		1.3	
IE3D100LX04	50	4	Y	3.0	1450	19.8	4	6.35		1.6	
IE3D100LX04	87	4	Δ	5.2	2511	19.8	4	11			1.7
IE3D112M04	50	4	Δ	4.0	1465	26.1	4.5	7.9		1.3	
IE3D132SX04	50	4	Δ	5.5	1465	36	3.3	10		1.0	1.9
IE3D132MX04	50	4	Δ	7.5	1470	49	3.9	16			1.2

6.4 Accessories

You can find information about the available accessories in the following chapters.

6.4.1 Safety technology

Information

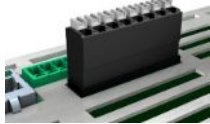
The drive controller is delivered in the standard design without safety technology (option SZ6). If you want a drive controller with integrated safety technology, you must order it together with the drive controller. The safety modules are an integrated part of the drive controllers and must not be modified.

SZ6 option – Without safety technology

ID No. 56660

Design without safety technology.

SR6 safety module – STO using terminals



ID No. 56661

Optional accessory for the use of the Safe Torque Off safety function (STO) in safety-relevant applications (PL e, SIL 3) in accordance with EN ISO 13849-1 and EN 61800-5-2. Connection to a higher-level safety circuit via terminal X12.

SY6 safety module – STO and SS1 using FSoE



ID No. 56662

Optional accessory for the use of the Safe Torque Off (STO) and Safe Stop 1 (SS1) safety functions in safety-relevant applications (PL e, SIL 3) in accordance with EN ISO 13849-1 and EN 61800-5-2. Connection to the higher-level safety circuit using Fail Safe over EtherCAT (FSoE).

SU6 safety module – STO and SS1 using PROFIsafe



ID No. 56696

Optional accessory for the use of the Safe Torque Off (STO) and Safe Stop 1 (SS1) safety functions in safety-relevant applications (PL e, SIL 3) in accordance with EN ISO 13849-1 and EN 61800-5-2. Connection to a higher-level safety circuit via PROFINET (PROFIsafe).

6.4.2 Communication

The drive controller has two interfaces for the fieldbus connection on the top of the device as well as an Ethernet service interface on the front of the device. Cables for the connection are available separately.

EtherCAT or PROFINET fieldbus system

EtherCAT 

PROFI
NET 

Please specify the desired fieldbus system when placing your order for the base device, since the fieldbus communication is defined using the firmware.

EtherCAT cables



Ethernet patch cable, CAT5e, yellow.

The following designs are available:

ID No. 49313: Length approx. 0.25 m.

ID No. 49314: Length approx. 0.5 m.

PC connecting cables



ID No. 49857

Cable for connecting the X9 service interface to the PC, CAT5e, blue, 5 m.

USB 2.0 Ethernet adapter



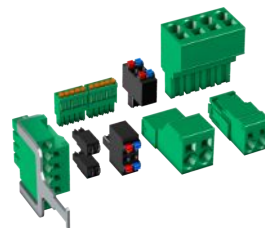
ID No. 49940

Adapter for connecting Ethernet to a USB port.

6.4.3 Terminal set

For connection, you need the fitting terminal set for each SC6 drive controller.

Terminal set for drive controllers – SZ6 option (without safety technology), SU6 option (STO and SS1 using PROFIsafe) or SY6 option (STO and SS1 using FSoE)



(Fig. similar)

The following designs are available:

ID No. 138652

Terminal set for SC6A062Z/U/Y.

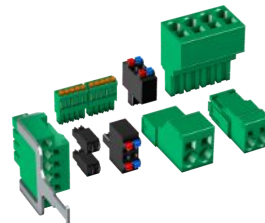
ID No. 138653

Terminal set for SC6A162Z/U/Y.

ID No. 138654

Terminal set for SC6A261Z/U/Y.

Terminal set for drive controllers – SR6 option (STO via terminals)



(Fig. similar)

The following designs are available:

ID No. 138680

Terminal set for SC6A062R.

ID No. 138681

Terminal set for SC6A162R.

ID No. 138682

Terminal set for SC6A261R.

6.4.4 DC link connection

If you want to connect SC6 drive controllers in the DC link group, you will need Quick DC-Link modules of type DL6B.

You receive the DL6B rear section modules in different designs for a horizontal connection, suitable for the size of the drive controller.

The quick fastening clamps for attaching the copper rails and an insulation connection piece are contained in the scope of delivery. The copper rails are not included in the scope of delivery. These must have a cross-section of 5 x 12 mm. Insulation end sections are available separately.

Quick DC-Link DL6B for drive controller



The following designs are available:

DL6B10

ID No. 56655

Rear section module for size 0 drive controller:

SC6A062

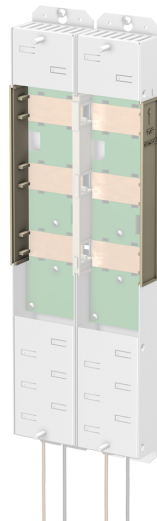
DL6B11

ID No. 56656

Rear section module for size 1 or 2 drive controller:

SC6A162 and SC6A261

Quick DC-Link DL6B insulation end section



ID No. 56659

Insulation end sections for the left and right termination of the group,
2 pcs.

6.4.5 Braking resistor

In addition to drive controllers, STOBBER offers the following braking resistors described below in various sizes and performance classes. For the selection, note the minimum permitted braking resistors specified in the technical data of the individual drive controller types.

6.4.5.1 Tubular fixed resistor FZMU, FZZMU

Type	FZMU 400×65	FZZMU 400×65
ID No.	49010	53895
SC6A062	X	—
SC6A162	(X)	X
SC6A261	(X)	X

Tab. 29: Assignment of FZMU, FZZMU braking resistor – SC6 drive controller

X	Recommended
(X)	Possible
—	Not possible

Properties

Specification	FZMU 400×65	FZZMU 400×65
ID No.	49010	53895
Type	Tubular fixed resistor	Tubular fixed resistor
Resistance [Ω]	100 \pm 10%	47 \pm 10%
Thermal drift	\pm 10%	\pm 10%
Power [W]	600	1200
Therm. time const. τ_{th} [s]	40	40
Pulse power for < 1 s [kW]	18	36
U_{max} [V]	848	848
Weight without packaging [g]	2200	4170
Protection class	IP20	IP20
Marks and test symbols	cURus, CE, UKCA	cURus, CE, UKCA

Tab. 30: FZMU, FZZMU specification

Dimensions

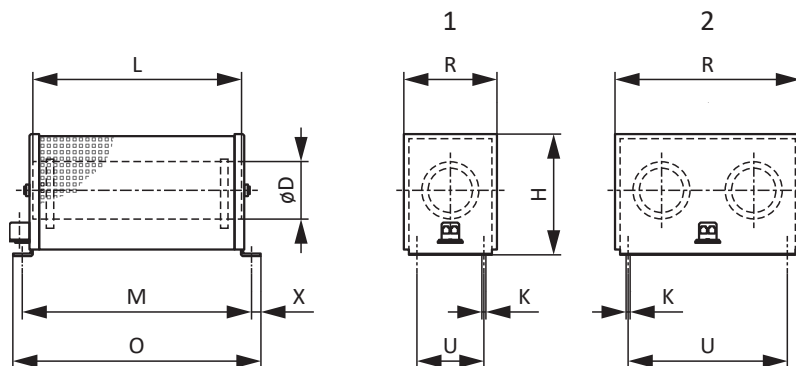


Fig. 4: FZMU (1), FZZMU (2) dimensional drawing

Dimension	FZMU 400×65	FZZMU 400×65
ID No.	49010	53895
L x D	400 × 65	400 × 65
H	120	120
K	6.5 × 12	6.5 × 12
M	430	426
O	485	485
R	92	185
U	64	150
X	10	10

Tab. 31: FZMU, FZZMU dimensions [mm]

6.4.5.2 GVADU, GBADU flat resistor

Type	GVADU 210×20	GBADU 265×30	GBADU 335×30
ID No.	55441	55442	55443
SC6A062	X	X	—
SC6A162	(X)	(X)	X
SC6A261	(X)	(X)	X

Tab. 32: Assignment of GVADU, GBADU braking resistor – SC6 drive controller

X	Recommended
(X)	Possible
—	Not possible

Properties

Specification	GVADU 210×20	GBADU 265×30	GBADU 335×30
ID No.	55441	55442	55443
Type	Flat resistor		
Resistance [Ω]	100 \pm 10%	100 \pm 10%	47 \pm 10%
Thermal drift	\pm 10%	\pm 10%	\pm 10%
Power [W]	150	300	400
Therm. time const. τ_{th} [s]	60	60	60
Pulse power for < 1 s [kW]	3.3	6.6	8.8
U_{max} [V]	848	848	848
Cable design	Radox	FEP	FEP
Cable length [mm]	500	1500	1500
Conductor cross-section [AWG]	18/19 (0.82 mm ²)	14/19 (1.9 mm ²)	14/19 (1.9 mm ²)
Weight without packaging [g]	300	930	1200
Protection class	IP54	IP54	IP54
Marks and test symbols	cURus, CE, UKCA		

Tab. 33: GVADU, GBADU specification

Dimensions

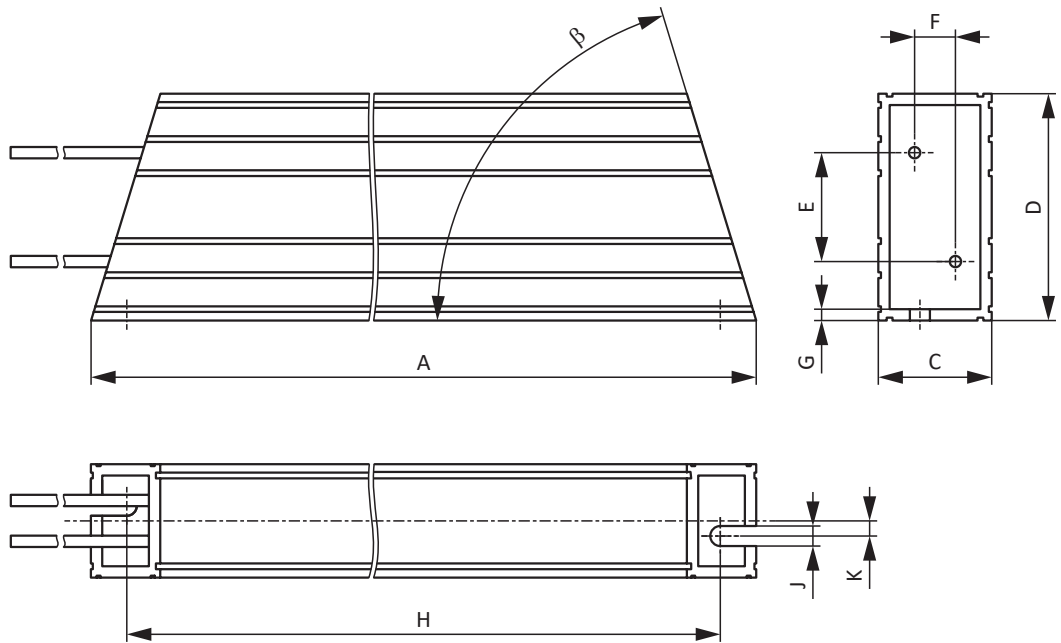


Fig. 5: GVADU, GBADU dimensional drawing

Dimension	GVADU 210×20	GBADU 265×30	GBADU 335×30
ID No.	55441	55442	55443
A	210	265	335
H	192	246	316
C	20	30	30
D	40	60	60
E	18.2	28.8	28.8
F	6.2	10.8	10.8
G	2	3	3
K	2.5	4	4
J	4.3	5.3	5.3
β	65°	73°	73°

Tab. 34: GVADU, GBADU dimensions [mm]

6.4.6 Choke

Technical specifications for suitable chokes can be found in the following chapters.

6.4.6.1 TEP output choke

Output chokes are required for connecting size 0 to 2 drive controllers to synchronous servo motors or asynchronous motors from a cable length > 50 m in order to reduce interference pulses and protect the drive system. If Lean motors are connected, output chokes must not be used.

Information

The following technical data only applies to a rotating magnetic field frequency of 200 Hz. For example, this rotating magnetic field frequency is achieved with a motor with 4 pole pairs and a nominal speed of 3000 rpm. Always observe the specified derating for higher rotating magnetic field frequencies. Also observe the relationship with the clock frequency.

Properties

Specification	TEP3720-0ES41	TEP3820-0CS41	TEP4020-0RS41
ID No.	53188	53189	53190
Voltage range	3 × 0 to 480 V _{AC}		
Frequency range	0 – 200 Hz		
Nominal current I _{N,MF} at 4 kHz	4 A	17.5 A	38 A
Nominal current I _{N,MF} at 8 kHz	3.3 A	15.2 A	30.4 A
Max. permitted motor cable length with output choke	100 m		
Max. surrounding temperature $\vartheta_{amb,max}$	40 °C		
Protection class	IP00		
Winding losses	11 W	29 W	61 W
Iron losses	25 W	16 W	33 W
Connection	Screw terminal		
Max. conductor cross-section	10 mm ²		
UL Recognized Component (CAN; USA)	Yes		
Marks and test symbols	cURus, CE		

Tab. 35: TEP specification

Dimensions

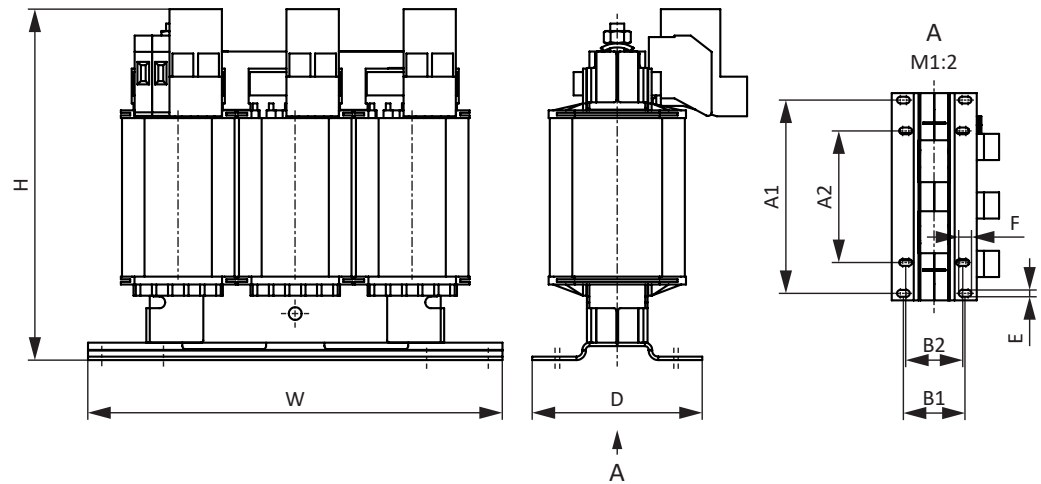


Fig. 6: TEP dimensional drawing

Dimension	TEP3720-0ES41	TEP3820-0CS41	TEP4020-0RS41
Height H [mm]	Max. 153	Max. 153	Max. 180
Width W [mm]	178	178	219
Depth D [mm]	73	88	119
Vertical distance – Fastening holes A1 [mm]	166	166	201
Vertical distance – Fastening holes A2 [mm]	113	113	136
Horizontal distance – Fastening holes B1 [mm]	53	68	89
Horizontal distance – Fastening holes B2 [mm]	49	64	76
Drill holes – Depth E [mm]	5.8	5.8	7
Drill holes – Width F [mm]	11	11	13
Screw connection – M	M5	M5	M6
Weight without packaging [g]	2900	5900	8800

Tab. 36: TEP dimensions and weight

6.4.7 HTL-to-TTL adapter

HT6 HTL-to-TTL adapter



ID No. 56665

Adapters for SC6 and SI6 series drive controllers for level conversion from HTL signals to TTL signals.

It is used to connect an HTL differential incremental encoder to terminal X4 of the drive controller.

6.5 Further information

6.5.1 Directives and standards

The following European directives and standards are relevant to the drive controllers:

- Machinery Directive 2006/42/EC
- Low Voltage Directive 2014/35/EU
- EMC Directive 2014/30/EU
- EN ISO 13849-1:2015
- EN ISO 13849-2:2012
- EN 61800-3:2018
- EN 61800-5-1:2017
- EN 61800-5-2:2017

6.5.2 Marks and test symbols

The following marks and test symbols are mentioned in the technical data.



RoHS lead-free mark

Marking in accordance with RoHS directive 2011-65-EU.



CE mark

Manufacturer's self declaration: The product meets the requirements of EU directives.



UKCA test symbol

Manufacturer's self declaration: The product meets the requirements of UK directives.



UL test symbol (cULus)

This product is listed by UL for the United States and Canada. Representative samples of this product have been evaluated by UL and meet the requirements of applicable standards.



UL test symbol for recognized component mark (cURus)

This component or material is recognized by UL. Representative samples of this product have been evaluated by UL and meet applicable requirements.

6.5.3 Additional documentation

Additional documentation related to the product can be found at

<http://www.stoeber.de/en/downloads/>

Enter the ID of the documentation in the Search field.

Documentation	ID
Manual for SC6 drive controllers	442790

7 SI6 Drive controllers

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7 Drive controllers

SI6

7.1 Overview

Drive control in a multi-axis drive system

Features

- Single or double-axis controller with a nominal output current up to 50 A and 250% overload capacity
- Supply modules up to 50 kW nominal power
- Sensorless position control of STOBER Lean motors
- Control of rotary synchronous servo motors, asynchronous motors and torque motors
- One Cable Solution EnDat 3
- Electronic motor nameplate via EnDat encoder interfaces
- Integrated EtherCAT or PROFINET communication
- STO safety technology using terminals or STO and SS1 using FSoE or PROFIsafe: SIL 3, PL e (Cat. 4)
- Integrated brake control
- Energy supply over DC link connection
- Single-ended nominal power consumption on double-axis controllers for operation of motors with different power
- Variable feed-in power using supply modules that can be connected in parallel

7.1.1 Features

The STOBBER multi-axis drive system is designed for multi-axis applications and consists of the SI6 drive controller and PS6 supply module combination. Matching Quick DC-Link modules handle the energy supply for the drive controllers in the group. The SI6 drive controller is available in four sizes as a single or double-axis controller with a nominal output current of up to 50 A. The PS6 supply module is available in three sizes with a nominal output power of 10 kW to 50 kW. As an economically attractive system with a minimized device width, the SI6 opens a new dimension in multi-axis applications.

The optimized vector control, sensorless vector control, U/f slip-compensated and U/f controller control types are available for use with asynchronous motors.



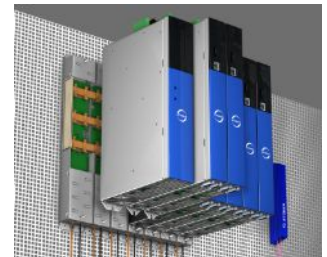
Drive control in multi-axis drive systems with SI6 and PS6

As small as a paperback

You save valuable space in your control cabinet because, with a width of just 45 mm, this drive controller is the most compact solution on the market. It offers all the features that a designer requires.

Dimension capacities precisely

4 axes? 16? Or even 97? A single SI6 drive controller can control up to two axes. Thanks to the multi-axis drive system, the number of motors or axes to be controlled can be scaled without limit. If required, SI6 drive controllers can be combined with stand-alone units from the STOBBER SC6 or SD6 series. For the general energy supply, the drive controllers from the SI6, SC6 and SD6 series can be connected to each other using Quick DC-Link modules.



Tailored energy usage

The SI6 drive controllers are connected to a central supply module. There is no need for decentralized supply modules or fuses and cabling for each axis. When using double-axis modules, the unused power reserves of one axis can be used for the second axis. A significant reduction in space and cost!

Fewer clicks, less wiring

Installation is exceptionally simple. No difficult wiring. The patented Quick DC-Link modules allow for a simple "click" into the standard copper rails, as well as the simple installation and connection of the drive controllers.

Safety functions

The safety concept of the drive controller is based on the STO (Safe Torque Off) function. The concept corresponds to SIL 3 according to DIN EN 61800-5-2 and PL e (Cat. 4) according to DIN EN ISO 13849-1. For double-axis controllers, the STO safety function has a two-channel structure that acts upon both axes. For connection to a higher-level safety circuit, different interfaces are available (terminals, FSoE or PROFIsafe).

Heavy duty

There is an extremely robust design concealed behind the elegant exterior. All components—from the stable, well-shielded sheet steel housing to the motor connectors—far exceed the set values of industry standards. The inside is also anything but small-scale: ample computer capacities, high-quality components, careful workmanship.

7.1.2 Software components**Project configuration and commissioning**

The 6th generation of DriveControlSuite project configuration and commissioning software has all the functions for the efficient use of drive controllers in single-axis and multi-axis applications. The program guides you step by step through the complete project configuration and parameterization process using wizards.

Open communication

The Ethernet-based EtherCAT and PROFINET fieldbus systems are available in the drive controller.

Applications

A controller-based application is recommended for the central motion control of complex machines.

With the controller-based operating modes of the CiA 402 application (csp, csv, cst, ip) or the controller-based application class of the PROFIdrive application (AC4), you can implement applications with synchronized, cyclic set value specification by a motion controller. In addition, the drive controllers can also independently handle motion tasks, such as referencing and jogging during commissioning.

Drive-based Drive Based and Drive Based Synchronous applications, drive-based operating modes of the CiA 402 application (pp, pv, pt) and drive-based application classes of the PROFIdrive application (AC1, AC3) are also available.

Furthermore, programming based on IEC 61131-3 with CFC can be used to create new applications or expand existing ones.

7.1.3 Application training

STOBER offers a multi-level training program that is essentially focused on the drive controller.

G6 Basic

Training content: System overview, installation and commissioning of the drive controller. Use of option modules. Parameterization, commissioning and diagnostics using the commissioning software. Remote maintenance. Basics of controller optimization. Configuration of the drive train. Integrated software functions. Software applications. Connection to a higher-level controller. Basics of safety technology. Practical exercises on training topics.

Software used: DriveControlSuite.

G6 Customized

Training content: Special knowledge for regulating, control and safety technology. Electronic cam disk. Practical exercises on training topics.

7.2 Technical data

Technical data for the drive controllers, supply modules and accessories can be found in the following chapters.

7.2.1 General technical data

The following specifications apply equally to the SI6 drive controller and the PS6 supply module.

Device features	
Protection class of the device	IP20
Protection class of the installation space	At least IP54
Protection class	Protection class I in accordance with EN 61140
Radio interference suppression	Integrated line filter in accordance with EN 61800-3, interference emission class C3
Overvoltage category	III in accordance with EN 61800-5-1
Marks and test symbols	CE, cULus, RoHS

Tab. 1: Device features

Transport and storage conditions	
Storage/transport temperature	-20 °C to +70 °C Maximum change: 20 K/h
Relative humidity	Maximum relative humidity 85%, non-condensing
Vibration (transport) in accordance with EN 60068-2-6	5 Hz ≤ f ≤ 9 Hz: 3.5 mm 9 Hz ≤ f ≤ 200 Hz: 10 m/s ² 200 Hz ≤ f ≤ 500 Hz: 15 m/s ²
Fall height for freefall ¹ Weight < 100 kg in accordance with EN 61800-2 (or IEC 60721-3-2, class 2M1)	0.25 m

Tab. 2: Transport and storage conditions

Operating conditions	
Surrounding temperature during operation	0 °C to 45 °C with nominal data 45 °C to 55 °C with derating -2.5% / K
Relative humidity	Maximum relative humidity 85%, non-condensing
Installation altitude	0 m to 1000 m above sea level without restrictions 1000 m to 2000 m above sea level with -1.5%/100 m derating
Pollution degree	Pollution degree 2 in accordance with EN 50178
Ventilation	Installed fan
Vibration (operation) in accordance with EN 60068-2-6	5 Hz ≤ f ≤ 9 Hz: 0.35 mm 9 Hz ≤ f ≤ 200 Hz: 1 m/s ²

Tab. 3: Operating conditions

Discharge times	
Self-discharge of DC link	15 min
Fast discharge of DC link	Thanks to PS6 supply module in combination with a braking resistor: < 1 min

Tab. 4: Discharge times of the DC link circuit

¹Only valid for components in original packaging

7.2.2 Drive controllers

The following chapters contain specifications for the electrical data, dimensions and weight of the drive controller.

7.2.2.1 Type designation

SI	6	A	0	6	1	Z
----	---	---	---	---	---	---

Tab. 5: Example code for drive controller type designation

Code	Designation	Design
SI	Series	
6	Generation	Generation 6
A	Version	
0 – 3	Size	
6	Power output stage	Power output stage within the size
1	Axis controller	Single-axis controller
2		Double-axis controller
Z	Safety technology	SZ6: Without safety technology
R		SR6: STO using terminals
U		SU6: STO and SS1 using PROFIsafe
Y		SY6: STO and SS1 using FSoE

Tab. 6: Meaning of the example code

7.2.2.2 Sizes

Type	ID No.	Size	Axis controller
SI6A061	56645	Size 0	Single-axis controller
SI6A062	56646	Size 0	Double-axis controller
SI6A161	56647	Size 1	Single-axis controller
SI6A162	56648	Size 1	Double-axis controller
SI6A261	56649	Size 2	Single-axis controller
SI6A262	56653	Size 2	Double-axis controller
SI6A361	56654	Size 3	Single-axis controller

Tab. 7: Available SI6 types and sizes



SI6 in sizes 0 to 3

Note that the basic device is delivered without terminals. Suitable terminal sets are available separately for each size.

7.2.2.3 Electrical data

The electrical data of the available SI6 sizes can be found in the following sections.

An explanation of the formula symbols used can be found in the chapter [\[13.1\]](#).

7.2.2.3.1 Control unit

Electrical data	All types
U_{1CU}	24 V _{DC} , +20%/–15%
I_{1maxCU}	0.5 A

Tab. 8: Control unit electrical data

7.2.2.3.2 Power unit: Size 0

Electrical data	SI6A061	SI6A062
U_{1PU}	280 – 800 V _{DC}	
f_{2PU}	0 – 700 Hz	
U_{2PU}	0 – max. $\frac{U_{1PU}}{\sqrt{2}}$	
C_{PU}	180 μF	270 μF

Tab. 9: SI6 electrical data, size 0

Nominal currents up to +45 °C (in the control cabinet)

Electrical data	SI6A061	SI6A062
$f_{PWM,PU}$	4 kHz	
$I_{2N,PU}$	5 A	2 × 5 A
I_{2maxPU}	210% for 2 s; 150% for 30 s	

Tab. 10: SI6 electrical data, size 0, for 4 kHz clock frequency

Electrical data	SI6A061	SI6A062
$f_{PWM,PU}$	8 kHz	
$I_{2N,PU}$	4.5 A	2 × 4.5 A
I_{2maxPU}	250% for 2 s; 200% for 5 s	

Tab. 11: SI6 electrical data, size 0, for 8 kHz clock frequency

7.2.2.3.3 Power unit: Size 1

Electrical data	SI6A161	SI6A162
U_{1PU}	280 – 800 V _{DC}	
f_{2PU}	0 – 700 Hz	
U_{2PU}	0 – max. $\frac{U_{1PU}}{\sqrt{2}}$	
C_{PU}	470 μF	940 μF

Tab. 12: SI6 electrical data, size 1

Nominal currents up to +45 °C (in the control cabinet)

Electrical data	SI6A161	SI6A162
$f_{PWM,PU}$	4 kHz	
$I_{2N,PU}$	12 A	2 × 12 A
I_{2maxPU}	210% for 2 s; 150% for 30 s	

Tab. 13: SI6 electrical data, size 1, for 4 kHz clock frequency

Electrical data	SI6A161	SI6A162
$f_{PWM,PU}$	8 kHz	
$I_{2N,PU}$	10 A	2 × 10 A
I_{2maxPU}	250% for 2 s; 200% for 5 s	

Tab. 14: SI6 electrical data, size 1, for 8 kHz clock frequency

7.2.2.3.4 Power unit: Size 2

Electrical data	SI6A261	SI6A262
U_{1PU}	280 – 800 V _{DC}	
f_{2PU}	0 – 700 Hz	
U_{2PU}	0 – max. $\frac{U_{1PU}}{\sqrt{2}}$	
C_{PU}	940 μ F	2250 μ F

Tab. 15: SI6 electrical data, size 2

Nominal currents up to +45 °C (in the control cabinet)

Electrical data	SI6A261	SI6A262
$f_{PWM,PU}$	4 kHz	
$I_{2N,PU}$	22 A	2 × 25 A
I_{2maxPU}	210% for 2 s; 150% for 30 s	

Tab. 16: SI6 electrical data, size 2, for 4 kHz clock frequency

Electrical data	SI6A261	SI6A262
$f_{PWM,PU}$	8 kHz	
$I_{2N,PU}$	20 A	2 × 20 A
I_{2maxPU}	250% for 2 s; 200% for 5 s	

Tab. 17: SI6 electrical data, size 2, for 8 kHz clock frequency

7.2.2.3.5 Power unit: Size 3

Electrical data	SI6A361
U_{1PU}	280 – 800 V _{DC}
f_{2PU}	0 – 700 Hz
U_{2PU}	0 – max. $\frac{U_{1PU}}{\sqrt{2}}$
C_{PU}	2250 μ F

Tab. 18: SI6 electrical data, size 3

Nominal currents up to +45 °C (in the control cabinet)

Electrical data	SI6A361
$f_{PWM,PU}$	4 kHz
$I_{2N,PU}$	50 A
I_{2maxPU}	210% for 2 s; 150% for 30 s

Tab. 19: SI6 electrical data, size 3, for 4 kHz clock frequency

Electrical data	SI6A361
$f_{PWM,PU}$	8 kHz
$I_{2N,PU}$	40 A
I_{2maxPU}	250% for 2 s; 200% for 5 s

Tab. 20: SI6 electrical data, size 3, for 8 kHz clock frequency

7.2.2.3.6 Single-ended nominal power consumption on double-axis controllers

Operating two motors on one double-axis controller makes it possible to operate one of the motors with a continuous current above the nominal current of the drive controller if the continuous current of the second connected motor is lower than the nominal current of the drive controller. This enables economical combinations of double-axis controllers and motors.

The nominal output current for axis B can be determined using the following formula if the output current for axis A is known:

Example 1

$$I_{2PU(B)} = I_{2N,PU} - (I_{2PU(A)} - I_{2N,PU}) \times \frac{3}{5} \quad \text{where} \quad 0 \leq I_{2PU(A)} \leq I_{2N,PU}$$

Example 2

$$I_{2PU(B)} = I_{2N,PU} - (I_{2PU(A)} - I_{2N,PU}) \times \frac{5}{3} \quad \text{where} \quad I_{2N,PU} \leq I_{2PU(A)} \leq 1,6 \times I_{2N,PU}$$

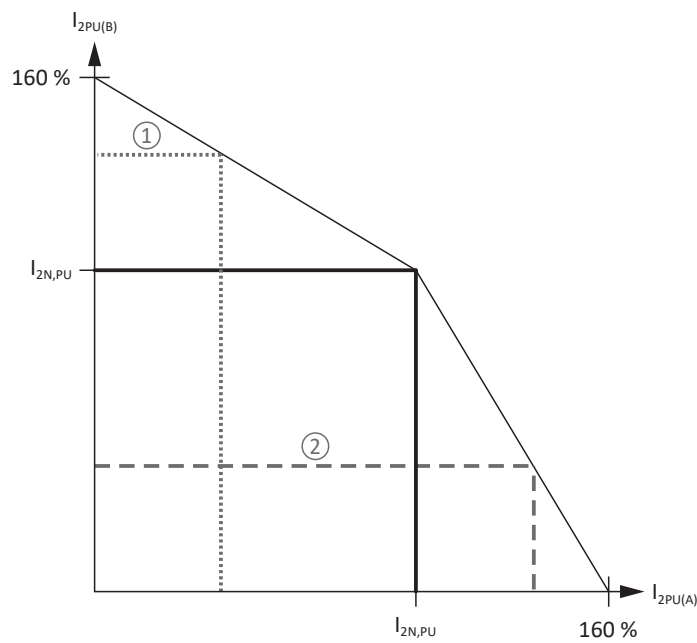


Fig. 1: Asymmetric load on double-axis controllers

Information

Note that the available maximum currents I_{2maxPU} of the axis controllers are also relative to the nominal output current $I_{2N,PU}$ for single-ended nominal power consumption.

7.2.2.3.7 Power loss data in accordance with EN 61800-9-2

Type	Nominal current $I_{2N,PU}$	Apparent power	Absolute losses $P_{V,CU}^2$	Operating points ³								IE class ⁴	Comparison ⁵	
				(0/25)	(0/50)	(0/100)	(50/25)	(50/50)	(50/100)	(90/50)	(90/100)			
				Relative losses										
				[A]	[kVA]	[W]	[%]							
SI6A06x	5	3.5	Max. 10	0.71	0.86	1.33	0.76	0.97	1.61	1.13	2.13	IE2		
SI6A16x	12	8.3	Max. 10	0.55	0.71	1.19	0.59	0.80	1.44	0.94	1.87	IE2		
SI6A261	22	16.6	Max. 10	0.55	0.71	1.19	0.59	0.80	1.44	0.94	1.87	IE2		
SI6A262	25	17.3	Max. 10	0.45	0.62	1.12	0.50	0.74	1.47	0.95	2.12	IE2		
SI6A361	50	34.6	Max. 10	0.45	0.62	1.12	0.50	0.74	1.47	0.95	2.12	IE2		
				Absolute losses P_V										
				[A]	[kVA]	[W]	[W]						[%]	
SI6A06x	5	3.5	Max. 10	25	30.2	46.5	26.5	33.8	56.5	39.5	74.4	IE2	24.9	
SI6A16x	12	8.3	Max. 10	45.7	58.7	98.7	49.1	66.3	119.6	78.1	155.4	IE2	26.7	
SI6A261	22	16.6	Max. 10	91.5	117.4	197.3	98.2	132.6	239.2	156.2	310.8	IE2	30.8	
SI6A262	25	17.3	Max. 10	77.9	106.5	193.0	87.1	127.9	254.3	163.8	367.6	IE2	36.4	
SI6A361	50	34.6	Max. 10	155.8	213.1	386.0	174.3	255.8	508.6	327.6	735.2	IE2	39.5	

Tab. 21: Power loss data in accordance with EN 61800-9-2 for one axis of a SI6 drive controller

General conditions

The specified losses apply to an axis of a drive controller and take into account the proportionate losses of the PS6 supply module for that axis.

For a group with a total of x axes, the values are to be multiplied by the number of axis controllers (x), e.g. x = 4 for 1 × PS6 and 2 × SI6A062.

The loss data applies to drive controllers without any accessories.

The power loss calculation is based on a three-phase supply voltage with 400 V_{AC}/50 Hz.

The calculated data includes a supplement of 10% in accordance with EN 61800-9-2.

The power loss specifications refer to a clock frequency of 4 kHz.

The absolute losses for a power unit that is switched off refer to the 24 V_{DC} power supply of the control electronics.

7.2.2.3.8 Power loss data of accessories

If you intend to order the drive controller with accessory parts, losses increase as follows.

Type	Absolute losses P_V [W]
SR6 safety module	1
SY6 or SU6 safety module	2

Tab. 22: Absolute losses of the accessories

Information

Note the absolute power loss of the encoder (usually < 3 W) and of the brake when designing as well.

Loss specifications for other optional accessories can be found in the technical data of the respective accessory part.

² Absolute losses for a power unit that is switched off

³ Operating points for relative motor stator frequency in % and relative torque current in %

⁴ IE class in accordance with EN 61800-9-2

⁵ Comparison of the losses for the reference related to IE2 in the nominal point (90, 100)

7.2.2.4 Cycle times

Possible cycle times can be found in the following table.

