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1 Safety information

1.1 General safety instructions



WARNING!
When connecting and operating the motors considerable hazards to the life and health of persons may occur!

- ▶ When connecting the motor observe the following safety instructions, the operating instructions for the motor and applicable national, local and system-specific regulations.

1.2 Safety when making the electrical connection



WARNING!
Electrical shock by touching live unpainted parts of the motor!

- ▶ The electrical connection of the motor may only be carried out by a qualified electrician.
- ▶ Before connecting the motor, switch the relevant system or machine to zero potential with the main switch and protect the main switch against being turned on again!
- ▶ Close the entire connector housing before turning on the motor.

Motor Connection Plan Asynchronous Motors

1.3 Avoid connection errors

NOTICE

Electrical connection errors can cause damage to the motor and its components.

- ▶ Make sure that the cables and connectors to be connected meet this motor connection plan.
- ▶ Carefully note the information on the motor name plate and this motor connection plan. For questions please contact STÖBER Service department.

1.4 Safe function and EMC of the drive system

NOTICE

If connection cables or a drive controller that are not designed for the motor are used to make the electrical connection for the motor, this may result in damage to the motor or that compliance with the legal requirements for EMC is no longer provided and claims under the warranty will be null and void.

- ▶ You should use connection cables and a drive controller specifically designed for your motor from the STÖBER product range.

1.5 Applied standards

Asynchronous motors meet the requirements of the standard VDE 0530 / DIN EN 60034.

Colors are coded as per IEC 60757 and are only relevant for the internal motor connection strands

2 Power connection

2.1 Asynchronous motor without pole-changing

NOTICE

The motor can be damaged by electrical connection errors!

- ▶ Check before making the connection whether the connection voltage and configuration of the motor (see name plate) match the supply voltage or the selected connection diagram.

Operating mode	Connection diagram	Configuration
Operation/direct start-up		Δ
Start-up star/delta (not permissible for operation on a drive controller)		Y / Δ
Operation/direct start-up		Y



Information

You can change the direction of rotation of the motor by exchanging the two supply lines.

2.2 Asynchronous motor with separated windings

NOTICE

The motor can be damaged by electrical connection errors!

- Note that a pole-changing motor is not suitable for operation on a drive controller.
- Check before making the connection whether the connection voltage and configuration of the motor (see name plate) match the supply voltage or the selected connection diagram.

Operating mode	Connection diagram	Configuration
Low speed		Y / Y
High speed		

2.3 Asynchronous motor with Dahlander windings

NOTICE

The motor can be damaged by electrical connection errors!

- Note that a pole-changing motor is not suitable for operation on a drive controller.
- Check before making the connection whether the connection voltage and configuration of the motor (see name plate) match the supply voltage or the selected connection diagram.

2.3.1 With 6 connection clamps (direct switching on)

Operating mode	Connection diagram	Configuration
Without pole-changing switch	Circuit on terminal board	Δ / YY, Y / YY
Low speed		
High speed		
With pole-changing switch		Δ / YY Y / YY

2.3.2 With 9 connection clamps

Operating mode	Connection diagram	Configuration
Without start-up pole-changing switch	Circuit on terminal board	Δ / YY, Y / YY
Start-up low speed		Δ / YY
Operation low speed		Δ / YY, Y / YY
Operation high speed		

Operating mode	Connection diagram	Configuration
With start-up pole-changing switch		Δ / YY, Y / YY

3 Options

3.1 Temperature sensor

NOTICE

The thermal winding protection can be damaged by electrical connection errors!

- Carefully note the type of the temperature sensor indicated on the motor name plate.



3.2 Connection for external fan motor

NOTICE

The external fan motor can be damaged by electrical connection errors!

- ▶ Check before making the connection whether the connection voltage and design of the external fan motor (see name plate) match the supply voltage or the selected connection diagram.

Connection type	Connection diagram
Three-phase current (delta configuration)	
Three-phase current (star configuration)	
Alternating current in the Steinmetz circuit with operating capacitor C _B	
Alternating current with operating capacitor C _B	

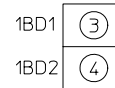
Connection type	Connection diagram
Alternating current	

3.3 Brake connection

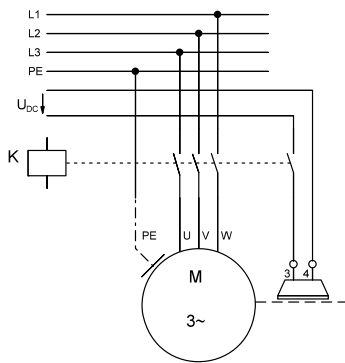
NOTICE

The brake can be damaged by electrical connection errors!

- ▶ Read before connecting the brake the corresponding operation manual.
- ▶ Check before connecting the brake whether the external DC voltage or the output voltage of the rectifier matches the connection voltage of the brake U_{DC} (see name plate).
- ▶ Note the connection designations of the brake and the rectifier.



3.3.1 Connection without rectifier



3.3.2 Connection with rectifier

NOTICE

The rectifier can be damaged by exceeding the maximum permissible ambient temperature!