Type	Cycle times	Relevant parameters
Application	250 μ s, 500 μ s, 1 ms, 2 ms, 4 ms, 8 ms	Adjustable in A150
EtherCAT fieldbus, cyclical communication	250 μ s, 500 μ s, 1 ms, 2 ms, 4 ms, 8 ms	Adjustable in A150
PROFINET RT fieldbus, cyclical communication	1 ms, 2 ms, 4 ms, 8 ms	Adjustable in A150
PROFINET IRT fieldbus, cyclical communication	1 ms, 2 ms, 4 ms	Adjustable in A150
Motion core (movement calculation)	250 μ s	—
Control cascade	62.5 μ s, 125 μ s	Depending on B24

Tab. 23: Cycle times

7.2.2.5 Derating

When dimensioning the drive controller, observe the derating of the nominal output current as a function of the clock frequency, surrounding temperature and installation altitude. There is no restriction for a surrounding temperature from 0 °C to 45 °C and an installation altitude of 0 m to 1000 m. The details given below apply to values outside these ranges.

7.2.2.5.1 Effect of the clock frequency

Changing the clock frequency f_{PWM} affects the amount of noise produced by the drive, among other things. However, increasing the clock frequency results in increased losses. During project configuration, define the highest clock frequency and use it to determine the nominal output current $I_{2\text{N,PU}}$ for dimensioning the drive controller.

Type	$I_{2\text{N,PU}}$ 4 kHz [A]	$I_{2\text{N,PU}}$ 8 kHz [A]	$I_{2\text{N,PU}}$ 16 kHz [A]
SI6A061	5	4.5	3.5
SI6A062	2 × 5	2 × 4.5	2 × 3.5
SI6A161	12	10	6
SI6A162	2 × 12	2 × 10	2 × 6
SI6A261	22	20	10
SI6A262	2 × 25	2 × 20	2 × 10
SI6A361	50	40	—

Tab. 24: Nominal output current $I_{2\text{N,PU}}$ dependent on the clock frequency

7.2.2.5.2 Effect of the surrounding temperature

Derating as a function of the surrounding temperature is determined as follows:

- 0 °C to 45 °C: No restrictions ($D_T = 100\%$)
- 45 °C to 55 °C: Derating $-2.5\%/K$

Example

The drive controller needs to be operated at 50 °C.

The derating factor D_T is calculated as follows

$$D_T = 100\% - 5 \times 2.5\% = 87.5\%$$

7.2.2.5.3 Effect of the installation altitude

Derating as a function of the installation altitude is determined as follows:

- 0 m to 1000 m: No restriction ($D_{IA} = 100\%$)
- 1000 m to 2000 m: Derating $-1.5\%/100\text{ m}$

Example

The drive controller needs to be installed at an altitude of 1500 m above sea level.

The derating factor D_{IA} is calculated as follows:

$$D_{IA} = 100\% - 5 \times 1.5\% = 92.5\%$$

7.2.2.5.4 Calculating the derating

Follow these steps for the calculation:

1. Determine the highest clock frequency (f_{PWM}) that will be used during operation and use it to determine the nominal current $I_{2\text{N,PU}}$.
2. Determine the derating factors for installation altitude and surrounding temperature.
3. Calculate the reduced nominal current $I_{2\text{N,PU}(\text{red})}$ in accordance with the following formula:

$$I_{2\text{N,PU}(\text{red})} = I_{2\text{N,PU}} \times D_T \times D_{IA}$$

Example

A drive controller of type SI6A061 needs to be operated at a clock frequency of 8 kHz at an altitude of 1500 m above sea level and a surrounding temperature of 50 °C.

The nominal current of the SI6A061 at 8 kHz is 4.5 A. The derating factor D_T is calculated as follows:

$$D_T = 100\% - 5 \times 2.5\% = 87.5\%$$

The derating factor D_{IA} is calculated as follows:

$$D_{IA} = 100\% - 5 \times 1.5\% = 92.5\%$$

The output current of importance for the project configuration is:

$$I_{2\text{N,PU}(\text{red})} = 4.5\text{ A} \times 0.875 \times 0.925 = 3.64\text{ A}$$

7.2.2.6 Dimensions

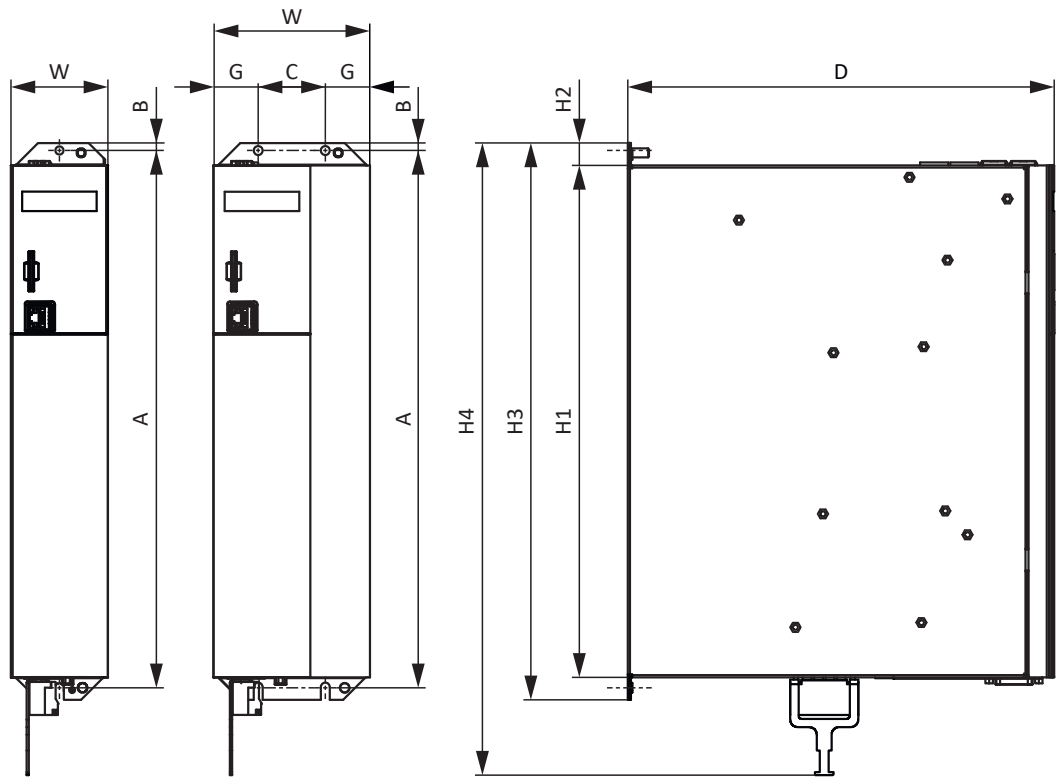


Fig. 2: SI6 dimensional drawing

Dimension			SI6A061 SI6A062	SI6A161 SI6A162	SI6A261	SI6A262	SI6A361
Drive controllers	Width	W	45	65		105	
	Depth	D	265	286			
	Body height	H1	343				
	Fastening clip height	H2	15				
	Height incl. fastening clips	H3	373				
	Total height incl. shield connection	H4	423				
Fastening holes (M5)	Vertical distance	A	360+2				
	Vertical distance to the upper edge	B	5				
	Horizontal spacing of the fastening holes	C	—			45	
	Horizontal distance to the side edge	G	—			30	

Tab. 25: SI6 dimensions [mm]

7.2.2.7 Weight

Type	Weight without packaging [g]	Weight with packaging [g]
SI6A061	2980	4600
SI6A062	3460	5060
SI6A161	3880	5260
SI6A162	4820	6240
SI6A261	4760	6200
SI6A262	6240	7420
SI6A361	6180	7360

Tab. 26: SI6 weight [g]

7.2.3 Supply module

The following section contains specifications for the electrical data, dimensions and weight of the PS6 supply module.

7.2.3.1 Type designation

PS	6	A	2	4
----	---	---	---	---

Tab. 27: Example code for supply module type designation

Code	Designation	Design
PS	Series	
6	Generation	Generation 6
A	Version	
2 – 4	Size	
4	Power output stage	

Tab. 28: Meaning of the example code

7.2.3.2 Sizes

Type	ID No.	Size
PS6A24	56650	Size 2
PS6A34	56651	Size 3
PS6A44	138679	Size 4

Tab. 29: Available PS6 types and sizes



PS6 in sizes 2 to 4

Note that the basic device is delivered without terminals. Suitable terminal sets are available separately for each size.

7.2.3.3 Electrical data

The electrical data of the available PS6 sizes as well as the properties of the brake chopper can be found in the following sections.

Information

The STO safety function is available for safe stopping as an alternative to continuous, cyclical power-on/power-off operation.

An explanation of the formula symbols used can be found in the chapter [▶ 13.1](#).

7.2.3.3.1 Control unit

Electrical data	All types
U_{1CU}	24 V _{DC} , +20%/–15%
I_{1maxCU}	0.5 A

Tab. 30: Control unit electrical data

7.2.3.3.2 Power unit: Size 2

Electrical data	PS6A24
U_{1PU}	3 × 400 V _{AC} , +32%/–50%, 50/60 Hz; 3 × 480 V _{AC} , +10%/–58%, 50/60 Hz
$U_{2PU,ZK}$	$\sqrt{2} \times U_{1PU}$
$P_{2N,PU}$	10 kW
$I_{1N,PU}$	25 A
I_{1maxPU}	$I_{1N,PU} \times 180\%$ for 5 s; $I_{1N,PU} \times 150\%$ for 30 s
$C_{N,PU}$	5000 μF

Tab. 31: PS6 electrical data, size 2

7.2.3.3.3 Power unit: Size 3

Electrical data	PS6A34
U_{1PU}	3 × 400 V _{AC} , +32%/–50%, 50/60 Hz; 3 × 480 V _{AC} , +10%/–58%, 50/60 Hz
$U_{2PU,ZK}$	$\sqrt{2} \times U_{1PU}$
$P_{2N,PU}$	20 kW
$I_{1N,PU}$	50 A
I_{1maxPU}	$I_{1N,PU} \times 180\%$ for 5 s; $I_{1N,PU} \times 150\%$ for 30 s
$C_{N,PU}$	10000 μF

Tab. 32: PS6 electrical data, size 3

7.2.3.3.4 Power unit: Size 4

Electrical data	PS6A44
U_{1PU}	3 × 400 V _{AC} , +32%/–50%, 50/60 Hz; 3 × 480 V _{AC} , +10%/–58%, 50/60 Hz
$U_{2PU,ZK}$	$\sqrt{2} \times U_{1PU}$
$P_{2N,PU}$	50 kW
$I_{1N,PU}$	92 A
I_{1maxPU}	$I_{1N,PU} \times 180\%$ for 5 s; $I_{1N,PU} \times 150\%$ for 30 s
$C_{N,PU}$	20000 μF

Tab. 33: PS6 electrical data, size 4

7.2.3.3.5 Parallel connection

Only supply modules of either size 2 or 3 may be connected in parallel.

The power and current increase if supply modules are connected in parallel. Take into account that the total is derated by a factor of 0.8 in doing so.

The charging capacity of the supply modules can be increased by a parallel connection only if the power grid supply is connected to all supply modules simultaneously. Increasing the charging capacity also requires derating the total by a factor of 0.8.

The following table shows example combinations for parallel connection.

Electrical data	2 x PS6A24	3 x PS6A24	2 x PS6A34	3 x PS6A34
$P_{2N,PU}$	16 kW	24 kW	32 kW	48 kW
$I_{1N,PU}$	40 A	60 A	80 A	120 A
C_{maxPU}	8000 μ F	12000 μ F	16000 μ F	24000 μ F

Tab. 34: Electrical data for parallel connection: Example combinations

The following general conditions apply to the parallel connection of several PS6 supply modules:

- Only supply modules of size 2 or 3 may be connected in parallel.
- Only the same sizes may be connected in parallel.
- You can connect a maximum of 3 PS6A34 in parallel.

7.2.3.3.6 Brake chopper

Electrical data	PS6A24	PS6A34
U_{onCH}	780 – 800 V_{DC}	
U_{offCH}	740 – 760 V_{DC}	
R_{2minRB}	22 Ω	
P_{maxRB}	29.1 kW	
P_{effRB}	27.2 kW	

Tab. 35: Brake chopper electrical data, size 2 and 3

Electrical data	PS6A44
U_{onCH}	780 – 800 V_{DC}
U_{offCH}	740 – 760 V_{DC}
R_{2minRB}	9.5 Ω
P_{maxRB}	67.3 kW
P_{effRB}	62.9 kW

Tab. 36: Brake chopper electrical data, size 4

7.2.3.3.7 Fast discharge

Fast discharge is activated when no supply voltage is present for 20 s and the DC link voltage has reduced over this time. For active fast discharge, the DC link is discharged via the brake chopper and the braking resistor. Fast discharge does not take place for constant or increasing DC link voltage as this behavior indicates a second supply module in the DC link group. If the temperature sensor of the braking resistor is active, the fast discharge also remains off.

7.2.3.4 Dimensions

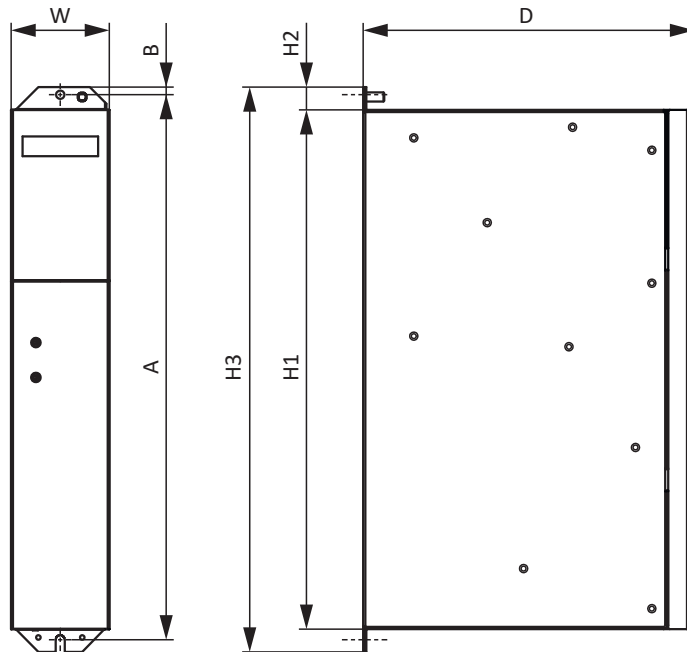


Fig. 3: PS6A24, PS6A34 dimensional drawing

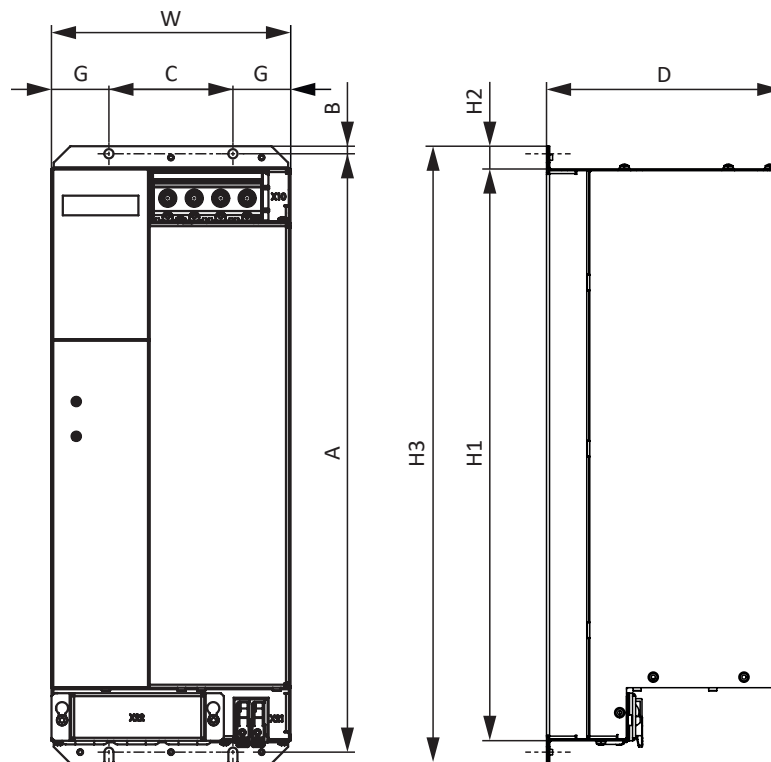


Fig. 4: PS6A44 dimensional drawing

Dimension			PS6A24	PS6A34	PS6A44
Supply module	Width	W	45	65	158
	Depth	D	204	219	156.5
	Body height	H1	343		378
	Fastening clip height	H2	15		
	Height incl. fastening clips	H3	373		408
Fastening holes (M5)	Vertical distance	A	360+2		396+2
	Vertical distance to the upper edge	B	5		
	Horizontal spacing of the fastening holes	C	—		82
	Horizontal distance to the side edge	G	—		38

Tab. 37: PS6 dimensions [mm]

7.2.3.5 Weight

Type	Weight without packaging [g]	Weight with packaging [g]
PS6A24	2680	4180
PS6A34	3820	4920
PS6A44	6640	7640

Tab. 38: PS6 weight [g]

7.2.4 DC link connection

The following section contains specifications for the electrical data, dimensions and weight of the DL6B modules Quick DC-Link.

7.2.4.1 General technical data

The following information applies to all Quick DC-Link modules and corresponds to the general technical data for the base device.

Device features	
Protection class of the device	IP20 (if built over with drive controller or supply module)
Protection class	Protection class I in accordance with EN 61140 (if built over with drive controller or supply module)
Protection class of the installation space	At least IP54

Tab. 39: Device features

Transport and storage conditions	
Storage/ transport temperature	-20 °C to +70 °C Maximum change: 20 K/h
Relative humidity	Maximum relative humidity 85%, non-condensing
Vibration (transport) in accordance with EN 60068-2-6	5 Hz ≤ f ≤ 9 Hz: 3.5 mm 9 Hz ≤ f ≤ 200 Hz: 10 m/s ² 200 Hz ≤ f ≤ 500 Hz: 15 m/s ²
Fall height for freefall ⁶ Weight < 100 kg in accordance with EN 61800-2 (or IEC 60721-3-2, class 2M1)	0.25 m

Tab. 40: Transport and storage conditions

Operating conditions	
Surrounding temperature during operation	0 °C to 45 °C with nominal data 45 °C to 55 °C with derating -2.5% / K
Relative humidity	Maximum relative humidity 85%, non-condensing
Installation altitude	0 m to 1000 m above sea level without restrictions 1000 m to 2000 m above sea level with -1.5%/100 m derating
Pollution degree	Pollution degree 2 in accordance with EN 50178
Vibration (operation) in accordance with EN 60068-2-6	5 Hz ≤ f ≤ 9 Hz: 0.35 mm 9 Hz ≤ f ≤ 200 Hz: 1 m/s ²

Tab. 41: Operating conditions

7.2.4.2 assignment to DL6B – SI6 and PS6

DL6B is available in the following designs suitable for the individual drive controller types and supply module types:

Type	DL6B10	DL6B11	DL6B12	DL6B20	DL6B21	DL6B22
ID No.	56655	56656	56663	56657	56658	5050114
SI6A061	X	—	—	—	—	—
SI6A062	X	—	—	—	—	—
SI6A161	—	X	—	—	—	—
SI6A162	—	X	—	—	—	—
SI6A261	—	X	—	—	—	—
SI6A262	—	—	X	—	—	—
SI6A361	—	—	X	—	—	—
PS6A24	—	—	—	X	—	—
PS6A34	—	—	—	—	X	—
PS6A44	—	—	—	—	—	X

Tab. 42: DL6B assignment to SI6 and PS6

7.2.4.3 Dimensions

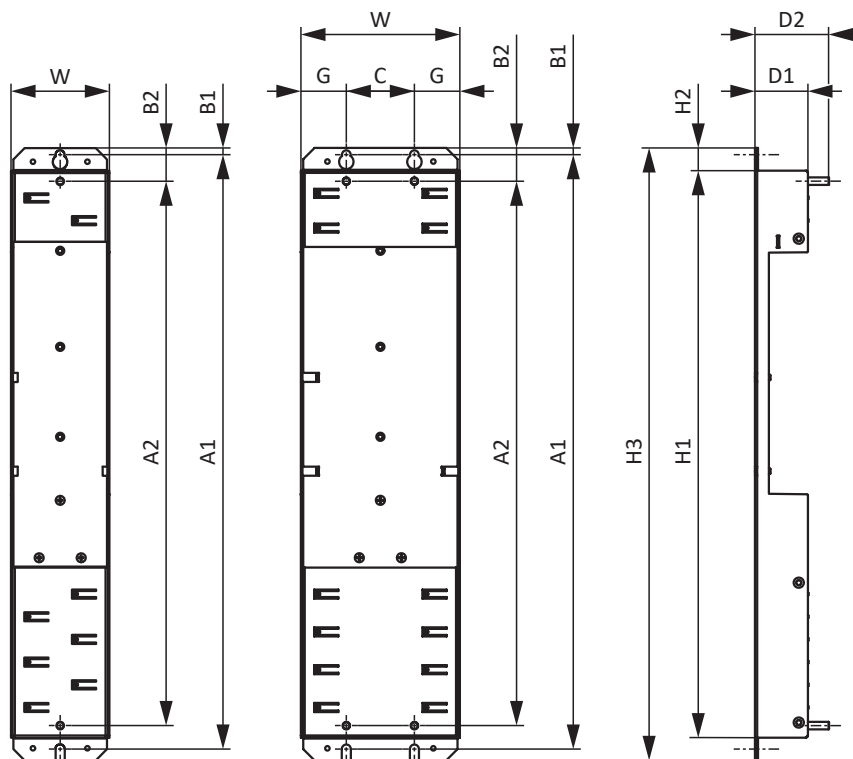


Fig. 5: Dimensional drawing of DL6B10 to DL6B21

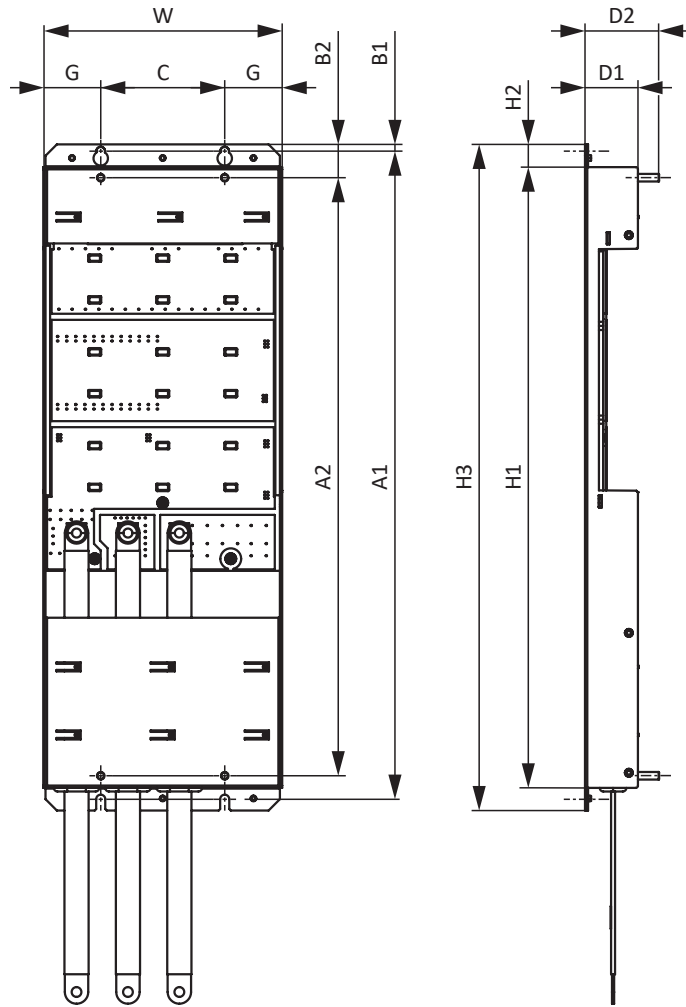


Fig. 6: DL6B22 dimensional drawing

Dimension			DL6B10 DL6B20	DL6B11 DL6B21	DL6B12	DL6B22	
Quick DC-Link	Width	W	45	65	105	158	
	Depth	D1	35				
	Depth incl. attachment bolts	D2	49				
	Height	H1	375				410.5
	Fastening clip height	H2	15				
	Height incl. fastening clips	H3	405				440.5
	Fastening holes	Vertical distance (wall mounting)	A1	393+2			
Vertical distance (module mounting)		A2	360				396
Vertical distance to the upper edge		B1	4.5				
Vertical distance to the upper edge		B2	22				
Horizontal spacing of the fastening holes		C	—		45	82	
Horizontal distance to the side edge		G	—		30	38	

Tab. 43: DL6B dimensions [mm]

7.2.4.4 Weight

Type	Weight without packaging [g]	Weight with packaging [g]
DL6B10	440	480
DL6B11	560	600
DL6B12	880	920
DL6B20	480	520
DL6B21	740	780
DL6B22	1400	1440

Tab. 44: DL6B weight [g]

7.2.5 Minimum clearances

Drive controllers and supply modules

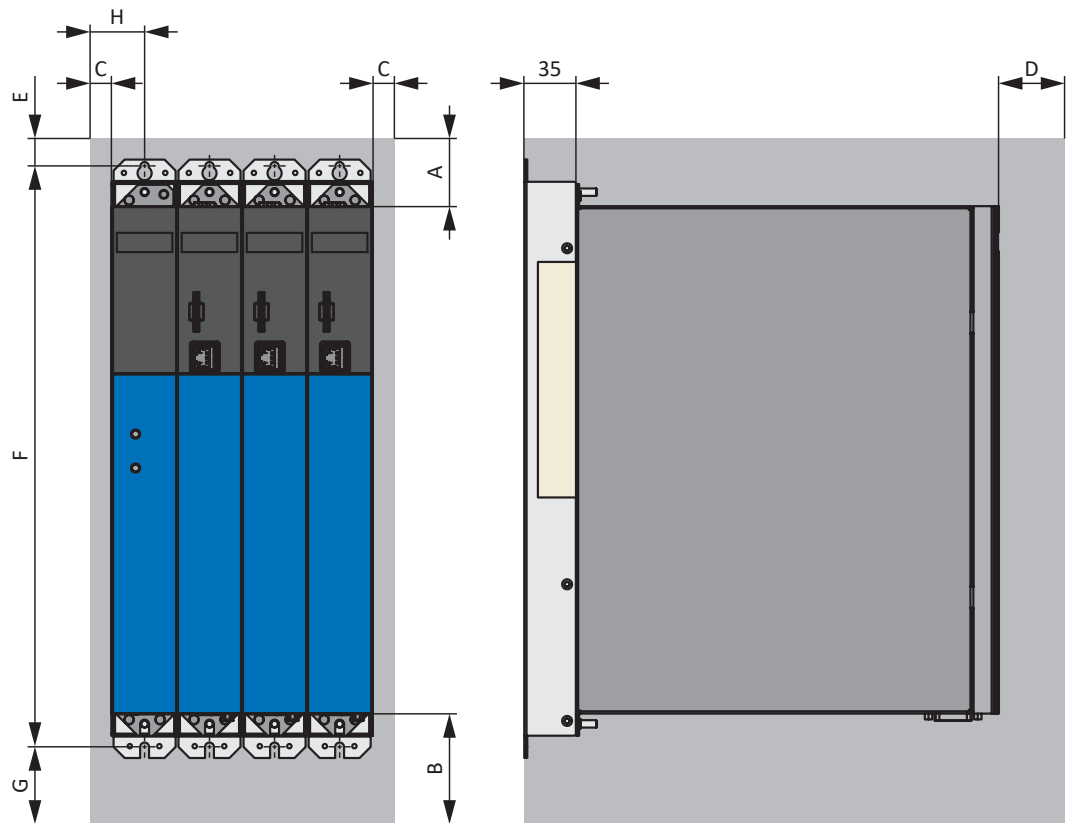


Fig. 7: Minimum clearances for drive controllers in combination with a PS6A24 or PS6A34 supply module

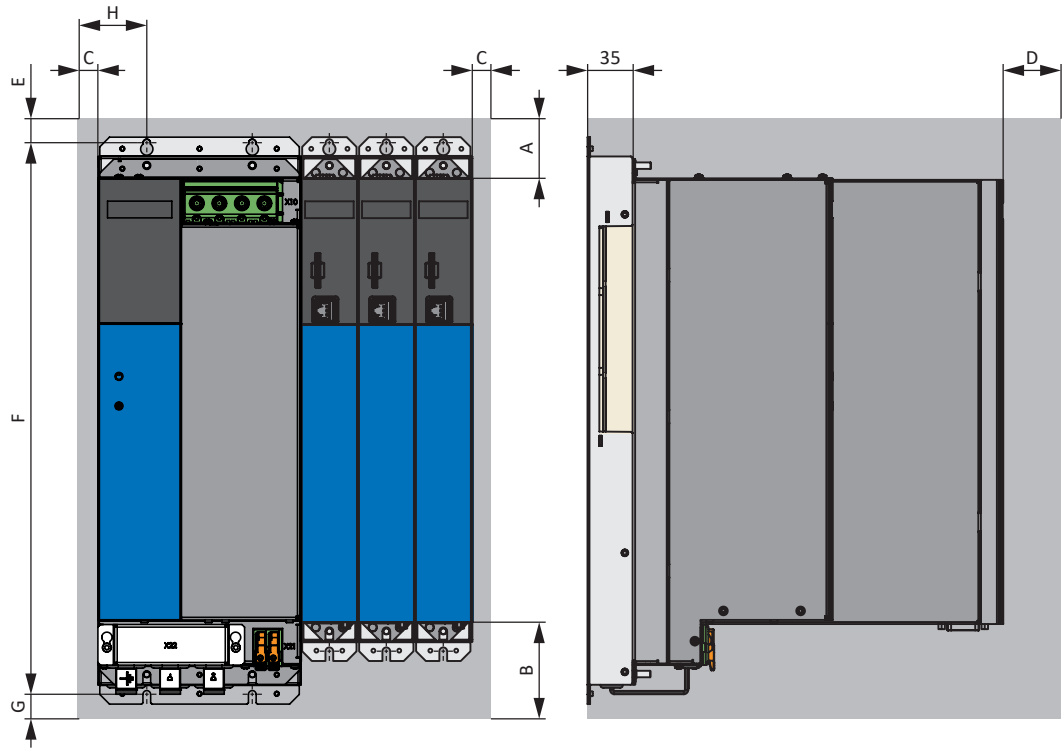


Fig. 8: Minimum clearances for drive controllers in combination with a PS6A44 supply module

The specified dimensions refer to the outside edges of the drive controller or supply module including the Quick DC-Link rear section module.

Minimum clearance	A (above)	B (below)	C (on the side)	D (in front)
All sizes	100	200	5	50 ⁷

Tab. 45: Minimum clearances [mm]

Dimension	E	F	G	H
PS6A24	73.5	393+2	approx. 174.5	27.5
PS6A34	73.5	393+2	approx. 174.5	37.5
PS6A44	73.5	429+2	approx. 138.5	43

Tab. 46: Dimensions [mm]

Chokes and filters

Avoid installation below drive controllers or supply modules. For installation in a control cabinet, a distance of approximately 100 mm to other neighboring components is recommended. This distance ensures proper heat dissipation for chokes and filters.

Braking resistors

Avoid installation below drive controllers or supply modules. In order for heated air to flow out unimpeded, a minimum clearance of approximately 200 mm must be maintained in relation to neighboring components or walls and approximately 300 mm must be maintained to components above or ceilings.

7.3 Drive controller/motor combinations

Parameterization of a STÖBER drive controller is remarkably easy, especially in combination with four-pole STÖBER asynchronous motors. The motor is fully typed by inputting just the motor size (e.g. 90L) and its wiring (star or delta). A delta connection (measurement point 230 V, 50 Hz) is available for motors up to 3 kW (size 100). By increasing the voltage at higher frequencies, the full torque can be drawn through the motor up to 87 Hz. It usually makes sense to take this expanded speed adjustment range into account when selecting the gear unit. You can find more detailed information in the chapter [▶ 5.6].

An explanation of the formula symbols used can be found in the chapter [▶ 13.1].

									SI6A061	SI6A161	SI6A261	SI6A262	SI6A361
									SI6A062	SI6A162			
									$I_{2N,PU}$ [A] ($f_{PWM,PU} = 4$ kHz)				
f_T [Hz]	pz	Con- nection	P_N [kW]	n_N [rpm]	M_N [Nm]	M_k/M_N	I_N [A]		5	12	22	25	50

Δ 230 V / Y 400 V motor winding									$I_{2N,PU} / I_N$				
IE3D080L04	50	4	Y	0.75	1445	5.0	3.7	1.7	2.9				
IE3D080L04	87	4	Δ	1.3	2503	5.0	3.7	2.94	1.7				
IE3D090S04	50	4	Y	1.1	1440	7.3	3.7	2.5	2.0				
IE3D090S04	87	4	Δ	1.91	2494	7.3	3.7	4.33	1.2				
IE3D090LX04	50	4	Y	1.5	1455	9.8	4.9	3.4	1.5				
IE3D090LX04	87	4	Δ	2.6	2503	9.8	4.9	5.89		2.0			
IE3D100KX04	50	4	Y	2.2	1450	14.5	3.8	4.55	1.1				
IE3D100KX04	87	4	Δ	3.81	2511	14.5	3.8	7.88		1.5			
IE3D100LX04	50	4	Y	3.0	1450	19.8	4	6.35		1.9			
IE3D100LX04	87	4	Δ	5.2	2511	19.8	4	11		1.1	2.0		
IE3D112M04	50	4	Δ	4.0	1465	26.1	4.5	7.9		1.5			
IE3D132SX04	50	4	Δ	5.5	1465	36	3.3	10		1.2	2.2		
IE3D132MX04	50	4	Δ	7.5	1470	49	3.9	16			1.4	1.6	
IE3D160MX04	50	4	Δ	11	1465	72	3.4	21			1.0	1.2	
IE3D160LX04	50	4	Δ	15	1475	97	3.5	27.5					1.8
IE3D180MX04	50	4	Δ	18.5	1475	120	3.3	34.5					1.4
IE3D180LX04	50	4	Δ	22	1475	142	3	41					1.2

7.4 Accessories

You can find information about the available accessories in the following chapters.

7.4.1 Safety technology

Information

The drive controller is delivered in the standard design without safety technology (option SZ6). If you want a drive controller with integrated safety technology, you must order it together with the drive controller. The safety modules are an integrated part of the drive controllers and must not be modified.

SZ6 option – Without safety technology

ID No. 56660

Design without safety technology.

SR6 safety module – STO using terminals



ID No. 56661

Optional accessory for the use of the Safe Torque Off safety function (STO) in safety-relevant applications (PL e, SIL 3) in accordance with EN ISO 13849-1 and EN 61800-5-2. Connection to a higher-level safety circuit via terminal X12.

SY6 safety module – STO and SS1 using FSoE



ID No. 56662

Optional accessory for the use of the Safe Torque Off (STO) and Safe Stop 1 (SS1) safety functions in safety-relevant applications (PL e, SIL 3) in accordance with EN ISO 13849-1 and EN 61800-5-2. Connection to the higher-level safety circuit using Fail Safe over EtherCAT (FSoE).

SU6 safety module – STO and SS1 using PROFINsafe



ID No. 56696

Optional accessory for the use of the Safe Torque Off (STO) and Safe Stop 1 (SS1) safety functions in safety-relevant applications (PL e, SIL 3) in accordance with EN ISO 13849-1 and EN 61800-5-2. Connection to a higher-level safety circuit via PROFINET (PROFINsafe).

7.4.2 Communication

The drive controller has two interfaces for the fieldbus connection on the top of the device as well as an Ethernet service interface on the front of the device. Cables for the connection are available separately.

EtherCAT or PROFINET fieldbus system



Please specify the desired fieldbus system when placing your order for the base device, since the fieldbus communication is defined using the firmware.

EtherCAT cables



Ethernet patch cable, CAT5e, yellow.

The following designs are available:

ID No. 49313: Length approx. 0.25 m.

ID No. 49314: Length approx. 0.5 m.

PC connecting cables

ID No. 49857

Cable for connecting the X9 service interface to the PC, CAT5e, blue, 5 m.

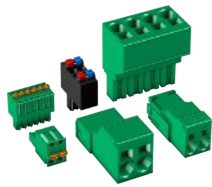
USB 2.0 Ethernet adapter

ID No. 49940

Adapter for connecting Ethernet to a USB port.

7.4.3 Terminal set

For the connection, you need suitable terminal sets for each PS6 supply module and each SI6 drive controller.

Terminal set for supply module

(Fig. similar)

The following designs are available:

ID No. 138660

Terminal set for PS6A24.

ID No. 138661

Terminal set for PS6A34.

ID No. 5050112

Terminal set for PS6A44.

Terminal set for drive controllers – SZ6 option (without safety technology), SU6 option (STO and SS1 using PROFIsafe) or SY6 option (STO and SS1 using FSoE)

(Fig. similar)

The following designs are available:

ID No. 138655

Terminal set for SI6A061Z/U/Y.

ID No. 138656

Terminal set for SI6A062Z/U/Y.

ID No. 138657

Terminal set for SI6A161Z/U/Y.

ID No. 138658

Terminal set for SI6A162Z/U/Y.

ID No. 138659

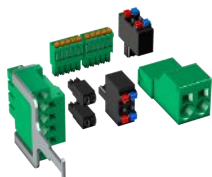
Terminal set for SI6A261Z/U/Y.

ID No. 138662

Terminal set for SI6A262Z/U/Y.

ID No. 138663

Terminal set for SI6A361Z/U/Y.

Terminal set for drive controllers – SR6 option (STO via terminals)

(Fig. similar)

The following designs are available:

ID No. 138683

Terminal set for SI6A061R.

ID No. 138684

Terminal set for SI6A062R.

ID No. 138685

Terminal set for SI6A161R.

ID No. 138686

Terminal set for SI6A162R.

ID No. 138687

Terminal set for SI6A261R.

ID No. 138688

Terminal set for SI6A262R.

ID No. 138689

Terminal set for SI6A361R.

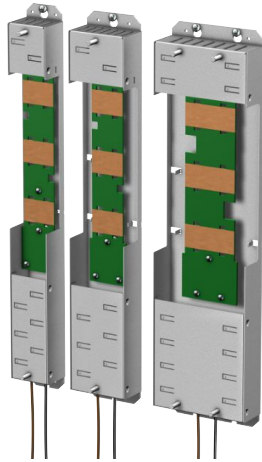
7.4.4 DC link connection

For the energy supply of the existing drive controllers in the group, you need suitable Quick DC-Link modules of type DL6B for each PS6 supply module and each SI6 drive controller.

For the horizontal connection, you receive DL6B rear section modules in various designs, matched to the size of the drive controller or supply module.

The quick fastening clamps for attaching the copper rails and an insulation connection piece are contained in the scope of delivery. The copper rails are not included in the scope of delivery. These must have a cross-section of 5 x 12 mm. Insulation end sections are available separately.

Quick DC-Link DL6B for drive controller



The following designs are available:

DL6B10

ID No. 56655

Rear section module for size 0 drive controller:

SI6A061 and SI6A062

DL6B11

ID No. 56656

Rear section module for size 1 or 2 (single-axis controller) drive controller:

SI6A161, SI6A162 and SI6A261

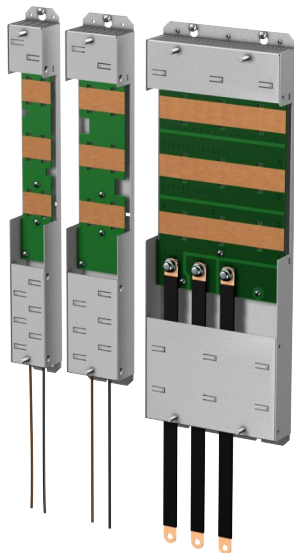
DL6B12

ID No. 56663

Rear section module for size 2 (double-axis controller) or 3 drive controller:

SI6A262 and SI6A361

Quick DC-Link DL6B for supply module



The following designs are available:

DL6B20

ID No. 56657

Rear section module for size 2 supply module:

PS6A24

DL6B21

ID No. 56658

Rear section module for size 3 supply module:

PS6A34

DL6B22

ID No. 5050114

Rear section module for size 4 supply module:

PS6A44

Quick DC-Link DL6B insulation end section

ID No. 56659

Insulation end sections for the left and right termination of the group,
2 pcs.

7.4.5 Braking resistor

In addition to the supply modules, STOBBER offers braking resistors in the various sizes and performance classes described below. For the selection, note the minimum permitted braking resistors specified in the technical data of the supply modules. In the event of a fault, such as a defective brake chopper, the supply module must be disconnected from the power supply.

7.4.5.1 Assignment of braking resistor – PS6

Type	KWADQU 420×91 with MWS306L	KWADQU 420×91 with MWS310L	FZZMQU 400×65	FGFKQU 31005	FGFKQU 31009	FGFKQU 31114
ID No.	138675	138676	56635	56636	5050115	5050116
PS6A24	(X)	X	X	X	—	—
PS6A34	(X)	X	X	X	—	—
PS6A44	(—)	(—)	(—)	(X)	X	X

Tab. 47: Braking resistor assignment to PS6 supply module

X	Recommended
(X)	Possible
(—)	Useful under certain conditions
—	Not possible

7.4.5.2 KWADQU flat resistor

The braking resistor is available with two different mounting bracket sets (MWS).

Properties

Specification	KWADQU 420×91 with MWS306L	KWADQU 420×91 with MWS310L
ID No.	138675	138676
Type	Flat resistor with temperature switch (incl. mounting bracket)	
Resistance [Ω]	100 \pm 10%	
Thermal drift	\pm 10%	
Power [W]	600	
Thermal time constant τ_{th} [s]	60	
Pulse power for < 1 s [kW]	13	
U_{max} [V]	848	
Cable design	FEP	
Cable length [mm]	500	
Conductor cross-section [AWG]	14/19 (1.9 mm ²)	
Weight without packaging [g]	2620	2770
Protection class	IP54	
Marks and test symbols	cURus, CE, UKCA	

Tab. 48: KWADQU specification

Specification	Temperature switch
Switching capacity	2 A / 24 V _{DC} (DC11)
Nominal response temperature ϑ_{NAT}	180 °C \pm 5 K
Type	NC
Cable design	FEP
Cable length [mm]	500
Conductor cross-section [AWG]	22

Tab. 49: Temperature switch specification

Dimensions

Braking resistor with MWS306L

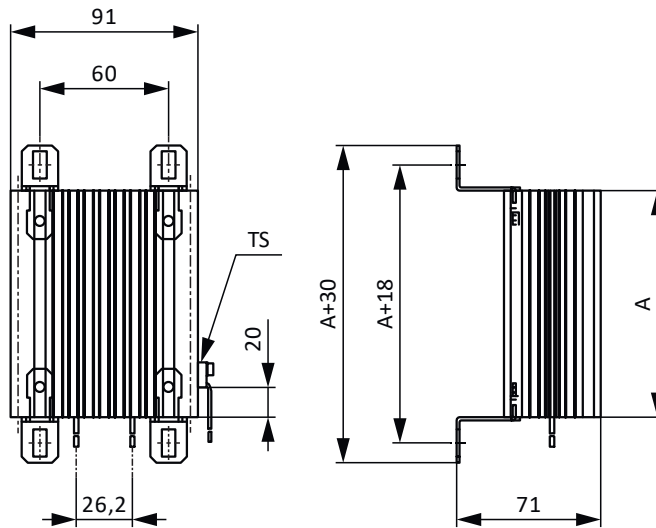


Fig. 9: KWADQU dimensional drawing with MWS306L

Braking resistor with MWS310L

The mounting brackets are freely positionable in the vertical direction over the entire length of the braking resistor.

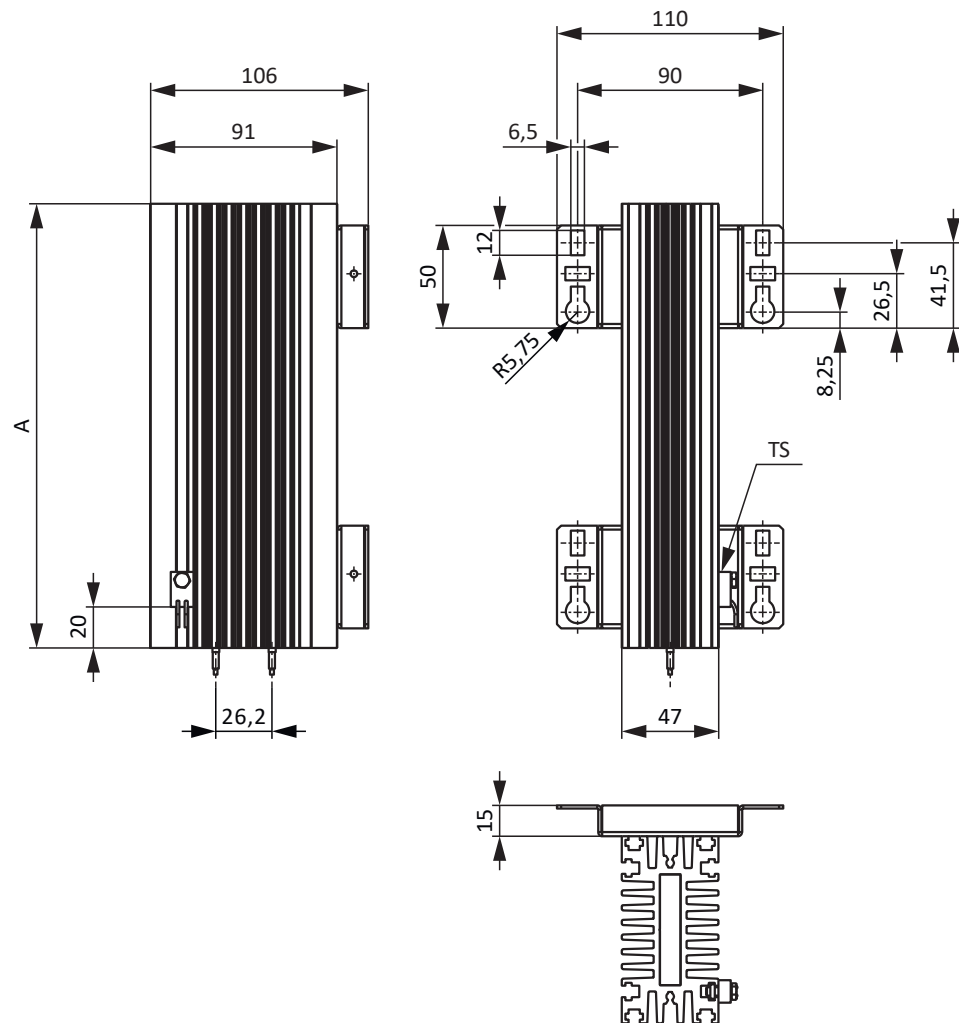


Fig. 10: KWADQU dimensional drawing with MWS310L

Dimension	KWADQU 420×91
A	420

Tab. 50: KWADQU dimensions [mm]

7.4.5.3 FZZMQU tubular fixed resistor

Properties

Specification	FZZMQU 400×65
ID No.	56635
Type	Tubular fixed resistor with temperature switch
Resistance [Ω]	47 ±10%
Thermal drift	±10%
Power [W]	1200
Thermal time constant τ_{th} [s]	40
Pulse power for < 1 s [kW]	36
U_{max} [V]	848
Weight without packaging [g]	4200
Protection class	IP20
Marks and test symbols	cURus, CE, UKCA

Tab. 51: FZZMQU specification

Specification	Temperature switch
Switching capacity	2 A / 24 V _{DC} (DC11)
Nominal response temperature ϑ_{NAT}	180 °C ± 5 K
Type	NC
Cable design	FEP
Cable length [mm]	500
Conductor cross-section [AWG]	22

Tab. 52: Temperature switch specification

Dimensions

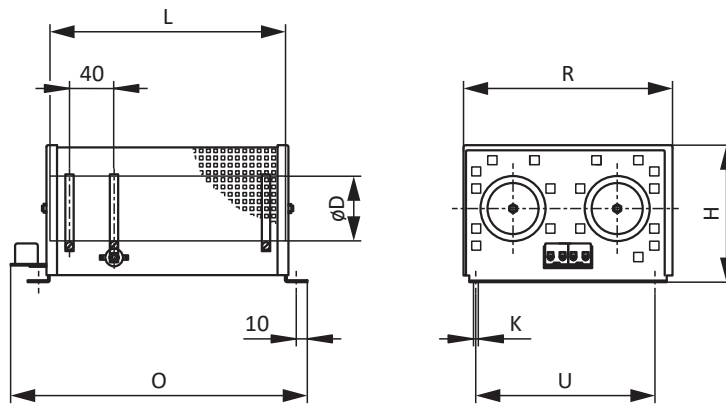


Fig. 11: FZZMQU dimensional drawing

Dimension	FZZMQU 400×65
L × D	400 × 65
H	120
K	6.5 × 12
O	485
R	185
U	150

Tab. 53: FZZMQU dimensions [mm]

7.4.5.4 FGFKQU steel-grid fixed resistor

Properties

Specification	FGFKQU 31005	FGFKQU 31009	FGFKQU 31114
ID No.	56636	5050115	5050116
Type	Steel-grid fixed resistor with temperature switch		
Resistance [Ω]	22 \pm 10%	14.4 \pm 10%	9.5 \pm 10%
Thermal drift	\pm 10%	\pm 10%	\pm 10%
Power [W]	2500	4500	7000
Thermal time constant τ_{th} [s]	30	30	20
Pulse power for < 1 s [kW]	50	90	140
U_{max} [V]	848		
Weight without packaging [g]	7500	9500	13000
Protection class	IP20		
Marks and test symbols	cURus, CE, UKCA		

Tab. 54: FGFKQU specification

Specification	Temperature switch
Switching capacity	2 A / 24 V _{DC} (DC11)
Nominal response temperature ϑ_{NAT}	100 °C \pm 5 K
Type	NC
Cable design	FEP
Cable length [mm]	500
Conductor cross-section [AWG]	22

Tab. 55: Temperature switch specification

Dimensions

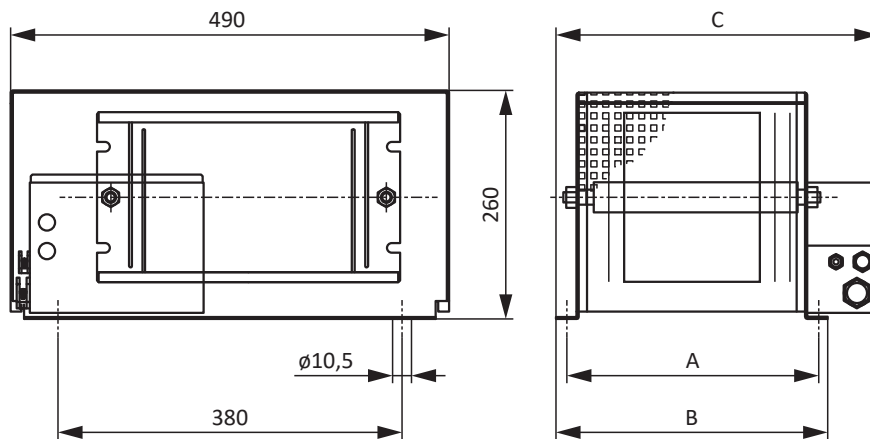


Fig. 12: FGFKQU dimensional drawing

Dimension	FGFKQU 31005	FGFKQU 31009	FGFKQU 31114
A	270	370	370
B	295	395	395
C	355	455	455

Tab. 56: FGFKQU dimensions [mm]

7.4.6 Choke

Technical specifications for suitable chokes can be found in the following chapters.

7.4.6.1 TEP power choke

Power chokes are used to dampen voltage and current peaks and reduce the load of the power feed-in of the supply modules.

Properties

Specification	TEP4010-2US00
ID No.	56528
Phases	3
Thermally allowed continuous current	100 A
Nominal current $I_{N,MF}$	90 A
Absolute loss P_V	103 W
Inductance	0.14 mH
Voltage range	3 × 400 V _{AC} +32%/-50% 3 × 480 V _{AC} +10%/-58%
Voltage drop U_k	2%
Frequency range	50/60 Hz
Protection class	IP00
Max. surrounding temperature $\vartheta_{amb,max}$	40 °C
Insulation class	B
Connection	Screw terminal
Connection type	Flexible with and without end sleeve
Max. conductor cross-section	6 – 35 mm ²
Tightening torque	2.5 Nm
Insulation stripping length	17 mm
Installation	Screws
Directive	EN 61558-2-20
UL Recognized Component (CAN; USA)	Yes
Marks and test symbols	cURus, CE

Tab. 57: TEP specification

Dimensions

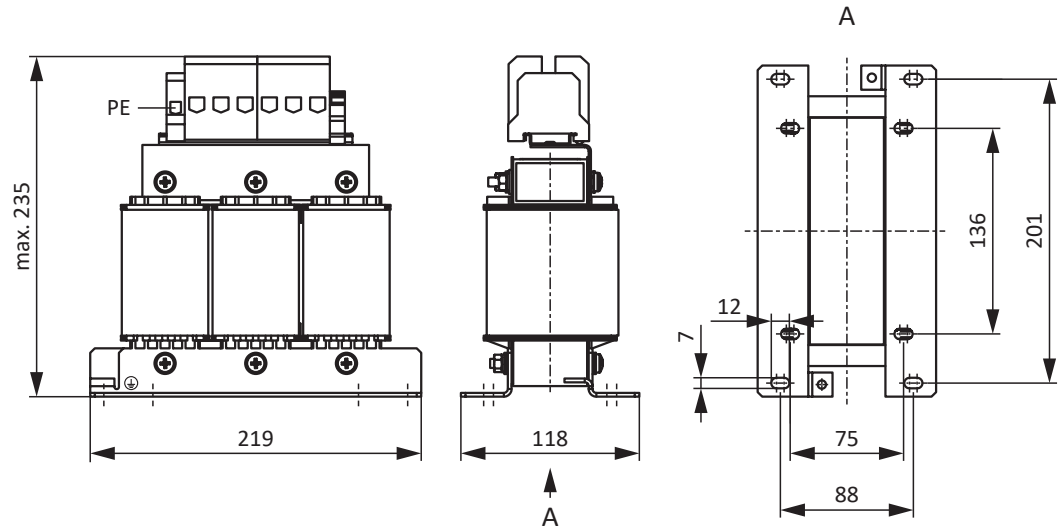


Fig. 13: Power choke dimensional drawing

Dimensions	TEP4010-2US00
Height [mm]	235
Width [mm]	219
Depth [mm]	118
Vertical distance 1 – fastening holes [mm]	201
Vertical distance 2 – Fastening holes [mm]	136
Horizontal distance 1 – fastening holes [mm]	88
Horizontal distance 2 – Fastening holes [mm]	75
Drill holes – Depth [mm]	7
Drill holes – Width [mm]	12
Screw connection – M	M6
Weight without packaging [g]	9900

Tab. 58: TEP dimensions and weight

7.4.6.2 TEP output choke

Output chokes are required for connecting size 0 to 2 drive controllers to synchronous servo motors or asynchronous motors from a cable length > 50 m in order to reduce interference pulses and protect the drive system. If Lean motors are connected, output chokes must not be used.

Information

The following technical data only applies to a rotating magnetic field frequency of 200 Hz. For example, this rotating magnetic field frequency is achieved with a motor with 4 pole pairs and a nominal speed of 3000 rpm. Always observe the specified derating for higher rotating magnetic field frequencies. Also observe the relationship with the clock frequency.

Properties

Specification	TEP3720-0ES41	TEP3820-0CS41	TEP4020-0RS41
ID No.	53188	53189	53190
Voltage range	3 × 0 to 480 V _{AC}		
Frequency range	0 – 200 Hz		
Nominal current I _{N,MF} at 4 kHz	4 A	17.5 A	38 A
Nominal current I _{N,MF} at 8 kHz	3.3 A	15.2 A	30.4 A
Max. permitted motor cable length with output choke	100 m		
Max. surrounding temperature $\vartheta_{amb,max}$	40 °C		
Protection class	IP00		
Winding losses	11 W	29 W	61 W
Iron losses	25 W	16 W	33 W
Connection	Screw terminal		
Max. conductor cross-section	10 mm ²		
UL Recognized Component (CAN; USA)	Yes		
Marks and test symbols	cURus, CE		

Tab. 59: TEP specification

Dimensions

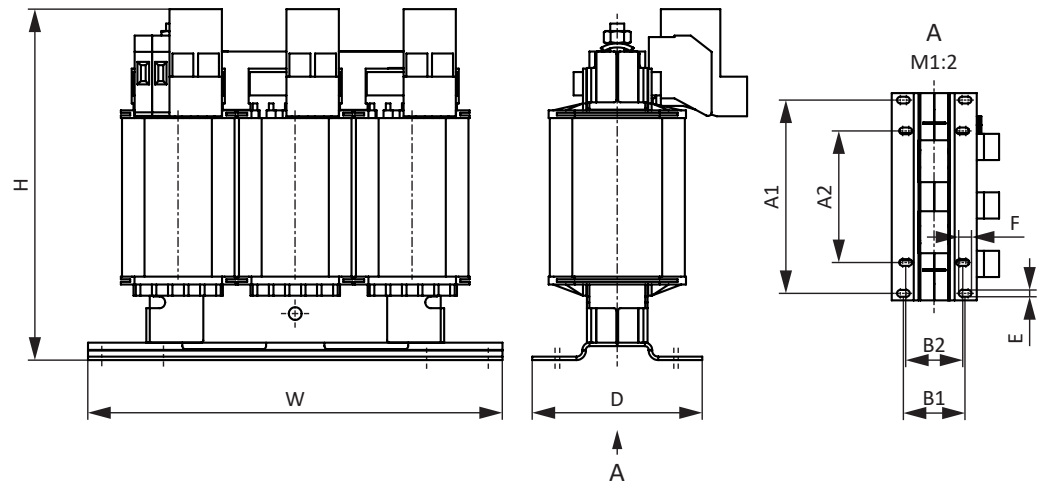


Fig. 14: TEP dimensional drawing

Dimension	TEP3720-0ES41	TEP3820-0CS41	TEP4020-0RS41
Height H [mm]	Max. 153	Max. 153	Max. 180
Width W [mm]	178	178	219
Depth D [mm]	73	88	119
Vertical distance – Fastening holes A1 [mm]	166	166	201
Vertical distance – Fastening holes A2 [mm]	113	113	136
Horizontal distance – Fastening holes B1 [mm]	53	68	89
Horizontal distance – Fastening holes B2 [mm]	49	64	76
Drill holes – Depth E [mm]	5.8	5.8	7
Drill holes – Width F [mm]	11	11	13
Screw connection – M	M5	M5	M6
Weight without packaging [g]	2900	5900	8800

Tab. 60: TEP dimensions and weight

7.4.7 HTL-to-TTL adapter

HT6 HTL-to-TTL adapter



ID No. 56665

Adapters for SC6 and SI6 series drive controllers for level conversion from HTL signals to TTL signals.

It is used to connect an HTL differential incremental encoder to terminal X4 of the drive controller.

7.5 Further information

7.5.1 Directives and standards

The following European directives and standards are relevant to the drive controllers:

- Machinery Directive 2006/42/EC
- Low Voltage Directive 2014/35/EU
- EMC Directive 2014/30/EU
- EN ISO 13849-1:2015
- EN ISO 13849-2:2012
- EN 61800-3:2018
- EN 61800-5-1:2017
- EN 61800-5-2:2017

7.5.2 Marks and test symbols

The following marks and test symbols are mentioned in the technical data.



RoHS lead-free mark

Marking in accordance with RoHS directive 2011-65-EU.



CE mark

Manufacturer's self declaration: The product meets the requirements of EU directives.



UKCA test symbol

Manufacturer's self declaration: The product meets the requirements of UK directives.



UL test symbol (cULus)

This product is listed by UL for the United States and Canada.

Representative samples of this product have been evaluated by UL and meet the requirements of applicable standards.



UL test symbol for recognized component mark (cURus)

This component or material is recognized by UL. Representative samples of this product have been evaluated by UL and meet applicable requirements.

7.5.3 Additional documentation

Additional documentation related to the product can be found at

<http://www.stoeber.de/en/downloads/>

Enter the ID of the documentation in the Search field.

Documentation	ID
Manual for SI6 drive controllers	442728

8 SD6 Drive controllers

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8 Drive controllers

SD6

8.1 Overview

High performance and flexibility

Features

- Nominal output current up to 85 A
- 250% overload capacity
- Control of linear and rotary synchronous servo motors and asynchronous motors
- Multi-functional encoder interfaces
- Automatic motor parameterization from the electronic motor nameplate
- Isochronic system bus (IGB motion bus) for parameterization and multi-axis applications
- Communication over CANopen, EtherCAT or PROFINET
- Safe Torque Off (STO) in the standard version, expanded safety technology (SS1, SS2, SLS, etc.) as an option
- Digital and analog inputs and outputs as an option
- Brake chopper, brake control and line filter
- Energy supply through direct power supply
- Flexible DC link connection for multi-axis applications
- Convenient operating unit consisting of graphical display and keys
- Paramodul removable data storage for quick commissioning and service

8.1.1 Features

STOBER drive controllers of the SD6 series offer maximum precision and productivity for automation technology and mechanical engineering despite ever more complex functions. Highly dynamic drives ensure the shortest recovery times from fast changes in set value and load jumps. There is also an option of connecting the drive controllers in a DC link for multi-axis applications, which improves the energy footprint of the entire system. The SD6 drive controller is available in four sizes with a nominal output current of up to 85 A.

The optimized vector control, sensorless vector control, U/f slip-compensated and U/f controller control types are available for use with asynchronous motors.



SD6 drive controller

Fully electronic STO as a standard feature

There is already a wear-free, fully electronic interface for the Safe Torque Off (STO) safety function available in the standard series version. The solution is a technical innovation that works without any system tests disrupting operation. In practical terms, this means an impressive increase in the availability of machines and systems. Time-consuming planning and documentation of tests are also eliminated. In multi-axis applications with SD6 drive controllers, the STO safety function can simply be looped through. The safety-relevant functions were developed together with Pils GmbH & Co. KG.



Expanded safety option

In addition to the safe stop functions Safe Stop 1 (SS1) and Safe Stop 2 (SS2), additional safety functions such as Safely-Limited Speed (SLS), Safe Brake Control (SBC), Safe Brake Test (SBT), Safe Direction (SDI) and Safely-Limited Increment (SLI) are also available.

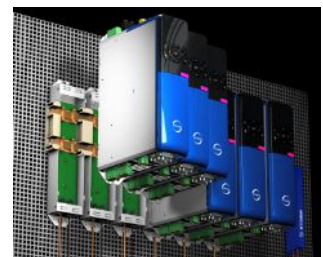
Certified safety

TÜV certification makes it possible to use SD6 drive controllers even in applications with challenging safety requirements:

- SIL 3, HFT 1 in accordance with EN 61800-5-2
- PL e, category 4 in accordance with DIN EN ISO 13849

Quick DC-Link

All the product types of the SD6 drive controller have the option of a DC link connection. This technology makes it possible for the regenerative production of energy from one drive to be used as motor energy by another drive. The Quick DC-Link rear structure element has been developed to set up a reliable and efficient rail connection to the DC link connection. This optionally available accessory connects the DC links of the individual drive controllers by means of copper rails that can carry a load of up to 200 A. The rails can be attached without any tools using quick fastening clamps.



Paramodul removable data storage

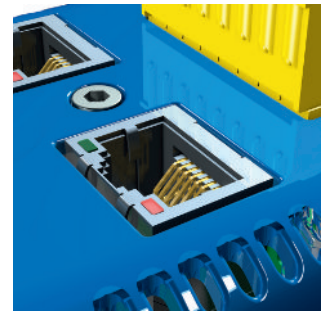
Removable data storage with integrated microSD card is available for fast series commissioning by copying and for easy service when replacing devices. It represents the ideal medium for saving additional project data and documentation and can be used for direct editing on a PC.



Integrated bus (IGB)

SD6 drive controllers have two interfaces for the integrated bus in the standard version. The integrated bus is used for easy configuration over Ethernet and isochronic data exchange for the following functions:

- Multi-axis synchronization between the drive controllers (IGB motion bus)
- Direct connection for remote maintenance of individual and multiple drive controllers
- Direct connection between one or more drive controllers and a PC



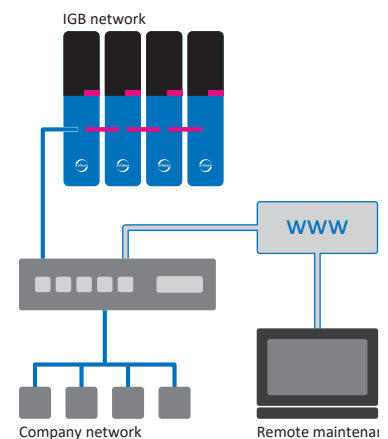
Interface for the Integrated Bus

IGB motion bus

The IGB motion bus allows for cyclic, isochronic data exchange between multiple SD6 drive controllers integrated into the IGB network. In addition to transferring guide values for master/slave operation, it is possible to exchange any other data as well.

STOBER remote maintenance concept

STOBER remote maintenance enables commissioning software to be used to perform all processes and sequences just like an on-site service visit. The concept guides users through a controlled and protected procedure. It ensures that the person responsible for the machine is there on site to pay attention to special situations and personal safety. On the other end, the remote maintenance specialist has the assurance of communicating with a responsible employee on site who is monitoring the situation on the machine.



Remote maintenance enables all processes and sequences to be performed just like an on-site service visit.

Brake management

The SD6 drive controller can activate a 24 V_{DC} brake using an integrated brake control. Brake management provides two functions for the brake system:

- Cyclic brake test
- Bed in brake

8.1.2 Software components

Project configuration and commissioning

The 6th generation of DriveControlSuite project configuration and commissioning software has all the functions for the efficient use of drive controllers in single-axis and multi-axis applications. The program guides you step by step through the complete project configuration and parameterization process using wizards.

Open communication

Device communication is possible using EtherCAT, CANopen or PROFINET.

Applications

A drive-based application is recommended for the decentralized motion control of sophisticated machines.

The drive-based application package from STOBBER is the right choice wherever universal and flexible solutions are needed. The Drive Based Synchronous application provides drive-based motion control for synchronous operation, positioning, velocity and torque/force with the PLCopen Motion Control command set. These standard commands have been combined into operating modes for different application cases and supplemented with additional functions such as motion block linking or cams. For the command operating mode, all properties of the movements are specified directly by the controller. The properties of the movements in the drive are predefined in the motion block operating mode so that only a start signal is necessary to perform the movement. Linking can be used to define complete motion sequences.

In addition, the CiA 402 application is also available, which includes both the controller-based and drive-based operating modes (csp, csv, cst, ip, pp, pv, pt).

Furthermore, programming based on IEC 61131-3 with CFC can be used to create new applications or expand existing ones.

8.1.3 Application training

STOBBER offers a multi-level training program that is essentially focused on the drive controller.

G6 Basic

Training content: System overview, installation and commissioning of the drive controller. Use of option modules. Parameterization, commissioning and diagnostics using the commissioning software. Remote maintenance. Basics of controller optimization. Configuration of the drive train. Integrated software functions. Software applications. Connection to a higher-level controller. Basics of safety technology. Practical exercises on training topics.

Software used: DriveControlSuite.

G6 Customized

Training content: Special knowledge for regulating, control and safety technology. Electronic cam disk. Practical exercises on training topics.

8.2 Technical data

Technical data for the drive controller can be found in the following chapters.

8.2.1 Type designation

SD	6	A	0	6	T	E	X
----	---	---	---	---	---	---	---

Tab. 1: Example code for type designation

Code	Designation	Design
SD	Series	
6	Generation	Generation 6
A, B	Version	
0 – 3	Size	
6 (0 – 9)	Power output stage	Power output stage within the size
T	Safety module	ST6: STO via terminals
E		SE6: Expanded safety functionality via terminals
N	Communication module	Empty
E		EC6: EtherCAT
C		CA6: CANopen
P		PN6: PROFINET
N	Terminal module	Empty
X		XI6: Extended
R		RI6: Resolver
I		IO6: Standard

Tab. 2: Meaning of the example code

8.2.2 Sizes

Type	Size
SD6A02	Size 0
SD6A04	Size 0
SD6A06	Size 0
SD6A14	Size 1
SD6A16	Size 1
SD6A24	Size 2
SD6A26	Size 2
SD6A34	Size 3
SD6A36	Size 3
SD6A38	Size 3

Tab. 3: Available SD6 types and sizes



SD6 in sizes 0, 1, 2 and 3

8.2.3 General technical data

The following information applies to all device types.

Device features	
Protection class of the device	IP20
Protection class of the installation space	At least IP54
Protection class	Protection class I in accordance with EN 61140
Radio interference suppression	Integrated line filter in accordance with EN 61800-3, interference emission class C3
Overvoltage category	III in accordance with EN 61800-5-1
Marks and test symbols	CE, cULus, RoHS

Tab. 4: Device features

Transport and storage conditions	
Storage/transport temperature	-20 °C to +70 °C Maximum change: 20 K/h
Relative humidity	Maximum relative humidity 85%, non-condensing
Vibration (transport) in accordance with EN 60068-2-6	5 Hz ≤ f ≤ 9 Hz: 3.5 mm 9 Hz ≤ f ≤ 200 Hz: 10 m/s ² 200 Hz ≤ f ≤ 500 Hz: 15 m/s ²
Fall height for freefall ¹ Weight < 100 kg in accordance with EN 61800-2 (or IEC 60721-3-2, class 2M1)	0.25 m

Tab. 5: Transport and storage conditions

Operating conditions	
Surrounding temperature during operation	0 °C to 45 °C with nominal data 45 °C to 55 °C with derating -2.5% / K
Relative humidity	Maximum relative humidity 85%, non-condensing
Installation altitude	0 m to 1000 m above sea level without restrictions 1000 m to 2000 m above sea level with -1.5%/100 m derating
Pollution degree	Pollution degree 2 in accordance with EN 50178
Ventilation	Installed fan
Vibration (operation) in accordance with EN 60068-2-6	5 Hz ≤ f ≤ 9 Hz: 0.35 mm 9 Hz ≤ f ≤ 200 Hz: 1 m/s ²

Tab. 6: Operating conditions

Discharge times	
Self-discharge of DC link	6 min

Tab. 7: Discharge times of the DC link circuit

¹Only valid for components in original packaging

8.2.4 Electrical data

The electrical data of the available SD6 sizes as well as the properties of the brake chopper can be found in the following chapters.

Information

For the time span between energizing two devices, note that:

- Direct, repeat activation of the supply voltage is possible for cyclical power-on/power-off operation.

Information

The STO safety function is available for safe stopping as an alternative to continuous, cyclical power-on/power-off operation.

An explanation of the formula symbols used can be found in the chapter [▶ 13.1](#).