- ▶ If you take full advantage of the rated power of the motor or operate the motor without forced air ventilation in the lower speed range on a drive controller, do not build a rectifier in the terminal box of the motor, but in a well-ventilated cabinet.



Information

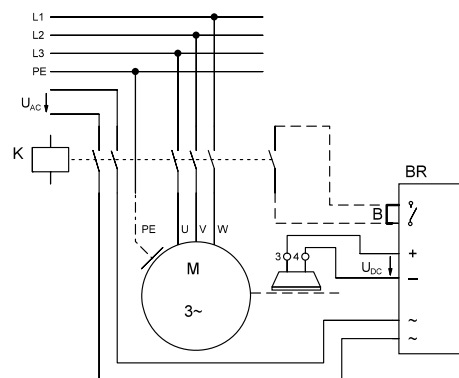
When the brake needs to engage faster in time-critical applications, remove the bridge B and switch the brake simultaneously on the DC side (in the following circuit diagrams displayed as a dashed line).

3.3.2.1 Rectifier with external power supply

NOTICE

The rectifier or brake can be damaged by electrical connection errors!

- ▶ Check before connecting the rectifier whether the external power supply matches the connection voltage of the rectifier U_{AC}. For the Powerbox rectifier is valid: 220 V ≤ U_{AC} ≤ 277 V.



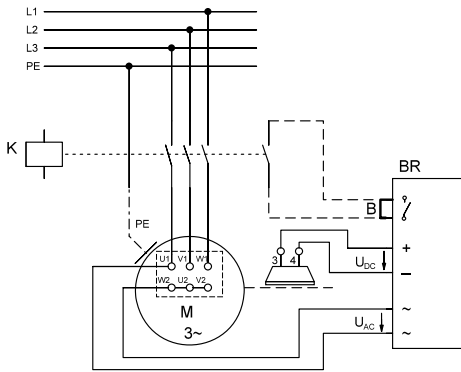
3.3.2.2 Rectifier with power supply from the motor terminals (star configuration)

* This option is available only for asynchronous motors without pole-changing.

NOTICE

The rectifier or brake can be damaged by electrical connection errors!

- ▶ For the connection voltage of the rectifier is valid:
 $U_{AC} \geq \text{Line voltage } U_L \times 0,58$.
 For the Powerbox rectifier is valid additionally: $220 \text{ V} \leq U_{AC} \leq 277 \text{ V}$.
- ▶ The motor must not be connected to a drive controller, but only directly to the mains.
- ▶ The motor may start only connected directly to the mains (no star-delta configuration).
- ▶ The configuration of the motor on the name plate must be "star".



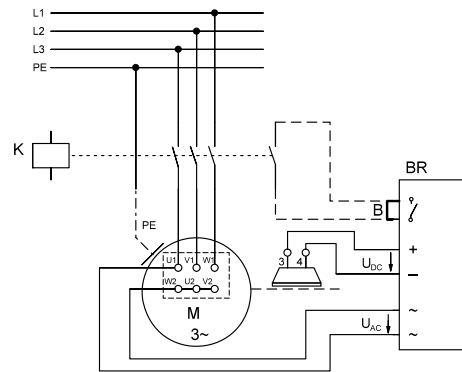
3.3.2.3 Rectifier with power supply from the motor terminals (delta configuration)

* This option is available only for asynchronous motors without pole-changing.

NOTICE

The rectifier or brake can be damaged by electrical connection errors!

- ▶ The Powerbox rectifier may **not** be connected to the motor terminals with delta configuration.
- ▶ For the connection voltage of the rectifier is valid:
 $U_{AC} \geq \text{Line voltage } U_L$.
- ▶ The motor must not be connected to a drive controller, but only directly to the mains.
- ▶ The motor may start up only connected directly to the mains (no star-delta configuration).
- ▶ The configuration of the motor on the name plate must be "delta".



3.4 Connection for encoder

NOTICE

The encoder can be damaged by connection errors!

- ▶ You should therefore check before making the connection whether the type of the encoder (see motor name plate) and the pin assignment of the plug connector match your application.

3.4.1 Incremental encoder

Incremental encoder (HTL or TTL)		
Typ in accordance with specifications on the nameplate		
Socket	Pin	Signal
<p>Size con.23</p>	1	B inverted
	2	U sense (if present)
	3	N
	4	N inverted
	5	A
	6	A inverted
	7	
	8	B
	9	As of 05/2006 no longer contacted in the encoder
	10	0 V GND
	11	0 V GND
	12	+ UB (see nameplate)

3.4.2 Absolute value encoder*

* This option is available only for asynchronous motors with external fan.

Multiturn absolute value encoder (SSI)			
Socket	Pin	Signal	Color
<p>Size con.23</p>	1	Clock +	VT
	2**	U sense	WHGN
	3		
	4		
	5	Data -	PK
	6	Data +	GY
	7		
	8	Clock -	YE
	9		
	10	0 V GND	WHGN
	11		
	12	Up +	BNGN

** Pin 2 is connected with pin 10 in the connection socket

3.4.3 Additional options

NOTICE

If your motor includes other options or attachment parts, make note of the corresponding technical documentation in addition.