8.2.4.1 Control unit

Electrical data	All types
U_{1CU}	24 V _{DC} , +20%/–15%
I_{1maxCU}	1.5 A

Tab. 8: Control unit electrical data

8.2.4.2 Power unit: Size 0

Electrical data	SD6A02	SD6A04	SD6A06
U_{1PU}	1 × 230 V _{AC} , +20% / –40%, 50/60 Hz	3 × 400 V _{AC} , +32% / –50%, 50/60 Hz; 3 × 480 V _{AC} , +10% / –58%, 50/60 Hz	
f_{2PU}	0 – 700 Hz		
U_{2PU}	0 – max. U_{1PU}		
$U_{2PU,ZK}$	$\sqrt{2} \times U_{1PU}$		
C_{PU}	340 μF	135 μF	135 μF
$C_{N,PU}$	1620 μF	540 μF	540 μF

Tab. 9: SD6 electrical data, size 0

Nominal currents up to +45 °C (in the control cabinet)

Electrical data	SD6A02	SD6A04	SD6A06
$f_{PWM,PU}$	4 kHz		
$I_{1N,PU}$	8.3 A	2.8 A	5.4 A
$I_{2N,PU}$	4 A	2.3 A	4.5 A
I_{2maxPU}	180% for 5 s; 150% for 30 s		

Tab. 10: SD6 electrical data, size 0, for 4 kHz clock frequency

Electrical data	SD6A02	SD6A04	SD6A06
$f_{PWM,PU}$	8 kHz		
$I_{1N,PU}$	6 A	2.2 A	4 A
$I_{2N,PU}$	3 A	1.7 A	3.4 A
I_{2maxPU}	250% for 2 s; 200% for 5 s		

Tab. 11: SD6 electrical data, size 0, for 8 kHz clock frequency

Electrical data	SD6A02	SD6A04	SD6A06
U_{onCH}	400 – 420 V _{DC}	780 – 800 V _{DC}	
U_{offCH}	360 – 380 V _{DC}	740 – 760 V _{DC}	
R_{2minRB}	100 Ω		
P_{maxRB}	1.8 kW	6.4 kW	
P_{effRB}	1.0 kW	2.9 kW	

Tab. 12: Brake chopper electrical data, size 0

8.2.4.3 Power unit: Size 1

Electrical data	SD6A14	SD6A16
U_{1PU}	3 × 400 V _{AC} , +32% / -50%, 50/60 Hz; 3 × 480 V _{AC} , +10% / -58%, 50/60 Hz	
f_{2PU}	0 – 700 Hz	
U_{2PU}	0 – max. U_{1PU}	
$U_{2PU,ZK}$	$\sqrt{2} \times U_{1PU}$	
C_{PU}	470 μF	560 μF
$C_{N,PU}$	1400 μF	1400 μF

Tab. 13: SD6 electrical data, size 1

Nominal currents up to +45 °C (in the control cabinet)

Electrical data	SD6A14	SD6A16
$f_{PWM,PU}$	4 kHz	
$I_{1N,PU}$	12 A	19.2 A
$I_{2N,PU}$	10 A	16 A
I_{2maxPU}	180% for 5 s; 150% for 30 s	

Tab. 14: SD6 electrical data, size 1, for 4 kHz clock frequency

Electrical data	SD6A14	SD6A16
$f_{PWM,PU}$	8 kHz	
$I_{1N,PU}$	9.3 A	15.8 A
$I_{2N,PU}$	6 A	10 A
I_{2maxPU}	250% for 2 s; 200% for 5 s	

Tab. 15: SD6 electrical data, size 1, for 8 kHz clock frequency

Electrical data	SD6A14	SD6A16
U_{onCH}	780 – 800 V _{DC}	
U_{offCH}	740 – 760 V _{DC}	
R_{2minRB}	47 Ω	
P_{maxRB}	13.6 kW	
P_{effRB}	6.2 kW	

Tab. 16: Brake chopper electrical data, size 1

8.2.4.4 Power unit: Size 2

Electrical data	SD6A24	SD6A26
U_{1PU}	3 × 400 V _{AC} , +32% / -50%, 50/60 Hz; 3 × 480 V _{AC} , +10% / -58%, 50/60 Hz	
f_{2PU}	0 – 700 Hz	
U_{2PU}	0 – max. U_{1PU}	
$U_{2PU,ZK}$	$\sqrt{2} \times U_{1PU}$	
C_{PU}	680 μF	1000 μF
$C_{N,PU}$	1400 μF	1400 μF

Tab. 17: SD6 electrical data, size 2

Nominal currents up to +45 °C (in the control cabinet)

Electrical data	SD6A24	SD6A26
$f_{\text{PWM,PU}}$	4 kHz	
$I_{1\text{N,PU}}$	26.4 A	38.4 A
$I_{2\text{N,PU}}$	22 A	32 A
$I_{2\text{maxPU}}$	180% for 5 s; 150% for 30 s	

Tab. 18: SD6 electrical data, size 2, for 4 kHz clock frequency

Electrical data	SD6A24	SD6A26
$f_{\text{PWM,PU}}$	8 kHz	
$I_{1\text{N,PU}}$	24.5 A	32.6 A
$I_{2\text{N,PU}}$	14 A	20 A
$I_{2\text{maxPU}}$	250% for 2 s; 200% for 5 s	

Tab. 19: SD6 electrical data, size 2, for 8 kHz clock frequency

Electrical data	SD6A24	SD6A26
U_{onCH}	780 – 800 V _{DC}	
U_{offCH}	740 – 760 V _{DC}	
$R_{2\text{minRB}}$	22 Ω	
P_{maxRB}	29.1 kW	
P_{effRB}	13.2 kW	

Tab. 20: Brake chopper electrical data, size 2

8.2.4.5 Power unit: Size 3

Electrical data	SD6A34	SD6A36	SD6A38
$U_{1\text{PU}}$	3 × 400 V _{AC} , +32% / -50%, 50/60 Hz; 3 × 480 V _{AC} , +10% / -58%, 50/60 Hz		
$f_{2\text{PU}}$	0 – 700 Hz		
$U_{2\text{PU}}$	0 – max. $U_{1\text{PU}}$		
$U_{2\text{PU,ZK}}$	$\sqrt{2} \times U_{1\text{PU}}$		
C_{PU}	430 μF	900 μF	900 μF
$C_{\text{N,PU}}$	5100 μF	5100 μF	5100 μF

Tab. 21: SD6 electrical data, size 3

Nominal currents up to +45 °C (in the control cabinet)

Electrical data	SD6A34	SD6A36	SD6A38
$f_{\text{PWM,PU}}$	4 kHz		
$I_{1\text{N,PU}}$	45.3 A	76 A	76 A
$I_{2\text{N,PU}}$	44 A	70 A	85 A ²
$I_{2\text{maxPU}}$	180% for 5 s; 150% for 30 s		

Tab. 22: SD6 electrical data, size 3, for 4 kHz clock frequency

Electrical data	SD6A34	SD6A36	SD6A38
$f_{\text{PWM,PU}}$	8 kHz		
$I_{1\text{N,PU}}$	37 A	62 A	76 A
$I_{2\text{N,PU}}$	30 A	50 A	60 A
$I_{2\text{maxPU}}$	250% for 2 s; 200% for 5 s		

Tab. 23: SD6 electrical data, size 3, for 8 kHz clock frequency

Electrical data	SD6A34	SD6A36	SD6A38
U_{onCH}	780 – 800 V _{DC}		
U_{offCH}	740 – 760 V _{DC}		
R_{intRB}	30 Ω (PTC resistance; 100 W; max. 1 kW for 1 s; τ = 40 s)		
$R_{2\text{minRB}}$	15 Ω		
P_{maxRB}	42 kW		
P_{effRB}	19.4 kW		

Tab. 24: Brake chopper electrical data, size 3

8.2.4.6 Power loss data in accordance with EN 61800-9-2

Type	Nominal current $I_{2N,PU}$	Apparent power	Absolute losses $P_{V,CU}^3$	Operating points ⁴								IE class ⁵	Comparison ⁶
				(0/25)	(0/50)	(0/100)	(50/25)	(50/50)	(50/100)	(90/50)	(90/100)		
				Relative losses									
	[A]	[kVA]	[W]	[%]									
SD6A02	4	0.9	10	5.01	5.07	5.68	5.20	5.37	6.30	5.88	7.43	IE2	
SD6A04	2.3	1.6	10	2.98	3.13	3.49	3.02	3.22	3.71	3.36	4.09	IE2	
SD6A06	4.5	3.1	12	1.71	1.86	2.24	1.75	1.97	2.51	2.16	3.04	IE2	
SD6A14	10	6.9	12	1.38	1.54	1.93	1.43	1.64	2.17	1.80	2.57	IE2	
SD6A16	16	11.1	12	0.95	1.12	1.66	0.99	1.23	1.98	1.41	2.52	IE2	
SD6A24	22	15.2	15	0.80	0.97	1.49	0.84	1.06	1.75	1.21	2.19	IE2	
SD6A26	32	22.2	15	0.70	0.87	1.40	0.74	0.97	1.67	1.11	2.10	IE2	
SD6A34	44	30.5	35	0.61	0.76	1.21	0.68	0.90	1.53	1.06	1.96	IE2	
SD6A36	70	48.5	35	0.53	0.69	1.18	0.59	0.82	1.49	0.97	1.89	IE2	
SD6A38	85	58.9	35	0.47	0.64	1.18	0.54	0.78	1.50	0.94	1.94	IE2	
				Absolute losses									
	[A]	[kVA]	[W]	P_V									[%]
SD6A02	4	0.9	10	45.1	45.6	51.1	46.8	48.3	56.7	52.9	66.9	IE2	51.8
SD6A04	2.3	1.6	10	47.7	50.1	55.8	48.3	51.5	59.3	53.8	65.4	IE2	40.2
SD6A06	4.5	3.1	12	52.9	57.6	69.3	54.4	61.0	77.9	67.1	94.1	IE2	39.6
SD6A14	10	6.9	12	95.3	106.1	133.3	98.6	113.2	149.9	123.9	177.0	IE2	37.1
SD6A16	16	11.1	12	104.9	124.0	184.6	110.3	136.6	219.8	156.0	279.8	IE2	35.8
SD6A24	22	15.2	15	121.5	146.9	226.1	128.1	161.6	266.0	183.7	332.7	IE2	32.9
SD6A26	32	22.2	15	154.7	192.8	311.3	164.7	214.9	370.5	246.9	465.9	IE2	38.6
SD6A34	44	30.5	35	187.5	232.2	368.7	207.7	273.9	466.8	323.0	597.8	IE2	32.1
SD6A36	70	48.5	35	256.6	332.3	570.8	287.9	397.0	721.5	471.0	915.9	IE2	33.9
SD6A38	85	58.9	35	277.8	376.9	692.3	317.4	459.0	886.1	554.6	1143.1	IE2	35.3

Tab. 25: Power loss data of the SD6 drive controller in accordance with EN 61800-9-2

General conditions

The loss data applies to drive controllers without any accessories.

The power loss calculation is based on a three-phase supply voltage with 400 V_{AC}/50 Hz.

The calculated data includes a supplement of 10% in accordance with EN 61800-9-2.

The power loss specifications refer to a clock frequency of 4 kHz.

The absolute losses for a power unit that is switched off refer to the 24 V_{DC} power supply of the control electronics.

³ Absolute losses for a power unit that is switched off

⁴ Operating points for relative motor stator frequency in % and relative torque current in %

⁵ IE class in accordance with EN 61800-9-2

⁶ Comparison of the losses for the reference related to IE2 in the nominal point (90, 100)

8.2.4.7 Power loss data of accessories

If you intend to order the drive controller with accessory parts, losses increase as follows:

Type	Absolute losses P_v [W]
SE6 safety module	< 4
ST6 safety module	1
IO6 terminal module	< 2
XI6 terminal module	< 5
RI6 terminal module	< 5
CA6 communication module	1
EC6 communication module	< 2
PN6 communication module	< 4

Tab. 26: Absolute losses of the accessories

Information

Note the absolute power loss of the encoder (usually < 3 W) and of the brake when designing as well.

Loss specifications for other optional accessories can be found in the technical data of the respective accessory part.

8.2.5 Cycle times

Possible cycle times can be found in the following table.

Type	Cycle times	Relevant parameters
Application	1 ms, 2 ms, 4 ms, 8 ms	Adjustable in A150
EtherCAT fieldbus, cyclical communication	1 ms, 2 ms, 4 ms, 8 ms	Adjustable in A150
PROFINET RT fieldbus, cyclical communication	1 ms, 2 ms, 4 ms, 8 ms	Adjustable in A150
Motion core (movement calculation)	250 μ s	—
Control cascade	62.5 μ s, 125 μ s	Depending on B24

Tab. 27: Cycle times

8.2.6 Derating

When dimensioning the drive controller, observe the derating of the nominal output current as a function of the clock frequency, surrounding temperature and installation altitude. There is no restriction for a surrounding temperature from 0 °C to 45 °C and an installation altitude of 0 m to 1000 m. The details given below apply to values outside these ranges.

8.2.6.1 Effect of the clock frequency

Changing the clock frequency f_{PWM} affects the amount of noise produced by the drive, among other things. However, increasing the clock frequency results in increased losses. During project configuration, define the highest clock frequency and use it to determine the nominal output current $I_{2N,PU}$ for dimensioning the drive controller.

Type	$I_{2N,PU}$ 4 kHz	$I_{2N,PU}$ 8 kHz	$I_{2N,PU}$ 16 kHz
SD6A02	4 A	3 A	2 A
SD6A04	2.3 A	1.7 A	1.1 A
SD6A06	4.5 A	3.4 A	2.3 A
SD6A14	10 A	6 A	4 A
SD6A16	16 A	10 A	5.7 A
SD6A24	22 A	14 A	8.1 A
SD6A26	32 A	20 A	12 A
SD6A34	44 A	30 A	18 A
SD6A36	70 A	50 A	31 A
SD6A38	85 A ⁷	60 A	37.8 A

Tab. 28: Nominal output current $I_{2N,PU}$ dependent on the clock frequency

⁷Specification applies to the default value of the field weakening voltage limit: B92 = 80%.

8.2.6.2 Effect of the installation altitude

Derating as a function of the installation altitude is determined as follows:

- 0 m to 1000 m: No restriction ($D_{IA} = 100\%$)
- 1000 m to 2000 m: Derating $-1.5\%/100$ m

Example

The drive controller needs to be installed at an altitude of 1500 m above sea level.

The derating factor D_{IA} is calculated as follows:

$$D_{IA} = 100\% - 5 \times 1.5\% = 92.5\%$$

8.2.6.3 Effect of the surrounding temperature

Derating as a function of the surrounding temperature is determined as follows:

- 0 °C to 45 °C: No restrictions ($D_T = 100\%$)
- 45 °C to 55 °C: Derating $-2.5\%/K$

Example

The drive controller needs to be operated at 50 °C.

The derating factor D_T is calculated as follows

$$D_T = 100\% - 5 \times 2.5\% = 87.5\%$$

8.2.6.4 Calculating the derating

Follow these steps for the calculation:

1. Determine the highest clock frequency (f_{PWM}) that will be used during operation and use it to determine the nominal current $I_{2N,PU}$.
2. Determine the derating factors for installation altitude and surrounding temperature.
3. Calculate the reduced nominal current $I_{2N,PU(red)}$ in accordance with the following formula:

$$I_{2N,PU(red)} = I_{2N,PU} \times D_T \times D_{IA}$$

Example

A drive controller of type SD6A06 needs to be operated at a clock frequency of 8 kHz at an altitude of 1500 m above sea level and a surrounding temperature of 50 °C.

The nominal current of the SD6A06 at 8 kHz is 3.4 A. The derating factor D_T is calculated as follows:

$$D_T = 100\% - 5 \times 2.5\% = 87.5\%$$

The derating factor D_{IA} is calculated as follows:

$$D_{IA} = 100\% - 5 \times 1.5\% = 92.5\%$$

The output current of importance for the project configuration is:

$$I_{2N,PU(red)} = 3.4 \text{ A} \times 0.875 \times 0.925 = 2.75 \text{ A}$$

8.2.7 Dimensions

The dimensions of the available SD6 sizes can be found in the following chapters.

8.2.7.1 Dimensions: sizes 0 to 2

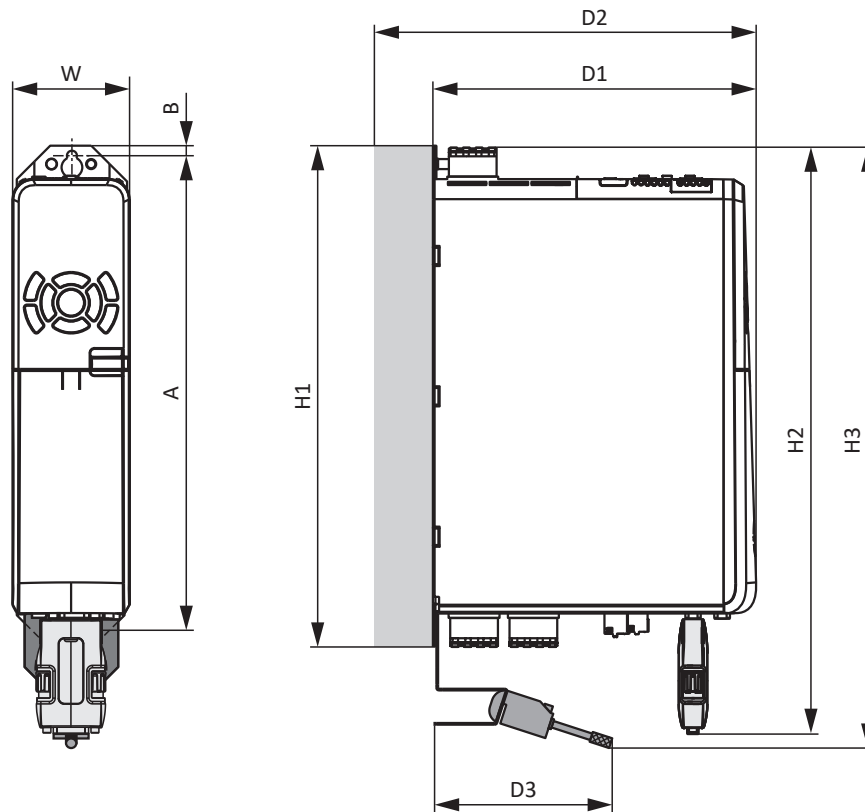


Fig. 1: SD6 dimensional drawing, sizes 0 to 2

Dimension			Size 0	Size 1	Size 2
Drive controller	Width	W	70	70	105
	Depth	D1	194	284	
	Depth incl. RB 5000 braking resistor	D2	212	302	
	Depth incl. Quick DC-Link	D2	229	319	
	Height incl. fastening clips	H1		300	
	Height incl. AES	H2		367	
	Height incl. EMC shroud	H3		approx. 376	
EMC shroud incl. shield connection terminal	Depth	D3		approx. 111	
Fastening holes	Vertical distance	A		283+2	
	Vertical distance to the upper edge	B		6	

Tab. 29: SD6 dimensions, sizes 0 to 2 [mm]

8.2.7.2 Dimensions: size 3

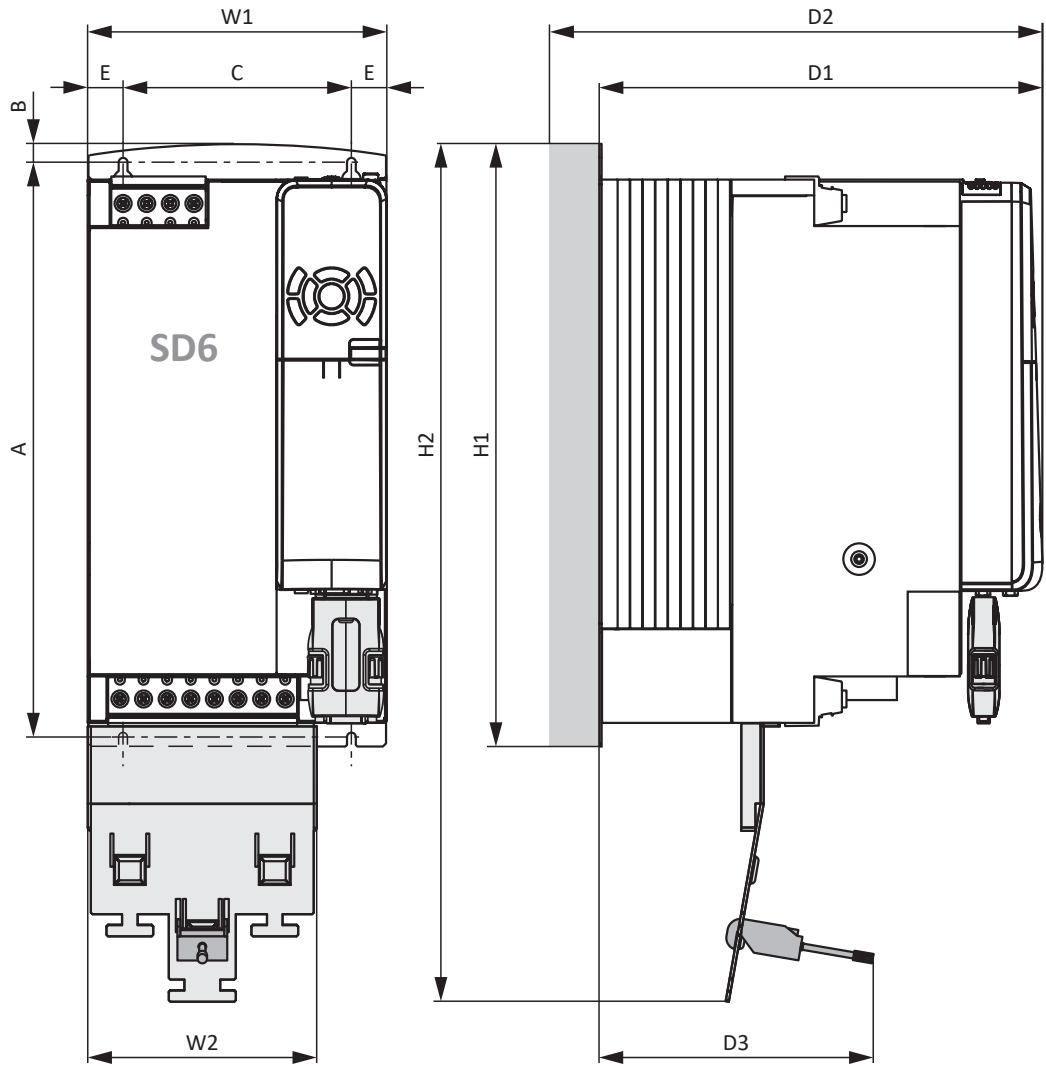


Fig. 2: SD6 dimensional drawing, size 3

Dimension		Size 3	
Drive controller	Width	W1	190
	Depth	D1	305
	Depth incl. Quick DC-Link	D2	340
	Height incl. fastening clips	H1	382.5
	Height incl. EMC shroud	H2	540
EMC shroud incl. shield	Width	W2	147
connection terminal	Depth	D3	approx. 174
Fastening holes	Vertical distance	A	365+2
	Vertical distance to the upper edge	B	11.5
	Horizontal distance between the fastening holes of the drive controller	C	150+0.2/-0.2
	Horizontal distance to the side edge of the drive controller	E	20

Tab. 30: SD6 dimensions, size 3 [mm]

8.2.8 Minimum clearances

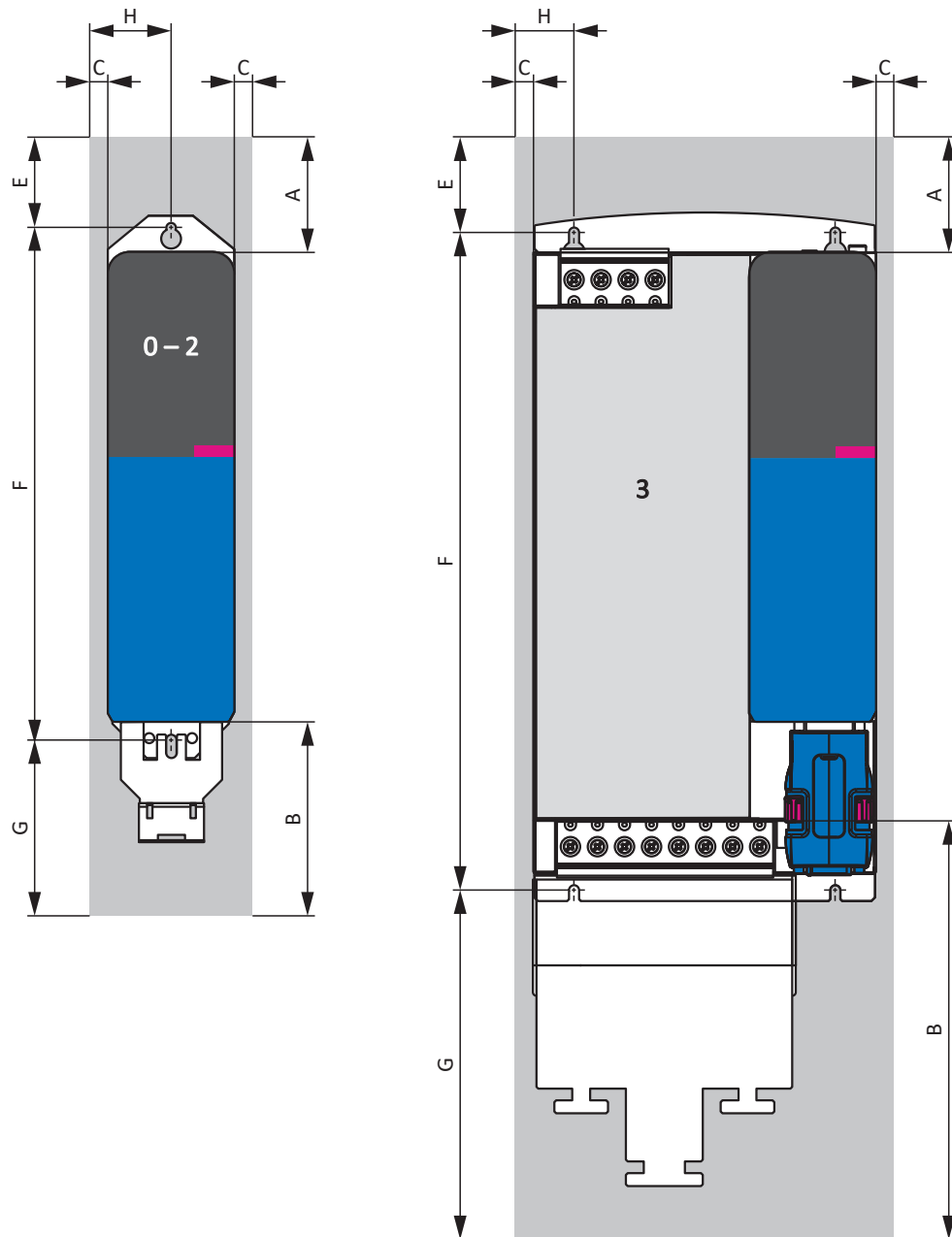


Fig. 3: Minimum clearances

The specified dimensions relate to the outer edges of the drive controller.

Minimum clearance	A (above)	B (below)	C (one the side) ⁸
Size 0 – Size 2	100	100	5
... with EMC shroud	100	120	5
Size 3	100	100	5
... with EMC shroud	100	220	5

Tab. 31: Minimum clearances [mm]

Dimension	E	F	G	H
Size 0, size 1	86	283+2	approx. 89	40
... with EMC shroud	86	283+2	approx. 109	40
Size 2	86	283+2	approx. 89	57.5
... with EMC shroud	86	283+2	approx. 109	57.5
Size 3	89	365+2	approx. 59.5	25
... with EMC shroud	89	365+2	approx. 179.5	25

Tab. 32: Dimensions [mm]

⁸ Installation without Quick DC-Link module

Chokes and filters

Avoid installation below drive controllers or supply modules. For installation in a control cabinet, a distance of approximately 100 mm to other neighboring components is recommended. This distance ensures proper heat dissipation for chokes and filters.

Braking resistors

Avoid installation below drive controllers or supply modules. In order for heated air to flow out unimpeded, a minimum clearance of approximately 200 mm must be maintained in relation to neighboring components or walls and approximately 300 mm must be maintained to components above or ceilings.

8.3 Drive controller/motor combinations

Parameterization of a STOBBER drive controller is remarkably easy, especially in combination with four-pole STOBBER asynchronous motors. The motor is fully typed by inputting just the motor size (e.g. 90L) and its wiring (star or delta). A delta connection (measurement point 230 V, 50 Hz) is available for motors up to 3 kW (size 100). By increasing the voltage at higher frequencies, the full torque can be drawn through the motor up to 87 Hz. It usually makes sense to take this expanded speed adjustment range into account when selecting the gear unit. You can find more detailed information in the chapter [▶ 5.6].

An explanation of the formula symbols used can be found in the chapter [▶ 13.1].

									SD6 A02	SD6 A04	SD6 A06	SD6 A14	SD6 A16	SD6 A24	SD6 A26	SD6 A34	SD6 A36	SD6 A38
									$I_{2N,PU}$ [A] ($f_{PWM,PU} = 4$ kHz)									
f_T [Hz]	pz	Con- nection	P_N [kW]	n_N [rpm]	M_N [Nm]	M_R/M_N	I_N [A]		4	2.3	4.5	10	16	22	32	44	70	85
Δ 230 V / Y 400 V motor winding									$I_{2N,PU} / I_N$									
IE3D080L04	50	4	Y	0.75	1445	5.0	3.7	1.7		1.4								
IE3D080L04	87	4	Δ	1.3	2503	5.0	3.7	2.94	1.4		1.5							
IE3D090S04	50	4	Y	1.1	1440	7.3	3.7	2.5	1.6		1.8							
IE3D090S04	87	4	Δ	1.91	2494	7.3	3.7	4.33			1.0							
IE3D090LX04	50	4	Y	1.5	1455	9.8	4.9	3.4	1.2		1.3							
IE3D090LX04	87	4	Δ	2.6	2520	9.8	4.9	5.89				1.7						
IE3D100KX04	50	4	Y	2.2	1450	14.5	3.8	4.55			1.0	2.2						
IE3D100KX04	87	4	Δ	3.81	2511	14.5	3.8	7.88				1.3	2.0					
IE3D100LX04	50	4	Y	3.0	1450	19.8	4	6.35				1.6						
IE3D100LX04	87	4	Δ	5.2	2511	19.8	4	11					1.5	2.0				
IE3D112M04	50	4	Δ	4.0	1465	26.1	4.5	7.9				1.3	2.0					
IE3D132SX04	50	4	Δ	5.5	1465	36	3.3	10				1.0	1.6	2.2				
IE3D132MX04	50	4	Δ	7.5	1470	49	3.9	16					1.0	1.4	2.0			
IE3D160MX04	50	4	Δ	11	1465	72	3.4	21						1.0	1.5	2.1		
IE3D160LX04	50	4	Δ	15	1475	97	3.5	27.5							1.2	1.6		
IE3D180MX04	50	4	Δ	18.5	1475	120	3.3	34.5								1.3	2.0	
IE3D180LX04	50	4	Δ	22	1475	142	3	41								1.1	1.7	2.1
IE3D200LX04	50	4	Δ	30	1480	194	2.5	54									1.3	1.6

8.4 Accessories

You can find information about the available accessories in the following chapters.

8.4.1 Safety technology

Information

The drive controller is delivered with the ST6 safety module in the standard design. If you want a drive controller with advanced safety technology, you must order it together with the drive controller. The safety modules are an integrated part of the drive controllers and must not be modified.

ST6 safety module – STO using terminals

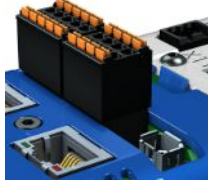
Included in the standard version.



ID No. 56431

Accessory for the use of the Safe Torque Off safety function (STO) in safety-relevant applications (PL e, SIL 3) in accordance with EN ISO 13849-1 and EN 61800-5-2. Connection to a higher-level safety circuit via terminal X12.

SE6 safety module – Expanded safety functionality via terminals



ID No. 56432

Optional accessory for use in safety-related applications up to PL e, SIL 3 in accordance with EN ISO 13849-1 and EN 61800-5-2. In addition to the basic Safe Torque Off (STO) safety function, SE6 provides other safety functions specified in EN 61800-5-2. In addition to the safe stop functions Safe Stop 1 (SS1) and Safe Stop 2 (SS2), these also include Safely-Limited Speed (SLS), Safe Brake Control (SBC), Safe Direction (SDI) and Safely-Limited Increment (SLI). The normative safety functions are supplemented by practical additional functions such as Safe Brake Test (SBT). Connection to the higher-level safety circuit using terminals X14 and X15.

X50 adapter cable (SE6 option)



ID No. 56434

Connection cable for the X50 encoder interface of the SE6 safety module with open cable ends. 1.5 m.

8.4.2 Communication

The SD6 drive controller has two interfaces for IGB communication on the top of the device as standard. The communication module is installed in the shaft at the top and it is used to connect the drive controller to the fieldbus system.

The following communication modules are available:

- EC6 for the EtherCAT connection
- CA6 for the CANopen connection
- PN6 for the PROFINET connection

IGB connecting cable



Cable for connecting the X3A or X3B interface for IGB, CAT5e, magenta.

The following designs are available:

ID No. 56489: 0.4 m.

ID No. 56490: 2 m.

PC connecting cables



ID No. 49857

Cable for connecting the X3A or X3B interface with the PC, CAT5e, blue, 5 m.

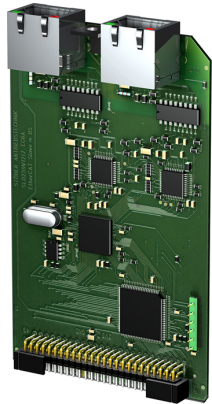
USB 2.0 Ethernet adapter



ID No. 49940

Adapter for connecting Ethernet to a USB port.

EC6 communication module



ID No. 138425

Communication module for the EtherCAT connection.

EtherCAT cables



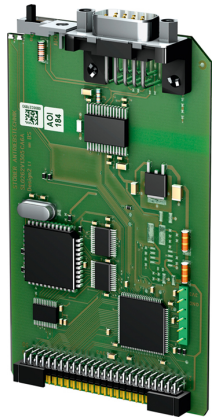
Ethernet patch cable, CAT5e, yellow.

The following designs are available:

ID No. 49313: Length approx. 0.25 m.

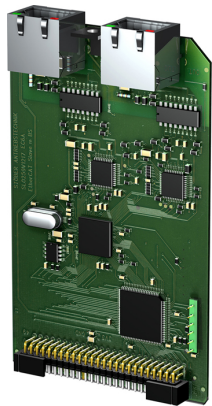
ID No. 49314: Length approx. 0.5 m.

CA6 communication module



ID No. 138427
 Communication module for the CANopen connection.

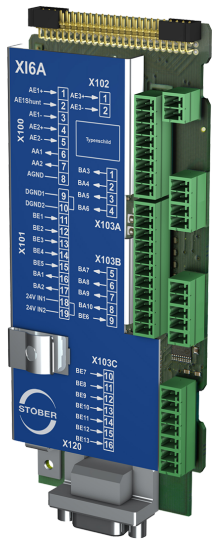
PN6 communication module



ID No. 138426
 Communication module for the PROFINET connection.

8.4.3 Terminal module

XI6 terminal module



ID no. 138421
 Terminal module for connecting analog and digital signals as well as encoders.

Supported inputs and outputs:

- 13 digital inputs (24 V_{DC})
- 10 digital outputs (24 V_{DC})
- 3 analog inputs (±10 V_{DC}, 1 x 0 – 20 mA, 16 bits)
- 2 analog outputs (±10 V_{DC}, 12 bits)

Supported encoders / interfaces:

- SSI encoder (simulation and evaluation)
- TTL incremental encoder, differential (simulation and evaluation)
- HTL incremental encoder, single-ended (simulation and evaluation)
- TTL pulse/direction interface, differential (simulation and evaluation)
- HTL pulse/direction interface, single-ended (simulation and evaluation)

RI6 terminal module



ID no. 138422

Terminal module for connecting analog and digital signals as well as encoders.

Supported inputs and outputs:

- 5 digital inputs ($24 V_{DC}$)
- 2 digital outputs ($24 V_{DC}$)
- 2 analog inputs ($\pm 10 V_{DC}$, $1 \times 0 - 20 \text{ mA}$, 16 bits)
- 2 analog outputs ($\pm 10 V_{DC}$, $\pm 20 \text{ mA}$, 12 bits)

Supported encoders / interfaces:

- Resolver (evaluation)
- EnDat 2.1 sin/cos encoder (evaluation)
- EnDat 2.1/2.2 digital encoder (evaluation)
- Sin/cos encoder (evaluation)
- SSI encoder (simulation and evaluation)
- TTL incremental encoder, differential (simulation and evaluation)
- TTL incremental encoder, single-ended (evaluation)
- HTL incremental encoder, single-ended (simulation and evaluation)
- TTL pulse/direction interface, differential (simulation and evaluation)
- TTL pulse/direction interface, single-ended (evaluation)
- HTL pulse/direction interface, single-ended (simulation and evaluation)

Information

For connecting STOBER EnDat 2.1 sin/cos cables with a 15-pin D-sub connector to an integrated motor temperature sensor, you must use the AP6A02 interface adapter (ID No. 56523), available separately, to lead out the temperature sensor cores.

IO6 terminal module



ID no. 138420

Terminal module for connecting analog and digital signals as well as encoders.

Supported inputs and outputs:

- 5 digital inputs ($24 V_{DC}$)
- 2 digital outputs ($24 V_{DC}$)
- 2 analog inputs ($\pm 10 V_{DC}$, $1 \times 0 - 20 \text{ mA}$, 12 bits)
- 2 analog outputs ($\pm 10 V_{DC}$, $\pm 20 \text{ mA}$, 12 bits)

Supported encoders / interfaces:

- HTL incremental encoder, single-ended (simulation and evaluation)
- HTL pulse/direction interface, single-ended (simulation and evaluation)

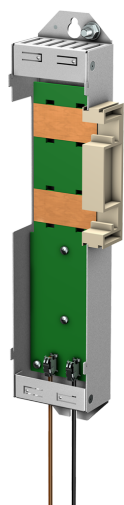
8.4.4 DC link connection

If you want to connect SD6 drive controllers in the DC link group, you will need Quick DC-Link modules of type DL6A.

You receive the DL6A rear section modules in different designs for a horizontal connection, suitable for the size of the drive controller.

The quick fastening clamps for attaching the copper rails and an insulation connection piece are contained in the scope of delivery. The copper rails are not included in the scope of delivery. These must have a cross-section of 5 x 12 mm. Insulation end sections are available separately.

DL6A Quick DC-Link for drive controllers



The following designs are available:

DL6A0

ID No. 56440

Rear section module for size 0 drive controller.

DL6A1

ID No. 56441

Rear section module for size 1 drive controller.

DL6A2

ID No. 56442

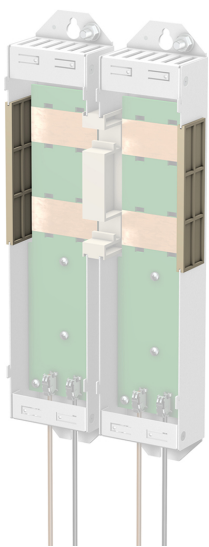
Rear section module for size 2 drive controller.

DL6A3

ID No. 56443

Rear section module for size 3 drive controller.

DL6A Quick DC-Link insulation end section



ID No. 56494

Insulation end sections for the left and right termination of the group,
2 pcs.

8.4.5 Braking resistor

In addition to drive controllers, STÖBER offers the following braking resistors described below in various sizes and performance classes. For the selection, note the minimum permitted braking resistors specified in the technical data of the individual drive controller types.

8.4.5.1 Tubular fixed resistor FZMU, FZZMU

Type	FZMU 400×65			FZZMU 400×65		
	49010	55445	55446	53895	55447	55448
SD6A02	X	—	—	—	—	—
SD6A04	X	—	—	—	—	—
SD6A06	X	—	—	—	—	—
SD6A14	(X)	—	—	X	—	—
SD6A16	(X)	—	—	X	—	—
SD6A24	(—)	X	—	(X)	X	—
SD6A26	(—)	X	—	(X)	X	—
SD6A34	(—)	(X)	X	(—)	(X)	X
SD6A36	(—)	(X)	X	(—)	(X)	X
SD6A38	(—)	(X)	X	(—)	(X)	X

Tab. 33: Assignment of FZMU, FZZMU braking resistor – SD6 drive controller

X	Recommended
(X)	Possible
(—)	Useful under certain conditions
—	Not possible

Properties

Specification	FZMU 400×65			FZZMU 400×65		
	49010	55445	55446	53895	55447	55448
ID No.	49010	55445	55446	53895	55447	55448
Type	Tubular fixed resistor			Tubular fixed resistor		
Resistance [Ω]	100 \pm 10%	22 \pm 10%	15 \pm 10%	47 \pm 10%	22 \pm 10%	15 \pm 10%
Thermal drift	\pm 10%			\pm 10%		
Power [W]	600			1200		
Therm. time const. τ_{th} [s]	40			40		
Pulse power for < 1 s [kW]	18			36		
U_{max} [V]	848			848		
Weight without packaging [g]	2200			4170		
Protection class	IP20			IP20		
Marks and test symbols	cURus, CE, UKCA			cURus, CE, UKCA		

Tab. 34: FZMU, FZZMU specification

Dimensions

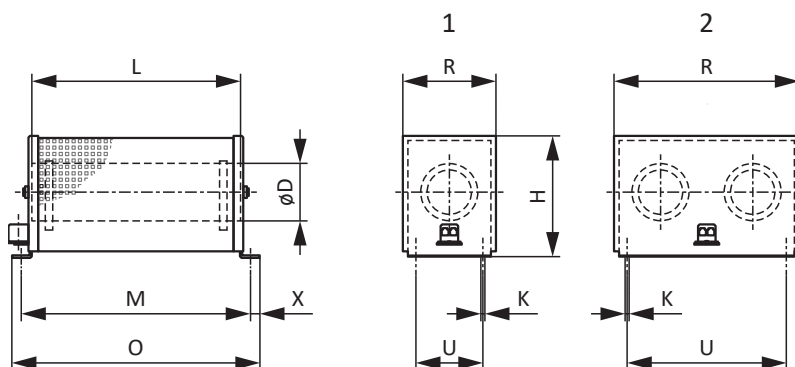


Fig. 4: FZMU (1), FZZMU (2) dimensional drawing

Dimension	FZMU 400×65			FZZMU 400×65		
	49010	55445	55446	53895	55447	55448
L x D	400 × 65			400 × 65		
H	120			120		
K	6.5 × 12			6.5 × 12		
M	430			426		
O	485			485		
R	92			185		
U	64			150		
X	10			10		

Tab. 35: FZMU, FZZMU dimensions [mm]

8.4.5.2 GVADU, GBADU flat resistor

Type	GVADU 210×20	GBADU 265×30	GBADU 405×30	GBADU 335×30	GBADU 265×30
ID No.	55441	55442	55499	55443	55444
SD6A02	X	X	X	—	—
SD6A04	X	X	X	—	—
SD6A06	X	X	X	—	—
SD6A14	(X)	(X)	(X)	X	—
SD6A16	(X)	(X)	(X)	X	—
SD6A24	(—)	(—)	(—)	(X)	X
SD6A26	(—)	(—)	(—)	(X)	X
SD6A34	(—)	(—)	(—)	(—)	(X)
SD6A36	(—)	(—)	(—)	(—)	(X)
SD6A38	(—)	(—)	(—)	(—)	(X)

Tab. 36: Assignment of GVADU, GBADU braking resistor – SD6 drive controller

X	Recommended
(X)	Possible
(—)	Useful under certain conditions
—	Not possible

Properties

Specification	GVADU 210×20	GBADU 265×30	GBADU 405×30	GBADU 335×30	GBADU 265×30
ID No.	55441	55442	55499	55443	55444
Type	Flat resistor				
Resistance [Ω]	100 \pm 10%	100 \pm 10%	100 \pm 10%	47 \pm 10%	22 \pm 10%
Thermal drift	\pm 10%	\pm 10%	\pm 10%	\pm 10%	\pm 10%
Power [W]	150	300	500	400	300
Therm. time const. τ_{th} [s]	60	60	60	60	60
Pulse power for < 1 s [kW]	3.3	6.6	11	8.8	6.6
U_{max} [V]	848	848	848	848	848
Cable design	Radox	FEP	FEP	FEP	FEP
Cable length [mm]	500	1500	500	1500	1500
Conductor cross-section [AWG]	18/19 (0.82 mm ²)	14/19 (1.9 mm ²)	14/19 (1.9 mm ²)	14/19 (1.9 mm ²)	14/19 (1.9 mm ²)
Weight without packaging [g]	300	930	1410	1200	930
Protection class	IP54	IP54	IP54	IP54	IP54
Test symbols	cURus, CE, UKCA				

Tab. 37: GVADU, GBADU specification

Dimensions

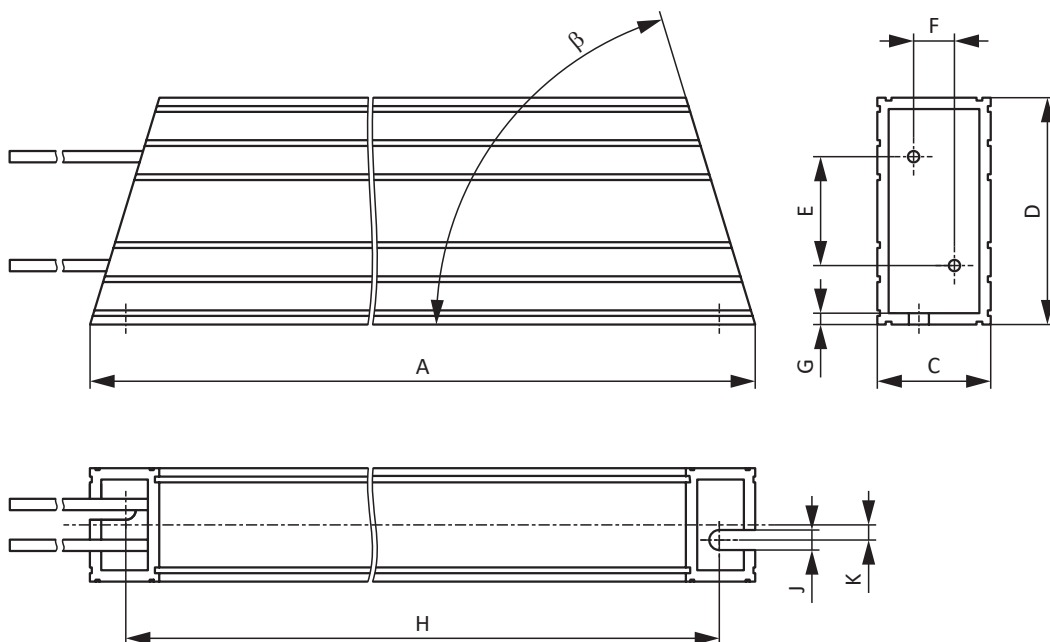


Fig. 5: GVADU, GBADU dimensional drawing

Dimension	GVADU 210×20	GBADU 265×30	GBADU 405×30	GBADU 335×30	GBADU 265×30
ID No.	55441	55442	55499	55443	55444
A	210	265	405	335	265
H	192	246	386	316	246
C	20	30	30	30	30
D	40	60	60	60	60
E	18.2	28.8	28.8	28.8	28.8
F	6.2	10.8	10.8	10.8	10.8
G	2	3	3	3	3
K	2.5	4	4	4	4
J	4.3	5.3	5.3	5.3	5.3
β	65°	73°	73°	73°	73°

Tab. 38: GVADU, GBADU dimensions [mm]

8.4.5.3 FGFKU steel-grid fixed resistor

Type	FGFKU 3100502	FGFKU 3100502	FGFKU 3111202	FGFKU 3121602
ID No.	55449	55450	55451	53897
SD6A24	X	—	—	—
SD6A26	X	—	—	—
SD6A34	(X)	X	X	X
SD6A36	(X)	X	X	X
SD6A38	(X)	X	X	X

Tab. 39: Assignment of FGFKU braking resistor – SD6 drive controller

X	Recommended
(X)	Possible
—	Not possible

Properties

Specification	FGFKU 3100502	FGFKU 3100502	FGFKU 3111202	FGFKU 3121602
ID No.	55449	55450	55451	53897
Type	Steel-grid fixed resistor			
Resistance [Ω]	22 \pm 10%	15 \pm 10%	15 \pm 10%	15 \pm 10%
Thermal drift	\pm 10%	\pm 10%	\pm 10%	\pm 10%
Power [W]	2500	2500	6000	8000
Therm. time const. τ_{th} [s]	30	30	20	20
Pulse power for < 1 s [kW]	50	50	120	160
U_{max} [V]	848	848	848	848
Weight without packaging [g]	7500	7500	12000	18000
Protection class	IP20	IP20	IP20	IP20
Marks and test symbols	cURus, CE, UKCA			

Tab. 40: FGFKU specification

Dimensions

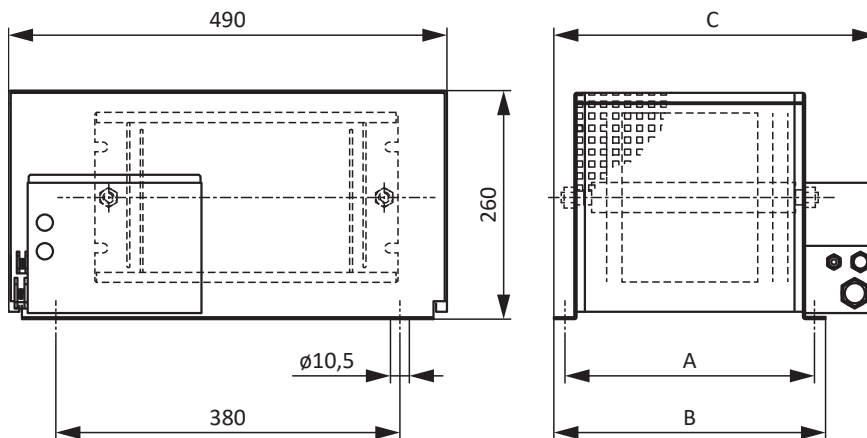


Fig. 6: FGFKU dimensional drawing

Dimension	FGFKU 3100502	FGFKU 3100502	FGFKU 3111202	FGFKU 3121602
ID No.	55449	55450	55451	53897
A	270	270	370	570
B	295	295	395	595
C	355	355	455	655

Tab. 41: FGFKU dimensions [mm]

8.4.5.4 Rear section braking resistor RB 5000

Type	RB 5022	RB 5047	RB 5100
ID No.	45618	44966	44965
SD6A02	—	—	X
SD6A04	—	—	X
SD6A06	—	—	X
SD6A14	—	X	(X)
SD6A16	—	X	(X)
SD6A24	X	—	—
SD6A26	X	—	—
SD6A34	—	—	—
SD6A36	—	—	—
SD6A38	—	—	—

Tab. 42: Assignment of RB 5000 braking resistor – SD6 drive controller

X	Recommended
(X)	Possible
—	Not possible

Properties

Specification	RB 5022	RB 5047	RB 5100
ID No.	45618	44966	44965
Resistance [Ω]	22 \pm 10%	47 \pm 10%	100 \pm 10%
Thermal drift	\pm 10%	\pm 10%	\pm 10%
Power [W]	100	60	60
Therm. time const. τ_{th} [s]	8	8	8
Pulse power for < 1 s [kW]	1.5	1.0	1.0
U_{max} [V]	800	800	800
Weight without packaging [g]	640	460	440
Cable design	Radox	Radox	Radox
Cable length [mm]	250	250	250
Conductor cross-section [AWG]	18/19	18/19	18/19
	(0.82 mm ²)	(0.82 mm ²)	(0.82 mm ²)
Maximum torque of M5 threaded bolts [Nm]	5	5	5
Protection class	IP40	IP40	IP40
Marks and test symbols	cURus, CE, UKCA	cURus, CE, UKCA	cURus, CE, UKCA

Tab. 43: RB 5000 specification

Dimensions

Dimension	RB 5022	RB 5047	RB 5100
ID No.	45618	44966	44965
Height	300	300	300
Width	94	62	62
Depth	18	18	18
Drilling diagram corresponds to size	Size 2	Size 1	Size 0 and Size 1

Tab. 44: RB 5000 dimensions [mm]

8.4.6 Choke

Technical specifications for suitable chokes can be found in the following chapters.

8.4.6.1 TEP power choke

For each size 3 SD6 drive controller, you need one power choke. It dampens voltage and current peaks and reduces the load of the drive controller power feed-in.

Properties

Specification	TEP4010-2US00
ID No.	56528
Phases	3
Thermally allowed continuous current	100 A
Nominal current $I_{N,MF}$	90 A
Absolute loss P_V	103 W
Inductance	0.14 mH
Voltage range	3 × 400 V _{AC} +32%/-50% 3 × 480 V _{AC} +10%/-58%
Voltage drop U_k	2%
Frequency range	50/60 Hz
Protection class	IP00
Max. surrounding temperature $\vartheta_{amb,max}$	40 °C
Insulation class	B
Connection	Screw terminal
Connection type	Flexible with and without end sleeve
Max. conductor cross-section	6 – 35 mm ²
Tightening torque	2.5 Nm
Insulation stripping length	17 mm
Installation	Screws
Directive	EN 61558-2-20
UL Recognized Component (CAN; USA)	Yes
Marks and test symbols	cURus, CE

Tab. 45: TEP specification

Dimensions

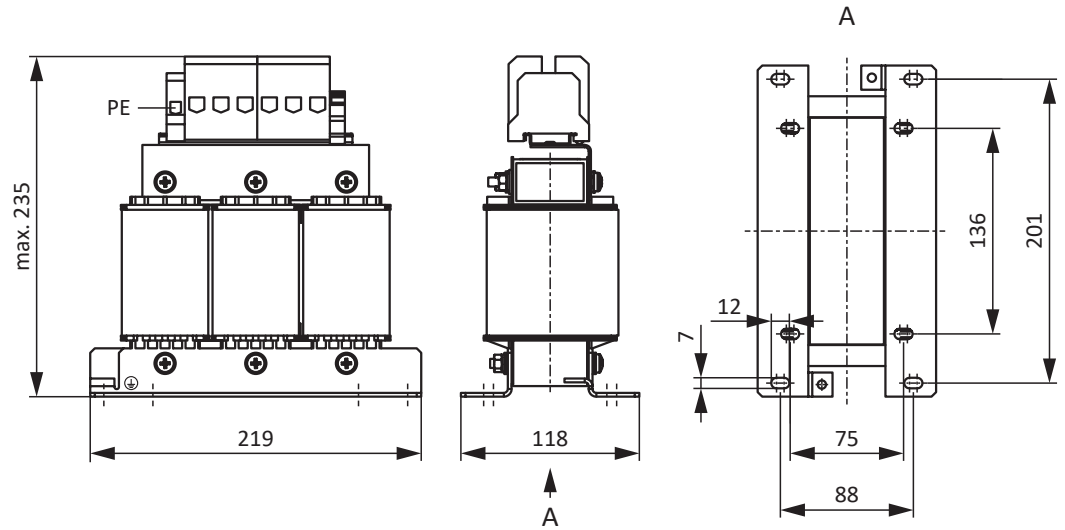


Fig. 7: Power choke dimensional drawing

Dimensions	TEP4010-2US00
Height [mm]	235
Width [mm]	219
Depth [mm]	118
Vertical distance 1 – fastening holes [mm]	201
Vertical distance 2 – Fastening holes [mm]	136
Horizontal distance 1 – fastening holes [mm]	88
Horizontal distance 2 – Fastening holes [mm]	75
Drill holes – Depth [mm]	7
Drill holes – Width [mm]	12
Screw connection – M	M6
Weight without packaging [g]	9900

Tab. 46: TEP dimensions and weight

8.4.6.2 TEP output choke

Output chokes are required for connecting size 0 to 2 drive controllers from a cable length > 50 m in order to reduce interference pulses and protect the drive system.

Information

The following technical data only applies to a rotating magnetic field frequency of 200 Hz. For example, this rotating magnetic field frequency is achieved with a motor with 4 pole pairs and a nominal speed of 3000 rpm. Always observe the specified derating for higher rotating magnetic field frequencies. Also observe the relationship with the clock frequency.

Properties

Specification	TEP3720-0ES41	TEP3820-0CS41	TEP4020-0RS41
ID No.	53188	53189	53190
Voltage range	3 × 0 to 480 V _{AC}		
Frequency range	0 – 200 Hz		
Nominal current I _{N,MF} at 4 kHz	4 A	17.5 A	38 A
Nominal current I _{N,MF} at 8 kHz	3.3 A	15.2 A	30.4 A
Max. permitted motor cable length with output choke	100 m		
Max. surrounding temperature $\vartheta_{amb,max}$	40 °C		
Protection class	IP00		
Winding losses	11 W	29 W	61 W
Iron losses	25 W	16 W	33 W
Connection	Screw terminal		
Max. conductor cross-section	10 mm ²		
UL Recognized Component (CAN; USA)	Yes		
Marks and test symbols	cURus, CE		

Tab. 47: TEP specification

Dimensions

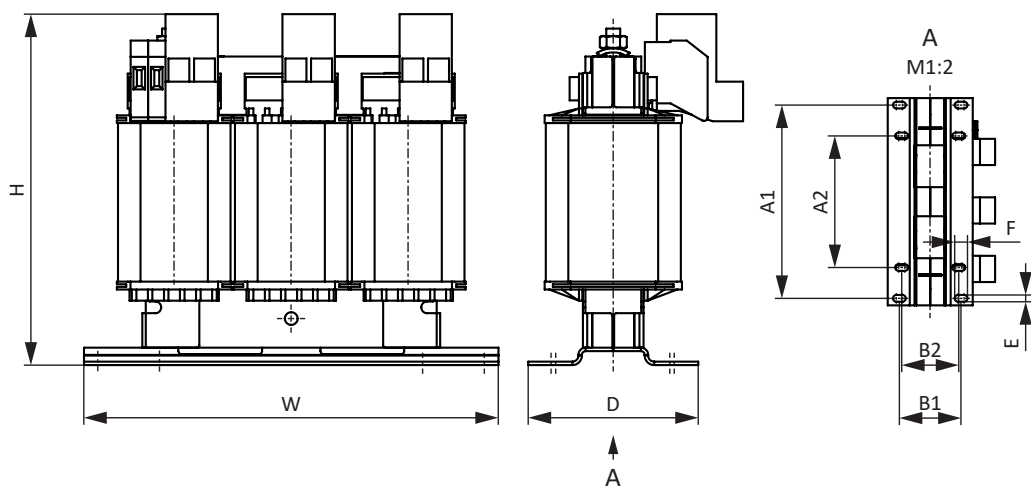


Fig. 8: TEP dimensional drawing

Dimension	TEP3720-0ES41	TEP3820-0CS41	TEP4020-0RS41
Height H [mm]	Max. 153	Max. 153	Max. 180
Width W [mm]	178	178	219
Depth D [mm]	73	88	119
Vertical distance – Fastening holes A1 [mm]	166	166	201
Vertical distance – Fastening holes A2 [mm]	113	113	136
Horizontal distance – Fastening holes B1 [mm]	53	68	89
Horizontal distance – Fastening holes B2 [mm]	49	64	76
Drill holes – Depth E [mm]	5.8	5.8	7
Drill holes – Width F [mm]	11	11	13
Screw connection – M	M5	M5	M6
Weight without packaging [g]	2900	5900	8800

Tab. 48: TEP dimensions and weight

8.4.7 EMC shroud

You can use the EM6A EMC shroud to connect the cable shield of the power cable. Two different designs are available.

EM6A0 EMC shroud



ID No. 56459

EMC shroud for the SD6 drive controller up to size 2.

Accessory part for shield connection of the power cable.

Can be attached to the drive controller housing.

Including shield connection terminal.

EM6A3 EMC shroud



ID No. 56521

EMC shroud for drive controllers of the MDS 5000, SDS 5000 and SD6 series.

Accessory part for shield connection of the power cable for drive controllers up to size 3.

Can be attached to the drive controller housing.

Including shield connection terminal.

If necessary, you can also connect the cable shield of the braking resistor and DC link connection to the shroud.

8.4.8 Removable data storage

Paramodul removable data storage

Included in the standard version.



ID No. 56403

The plug-in Paramodul with integrated microSD card (from 512 MB, industrial type) is available as a storage medium.

8.5 Further information

8.5.1 Directives and standards

The following European directives and standards are relevant to the drive controllers:

- Machinery Directive 2006/42/EC
- Low Voltage Directive 2014/35/EU
- EMC Directive 2014/30/EU
- EN ISO 13849-1:2015
- EN ISO 13849-2:2012
- EN 61800-3:2004 and A1:2012
- EN 61800-5-1:2007
- EN 61800-5-2:2007

8.5.2 Marks and test symbols

The following marks and test symbols are mentioned in the technical data.



RoHS lead-free mark

Marking in accordance with RoHS directive 2011-65-EU.



CE mark

Manufacturer's self declaration: The product meets the requirements of EU directives.



UKCA test symbol

Manufacturer's self declaration: The product meets the requirements of UK directives.



UL test symbol (cULus)

This product is listed by UL for the United States and Canada. Representative samples of this product have been evaluated by UL and meet the requirements of applicable standards.



UL test symbol for recognized component mark (cURus)

This component or material is recognized by UL. Representative samples of this product have been evaluated by UL and meet applicable requirements.

8.5.3 Additional documentation

Additional documentation related to the product can be found at

<http://www.stoeber.de/en/downloads/>

Enter the ID of the documentation in the Search field.

Documentation	ID
SD6 drive controller manual	442426
SE6 safety module manual	442796

9 POSIDYN SDS 5000 servo inverters

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9

Servo inverters

POSIDYN SDS 5000

9.1 Overview

High dynamics for fully digital servo axes

Features

- Nominal output current up to 85 A
- 250% overload capacity
- Power range: 0.75 kW to 45 kW
- Control of rotary synchronous servo motors and asynchronous motors
- Multi-functional encoder interfaces
- Automatic motor parameterization from the electronic motor nameplate
- Isochronic system bus (IGB motion bus) for parameterization and multi-axis applications
- Communication using PROFIBUS DP, PROFINET, CANopen or EtherCAT
- Safe Torque Off (STO) and Safe Stop 1 (SS1) safety functions: SIL 3, PL e (cat. 3)
- Digital and analog inputs and outputs as an option
- Brake chopper, brake control and line filter
- Convenient operating unit consisting of plain-text display and buttons
- Paramodul removable data storage

9.1.1 Features

The 5th generation series of STÖBER inverters are purely digital, modular inverter systems for operating rotary synchronous and asynchronous motors. It includes product types for direct operation on a one or three-phase network in a voltage range from 200 V_{AC} to 528 V_{AC}. An EMC line filter is integrated. EnDat 2.1/2.2 digital, SSI and incremental (HTL/TTL) are available as encoder interfaces in the standard design. A resolver evaluation is available as an option. The inverter can be adapted to the requirements of individual applications using different option modules. The ASP 5001 safety module makes it possible to implement the Safe Torque Off (STO) and Safe Stop 1 (SS1) safety functions in accordance with DIN EN ISO 13849-1 and DIN EN 61800-5-2 for safety-relevant applications. Communication modules provide the connection to a controller over the PROFIBUS DP, PROFINET, CANopen or EtherCAT fieldbus. In addition, terminal modules are available for connecting analog and digital signals as well as additional encoder signals. A plain text display and keyboard simplify diagnostics in the event of a fault and enable fast access to parameters. The Paramodul removable data storage can be used to transfer all application-relevant data from one inverter to another.

The vector control, sensorless vector control, high performance sensorless vector control and U/f controller control modes are available for use with asynchronous motors.



POSIDYN SDS 5000

Integrated bus (IGB) for performance, convenience and safety

SDS 5000 servo inverters feature two interfaces for the integrated bus in the standard version. The integrated bus is used for easy configuration over Ethernet and isochronic data exchange for the following functions:

- Multi-axis synchronization between the servo inverters (IGB motion bus)
- Internet connection for remote maintenance of individual and multiple inverters
- Direct connection between servo inverter and PC

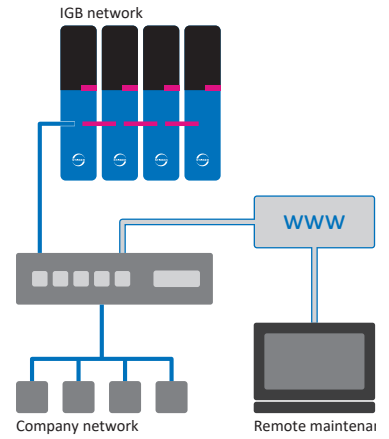
IGB motion bus

The IGB motion bus allows for cyclic, isochronic data exchange between multiple POSIDYN SDS 5000 units integrated into the IGB network. In addition to transferring guide values for master/slave operation, any other data items can also be exchanged, such as tailor-made applications.



STOBER remote maintenance concept

STOBER remote maintenance enables commissioning software to be used to perform all processes and sequences just like an on-site service visit. The concept guides users through a controlled and protected procedure. It ensures that the person responsible for the machine is there on site to pay attention to special situations and personal safety. On the other end, the remote maintenance specialist has the assurance of communicating with a responsible employee on site who is monitoring the situation on the machine.



Remote maintenance enables all processes and sequences to be performed just like an on-site service visit.

Brake management

Using the optional BRS 5001 brake module, the POSIDYN SDS 5000 servo inverter can activate one or two 24 V_{DC} brake systems. Brake management provides the following functions for both brake systems:

- Cyclic brake test
- Bed in brake



Optionally available: BRS 5001 brake module

POSITool

The 5th generation of POSITool project configuration and commissioning software has all the functions needed for efficient use of inverters in single and multi-axis applications.

Paramodul removable data storage

Removable data storage for fast series commissioning by copying and easy service when replacing devices.



9.1.2 Software components

Modular application software

Various standard applications can be loaded onto the devices of the 5th STOBER inverter generation with the POSITool commissioning software as needed. Furthermore, programming based on IEC 61131-3 with CFC can be used to create new applications or expand existing ones. The inverter operating system is multi-axis capable. It supports up to four axes with separate application and parameter ranges.

Velocity mode (standard application)

- **Fast set value**
Simple speed application for lean applications. The speed reference value and torque limiting can be specified using analog inputs as well as digitally.

Torque/force and velocity mode (standard application)

- **Comfort set value**
Expanded torque and speed set value application. Set values and limits can be assigned with the fast set value as well as using fixed values, motor potentiometers and other functions.
- **Technology controller**
PID controller for torque or speed-controlled applications.

Positioning and master/slave mode (standard application)

- **Command, synchronous command**
High-performance positioning application with a command interface based on PLCopen. The data for a motion task including target position, velocity and acceleration are transferred together over fieldbus to the inverter, which then processes them independently. The functional scope is rounded out by an electrical cam, motion block switching point and Posi-Latch.
- **Motion block**
Extensive positioning application with up to 256 motion blocks based on PLCopen. The motion blocks can be selected individually over fieldbus or with digital inputs. They can also be started in a chain. The functional scope is rounded out by an electrical cam and Posi-Latch.

Electronic cam disk with PLCopen interface (tailor-made applications)

The electronic cam disk application makes it possible to implement complex motion tasks such as:

- Flying saw
- Synchronizer (clock in/clock out)
- Cross cutter
- Welding bar/embossing stamp
- Print mark control

These applications can be implemented quickly and easily using readily understandable, free graphical programming based on IEC 61131-3 CFC. This also allows for customer-specific adaptations to special system conditions. Function blocks based on PLCopen Motion Control are available for this purpose for trained users.

9.1.3 Application training

STOBER offers a multi-level training program that is essentially focused on the inverter.

G5 Basic

Training content: System overview, installation and commissioning of the inverter. Use of option modules. Parameterization, commissioning and diagnostics using the integrated display and commissioning software. Remote maintenance. Basics of controller optimization. Configuration of the drive train. Integrated software functions. Software applications. Connection to a higher-level controller. Basics of safety technology. Practical exercises on training topics.

Software used: POSITool.

G5 Customized

Training content: Graphical programming with CFC. Special knowledge for regulating, control and safety technology. Electronic cam disk. Practical exercises on training topics.

9.2 Technical data

Technical data for inverters can be found in the following sections.

9.2.1 Type designation

SDS	5	075	A
-----	---	-----	---

Tab. 1: Example code for type designation

Code	Designation	Design
SDS	Series	
5	Generation	Generation 5
075	Power	075 = 7.5 kW
–	Hardware variants	No identification: HW 199 or lower
A		A: HW 200 or higher

Tab. 2: Meaning of the example code

9.2.2 Sizes

Type	ID No.	Size
SDS 5007A	55428	Size 0
SDS 5008A	55429	Size 0
SDS 5015A	55430	Size 0
SDS 5040A	55431	Size 1
SDS 5075A	55432	Size 1
SDS 5110A	55433	Size 2
SDS 5150A	55434	Size 2
SDS 5220A	55435	Size 3
SDS 5370A	55436	Size 3
SDS 5450A	55437	Size 3

Tab. 3: Available SDS 5000 types and sizes



SDS 5000 in sizes 3, 2, 1 and 0

9.2.3 General technical data

The following information applies to all inverter types.

Device features	
Protection class of the device	IP20
Protection class of the installation space	At least IP54
Protection class	Protection class I in accordance with EN 61140
Radio interference suppression	Integrated line filter in accordance with EN 61800-3, interference emission class C3
Overvoltage category	III in accordance with EN 61800-5-1
Marks and test symbols	CE, cULus, RoHS

Tab. 4: Device features

Transport and storage conditions	
Storage/transport temperature	-20 °C to +70 °C Maximum change: 20 K/h
Relative humidity	Maximum relative humidity 85%, non-condensing
Vibration (transport) in accordance with EN 60068-2-6	5 Hz ≤ f ≤ 9 Hz: 3.5 mm 9 Hz ≤ f ≤ 200 Hz: 10 m/s ² 200 Hz ≤ f ≤ 500 Hz: 15 m/s ²
Fall height for freefall ¹ Weight < 100 kg in accordance with EN 61800-2 (or IEC 60721-3-2, class 2M1)	0.25 m

Tab. 5: Transport and storage conditions

Operating conditions	
Surrounding temperature during operation	0 °C to 45 °C with nominal data 45 °C to 55 °C with derating -2.5% / K
Relative humidity	Maximum relative humidity 85%, non-condensing
Installation altitude	0 m to 1000 m above sea level without restrictions 1000 m to 2000 m above sea level with -1.5%/100 m derating
Pollution degree	Pollution degree 2 in accordance with EN 50178
Ventilation	Installed fan
Vibration (operation) in accordance with EN 60068-2-6	5 Hz ≤ f ≤ 9 Hz: 0.35 mm 9 Hz ≤ f ≤ 200 Hz: 1 m/s ²

Tab. 6: Operating conditions

Discharge times	
Self-discharge of DC link	6 min

Tab. 7: Discharge times of the DC link circuit

¹Only valid for components in original packaging

9.2.4 Electrical data

The electrical data of the available sizes as well as the properties of the brake chopper can be found in the following sections.

An explanation of the formula symbols used can be found in the chapter [\[13.1 \]](#).

9.2.4.1 Size 0: SDS 5007A to SDS 5015A

Electrical data	SDS 5007A	SDS 5008A	SDS 5015A
ID No.	55428	55429	55430
Recommended motor rating	0.75 kW	0.75 kW	1.5 kW
U_{1PU}	1 × 230 V, +20% / -40%, 50/60 Hz	3 × 400 V, +32% / -50%, 50 Hz; 3 × 480 V, +10% / -58%, 60 Hz	
$I_{1N,PU}$	1 × 5.9 A	3 × 2.2 A	3 × 4 A
f_{2PU}	0 – 700 Hz		
U_{2PU}	0 – 230 V	0 – 400 V	
U_{maxPU}	440 V	830 V	

Tab. 8: SDS 5000 electrical data, size 0

Nominal currents up to +45 °C (in the control cabinet)

Operation with asynchronous motor

Electrical data	SDS 5007A	SDS 5008A	SDS 5015A
$I_{2N,PU}$	3 × 4 A	3 × 2.3 A	3 × 4.5 A
I_{2maxPU}	180% for 5 s; 150% for 30 s		
$f_{PWM,PU}$	4 kHz ²		

Tab. 9: SDS 5000 electrical data, size 0, for 4 kHz clock frequency

Operation with synchronous servo motor

Electrical data	SDS 5007A	SDS 5008A	SDS 5015A
$I_{2N,PU}$	3 × 3 A	3 × 1.7 A	3 × 3.4 A
I_{2maxPU}	250% for 2 s; 200% for 5 s		
$f_{PWM,PU}$	8 kHz ³		

Tab. 10: SDS 5000 electrical data, size 0, for 8 kHz clock frequency

Electrical data	SDS 5007A	SDS 5008A	SDS 5015A
U_{onCH}	400 – 420 V	780 – 800 V	
U_{offCH}	360 – 380 V	740 – 760 V	
R_{2minRB}	100 Ω	100 Ω	
P_{maxRB}	1.8 kW	6.4 kW	

Tab. 11: Brake chopper electrical data, size 0

² Clock frequency adjustable from 4 to 16 kHz (see the chapter on derating)

³ Clock frequency adjustable from 4 to 16 kHz (see the chapter on derating)

9.2.4.2 Size 1: SDS 5040A to SDS 5075A

Electrical data	SDS 5040A	SDS 5075A
ID No.	55431	55432
Recommended motor rating	4.0 kW	7.5 kW
U_{1PU}	3 × 400 V, +32% / -50%, 50 Hz; 3 × 480 V, +10% / -58%, 60 Hz	
$I_{1N,PU}$	3 × 9.3 A	3 × 15.8 A
f_{2PU}	0 – 700 Hz	
U_{2PU}	0 – 400 V	
U_{maxPU}	830 V	

Tab. 12: SDS 5000 electrical data, size 1

Nominal currents up to +45 °C (in the control cabinet)

Operation with asynchronous motor

Electrical data	SDS 5040A	SDS 5075A
$I_{2N,PU}$	3 × 10 A	3 × 16 A
I_{2maxPU}	180% for 5 s; 150% for 30 s	
$f_{PWM,PU}$	4 kHz ⁴	

Tab. 13: SDS 5000 electrical data, size 1, for 4 kHz clock frequency

Operation with synchronous servo motor

Electrical data	SDS 5040A	SDS 5075A
$I_{2N,PU}$	3 × 6 A	3 × 10 A
I_{2maxPU}	250% for 2 s; 200% for 5 s	
$f_{PWM,PU}$	8 kHz ⁵	

Tab. 14: SDS 5000 electrical data, size 1, for 8 kHz clock frequency

Electrical data	SDS 5040A	SDS 5075A
U_{onCH}	780 – 800 V	
U_{offCH}	740 – 760 V	
R_{2minRB}	47 Ω	47 Ω
P_{maxRB}	13.6 kW	13.6 kW

Tab. 15: Brake chopper electrical data, size 1

⁴ Clock frequency adjustable from 4 to 16 kHz (see the chapter on derating)⁵ Clock frequency adjustable from 4 to 16 kHz (see the chapter on derating)

9.2.4.3 Size 2: SDS 5110A to SDS 5150A

Electrical data	SDS 5110A	SDS 5150A
ID No.	55433	55434
Recommended motor rating	11 kW	15 kW
U_{1PU}	3 × 400 V, +32% / -50%, 50 Hz; 3 × 480 V, +10% / -58%, 60 Hz	
$I_{1N,PU}$	3 × 24.5 A	3 × 32.6 A
f_{2PU}	0 – 700 Hz	
U_{2PU}	0 – 400 V	
U_{maxPU}	830 V	

Tab. 16: SDS 5000 electrical data, size 2

Nominal currents up to +45 °C (in the control cabinet)

Operation with asynchronous motor

Electrical data	SDS 5110A	SDS 5150A
$I_{2N,PU}$	3 × 22 A	3 × 32 A
I_{2maxPU}	180% for 5 s; 150% for 30 s	
$f_{PWM,PU}$	4 kHz ⁶	

Tab. 17: SDS 5000 electrical data, size 2, for 4 kHz clock frequency

Operation with synchronous servo motor

Electrical data	SDS 5110A	SDS 5150A
$I_{2N,PU}$	3 × 14 A	3 × 20 A
I_{2maxPU}	250% for 2 s; 200% for 5 s	
$f_{PWM,PU}$	8 kHz ⁷	

Tab. 18: SDS 5000 electrical data, size 2, for 8 kHz clock frequency

Electrical data	SDS 5110A	SDS 5150A
U_{onCH}	780 – 800 V	
U_{offCH}	740 – 760 V	
R_{2minRB}	22 Ω	
P_{maxRB}	29.1 kW	

Tab. 19: Brake chopper electrical data, size 2

⁶ Clock frequency adjustable from 4 to 16 kHz (see the chapter on derating)⁷ Clock frequency adjustable from 4 to 16 kHz (see the chapter on derating)

9.2.4.4 Size 3: SDS 5220A to SDS 5450A

Electrical data	SDS 5220A	SDS 5370A	SDS 5450A
ID No.	55435	55436	55437
Recommended motor rating	22 kW	37 kW	45 kW
U_{1PU}		3 × 400 V, +32% / -50%, 50 Hz; 3 × 480 V, +10% / -58%, 60 Hz	
$I_{1N,PU}$	1 × 37 A	3 × 62 A	3 × 76 A
f_{2PU}		0 – 700 Hz	
U_{2PU}		0 – 400 V	
U_{maxPU}		830 V	

Tab. 20: SDS 5000 electrical data, size 3

Nominal currents up to +45 °C (in the control cabinet)

Operation with asynchronous motor

Electrical data	SDS 5220A	SDS 5370A	SDS 5450A
$I_{2N,PU}$	3 × 44 A	3 × 70 A	3 × 85 A
I_{2maxPU}	180% for 5 s; 150% for 30 s		
$f_{PWM,PU}$	4 kHz ⁸		

Tab. 21: SDS 5000 electrical data, size 3, for 4 kHz clock frequency

Operation with synchronous servo motor

Electrical data	SDS 5220A	SDS 5370A	SDS 5450A
$I_{2N,PU}$	3 × 30 A	3 × 50 A	3 × 60 A
I_{2maxPU}	250% for 2 s; 200% for 5 s		
$f_{PWM,PU}$	8 kHz ⁹		

Tab. 22: SDS 5000 electrical data, size 3, for 8 kHz clock frequency

Electrical data	SDS 5220A	SDS 5370A	SDS 5450A
U_{onCH}		780 – 800 V	
U_{offCH}		740 – 760 V	
R_{intRB}	30 Ω (PTC resistance; 100 W; max. 1 kW for 1 s; $\tau = 40$ s)		
R_{2minRB}		15 Ω	
P_{maxRB}		42 kW	

Tab. 23: Brake chopper electrical data, size 3

⁸ Clock frequency adjustable from 4 to 16 kHz (see the chapter on derating)⁹ Clock frequency adjustable from 4 to 16 kHz (see the chapter on derating)

9.2.4.5 Power loss data in accordance with EN 61800-9-2

Type	Nominal current $I_{2N,PU}$	Apparent power	Absolute losses $P_{V,CU}^{10}$	Operating points ¹¹								IE class ¹²
				(0/25)	(0/50)	(0/100)	(50/25)	(50/50)	(50/100)	(90/50)	(90/100)	
				Relative losses								
				[%]								
	[A]	[kVA]	[W]									
SDS 5007A	4	0.9	10	5.01	5.07	5.68	5.20	5.37	6.30	5.88	7.43	IE2
SDS 5008A	2.3	1.6	10	2.98	3.13	3.49	3.02	3.22	3.71	3.36	4.09	IE2
SDS 5015A	4.5	3.1	12	1.71	1.86	2.24	1.75	1.97	2.51	2.16	3.04	IE2
SDS 5040A	10	6.9	12	1.38	1.54	1.93	1.43	1.64	2.17	1.80	2.57	IE2
SDS 5075A	16	11.1	12	0.95	1.12	1.66	0.99	1.23	1.98	1.41	2.52	IE2
SDS 5110A	22	15.2	15	0.80	0.97	1.49	0.84	1.06	1.75	1.21	2.19	IE2
SDS 5150A	32	22.2	15	0.70	0.87	1.40	0.74	0.97	1.66	1.11	2.08	IE2
SDS 5220A	44	30.5	35	0.61	0.76	1.21	0.68	0.90	1.53	1.06	1.96	IE2
SDS 5370A	70	48.5	35	0.53	0.69	1.18	0.59	0.82	1.49	0.97	1.89	IE2
SDS 5450A	85	58.9	35	0.47	0.64	1.18	0.54	0.78	1.50	0.94	1.94	IE2

Tab. 24: Relative losses of SDS 5000 inverters according to EN 61800-9-2

¹⁰ Absolute losses for a power unit that is switched off¹¹ Operating points for relative motor stator frequency in % and relative torque current in %¹² IE class in accordance with EN 61800-9-2

Type	Nominal current $I_{2N,PU}$	Apparent power	Absolute losses $P_{V,CU}^{13}$	Operating points ¹⁴								IE class ¹⁵	Comparison ¹⁶
				(0/25)	(0/50)	(0/100)	(50/25)	(50/50)	(50/100)	(90/50)	(90/100)		
				Absolute losses P_V									
			[W]	[W]									[%]
SDS 5007A	4	0.9	10	45.1	45.6	51.1	46.8	48.3	56.7	52.9	66.9	IE2	51.8
SDS 5008A	2.3	1.6	10	47.7	50.1	55.8	48.3	51.5	59.3	53.8	65.4	IE2	40.2
SDS 5015A	4.5	3.1	12	52.9	57.6	69.3	54.4	61.0	77.9	67.1	94.1	IE2	39.6
SDS 5040A	10	6.9	12	95.3	106.1	133.3	98.6	113.2	149.9	123.9	177.0	IE2	37.1
SDS 5075A	16	11.1	12	104.9	124.0	184.6	110.3	136.6	219.8	156.0	279.8	IE2	35.8
SDS 5110A	22	15.2	15	121.5	146.9	226.1	128.1	161.6	266.0	183.7	332.7	IE2	32.9
SDS 5150A	32	22.2	15	154.7	192.8	311.3	164.6	214.6	369.3	245.9	462.1	IE2	38.3
SDS 5220A	44	30.5	35	187.5	232.2	368.7	207.7	273.9	466.8	323.0	597.8	IE2	32.1
SDS 5370A	70	48.5	35	256.6	332.3	570.8	287.9	397.0	721.5	471.0	915.9	IE2	33.9
SDS 5450A	85	58.9	35	277.8	376.9	692.3	317.4	459.0	886.1	554.6	1143.1	IE2	35.3

Tab. 25: Absolute losses in SDS 5000 inverters in accordance with EN 61800-9-2

General conditions

The loss data applies to inverters without accessories.

The power loss calculation is based on a three-phase supply voltage with 400 V_{AC}/50 Hz.

The calculated data includes a supplement of 10% in accordance with EN 61800-9-2.

The power loss specifications refer to a clock frequency of 4 kHz.

The absolute losses for a power unit that is switched off refer to the 24 V_{DC} power supply of the control electronics.

¹³ Absolute losses for a power unit that is switched off

¹⁴ Operating points for relative motor stator frequency in % and relative torque current in %

¹⁵ IE class in accordance with EN 61800-9-2

¹⁶ Comparison of the losses for the reference inverter related to IE2 in the nominal point (90, 100)

9.2.4.6 Power loss data of accessories

If the inverter needs to be ordered with accessory parts, the losses increase as follows:

Type	Absolute losses P_v [W]
ASP 5001 safety module	1
SEA 5001 terminal module	< 2
XEA 5001 terminal module	< 5
REA 5001 terminal module	< 5
CAN 5000 communication module	1
DP 5000 communication module	< 2
ECS 5000 communication module	< 2
PN 5000 communication module	< 4
BRM 5000 / BRS 5001 brake module	< 1

Tab. 26: Absolute losses of the accessories

Information

Note the absolute power loss of the encoder (usually < 3 W) and of the brake when designing as well.

Loss specifications for other optional accessories can be found in the technical data of the respective accessory part.

9.2.5 Derating by increasing the clock frequency

Depending on the clock frequency $f_{\text{PWM,PU}}$, the following values for nominal output currents $I_{2\text{N,PU}}$ arise.

Type	$I_{2\text{N,PU}}$ 4 kHz	$I_{2\text{N,PU}}$ 8 kHz	$I_{2\text{N,PU}}$ 16 kHz
SDS 5007A	4 A	3 A	2 A
SDS 5008A	2.3 A	1.7 A	1.2 A
SDS 5015A	4.5 A	3.4 A	2.2 A
SDS 5040A	10 A	6 A	3.3 A
SDS 5075A	16 A	10 A	5.7 A
SDS 5110A	22 A	14 A	8.1 A
SDS 5150A	32 A	20 A	11.4 A
SDS 5220A	44 A	30 A	18.3 A
SDS 5370A	70 A	50 A	31.8 A
SDS 5450A	85 A	60 A	37.8 A

Tab. 27: Nominal output current $I_{2\text{N,PU}}$ dependent on the clock frequency

9.2.6 Dimensions

The dimensions of the available SDS 5000 sizes can be found in the following chapters.

9.2.6.1 Dimensions: sizes 0 to 2

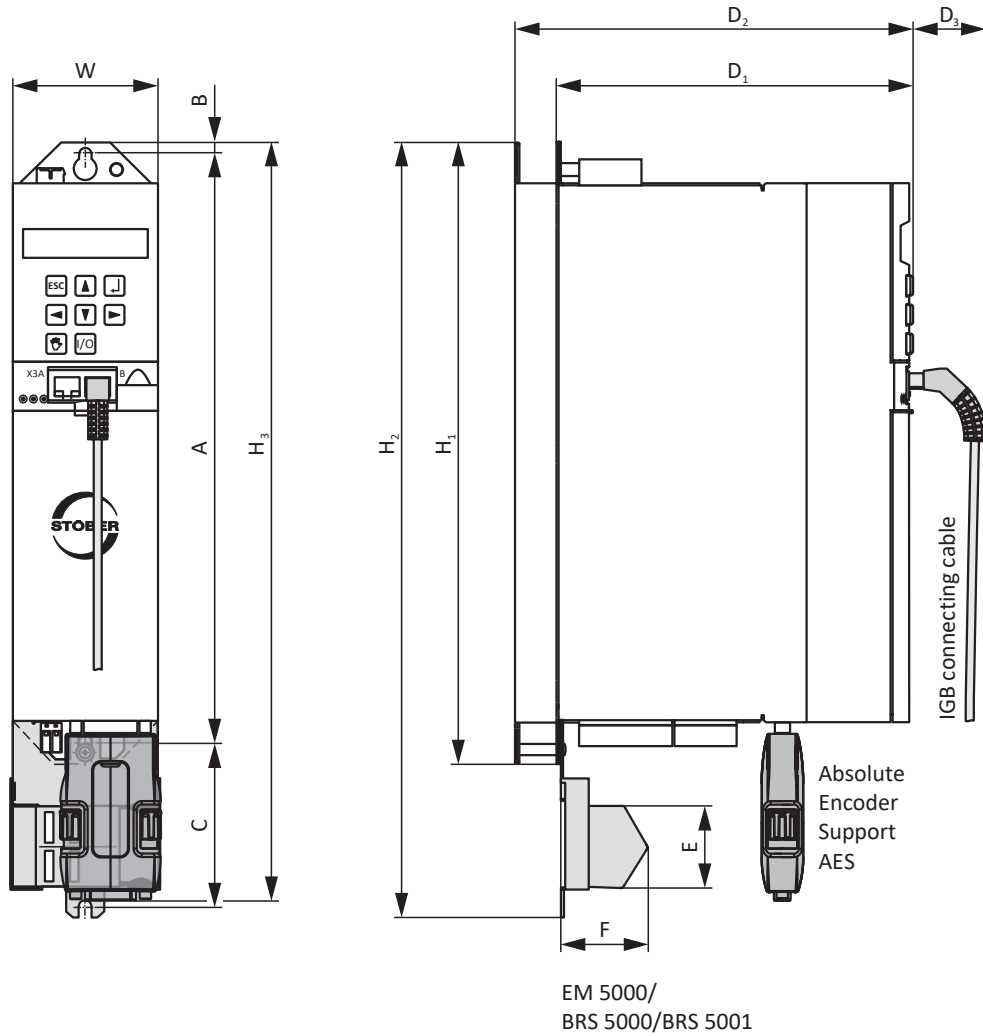


Fig. 1: SDS 5000 dimensional drawing, sizes 0 to 2

Dimensions [mm]		Size 0	Size 1	Size 2
Inverter	Height	H ₁	300	
		H ₂	360 ¹⁷ / 373 ¹⁸	
		H ₃ ¹⁹	365	
	Width	W	70	105
	Depth	D ₁	175	260
D ₂ ²⁰		193	278	278
D ₃		40		
EMC shroud	Height	E	37.5 ²¹ / 44 ²²	
	Depth	F	40	
Fastening holes	Vertical distance to the upper edge	B	6	
	Vertical distance	A	283+2	
	Vertical distance	C ²³	79	

Tab. 28: SDS 5000 dimensions, sizes 0 to 2 [mm]

¹⁷ H₂ = Height incl. EM 5000 EMC shroud

¹⁸ H₂ = Height incl. BRS 5001 brake module

¹⁹ H₃ = Height incl. AES

²⁰ D₂ = Depth incl. RB 5000 braking resistor

²¹ E = Height of EM 5000 EMC shroud

²² E = Height of BRS 5001 brake module

²³ C = Vertical distance with BRS 5001 brake module

9.2.6.2 Dimensions: size 3

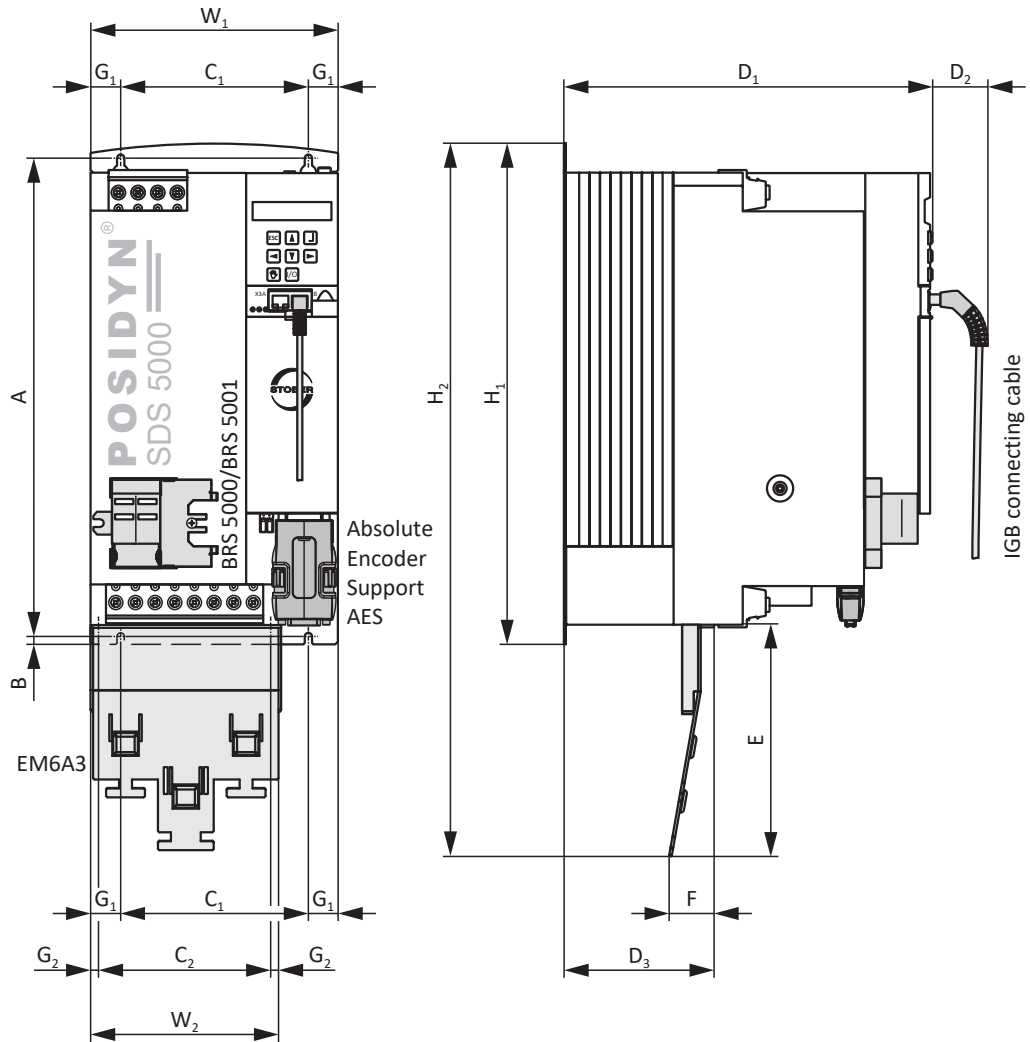


Fig. 2: SDS 5000 dimensional drawing, size 3

Dimensions [mm]			Size 3
Inverter	Height	H ₁	382.5
		H ₂ ²⁴	540
	Width	W ₁	194
	Depth	D ₁	276
D ₂		40	
EMC shroud	Height	E	174
	Width	W ₂	147
	Depth	F	34
	Depth	D ₃	113
Fastening holes	Vertical distance	A	365+2
	Vertical distance to the bottom edge	B	6
	Horizontal distance	C ₁ ²⁵	150+0.2/-0.2
	Horizontal distance to the side edge	G ₁ ²⁶	20
	Horizontal distance	C ₂ ²⁷	132
	Horizontal distance to the side edge	G ₂ ²⁸	7.5

Tab. 29: SDS 5000 dimensions, size 3 [mm]

²⁴ H₂ = Height incl. EM6A3 EMC shroud

²⁵ C₁ = Horizontal distance of the fastening holes of the inverter

²⁶ G₁ = Horizontal distance to the side edge of the inverter

²⁷ C₂ = Horizontal distance of the fastening holes of the EM6A3 EMC shroud

²⁸ G₂ = Horizontal distance to the side edge of the EM6A3 EMC shroud

9.2.7 Minimum clearances

The specified dimensions refer to the outside edges of the inverter.

Minimum clearance	Above	Below	On the side
Size 0 – Size 2	100	100	5
... with EMC shroud or brake module	100	120	5
Size 3	100	100	5
... with EMC shroud	100	220	5

Tab. 30: Minimum clearances [mm]

9.3 Inverter/motor combinations

Parameterization of a STOBBER inverter is remarkably easy, especially in combination with four-pole STOBBER asynchronous motors. The motor is fully typified by inputting just the motor size (e.g. 90L) and its wiring (star or delta). A delta connection (measurement point 230 V, 50 Hz) is available for motors up to 3 kW (size 100). By increasing the voltage at higher frequencies, the full torque can be drawn through the motor up to 87 Hz. It usually makes sense to take this expanded speed adjustment range into account when selecting the gear unit. You can find more detailed information in the chapter [▶ 5.6].

An explanation of the formula symbols used can be found in the chapter [▶ 13.1].

									SDS 5007A	SDS 5008A	SDS 5015A	SDS 5040A	SDS 5075A	SDS 5110A	SDS 5150A	SDS 5220A	SDS 5370A	SDS 5450A	
									$I_{2N,PU}$ [A] ($f_{PWM,PU} = 4$ kHz)										
	f_T [Hz]	pz	Con- nection	P_N [kW]	n_N [rpm]	M_N [Nm]	M_R/M_N	I_N [A]	4	2.3	4.5	10	16	22	32	44	70	85	
Δ 230 V / Y 400 V motor winding									$I_{2N,PU} / I_N$										
IE3D071K04	50	4	Y	0.25	1430	1.67	2.9	0.66											
IE3D071K04	87	4	Δ	0.43	2477	1.67	2.9	1.1		2.0									
IE3D071L04	50	4	Y	0.37	1430	2.5	3.2	0.98											
IE3D071L04	87	4	Δ	0.64	2477	2.5	3.2	1.7		1.4									
IE3D080K04	50	4	Y	0.55	1440	3.65	3.6	1.27		1.8									
IE3D080K04	87	4	Δ	1.0	2494	3.65	3.6	2.2	1.8	1.0	2.0								
IE3D080L04	50	4	Y	0.75	1445	5.0	3.7	1.7		1.4									
IE3D080L04	87	4	Δ	1.3	2503	5.0	3.7	2.94	1.4		1.5								
IE3D090S04	50	4	Y	1.1	1440	7.3	3.7	2.5	1.6		1.8								
IE3D090S04	87	4	Δ	1.91	2494	7.3	3.7	4.33			1.0								
IE3D090LX04	50	4	Y	1.5	1455	9.8	4.9	3.4	1.2		1.3								
IE3D090LX04	87	4	Δ	2.6	2503	9.8	4.9	5.89				1.7							
IE3D100KX04	50	4	Y	2.2	1450	14.5	3.8	4.55				2.2							
IE3D100KX04	87	4	Δ	3.81	2511	14.5	3.8	7.88				1.3	2.0						
IE3D100LX04	50	4	Y	3.0	1450	19.8	4	6.35				1.6							
IE3D100LX04	87	4	Δ	5.2	2511	19.8	4	11					1.5	2.0					
IE3D112M04	50	4	Δ	4.0	1465	26.1	4.5	7.9				1.3	2.0						
IE3D132SX04	50	4	Δ	5.5	1465	36	3.3	10				1.0	1.6	2.2					
IE3D132MX04	50	4	Δ	7.5	1470	49	3.9	16					1.0	1.4	2.0				
IE3D160MX04	50	4	Δ	11	1465	72	3.4	21						1.0	1.5	2.1			
IE3D160LX04	50	4	Δ	15	1475	97	3.5	27.5							1.2	1.6			
IE3D180MX04	50	4	Δ	18.5	1475	120	3.3	34.5								1.3	2.0		
IE3D180LX04	50	4	Δ	22	1475	142	3	41								1.1	1.7	2.1	
IE3D200LX04	50	4	Δ	30	1480	194	2.5	54									1.3	1.6	

9.4 Accessories

You can find information about the available accessories in the following chapters.

9.4.1 Safety technology

ASP 5001 – Safe Torque Off

Information

The drive controller is delivered in the standard design without safety technology. If you want a drive controller with integrated safety technology, you must order it together with the drive controller. The safety modules are an integrated part of the drive controller and must not be modified.

Available with the standard design.



Option module for implementation of integrated safety function Safe Torque Off (STO).

9.4.2 Communication

IGB connecting cable



Cable for connecting the interface X3A or X3B on the inverter front for IGB, CAT5e, magenta, connector angled at 45°.

The following versions are available:

ID No. 49855: 0.4 m.

ID No. 49856: 2 m.

PC connecting cables



ID No. 49857

Cable for connecting the X3A or X3B interface with the PC, CAT5e, blue, 5 m.

USB 2.0 Ethernet adapter



ID No. 49940

Adapter for connecting Ethernet to a USB port.

CANopen DS-301 CAN 5000 communication module



ID No. 44574

Accessory part for connecting CAN bus.

PROFIBUS DP-V1 DP 5000 communication module



ID No. 44575
Accessory module for connecting PROFIBUS DP-V1.

EtherCAT ECS 5000 communication module



ID No. 49014
Accessory part for connecting EtherCAT (CANopen over EtherCAT).

EtherCAT cables



Ethernet patch cable, CAT5e, yellow.
The following designs are available:
ID No. 49313: Length approx. 0.25 m.
ID No. 49314: Length approx. 0.5 m.

PROFINET PN 5000 communication module



ID No. 53893
Accessory part for connecting PROFINET.

9.4.3 Terminal module

SEA 5001 standard terminal module



ID No. 49576

Terminals:

- 2 analog inputs
- 2 analog outputs
- 5 digital inputs
- 2 digital outputs

XEA 5001 extended terminal module



ID No. 49015

Terminals:

- 3 analog inputs
- 2 analog outputs
- 13 digital inputs
- 10 digital outputs

Encoder / interfaces:

- TTL incremental encoder (simulation and evaluation)
- Pulse/direction interface (simulation and evaluation)
- SSI encoder (simulation and evaluation)

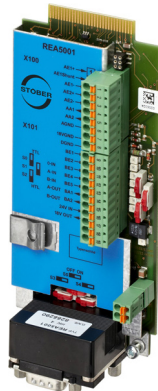
X120 SSI/TTL connection cable



ID No. 49482

Cable for connecting the X120 TTL interface on the SD6 drive controller (on terminal module RI6 or XI6) with the X301 interface on the LA6 adapter box in order to transfer Hall sensor signals. 0.3 m.

REA 5001 resolver terminal module



ID No. 49854

Terminals:

- 2 analog inputs
- 2 analog outputs
- 5 binary inputs
- 2 binary outputs

Encoder / interfaces:

- Resolver
- EnDat 2.1 sin/cos encoders
- TTL incremental encoder (simulation and evaluation)
- SSI encoder (simulation and evaluation)
- Pulse/direction interface (simulation and evaluation)



Resolver cables that were connected to an POSIDYN SDS 4000 can be connected using the resolver adapter (9-pin to 15-pin) included in the scope of delivery to terminal X140 of REA 5001.

9.4.4 Braking resistor

In addition to the inverters, STOBBER offers braking resistors in different sizes and performance classes described below. For the selection, note the minimum permitted braking resistances specified in the technical data of the individual inverter types.

9.4.4.1 FZMU, FZZMU tubular fixed resistor

Type	FZMU 400×65			FZZMU 400×65		
	49010	55445	55446	53895	55447	55448
ID No.	49010	55445	55446	53895	55447	55448
SDS 5007A	X	—	—	—	—	—
SDS 5008A	X	—	—	—	—	—
SDS 5015A	X	—	—	—	—	—
SDS 5040A	(X)	—	—	X	—	—
SDS 5075A	(X)	—	—	X	—	—
SDS 5110A	(—)	X	—	(X)	X	—
SDS 5150A	(—)	X	—	(X)	X	—
SDS 5220A	(—)	(X)	X	(—)	(X)	X
SDS 5370A	(—)	(X)	X	(—)	(X)	X
SDS 5450A	(—)	(X)	X	(—)	(X)	X

Tab. 31: Assignment of FZMU, FZZMU braking resistor – SDS 5000 inverter

X	Recommended
(X)	Possible
(—)	Useful under certain conditions
—	Not possible

Properties

Specification	FZMU 400×65			FZZMU 400×65		
	49010	55445	55446	53895	55447	55448
ID No.	49010	55445	55446	53895	55447	55448
Type	Tubular fixed resistor			Tubular fixed resistor		
Resistance [Ω]	100 \pm 10%	22 \pm 10%	15 \pm 10%	47 \pm 10%	22 \pm 10%	15 \pm 10%
Thermal drift	\pm 10%			\pm 10%		
Power [W]	600			1200		
Therm. time const. τ_{th} [s]	40			40		
Pulse power for < 1 s [kW]	18			36		
U_{max} [V]	848			848		
Weight without packaging [g]	2200			4170		
Protection class	IP20			IP20		
Marks and test symbols	cURus, CE, UKCA			cURus, CE, UKCA		

Tab. 32: FZMU, FZZMU specification

Dimensions

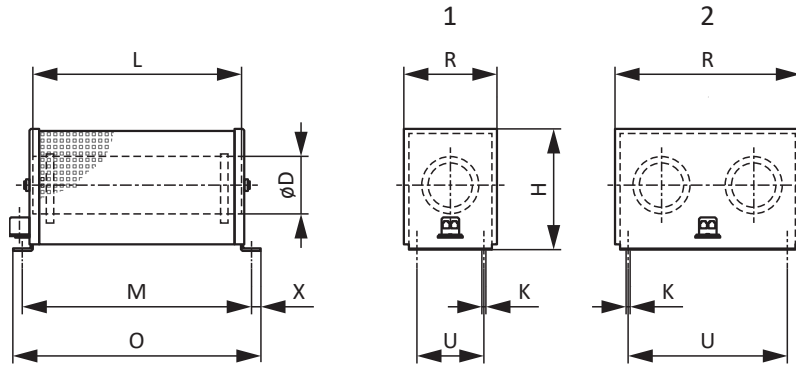


Fig. 3: FZMU (1), FZZMU (2) dimensional drawing

Dimension	FZMU 400×65			FZZMU 400×65		
	49010	55445	55446	53895	55447	55448
L x D	400 × 65			400 × 65		
H	120			120		
K	6.5 × 12			6.5 × 12		
M	430			426		
O	485			485		
R	92			185		
U	64			150		
X	10			10		

Tab. 33: FZMU, FZZMU dimensions [mm]

9.4.4.2 GVADU, GBADU flat resistor

Type	GVADU 210×20	GBADU 265×30	GBADU 405×30	GBADU 335×30	GBADU 265×30
ID No.	55441	55442	55499	55443	55444
SDS 5007A	X	X	X	—	—
SDS 5008A	X	X	X	—	—
SDS 5015A	X	X	X	—	—
SDS 5040A	(X)	(X)	(X)	X	—
SDS 5075A	(X)	(X)	(X)	X	—
SDS 5110A	(—)	(—)	(—)	(X)	X
SDS 5150A	(—)	(—)	(—)	(X)	X
SDS 5220A	(—)	(—)	(—)	(—)	(X)
SDS 5370A	(—)	(—)	(—)	(—)	(X)
SDS 5450A	(—)	(—)	(—)	(—)	(X)

Tab. 34: Assignment of GVADU, GBADU braking resistor – SDS 5000 inverters

- X Recommended
- (X) Possible
- (—) Useful under certain conditions
- Not possible

Properties

Specification	GVADU 210×20	GBADU 265×30	GBADU 405×30	GBADU 335×30	GBADU 265×30
ID No.	55441	55442	55499	55443	55444
Type	Flat resistor				
Resistance [Ω]	100 ±10%	100 ±10%	100 ±10%	47 ±10%	22 ±10%
Thermal drift	±10%	±10%	±10%	±10%	±10%
Power [W]	150	300	500	400	300
Therm. time const. τ_{th} [s]	60	60	60	60	60
Pulse power for < 1 s [kW]	3.3	6.6	11	8.8	6.6
U_{max} [V]	848	848	848	848	848
Cable design	Radox	FEP	FEP	FEP	FEP
Cable length [mm]	500	1500	500	1500	1500
Conductor cross-section [AWG]	18/19	14/19	14/19	14/19	14/19
	(0.82 mm ²)	(1.9 mm ²)	(1.9 mm ²)	(1.9 mm ²)	(1.9 mm ²)
Weight without packaging [g]	300	930	1410	1200	930
Protection class	IP54	IP54	IP54	IP54	IP54
Test symbols	cURus, CE, UKCA				

Tab. 35: GVADU, GBADU specification

Dimensions

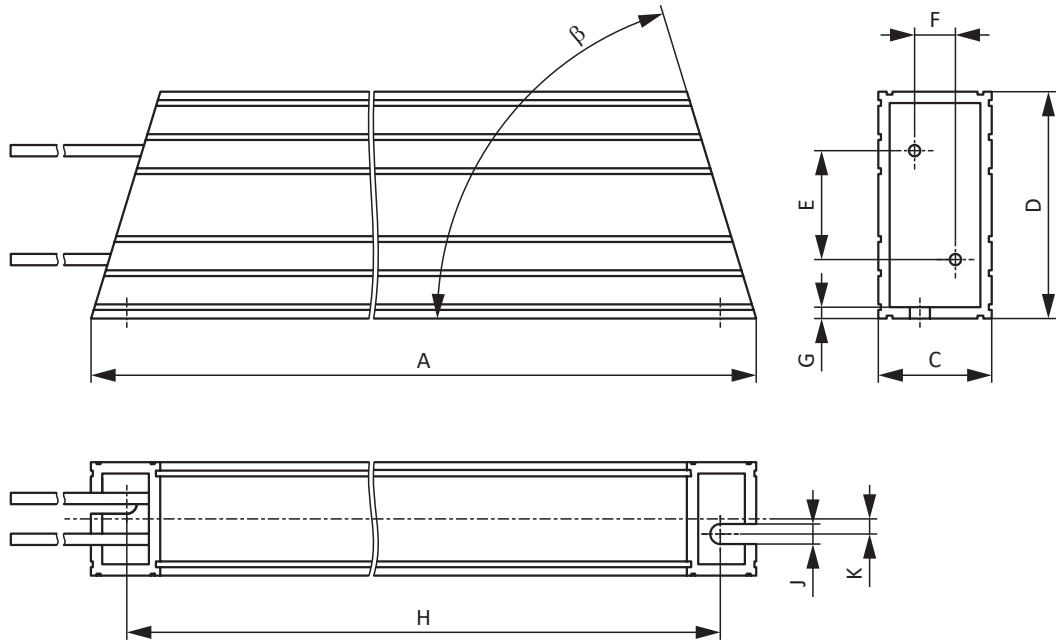


Fig. 4: GVADU, GBADU dimensional drawing

Dimension	GVADU 210×20	GBADU 265×30	GBADU 405×30	GBADU 335×30	GBADU 265×30
ID No.	55441	55442	55499	55443	55444
A	210	265	405	335	265
H	192	246	386	316	246
C	20	30	30	30	30
D	40	60	60	60	60
E	18.2	28.8	28.8	28.8	28.8
F	6.2	10.8	10.8	10.8	10.8
G	2	3	3	3	3
K	2.5	4	4	4	4
J	4.3	5.3	5.3	5.3	5.3
β	65°	73°	73°	73°	73°

Tab. 36: GVADU, GBADU dimensions [mm]

9.4.4.3 FGFKU steel-grid fixed resistor

Type	FGFKU 3100502	FGFKU 3100502	FGFKU 3111202	FGFKU 3121602
ID No.	55449	55450	55451	53897
SDS 5110A	X	—	—	—
SDS 5150A	X	—	—	—
SDS 5220A	(X)	X	X	X
SDS 5370A	(X)	X	X	X
SDS 5450A	(X)	X	X	X

Tab. 37: Assignment of FGFKU braking resistor – SDS 5000 inverter

- X Recommended
- (X) Possible
- Not possible

Properties

Specification	FGFKU 3100502	FGFKU 3100502	FGFKU 3111202	FGFKU 3121602
ID No.	55449	55450	55451	53897
Type	Steel-grid fixed resistor			
Resistance [Ω]	22 \pm 10%	15 \pm 10%	15 \pm 10%	15 \pm 10%
Thermal drift	\pm 10%	\pm 10%	\pm 10%	\pm 10%
Power [W]	2500	2500	6000	8000
Therm. time const. τ_{th} [s]	30	30	20	20
Pulse power for < 1 s [kW]	50	50	120	160
U_{max} [V]	848	848	848	848
Weight without packaging [g]	7500	7500	12000	18000
Protection class	IP20	IP20	IP20	IP20
Marks and test symbols	cURus, CE, UKCA			

Tab. 38: FGFKU specification

Dimensions

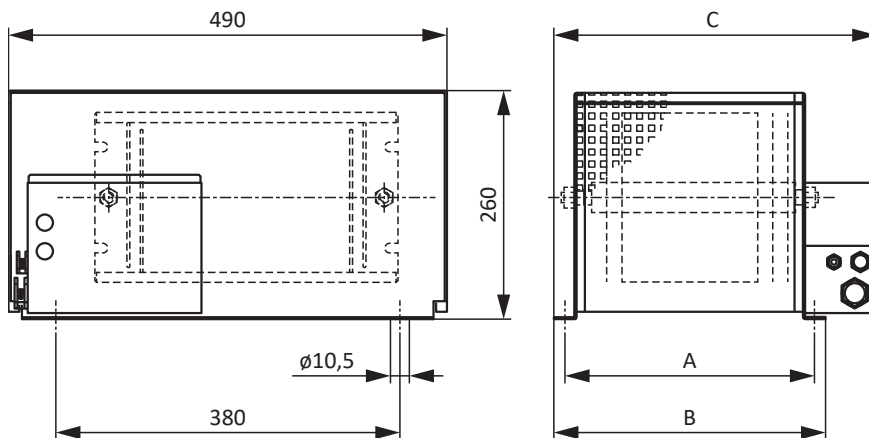


Fig. 5: FGFKU dimensional drawing

Dimension	FGFKU 3100502	FGFKU 3100502	FGFKU 3111202	FGFKU 3121602
ID No.	55449	55450	55451	53897
A	270	270	370	570
B	295	295	395	595
C	355	355	455	655

Tab. 39: FGFKU dimensions [mm]

9.4.4.4 RB 5000 rear section braking resistor

Type	RB 5022	RB 5047	RB 5100
ID No.	45618	44966	44965
SDS 5007A	—	—	X
SDS 5008A	—	—	X
SDS 5015A	—	—	X
SDS 5040A	—	X	(X)
SDS 5075A	—	X	(X)
SDS 5110A	X	—	—
SDS 5150A	X	—	—

Tab. 40: Assignment of RB 5000 braking resistor – SDS 5000 inverter

X	Recommended
(X)	Possible
—	Not possible

Properties

Specification	RB 5022	RB 5047	RB 5100
ID No.	45618	44966	44965
Resistance [Ω]	22 \pm 10%	47 \pm 10%	100 \pm 10%
Thermal drift	\pm 10%	\pm 10%	\pm 10%
Power [W]	100	60	60
Therm. time const. τ_{th} [s]	8	8	8
Pulse power for < 1 s [kW]	1.5	1.0	1.0
U_{max} [V]	800	800	800
Weight without packaging [g]	640	460	440
Cable design	Radox	Radox	Radox
Cable length [mm]	250	250	250
Conductor cross-section [AWG]	18/19	18/19	18/19
	(0.82 mm ²)	(0.82 mm ²)	(0.82 mm ²)
Maximum torque of M5 threaded bolts [Nm]	5	5	5
Protection class	IP40	IP40	IP40
Marks and test symbols	cURus, CE, UKCA	cURus, CE, UKCA	cURus, CE, UKCA

Tab. 41: RB 5000 specification

Dimensions

Dimension	RB 5022	RB 5047	RB 5100
ID No.	45618	44966	44965
Height	300	300	300
Width	94	62	62
Depth	18	18	18
Drilling diagram corresponds to size	Size 2	Size 1	Size 0 and Size 1

Tab. 42: RB 5000 dimensions [mm]

9.4.5 Choke

Technical specifications for suitable chokes can be found in the following chapters.

9.4.5.1 TEP output choke

Output chokes are required for connecting size 0 to 2 drive controllers from a cable length > 50 m in order to reduce interference pulses and protect the drive system.

Information

The following technical data only applies to a rotating magnetic field frequency of 200 Hz. For example, this rotating magnetic field frequency is achieved with a motor with 4 pole pairs and a nominal speed of 3000 rpm. Always observe the specified derating for higher rotating magnetic field frequencies. Also observe the relationship with the clock frequency.

Properties

Specification	TEP3720-0ES41	TEP3820-0CS41	TEP4020-0RS41
ID No.	53188	53189	53190
Voltage range	3 × 0 to 480 V _{AC}		
Frequency range	0 – 200 Hz		
Nominal current I _{N,MF} at 4 kHz	4 A	17.5 A	38 A
Nominal current I _{N,MF} at 8 kHz	3.3 A	15.2 A	30.4 A
Max. permitted motor cable length with output choke	100 m		
Max. surrounding temperature $\vartheta_{amb,max}$	40 °C		
Protection class	IP00		
Winding losses	11 W	29 W	61 W
Iron losses	25 W	16 W	33 W
Connection	Screw terminal		
Max. conductor cross-section	10 mm ²		
UL Recognized Component (CAN; USA)	Yes		
Marks and test symbols	cURus, CE		

Tab. 43: TEP specification

Dimensions

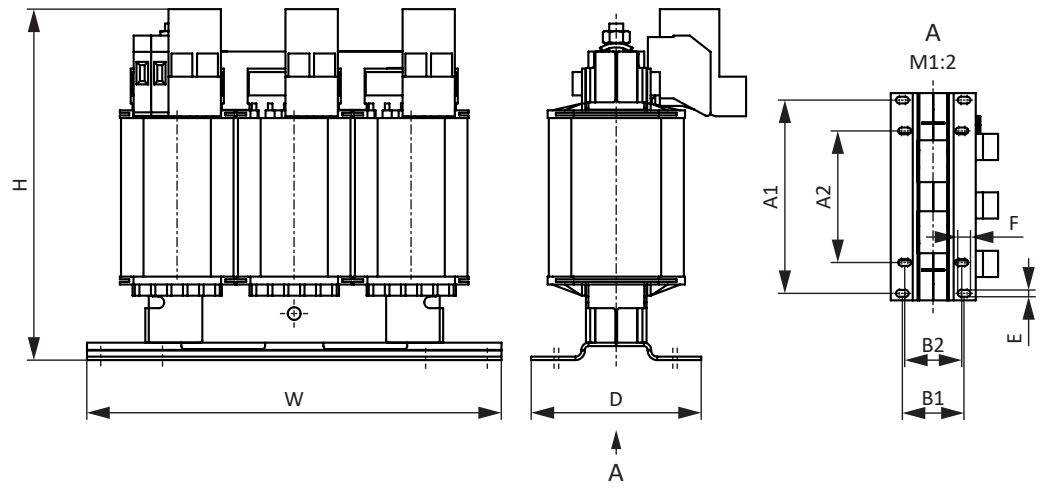


Fig. 6: TEP dimensional drawing

Dimension	TEP3720-0ES41	TEP3820-0CS41	TEP4020-0RS41
Height H [mm]	Max. 153	Max. 153	Max. 180
Width W [mm]	178	178	219
Depth D [mm]	73	88	119
Vertical distance – Fastening holes A1 [mm]	166	166	201
Vertical distance – Fastening holes A2 [mm]	113	113	136
Horizontal distance – Fastening holes B1 [mm]	53	68	89
Horizontal distance – Fastening holes B2 [mm]	49	64	76
Drill holes – Depth E [mm]	5.8	5.8	7
Drill holes – Width F [mm]	11	11	13
Screw connection – M	M5	M5	M6
Weight without packaging [g]	2900	5900	8800

Tab. 44: TEP dimensions and weight

9.4.6 Brake module and EMC shroud

BRS 5001 brake module



ID No. 56519

Brake module for inverters of the SDS 5000 series.

Accessory part for direct control of up to two brakes (24 V_{DC}) and (for inverters up to size 2) for connecting to the shield of the power cable.

Can be attached to the inverter housing.

Including connection cable for the inverter and shield connection terminal.

EM 5000 EMC shroud



ID No. 44959

EMC shroud for servo inverters of generation 5.

Accessory part for shield connection of the power cable for inverters up to size 2.

Can be attached to the inverter housing.

Including shield connection terminal.

EM6A3 EMC shroud



ID No. 56521

EMC shroud for drive controllers of the MDS 5000, SDS 5000 and SD6 series.

Accessory part for shield connection of the power cable for drive controllers up to size 3.

Can be attached to the drive controller housing.

Including shield connection terminal.

If necessary, you can also connect the cable shield of the braking resistor and DC link connection to the shroud.

9.4.7 Removable data storage

Paramodul removable data storage

Included in the standard version.



ID No. 55464

Memory module for configuration and parameters.

9.5 Further information

9.5.1 Directives and standards

The following European directives and standards are relevant for inverters:

- Machinery Directive 2006/42/EC
- Low Voltage Directive 2014/35/EU
- EMC Directive 2014/30/EU
- EN 61326-3-1:2008
- EN 61800-3:2012-09 and 1:2014-02
- EN 61800-5-1:2008-04 and 1:2010-04
- EN 61800-5-2:2016-04
- EN 50178:1997

9.5.2 Marks and test symbols

The following marks and test symbols are mentioned in the technical data.



RoHS lead-free mark

Marking in accordance with RoHS directive 2011-65-EU.



CE mark

Manufacturer's self declaration: The product meets the requirements of EU directives.



UKCA test symbol

Manufacturer's self declaration: The product meets the requirements of UK directives.



UL test symbol (cULus)

This product is listed by UL for the United States and Canada. Representative samples of this product have been evaluated by UL and meet the requirements of applicable standards.



UL test symbol for recognized component mark (cURus)

This component or material is recognized by UL. Representative samples of this product have been evaluated by UL and meet applicable requirements.

9.5.3 Additional documentation

Additional documentation related to the product can be found at

<http://www.stoeber.de/en/downloads/>

Enter the ID of the documentation in the Search field.

Documentation	ID
Configuration manual for POSIDYN SDS 5000 servo inverters	442277

10 POSIDRIVE FDS 5000 Frequency inverters

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10

Frequency inverters

POSIDRIVE FDS 5000

10.1 Overview

The purpose-built asynchronous servo axis

Features

- Nominal output current up to 16 A
- 180% overload capacity
- Power range: 0.37 kW to 7.5 kW
- Control of rotating asynchronous motors
- Interface for incremental encoder (HTL/TTL)
- Communication using PROFIBUS DP, PROFINET, CANopen or EtherCAT
- Safe Torque Off (STO) and Safe Stop 1 (SS1) safety functions: SIL 3, PL e (cat. 3)
- Digital and analog inputs and outputs
- Brake chopper and line filter
- Convenient operating unit consisting of plain-text display and buttons
- Paramodul removable data storage for quick commissioning and service

10.1.1 Features

The FDS 5000 series is a purely digital, modular inverter system for operating rotational asynchronous motors with product types for direct operation on a single-phase or three-phase network in a voltage range from 200 V_{AC} to 528 V_{AC}. An EMC line filter is integrated. An incremental encoder interface (HTL/TTL) is available by default. The ASP 5001 safety module makes it possible to implement the Safe Torque Off (STO) and Safe Stop 1 (SS1) safety functions in accordance with DIN EN ISO 13849-1 and DIN EN 61800-5-2 for safety-relevant applications. Communication modules provide the connection to a controller over the PROFIBUS DP, PROFINET, CANopen or EtherCAT fieldbus. Plain-text display and buttons simplify diagnostics in the event of faults and enable quick access to parameters. The Paramodul removable data storage can be used to transfer all application-relevant data from one inverter to another.

The vector control, sensorless vector control and U/f controller control modes are available for use with asynchronous motors.



POSIDRIVE FDS 5000

Paramodul removable data storage

Removable data storage for fast series commissioning by copying and easy service when replacing devices.



POSITool

The 5th generation of POSITool project configuration and commissioning software has all the functions needed for efficient use of inverters in single and multi-axis applications.

10.1.2 Software components

Modular application software

Various standard applications can be loaded onto the devices of the 5th STOBBER inverter generation with the POSITool commissioning software as needed. Furthermore, programming based on IEC 61131-3 with CFC can be used to create new applications or expand existing ones. The inverter operating system is multi-axis capable. It supports up to four axes with separate application and parameter ranges.

Velocity mode (standard application)

- **Fast set value**
Simple speed application for lean applications. The speed reference value and torque limiting can be specified using analog inputs as well as digitally.

Torque/force and velocity mode (standard application)

- **Comfort set value**
Expanded torque and speed set value application. Set values and limits can be assigned with the fast set value as well as using fixed values, motor potentiometers and other functions.
- **Technology controller**
PID controller for torque or speed-controlled applications.

Positioning and master/slave mode (standard application)

- **Command, synchronous command**
High-performance positioning application with a command interface based on PLCopen. The data for a motion task including target position, velocity and acceleration are transferred together over fieldbus to the inverter, which then processes them independently. The functional scope is rounded out by an electrical cam, motion block switching point and Posi-Latch.
- **Motion block**
Extensive positioning application with up to 256 motion blocks based on PLCopen. The motion blocks can be selected individually over fieldbus or with digital inputs. They can also be started in a chain. The functional scope is rounded out by an electrical cam and Posi-Latch.

Electronic cam disk with PLCopen interface (tailor-made applications)

The electronic cam disk application makes it possible to implement complex motion tasks such as:

- Flying saw
- Synchronizer (clock in/clock out)
- Cross cutter
- Welding bar/embossing stamp
- Print mark control

These applications can be implemented quickly and easily using readily understandable, free graphical programming based on IEC 61131-3 CFC. This also allows for customer-specific adaptations to special system conditions. Function blocks based on PLCopen Motion Control are available for this purpose for trained users.

10.1.3 Application training

STOBBER offers a multi-level training program that is essentially focused on the inverter.

The application training is performed on the SDS 5000 series.

G5 Basic

Training content: System overview, installation and commissioning of the inverter. Use of option modules. Parameterization, commissioning and diagnostics using the integrated display and commissioning software. Remote maintenance. Basics of controller optimization. Configuration of the drive train. Integrated software functions. Software applications. Connection to a higher-level controller. Basics of safety technology. Practical exercises on training topics.

Software used: POSITool.

G5 Customized

Training content: Graphical programming with CFC. Special knowledge for regulating, control and safety technology. Electronic cam disk. Practical exercises on training topics.

10.2 Technical data

Technical data for inverters can be found in the following sections.

10.2.1 Type designation

FDS	5	015	A
-----	---	-----	---

Tab. 1: Example code for type designation

Code	Designation	Design
FDS	Series	
5	Generation	Generation 5
075	Power	075 = 7.5 kW
–	Hardware variants	Without marking: Up to HW 199
A		A: Starting from HW 200
/H /L	Version	Auxiliary voltage for control electronics: <ul style="list-style-type: none"> Supply for control electronics over DC link; no additional 24 V_{DC} supply required Supply of control electronics over 24 V_{DC} to terminal X11

Tab. 2: Meaning of the example code

10.2.2 Sizes

Type	ID No. /H	ID No. /L	Size
FDS 5004A	55420	55412	Size 0
FDS 5007A	55421	55413	Size 0
FDS 5008A	55422	55414	Size 0
FDS 5015A	55423	55415	Size 0
FDS 5022A	55424	55416	Size 1
FDS 5040A	55425	55417	Size 1
FDS 5055A	55426	55418	Size 1
FDS 5075A	55427	55419	Size 1

Tab. 3: Available FDS 5000 types and sizes



FDS 5000 in sizes 0 and 1

10.2.3 General technical data

The following information applies to all inverter types.

Device features	
Protection class of the device	IP20
Protection class of the installation space	At least IP54
Protection class	Protection class I in accordance with EN 61140
Radio interference suppression	Integrated line filter in accordance with EN 61800-3, interference emission class C3
Overvoltage category	III in accordance with EN 61800-5-1
Marks and test symbols	CE, cULus, RoHS

Tab. 4: Device features

Transport and storage conditions	
Storage/transport temperature	-20 °C to +70 °C Maximum change: 20 K/h
Relative humidity	Maximum relative humidity 85%, non-condensing
Vibration (transport) in accordance with EN 60068-2-6	5 Hz ≤ f ≤ 9 Hz: 3.5 mm 9 Hz ≤ f ≤ 200 Hz: 10 m/s ² 200 Hz ≤ f ≤ 500 Hz: 15 m/s ²
Fall height for freefall ¹ Weight < 100 kg in accordance with EN 61800-2 (or IEC 60721-3-2, class 2M1)	0.25 m

Tab. 5: Transport and storage conditions

Operating conditions	
Surrounding temperature during operation	0 °C to 45 °C with nominal data 45 °C to 55 °C with derating -2.5% / K
Relative humidity	Maximum relative humidity 85%, non-condensing
Installation altitude	0 m to 1000 m above sea level without restrictions 1000 m to 2000 m above sea level with -1.5%/100 m derating
Pollution degree	Pollution degree 2 in accordance with EN 50178
Ventilation	Installed fan
Vibration (operation) in accordance with EN 60068-2-6	5 Hz ≤ f ≤ 9 Hz: 0.35 mm 9 Hz ≤ f ≤ 200 Hz: 1 m/s ²

Tab. 6: Operating conditions

Discharge times	
Self-discharge of DC link	6 min

Tab. 7: Discharge times of the DC link circuit

10.2.4 Electrical data

The electrical data of the available sizes as well as the properties of the brake chopper can be found in the following sections.

An explanation of the formula symbols used can be found in the chapter [\[13.1 \]](#).

10.2.4.1 Size 0: FDS 5007A to FDS 5015A

Electrical data	FDS 5007A	FDS 5004A	FDS 5008A	FDS 5015A
ID No. /H	55421	55420	55422	55423
ID No. /L	55413	55412	55414	55415
Recommended motor rating	0.75 kW	0.37 kW	0.75 kW	1.5 kW
U_{1PU}	1 × 230 V, +20% / -40%, 50/60 Hz		3 × 400 V, +32% / -50%, 50 Hz; 3 × 480 V, +10% / -58%, 60 Hz	
$I_{1N,PU}$	1 × 5.9 A	3 × 1.4 A	3 × 2.2 A	3 × 4 A
f_{2PU}	0 – 700 Hz			
U_{2PU}	0 – 230 V		0 – 400 V	
U_{maxPU}	440 V		830 V	

Tab. 8: FDS 5000 electrical data, size 0

Nominal currents up to +45 °C (in the control cabinet)

Operation with asynchronous motor

Electrical data	FDS 5007A	FDS 5004A	FDS 5008A	FDS 5015A
$I_{2N,PU}$	3 × 4 A	3 × 1.3 A	3 × 2.3 A	3 × 4.5 A
I_{2maxPU}	180% for 5 s; 150% for 30 s			
$f_{PWM,PU}$	4 kHz ²			

Tab. 9: FDS 5000 electrical data, size 0, at 4 kHz clock frequency

Electrical data	FDS 5007A	FDS 5004A	FDS 5008A	FDS 5015A
U_{onCH}	400 – 420 V		780 – 800 V	
U_{offCH}	360 – 380 V		740 – 760 V	
R_{2minRB}	100 Ω		100 Ω	
P_{maxRB}	1.8 kW		6.4 kW	

Tab. 10: Brake chopper electrical data, size 0

10.2.4.2 Size 1: FDS 5022A to FDS 5075A

Electrical data	FDS 5022A	FDS 5040A	FDS 5055A	FDS 5075A
ID No. /H	55424	55425	55426	55427
ID No. /L	55416	55417	55418	55419
Recommended motor rating	2.2 kW	4.0 kW	5.5 kW	7.5 kW
U_{1PU}			3 × 400 V, +32% / -50%, 50 Hz; 3 × 480 V, +10% / -58%, 60 Hz	
$I_{1N,PU}$	3 × 5.3 A	3 × 9.3 A	3 × 12.3 A	3 × 15.8 A
f_{2PU}	0 – 700 Hz			
U_{2PU}	0 – 400 V			
U_{maxPU}	830 V			

Tab. 11: FDS 5000 electrical data, size 1

² Clock frequency adjustable from 4 to 16 kHz (see the chapter on derating)

Nominal currents up to +45 °C (in the control cabinet)

Operation with asynchronous motor

Electrical data	FDS 5022A	FDS 5040A	FDS 5055A	FDS 5075A
$I_{2N,PU}$	3 × 5.5 A	3 × 10 A	3 × 12 A	3 × 16 A
I_{2maxPU}	180% for 5 s; 150% for 30 s			
$f_{PWM,PU}$	4 kHz ³			

Tab. 12: FDS 5000 electrical data, size 1, at 4 kHz clock frequency

Electrical data	FDS 5022A	FDS 5040A	FDS 5055A	FDS 5075A
U_{onCH}	780 – 800 V			
U_{offCH}	740 – 760 V			
R_{2minRB}	100 Ω		47 Ω	
P_{maxRB}	6.4 kW		13.6 kW	

Tab. 13: Brake chopper electrical data, size 1

10.2.4.3 Power loss data in accordance with EN 61800-9-2

Type	Nominal current $I_{2N,PU}$	Apparent power	Absolute losses $P_{V,CU}$ ⁴	Operating points ⁵								IE class ⁶
				(0/25)	(0/50)	(0/100)	(50/25)	(50/50)	(50/100)	(90/50)	(90/100)	
				Relative losses								
				[%]								
	[A]	[kVA]	[W]									
FDS 5004A	1.3	0.9	6	5.92	5.94	6.20	5.97	6.02	6.36	6.13	6.62	IE2
FDS 5007A	4	0.9	6	5.01	5.07	5.68	5.20	5.37	6.30	5.88	7.43	IE2
FDS 5008A	2.3	1.6	6	2.98	3.13	3.49	3.02	3.22	3.71	3.36	4.09	IE2
FDS 5015A	4.5	3.1	< 9	1.71	1.86	2.24	1.75	1.97	2.51	2.16	3.04	IE2
FDS 5022A	5.5	3.8	< 9	1.64	1.79	2.16	1.69	1.89	2.38	2.02	2.74	IE2
FDS 5040A	10	6.9	< 9	1.38	1.54	1.93	1.43	1.64	2.17	1.80	2.57	IE2
FDS 5055A	12	8.3	< 9	1.10	1.26	1.76	1.15	1.36	2.04	1.51	2.50	IE2
FDS 5075A	16	11.1	< 9	0.95	1.12	1.67	1.00	1.23	1.98	1.41	2.52	IE2

Tab. 14: Relative losses of FDS 5000 inverters in accordance with EN 61800-9-2

³ Clock frequency adjustable from 4 to 16 kHz (see the chapter on derating)

⁴ Absolute losses for a power unit that is switched off

⁵ Operating points for relative motor stator frequency in % and relative torque current in %

⁶ IE class in accordance with EN 61800-9-2

Type	Nominal current $I_{2N,PU}$	Apparent power	Absolute losses $P_{V,CU}$ ⁷	Operating points ⁸								IE class ⁹	Comparison ¹⁰
				(0/25)	(0/50)	(0/100)	(50/25)	(50/50)	(50/100)	(90/50)	(90/100)		
				Absolute losses P_V									
			[W]	[W]									[%]
FDS 5004A	1.3	0.9	6	53.3	53.5	55.8	53.7	54.2	57.2	55.2	59.6	IE2	46.2
FDS 5007A	4	0.9	6	45.1	45.6	51.1	46.8	48.3	56.7	52.9	66.9	IE2	51.8
FDS 5008A	2.3	1.6	6	47.7	50.1	55.8	48.3	51.5	59.3	53.8	65.4	IE2	40.2
FDS 5015A	4.5	3.1	< 9	52.9	57.6	69.3	54.4	61.0	77.9	67.1	94.1	IE2	39.6
FDS 5022A	5.5	3.8	< 9	62.4	68.0	82.0	64.1	71.7	90.6	76.9	104.1	IE2	34.9
FDS 5040A	10	6.9	< 9	95.3	106.1	133.3	98.6	113.2	149.9	123.9	177.0	IE2	37.1
FDS 5055A	12	8.3	< 9	91.3	104.6	145.9	95.1	113.1	169.2	125.7	207.7	IE2	35.7
FDS 5075A	16	11.1	< 9	104.9	124.0	184.6	110.3	136.6	219.8	156.0	279.8	IE2	35.8

Tab. 15: Absolute losses of FDS 5000 inverters in accordance with EN 61800-9-2

General conditions

The loss data applies to inverters without accessories.

The power loss calculation is based on a three-phase supply voltage with 400 V_{AC}/50 Hz.

The calculated data includes a supplement of 10% in accordance with EN 61800-9-2.

The power loss specifications refer to a clock frequency of 4 kHz.

The absolute losses for a power unit that is switched off refer to the 24 V_{DC} power supply of the control electronics.

10.2.5 Derating by increasing the clock frequency

Depending on the clock frequency $f_{PWM,PU}$, the following values for nominal output currents $I_{2N,PU}$ arise.

Type	$I_{2N,PU}$ 4 kHz	$I_{2N,PU}$ 8 kHz	$I_{2N,PU}$ 16 kHz
FDS 5004A	1.3 A	1.0 A	0.7 A
FDS 5007A	4.0 A	3.0 A	2.0 A
FDS 5008A	2.3 A	1.7 A	1.2 A
FDS 5015A	4.5 A	3.4 A	2.2 A
FDS 5022A	5.5 A	4.0 A	2.6 A
FDS 5040A	10 A	6 A	3.3 A
FDS 5055A	12.0 A	7.5 A	4.8 A
FDS 5075A	16.0 A	10.0 A	5.7 A

Tab. 16: Nominal output current $I_{2N,PU}$ dependent on the clock frequency

⁷ Absolute losses for a power unit that is switched off

⁸ Operating points for relative motor stator frequency in % and relative torque current in %

⁹ IE class in accordance with EN 61800-9-2

¹⁰ Comparison of the losses for the reference inverter related to IE2 in the nominal point (90, 100)

10.2.6 Dimensions

The dimensions of the available FDS 5000 sizes can be found in the following chapters.

10.2.6.1 Dimensions: size 0 to 1

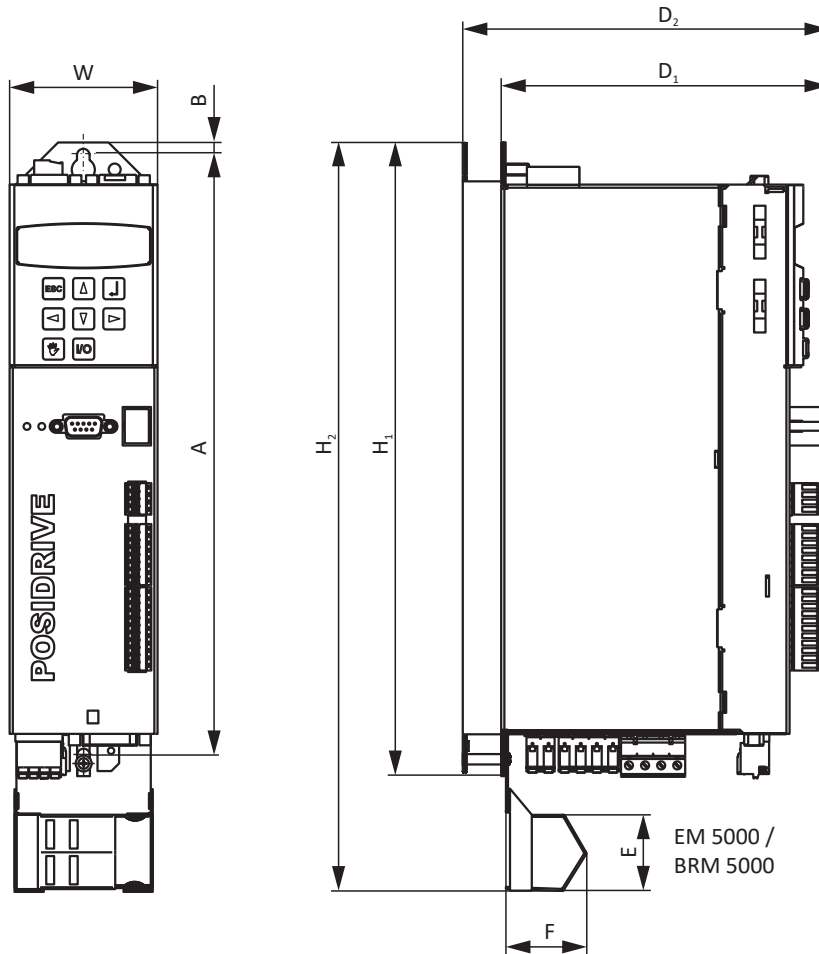


Fig. 1: FDS 5000 dimensional drawing

Dimensions [mm]			Size 0	Size 1
Inverter	Height	H ₁	300	
		H ₂ ¹¹	360	
	Width	W	70	
	Depth	D ₁	157	242
D ₂ ¹²		175	260	
EMC shroud	Height	E	37.5	
	Depth	F	40	
Fastening holes	Vertical distance	A	283	
	Vertical distance to the upper edge	B	6	

Tab. 17: FDS 5000 dimensions [mm]

10.2.7 Minimum clearances

The specified dimensions refer to the outside edges of the inverter.

Minimum clearance	Above	Below	On the side
Size 0 – Size 1	100	100	5
... with EMC shroud or brake module	100	120	5

Tab. 18: Minimum clearances [mm]

¹¹ H₂ = height incl. EM 5000 EMC shroud or BRM 5000 brake module

¹² D₂ = Depth incl. RB 5000 braking resistor

10.3 Inverter/motor combinations

Parameterization of a STOBBER inverter is remarkably easy, especially in combination with four-pole STOBBER asynchronous motors. The motor is fully typified by inputting just the motor size (e.g. 90L) and its wiring (star or delta). A delta connection (measurement point 230 V, 50 Hz) is available for motors up to 3 kW (size 100). By increasing the voltage at higher frequencies, the full torque can be drawn through the motor up to 87 Hz. It usually makes sense to take this expanded speed adjustment range into account when selecting the gear unit. You can find more detailed information in the chapter [\[5.6\]](#).

An explanation of the formula symbols used can be found in the chapter [\[13.1\]](#).

									FDS 5004A	FDS 5007A	FDS 5008A	FDS 5015A	FDS 5022A	FDS 5040A	FDS 5055A
									$I_{2N,PU}$ [A] ($f_{PWM,PU} = 4$ kHz)						
f_T [Hz]	pz	Con- nection	P_N [kW]	n_N [rpm]	M_N [Nm]	M_k/M_N	I_N [A]		1.3	4	2.3	4.5	5.5	10	12
Δ 230 V / Y 400 V motor winding									$I_{2N,PU} / I_N$						
IE3D063K04	50	4	Y	0.12	1400	0.82	2.3	0.35							
IE3D063K04	87	4	Δ	0.21	2425	0.82	2.3	0.61	2.1						
IE3D063M04	50	4	Y	0.18	1415	1.21	2.9	0.55							
IE3D063M04	87	4	Δ	0.31	2451	1.21	2.9	0.95	1.4						
IE3D071K04	50	4	Y	0.25	1430	1.67	2.9	0.66	2.0						
IE3D071K04	87	4	Δ	0.43	2477	1.67	2.9	1.1	1.1		2.0				
IE3D071L04	50	4	Y	0.37	1430	2.5	3.2	0.98	1.3						
IE3D071L04	87	4	Δ	0.64	2477	2.5	3.2	1.7			1.4				
IE3D080K04	50	4	Y	0.55	1440	3.65	3.6	1.27	1.0			1.8			
IE3D080K04	87	4	Δ	1.0	2494	3.65	3.6	2.2		1.8	1.0	2.0			
IE3D080L04	50	4	Y	0.75	1445	5.0	3.7	1.7				1.4			
IE3D080L04	87	4	Δ	1.3	2503	5.0	3.7	2.94		1.4		1.5	1.9		
IE3D090S04	50	4	Y	1.1	1440	7.3	3.7	2.5		1.6		1.8	2.2		
IE3D090S04	87	4	Δ	1.91	2494	7.3	3.7	4.33				1.0	1.3		
IE3D090LX04	50	4	Y	1.5	1455	9.8	4.9	3.4		1.2		1.3	1.6		
IE3D090LX04	87	4	Δ	2.6	2503	9.8	4.9	5.89						1.7	2.0
IE3D100KX04	50	4	Y	2.2	1450	14.5	3.8	4.55					1.2	2.2	
IE3D100KX04	87	4	Δ	3.81	2511	14.5	3.8	7.88						1.3	1.5
IE3D100LX04	50	4	Y	3.0	1450	19.8	4	6.35						1.6	1.9
IE3D100LX04	87	4	Δ	5.2	2511	19.8	4	11							1.1
IE3D112M04	50	4	Δ	4.0	1465	26.1	4.5	7.9						1.3	1.5
IE3D132SX04	50	4	Δ	5.5	1465	36	3.3	10						1.0	1.2
IE3D132MX04	50	4	Δ	7.5	1470	49	3.9	16							

10.4 Accessories

You can find information about the available accessories in the following chapters.

10.4.1 Safety technology

ASP 5001 – Safe Torque Off

Information

The drive controller is delivered in the standard design without safety technology. If you want a drive controller with integrated safety technology, you must order it together with the drive controller. The safety modules are an integrated part of the drive controller and must not be modified.

Available with the standard design.



Option module for implementation of integrated safety function Safe Torque Off (STO).

10.4.2 Communication

G3 connection cable



ID No. 41488

Cable for connecting the inverter to terminal X3 with the PC, D-sub connector, 9-pin, socket/socket, approx. 5 m.

USB adapter to RS232



ID No. 45616

Adapter for connecting RS232 to a USB port.

CANopen DS-301 CAN 5000 communication module



ID No. 44574

Accessory part for connecting CAN bus.

PROFIBUS DP-V1 DP 5000 communication module



ID No. 44575

Accessory module for connecting PROFIBUS DP-V1.

EtherCAT ECS 5000 communication module

ID No. 49014

Accessory part for connecting EtherCAT (CANopen over EtherCAT).

EtherCAT cables

Ethernet patch cable, CAT5e, yellow.

The following designs are available:

ID No. 49313: Length approx. 0.25 m.

ID No. 49314: Length approx. 0.5 m.

PROFINET PN 5000 communication module

ID No. 53893

Accessory part for connecting PROFINET.

10.4.3 Terminal module**LEA 5000 terminal module**

ID No. 49029

Terminals:

- 8 digital inputs
- 8 digital outputs

Delivery including mounting plate

10.4.4 Braking resistor

In addition to the inverters, STÖBER offers braking resistors in different sizes and performance classes described below. For the selection, note the minimum permitted braking resistances specified in the technical data of the individual inverter types.

10.4.4.1 FZMU, FZZMU tubular fixed resistor

Type	FZMU 400×65	FZZMU 400×65
ID No.	49010	53895
FDS 5007A	X	—
FDS 5004A	X	—
FDS 5008A	X	—
FDS 5015A	X	—
FDS 5022A	X	—
FDS 5040A	(X)	X
FDS 5055A	(X)	X
FDS 5075A	(X)	X

Tab. 19: Assignment of FZMU, FZZMU braking resistor – FDS 5000 inverter

X	Recommended
(X)	Possible
—	Not possible

Properties

Specification	FZMU 400×65	FZZMU 400×65
ID No.	49010	53895
Type	Tubular fixed resistor	Tubular fixed resistor
Resistance [Ω]	100 \pm 10%	47 \pm 10%
Thermal drift	\pm 10%	\pm 10%
Power [W]	600	1200
Therm. time const. τ_{th} [s]	40	40
Pulse power for < 1 s [kW]	18	36
U_{max} [V]	848	848
Weight without packaging [g]	2200	4170
Protection class	IP20	IP20
Marks and test symbols	cURus, CE, UKCA	cURus, CE, UKCA

Tab. 20: FZMU, FZZMU specification

Dimensions

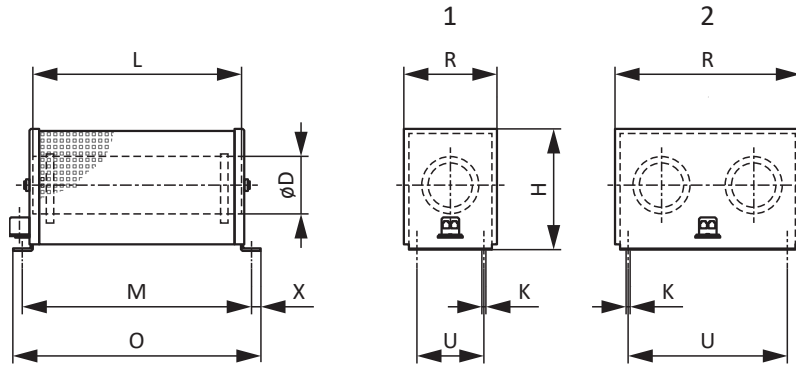


Fig. 2: FZMU (1), FZZMU (2) dimensional drawing

Dimension	FZMU 400×65	FZZMU 400×65
ID No.	49010	53895
L x D	400 × 65	400 × 65
H	120	120
K	6.5 × 12	6.5 × 12
M	430	426
O	485	485
R	92	185
U	64	150
X	10	10

Tab. 21: FZMU, FZZMU dimensions [mm]

10.4.4.2 GVADU, GBADU flat resistor

Type	GVADU 210×20	GBADU 265×30	GBADU 405×30	GBADU 335×30
ID No.	55441	55442	55499	55443
FDS 5007A	X	X	X	—
FDS 5004A	X	X	X	—
FDS 5008A	X	X	X	—
FDS 5015A	X	X	X	—
FDS 5022A	X	X	X	—
FDS 5040A	(X)	(X)	(X)	X
FDS 5055A	(X)	(X)	(X)	X
FDS 5075A	(X)	(X)	(X)	X

Tab. 22: Assignment of GVADU, GBADU braking resistor – FDS 5000 inverter

- X Recommended
- (X) Possible
- Not possible

Properties

Specification	GVADU 210×20	GBADU 265×30	GBADU 405×30	GBADU 335×30
ID No.	55441	55442	55499	55443
Type	Flat resistor			
Resistance [Ω]	100 ±10%	100 ±10%	100 ±10%	47 ±10%
Thermal drift	±10%	±10%	±10%	±10%
Power [W]	150	300	500	400
Therm. time const.	60	60	60	60
τ_{th} [s]				
Pulse power for < 1 s [kW]	3.3	6.6	11	8.8
U_{max} [V]	848	848	848	848
Cable design	Radox	FEP	FEP	FEP
Cable length [mm]	500	1500	500	1500
Conductor cross-section [AWG]	18/19	14/19	14/19	14/19
	(0.82 mm ²)	(1.9 mm ²)	(1.9 mm ²)	(1.9 mm ²)
Weight without packaging [g]	300	930	1410	1200
Protection class	IP54	IP54	IP54	IP54
Marks and test symbols	cURus, CE, UKCA			

Tab. 23: GVADU, GBADU specification

Dimensions

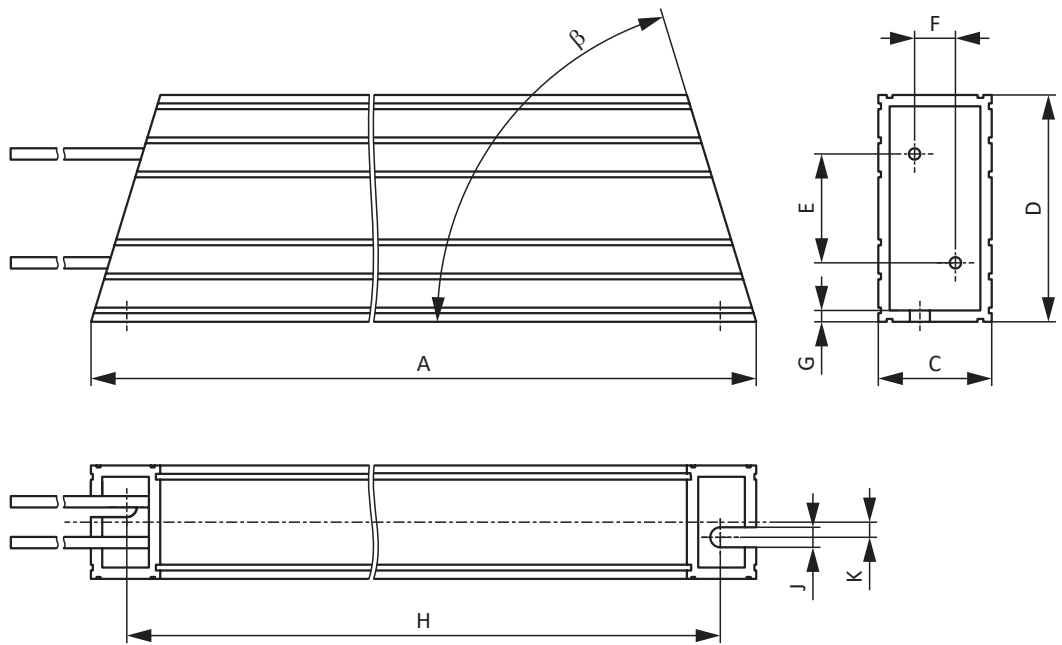


Fig. 3: GVADU, GBADU dimensional drawing

Dimension	GVADU 210×20	GBADU 265×30	GBADU 405×30	GBADU 335×30
ID No.	55441	55442	55499	55443
A	210	265	405	335
H	192	246	386	316
C	20	30	30	30
D	40	60	60	60
E	18.2	28.8	28.8	28.8
F	6.2	10.8	10.8	10.8
G	2	3	3	3
K	2.5	4	4	4
J	4.3	5.3	5.3	5.3
β	65°	73°	73°	73°

Tab. 24: GVADU, GBADU dimensions [mm]

10.4.4.3 RB 5000 rear section braking resistor

Type	RB 5047	RB 5100
ID No.	44966	44965
FDS 5007A	—	X
FDS 5004A	—	X
FDS 5008A	—	X
FDS 5015A	—	X
FDS 5022A	—	X
FDS 5040A	X	(X)
FDS 5055A	X	(X)
FDS 5075A	X	(X)

Tab. 25: Assignment of RB 5000 braking resistor – FDS 5000 inverter

X	Recommended
(X)	Possible
—	Not possible

Properties

Specification	RB 5047	RB 5100
ID No.	44966	44965
Resistance [Ω]	47 \pm 10%	100 \pm 10%
Thermal drift	\pm 10%	\pm 10%
Power [W]	60	60
Therm. time const. τ_{th} [s]	8	8
Pulse power for < 1 s [kW]	1.5	1.0
U_{max} [V]	800	800
Weight without packaging [g]	460	440
Cable design	Radox	Radox
Cable length [mm]	250	250
Conductor cross-section [AWG]	18/19 (0.82 mm ²)	18/19 (0.82 mm ²)
Maximum torque of M5 threaded bolts [Nm]	5	5
Protection class	IP40	IP40
Marks and test symbols	cURus, CE, UKCA	cURus, CE, UKCA

Tab. 26: RB 5000 specification

Dimensions

Dimension	RB 5047	RB 5100
ID No.	44966	44965
Height	300	300
Width	62	62
Depth	18	18
Drilling diagram corresponds to size	Size 1	Size 0 and Size 1

Tab. 27: RB 5000 dimensions [mm]

10.4.5 Choke

Technical specifications for suitable chokes can be found in the following chapters.

10.4.5.1 TEP output choke

Output chokes are required from a cable length > 50 m in order to reduce interference pulses and protect the drive system.

Information

The following technical data only applies to a rotating magnetic field frequency of 200 Hz. For example, this rotating magnetic field frequency is achieved with a motor with 4 pole pairs and a nominal speed of 3000 rpm. Always observe the specified derating for higher rotating magnetic field frequencies. Also observe the relationship with the clock frequency.

Properties

Specification	TEP3720-0ES41	TEP3820-0CS41
ID No.	53188	53189
Voltage range	3 × 0 to 480 V	
Frequency range	0 – 200 Hz	
Nominal current $I_{N,MF}$ at 4 kHz	4 A	17.5 A
Nominal current $I_{N,MF}$ at 8 kHz	3.3 A	15.2 A
Max. permitted motor cable length with output choke	100 m	
Max. surrounding temperature $\vartheta_{amb,max}$	40 °C	
Protection class	IP00	
Winding losses	11 W	29 W
Iron losses	25 W	16 W
Connection	Screw terminal	
Max. conductor cross-section	10 mm ²	
UL Recognized Component (CAN; USA)	Yes	
Marks and test symbols	cURus, CE	

Tab. 28: TEP specification

Dimensions

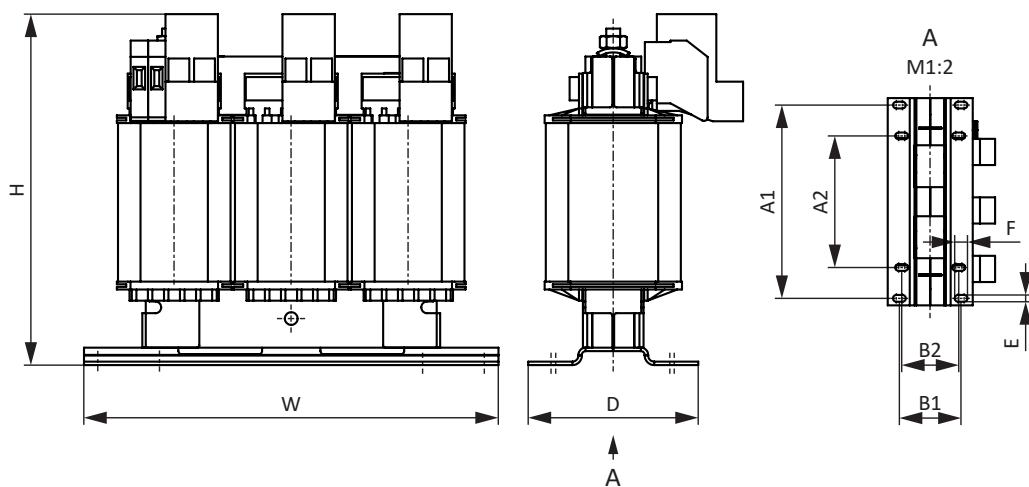


Fig. 4: TEP dimensional drawing

Dimension	TEP3720-0ES41	TEP3820-0CS41
Height h [mm]	Max. 153	Max. 153
Width w [mm]	178	178
Depth d [mm]	73	88
Vertical distance – Fastening holes a1 [mm]	166	166
Vertical distance – Fastening holes a2 [mm]	113	113
Horizontal distance – Fastening holes b1 [mm]	53	68
Horizontal distance – Fastening holes b2 [mm]	49	64
Drill holes – Depth e [mm]	5.8	5.8
Drill holes – Width f [mm]	11	11
Screw connection – M	M5	M5
Weight [g]	2900	5900

Tab. 29: TEP dimensions and weight

10.4.6 Brake module and EMC shroud

Brake module for 24 V brake BRM 5000



ID No. 44571

Brake module for inverters of the FDS 5000 and MDS 5000 series.

Accessory part for control of a brake (24 V_{DC}) and (for inverters up to size 2) for connecting to the shield of the power cable.

Can be attached to the inverter housing.

Including shield connection terminal.

EM 5000 EMC shroud



ID No. 44959

EMC shroud for servo inverters of generation 5.

Accessory part for shield connection of the power cable for inverters up to size 2.

Can be attached to the inverter housing.

Including shield connection terminal.

10.4.7 Control box

Control box



Operating device for parameterization and operation of servo inverters from the FDS 5000 and MDS 5000 series.

The connection cable with a length of 1.5 m is included in the scope of delivery.

The following designs are available:

ID No. 42224: Service variant.

ID No. 42225: Installation DIN housing 96 x 96 mm, protection class IP54.



Control box cable

Connection cable from control box to inverter.

The following designs are available:

ID No. 43216: 5 m.

ID No. 43217: 10 m.

10.4.8 Removable data storage

Paramodul removable data storage

Included in the standard version.



ID No. 55463

Memory module for configuration and parameters.

10.5 Further information

10.5.1 Directives and standards

The following European directives and standards are relevant for inverters:

- Machinery Directive 2006/42/EC
- Low Voltage Directive 2014/35/EU
- EMC Directive 2014/30/EU
- EN 61326-3-1:2008
- EN 61800-3:2012-09 and 1:2014-02
- EN 61800-5-1:2008-04 and 1:2010-04
- EN 61800-5-2:2016-04
- EN 50178:1997

10.5.2 Marks and test symbols

The following marks and test symbols are mentioned in the technical data.



RoHS lead-free mark

Marking in accordance with RoHS directive 2011-65-EU.



CE mark

Manufacturer's self declaration: The product meets the requirements of EU directives.



UKCA test symbol

Manufacturer's self declaration: The product meets the requirements of UK directives.



UL test symbol (cULus)

This product is listed by UL for the United States and Canada. Representative samples of this product have been evaluated by UL and meet the requirements of applicable standards.



UL test symbol for recognized component mark (cURus)

This component or material is recognized by UL. Representative samples of this product have been evaluated by UL and meet applicable requirements.

10.5.3 Additional documentation

Additional documentation related to the product can be found at

<http://www.stoeber.de/en/downloads/>

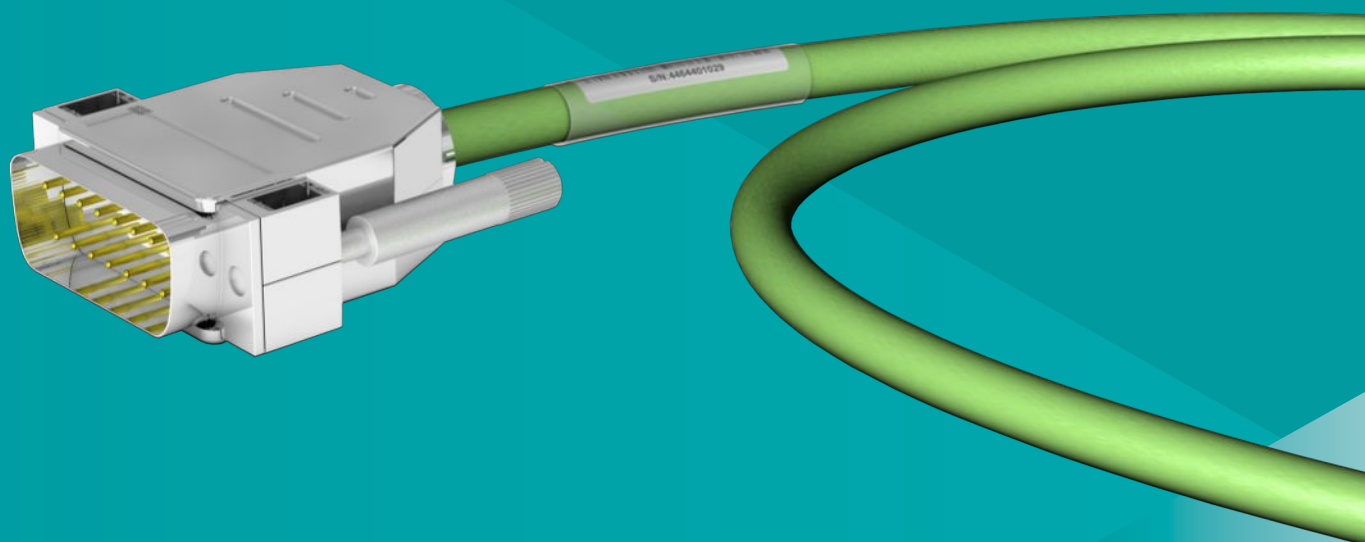
Enter the ID of the documentation in the Search field.

Documentation	ID
Configuration manual for POSIDRIVE FDS 5000 frequency inverters	442269

11 Connection method

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11 Connection method

11.1 Overview

Coordinated connection methods for STOBER drive controllers

Features

- Torsional stress $\pm 30^\circ/\text{m}$
- Bending resistance
- Oil resistance
- Chemical resistance

A drive controller, cable and motor that are not coordinated with one another can lead to impermissibly high voltage peaks in the drive system, which may cause damage to the motor. The legal requirements of (EMC) Directive 2014/30/EU must also be observed.

Combining STOBER motors, STOBER cables and STOBER drive controllers enables you to comply with these legal requirements.

STOBER offers a range of cables to match. Cables are available in different lengths and are ready-made on both ends.

Using unsuitable connection cables may void any claims made under the warranty.

11.2 Conventions for cables

In the cable connection descriptions, core colors are shortened and used as follows.

Cable colors

BK:	BLACK	PK:	PINK
BN:	BROWN	RD:	RED
BU:	BLUE	VT:	VIOLET
GN:	GREEN	WH:	WHITE
GY:	GRAY	YE:	YELLOW
OG:	ORANGE		

Formatting conventions

Two-colored core:	WHYE	WHITEYELLOW (white and yellow)
Single-colored core:	BK/BN	BLACK/BROWN (black or brown)

11.3 Encoder cables

STOBER motors are equipped with encoder systems and plug connectors as standard.

STOBER provides suitable cables in various lengths, conductor cross-sections and connector sizes.

The cables are available ready-made in the lengths 2.5 m, 5 m, 7.5 m, 10 m, 12.5 m, 15 m, 18 m, 20 m, 25 m, 30 m, 35 m, 40 m and 50 m.

Other lengths on request.

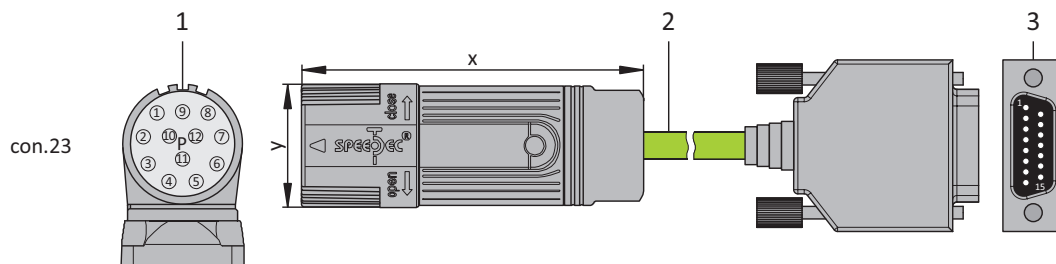
You can find the technical data for the encoder systems in the chapter Encoders.

11.3.1 Differential HTL incremental encoders

Suitable encoder cables are described below.

11.3.1.1 Connection description

The encoder cable is available in plug connector size con.23 with a speedtec quick lock.



- 1 Plug connectors
- 2 STOBER encoder cable
- 3 D-sub X4

Information

For the connection of an HTL incremental encoder to terminal X4 of SC6 or SI6 drive controllers, you need the HT6 adapter (ID No. 56665). HT6 takes over level conversion from HTL signals to TTL signals.

Encoder cables – con.23 plug connectors

Connection diagram	Motor (1)				Cable (2)	Drive controller (3)
	Pin	Designation	Core color up to size 80	Core color size 90 or larger	Core color	Pin X4
	1	B -	PK	BK	YE	9
	2	—	—	YE	—	—
	3	N +	BU	PK	PK	3
	4	N -	RD	WH	GY	10
	5	A +	GN	GN	BN	6
	6	A -	YE	BN	WH	11
	7	—	—	—	—	—
	8	B +	GY	GY	GN	1
	9	—	—	—	—	—
	10	0 V GND	WH	BU	BU	2 ¹
	11	—	—	VT	—	—
	12	U ₂	BN	RD	RD	4
Housing	Shield	—	—	—	Housing	

Tab. 1: con.23 encoder cable pin assignment, incremental HTL

Length x [mm]	Diameter y [mm]
58	26

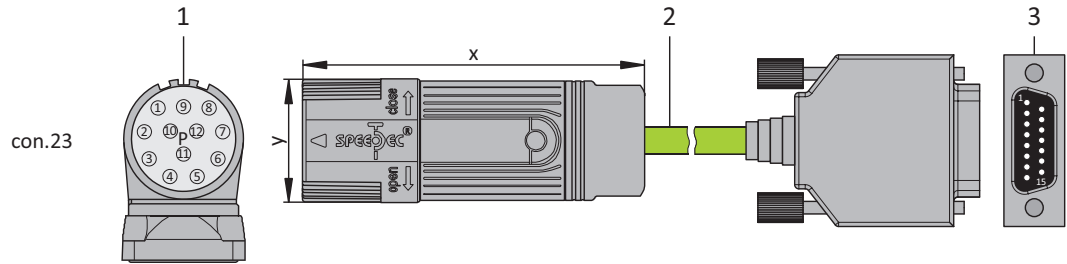
Tab. 2: con.23 dimensions

11.3.2 SSI encoders

Suitable encoder cables are described below.

11.3.2.1 Connection description

The encoder cable is available in plug connector size con.23 with a speedtec quick lock.



- 1 Plug connectors
- 2 STOEGER encoder cable
- 3 D-sub X4

Encoder cables – con.23 plug connectors

Connection diagram	Motor (1)			Cable (2)	Drive controller (3)
	Pin	Designation	Core color	Core color	Pin X4
	1	Clock +	VT	YE	8
	2	U ₂ Sense	BNGN	PK	12
	3	—	—	—	—
	4	—	—	—	—
	5	Data –	PK	BN	13
	6	Data +	GY	WH	5
	7	—	—	—	—
	8	Clock –	YE	GN	15
	9	—	—	—	—
	10	0 V GND	WHGN	BU	2
	11	—	—	—	—
	12	U ₂	BNGN	RD	4
Housing	Shield	—	—	Housing	

Tab. 3: con.23 encoder cable pin assignment, SSI

Length x [mm]	Diameter y [mm]
58	26

Tab. 4: con.23 dimensions

11.4 Additional documentation

Additional documentation related to the product can be found at

<http://www.stoeber.de/en/downloads/>

Enter the ID of the documentation in the Search field.

Documentation	ID
Connection method manual	443102



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13 Appendix

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13.1 Formula symbols

The formula symbols for values actually present in the application are marked with *.

Symbol	Unit	Explanation
C_F	μF	Capacitance of the operating capacitor for a Steinmetz connection
C_{maxPU}	F	Maximum charging capacity of the power unit
$\cos\phi_N$	–	Active factor for the motor at the nominal point
$\cos\phi_F$	–	Active factor of the forced ventilation unit at the nominal point
C_{PU}	F	Self-capacitance of the power unit
Δ	–	Delta connection
$\Delta\phi_2$	arcmin	Backlash at the output shaft with a blocked input
$\Delta\vartheta$	K	Temperature difference
ΔJ_B	kgcm^2	Additive mass moment of inertia of a motor with brake
Δm_B	kg	Additive weight of a motor with brake
D_{IA}	%	Reduction in the nominal current depending on the installation altitude
D_T	%	Reduction in the nominal current depending on the surrounding temperature
ED_{10}	%	Duty cycle based on 10 minutes
η	%	Efficiency
F_{2ax20}	N	Permitted axial force at the gear unit output for $n_{2m^*} \leq 20$ rpm (without radial force)
F_{2axN}	N	Permitted nominal axial force at the gear unit output (without radial force)
F_{2ax^*}	N	Actual axial force at the gear unit output
f_{2PU}	Hz	Output frequency of the power unit
F_{2rad20}	N	Permitted radial force on the gear unit output for $n_{2m^*} \leq 20$ rpm
F_{2radN}	N	Permitted nominal radial force at the gear unit output
F_{2rad^*}	N	Actual radial force on the gear unit output
fB_{mot}	–	Motor operating factor
fB_{op}	–	Operating mode operating factor
fB_t	–	Runtime operating factor
f_{mot^*}	Hz	Application-based motor rotating magnetic field frequency
f_N	Hz	Rotating magnetic field frequency at nominal speed
$f_{\text{PWM,PU}}$	Hz	Frequency of the pulse width modulation of the power unit
f_T	Hz	Rotating magnetic field frequency at nominal point
i	–	Gear ratio
i_{exact}	–	Mathematically exact gear ratio
$I_{1\text{maxCU}}$	A	Maximum input current of the control unit
$I_{1\text{mot}}$	A	Motor starting current
$I_{1N,PU}$	A	Nominal input current of the power unit
$I_{2\text{maxPU}}$	A	Maximum output current of the power unit
$I_{2N,PU}$	A	Nominal output current of the power unit
$I_{2N,PU(\text{red})}$	A	Reduced nominal output current of the power unit
$I_{2PU(A)}$	A	Output current of the power unit for axis A
$I_{2PU(B)}$	A	Output current of the power unit for axis B
I_C	A	Capacitor current for a Steinmetz connection
I_N	A	Nominal current
$I_{N,B}$	A	Nominal current of the brake at 20 °C
$I_{N,F}$	A	Nominal current of the forced ventilation unit
$I_{N,MF}$	A	Nominal current of the choke or motor filter
J	kgcm^2	Mass moment of inertia
J_1	kgcm^2	Mass moment of inertia relative to the gear unit input
J_{1^*}	kgcm^2	Actual mass moment of inertia relative to the gear unit input
J_{2^*}	kgcm^2	Actual mass moment of inertia relative to the gear unit output
K_{Bpb}	–	Factor by which the intervals between maintenance for the brake are extended if a Powerbox rectifier is used instead of a half-wave or bridge rectifier
l	mm	Length of the output shaft
$L_{pA,F}$	dB(A)	Noise level of the forced ventilation unit in the optimal operating range
m	kg	Weight (for gear units without lubricant)

Symbol	Unit	Explanation
M_{1mot}	Nm	Motor starting torque
M_{2k20}	Nm	Permitted tilting torque on the gear unit output for $n_{2m^*} \leq 20$ rpm
M_{2kN}	Nm	Permitted nominal tilting torque at the gear unit output
M_{2k^*}	Nm	Actual tilting torque on the gear unit output
M_{2N}	Nm	Nominal torque on the gear unit output (relative to n_{1N})
M_{2N^*}	Nm	Actual nominal torque at the gear unit output (relative to n_{1N})
M_{k^*}	Nm	Actual tilting torque on the output
M_{k100}	Nm	Permitted tilting torque on the output for $n_{m^*} \leq 100$ rpm
M_k	Nm	Permitted tilting torque on the output
$M_{N,B}$	Nm	Nominal braking torque
n_{1N}	rpm	Nominal speed at the gear unit input
n_2	rpm	Speed at the gear unit output
n_{2^*}	rpm	Actual speed at the gear unit output
n_{2m^*}	rpm	Actual average output speed
n_f	rpm	Nominal speed of the forced ventilation unit
n_{m^*}	rpm	Actual average motor speed
n_N	rpm	Nominal speed: The speed for which the nominal torque M_N is specified
p	–	Number of pole pairs
P_{B20}	W	Power consumption of the brake at 20 °C
P_{effRB}	W	Effective power at the external braking resistor
P_{maxRB}	W	Maximum power at the external braking resistor
P_N	kW	Nominal power: the power the motor is able to deliver long term in S1 mode at the nominal point (tolerance $\pm 5\%$)
P_{N^*}	kW	Actual nominal power that the motor can output in S1 operation at the nominal point
$P_{2N,PU}$	W	Nominal output power of the power unit
P_V	W	Power loss
$P_{V,CU}$	W	Power loss of the control unit
p_z	–	Number of poles
q_{vF}	m ³ /h	Delivery capacity of the forced ventilation unit in open air
R_{2minRB}	Ω	Minimum resistance of the external braking resistor
R_{intRB}	Ω	Resistance of the internal braking resistor
S	–	Service factor: Quotient of the nominal torque from the gear unit and the motor without consideration for thermal limiting performance. Represents a value for the reserve of the geared motor.
$\vartheta_{amb,max}$	°C	Maximum surrounding temperature
ϑ_{NAT}	°C	Nominal response temperature
T	min	Cycle time
$t_{11B,AC}$	ms	Response delay: Time from when the current is turned off until the braking torque increases for AC-side switching of the brake rectifier
$t_{11B,AC,DC}$	ms	Response delay: Time from when the current is turned off until the braking torque increases for AC-side and DC-side switching of the brake rectifier
t_{2B}	ms	Disengagement time: time from when the current is turned on until the torque begins to drop
t_{op}	min	Operating time
τ_{th}	°C	Thermal time constant
U_{1CU}	V	Input voltage of the control unit
U_{1PU}	V	Input voltage of the power unit
U_{1rf}	V	Input voltage of the rectifier
U_{2PU}	V	Output voltage of the power unit
$U_{2PU,ZK}$	V	Output voltage of the power unit for the DC link connection (typical values: 400 V _{AC} corresponds to 560 V _{DC} , 480 V _{AC} corresponds to 680 V _{DC})
U_{2rf}	V	Output voltage of the rectifier
U_{max}	V	Maximum voltage
U_{MOT}	V	Motor voltage
U_N	V	Nominal voltage of the motor
$U_{N,B}$	V	Nominal voltage of brake
$U_{N,F}$	V	Nominal voltage of the forced ventilation unit

Symbol	Unit	Explanation
U_{offCH}	V	Switch-off threshold of the brake chopper
U_{onCH}	V	On limit of the brake chopper
$W_{\text{B,R01}}$	10^6 J	Work done by friction until reaching 0.1 mm of wear
$W_{\text{B,Radj}}$	10^6 J	Work done by friction achievable by the brake until readjustment is necessary
X_2	mm	Distance of the shaft shoulder to the force application point
X_{Bmax}	mm	Maximum permitted air gap at which the braking armature still experiences attraction
$X_{\text{B,N}}$	mm	Nominal air gap of brake
Y	–	Star connection
Y_2	mm	Distance of the shaft axis to the axial force application point
Y_{Blim}	mm	Wear limit of the brake disc
Z_2	mm	Distance of the shaft shoulder to the middle of the output bearing
Z_{Bmax}	h^{-1}	Maximum permitted switching frequency of the brake

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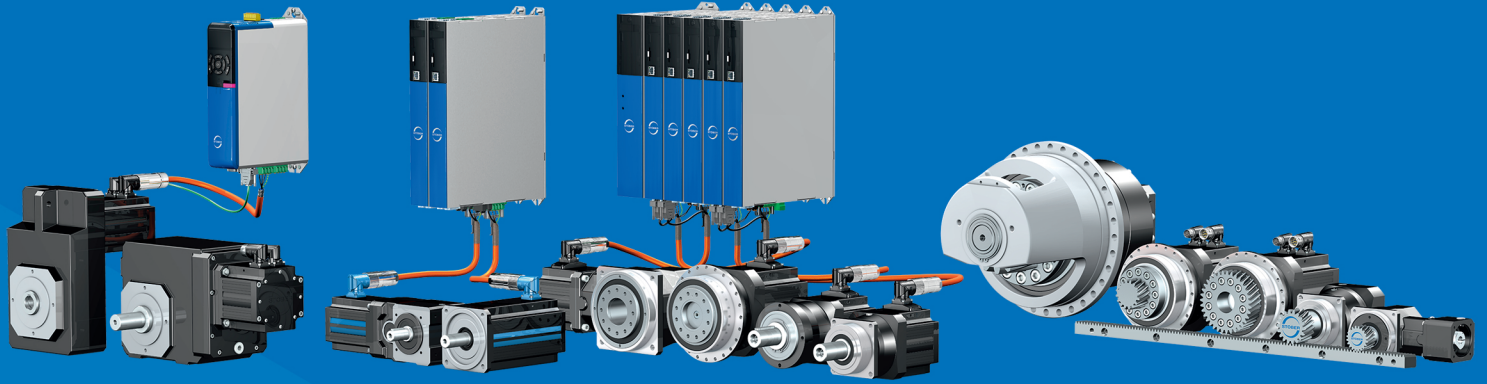
13.3 Sales terms and delivery conditions

You can find our current sales terms and delivery conditions at <http://www.stoeber.de/en/gtc>.

13.4 Publication details

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You can find current versions of PDF files online at <http://www.stoeber.de/en/downloads/>.



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